

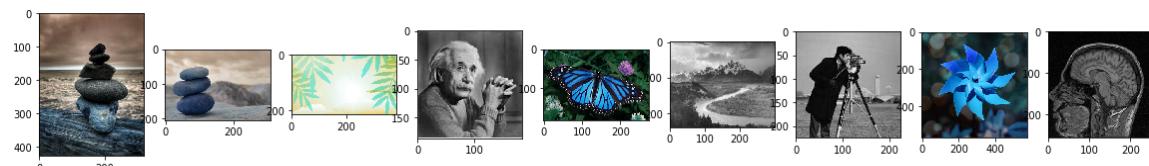
In [1]:

```
# -*- coding: utf-8 -*-
"""
@author: UzairAzhar
"""

#helper functions in helper_functions.py file
from helper_functions import load_images_from_folder
from helper_functions import plot_image
from helper_functions import hist_equalization
from helper_functions import rgbExclusion
from helper_functions import convolution
from helper_functions import box_filter_conv
from helper_functions import gaussian_filter_conv
from helper_functions import add_noise
from helper_functions import gaussianFilter_and_medianFilters
from helper_functions import mesh_plots
from helper_functions import sobel
from helper_functions import laplacian
from helper_functions import canny
```

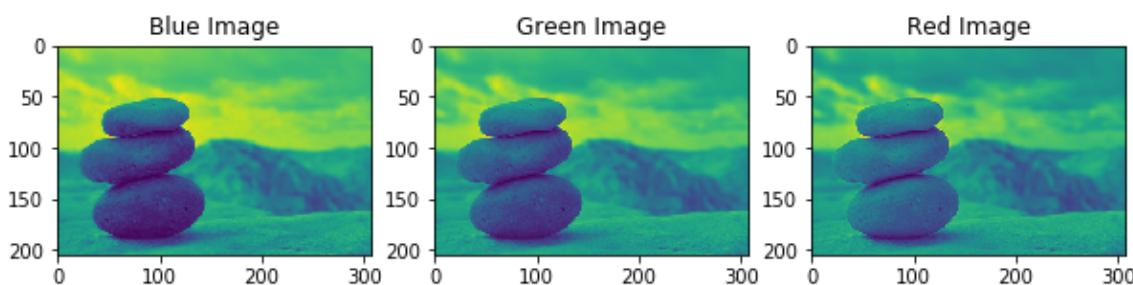
In [2]:

```
#2.1
#Add path where images are and plot them
path_of_img_dir=(r"images")
images=load_images_from_folder(path_of_img_dir)
plot_image(images)
```



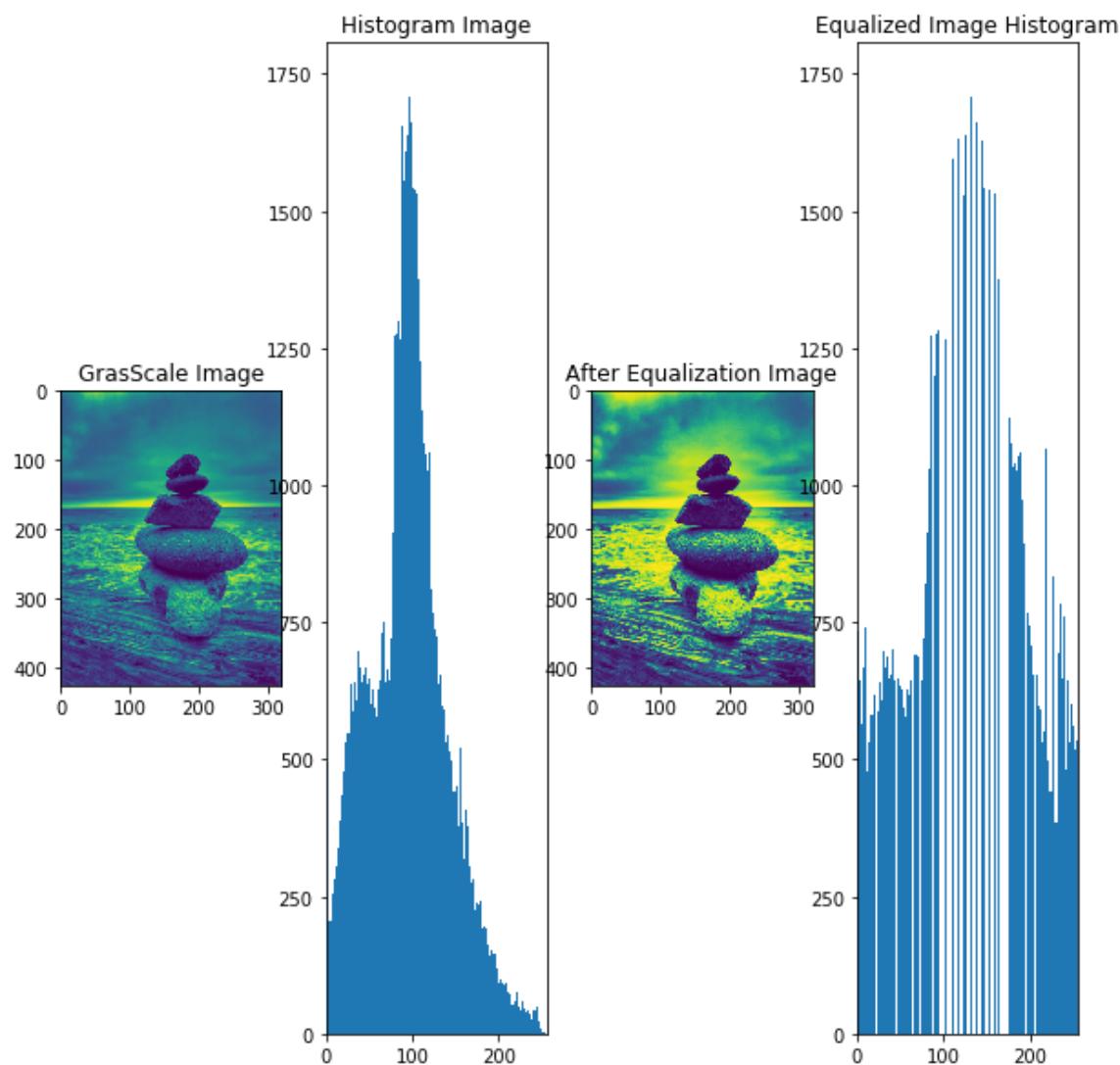
In [3]:

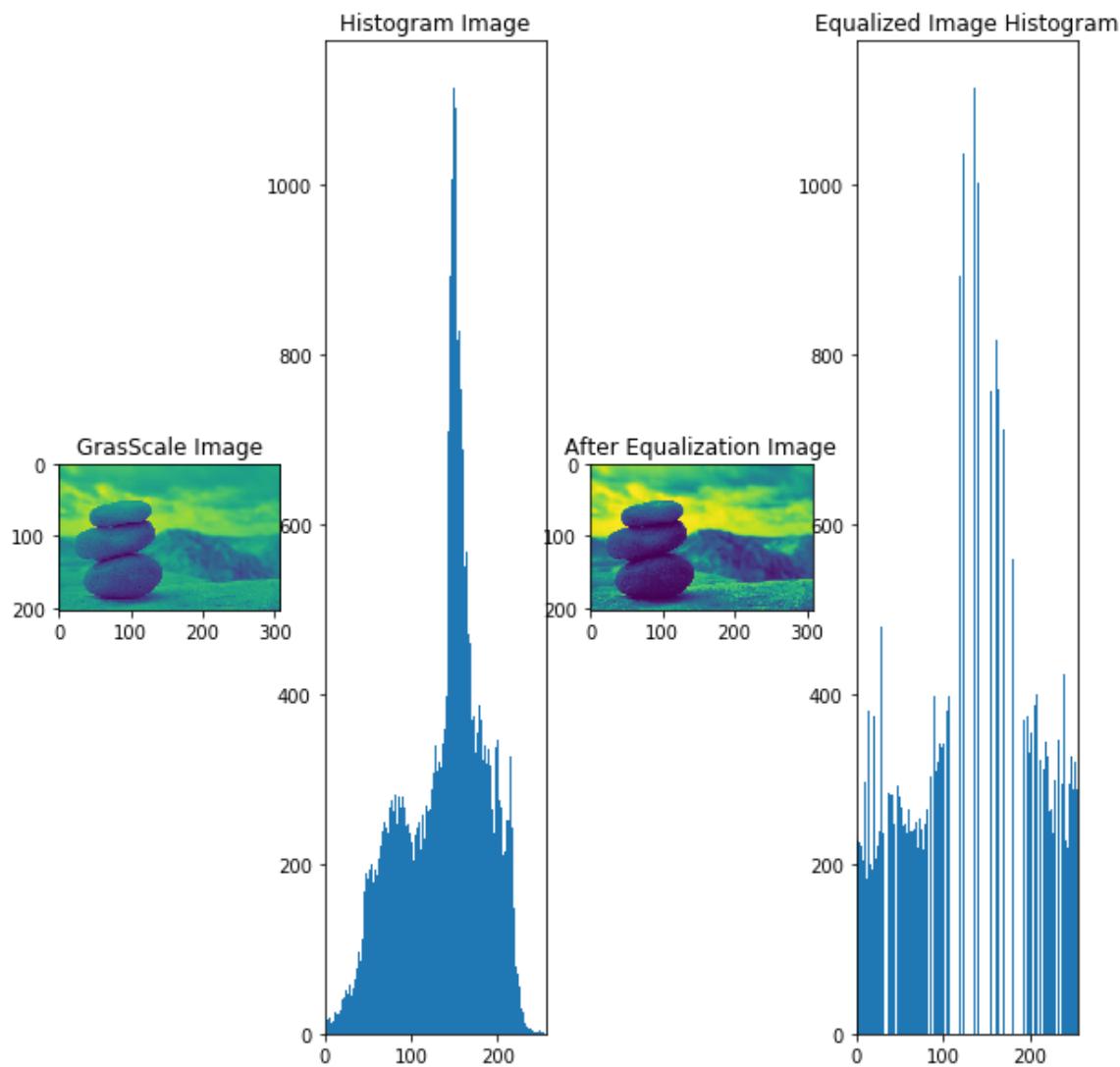
```
# In[] : 2.2 #rgbExclusion
# RGB Exclusion done for any particular Image
image_number=1 # 2nd image in dir has been selected for rgbExclusion
[B,G,R]=rgbExclusion(images[image_number])
```

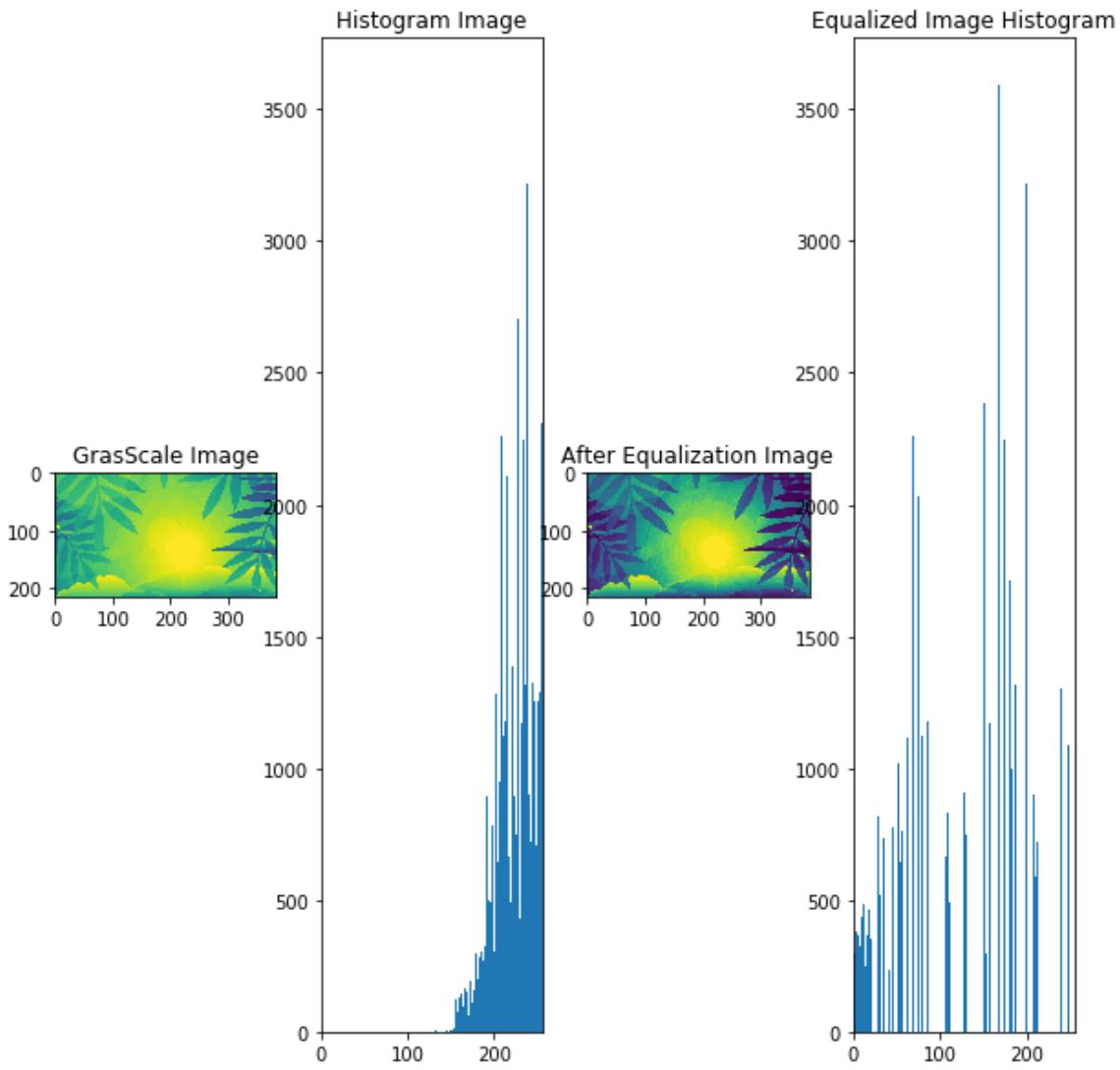


In [4]:

```
# In[] : 2.3 # Equalization
#In this function first histogram of original image has been drawn and then after equalization, both image and histogram is drawn
hist_equalization(images)
```





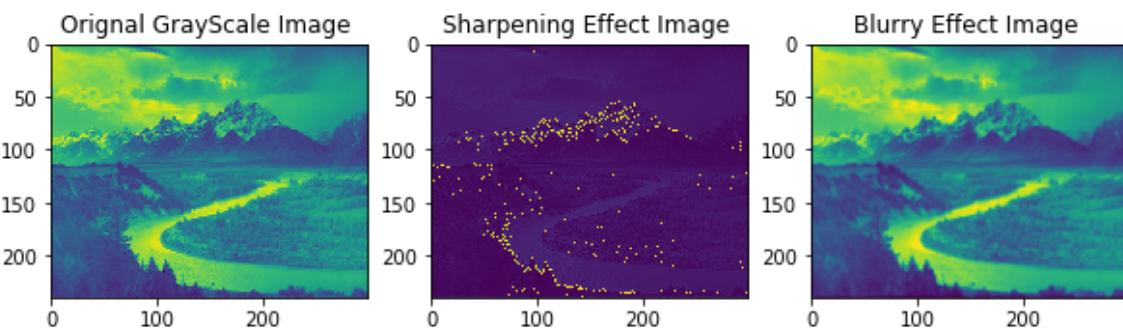


In [5]:

```
# In[ ] : 2.4 # Convolution
# here we have done convolution with sharpening filter and blurry filter(box) using own
implementation of
#conv and compared it with built in implementation
image=images[5] # image 6 in dir has been selected for convolution implementation purpo
se
conv_img_diff=convolution(image)
print('Diff in Images = %d\nHence both Manual and Libs Convolution results are same'%co
nv_img_diff)
```

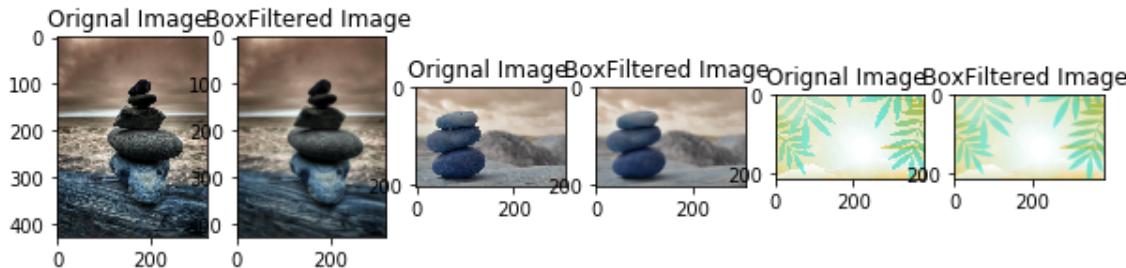
Diff in Images = 0

Hence both Manual and Libs Convolution results are same



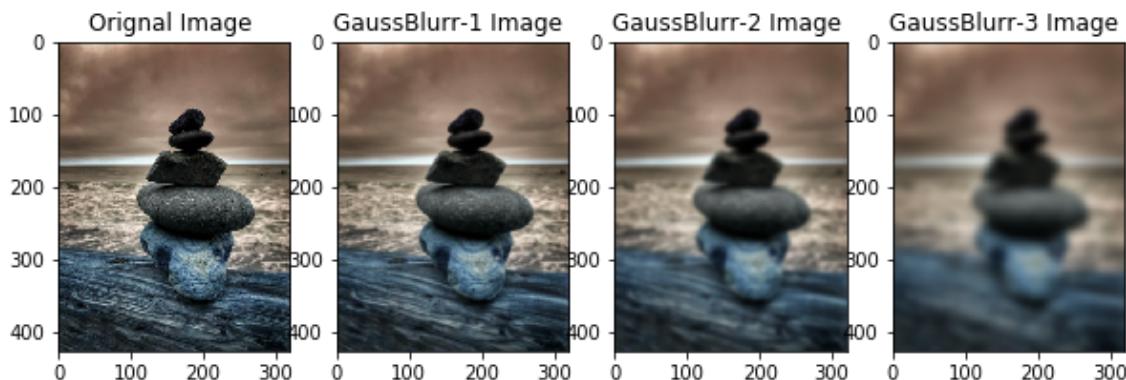
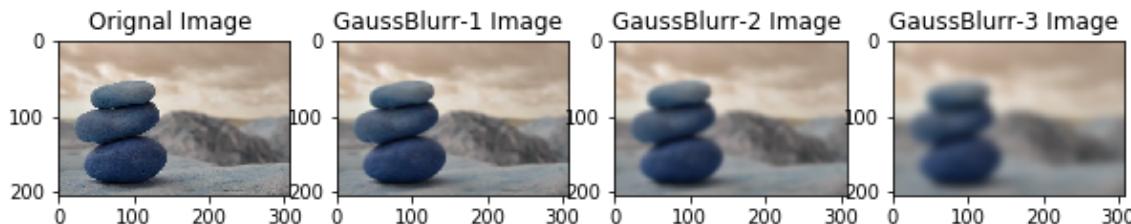
In [7]:

```
# In[] : 2.5 # Image Processing Operations  
#2.51  
# here box filter has been applied on any 3 images  
box_filter_conv(images)
```



In [8]:

```
#2.52  
# here gaussian filter has been applied on two images with varying kernel size to vary  
sigma  
gaussian_filter_conv(images)
```



In [9]:

```
#2.53
# Here on all images
# 1) Gaussian Noise
# 2) Salt and Pepper
# has been added, but only one image has been displayed, rest are just output for further use
[sp_noise_images,gauss_noise_images]=add_noise(images)
```

C:\Users\uzair\Documents\MuhammadUzair-Azhar\helper_functions.py:231: MatplotlibDeprecationWarning: Adding an axes using the same arguments as a previous axes currently reuses the earlier instance. In a future version, a new instance will always be created and returned. Meanwhile, this warning can be suppressed, and the future behavior ensured, by passing a unique label to each axes instance.

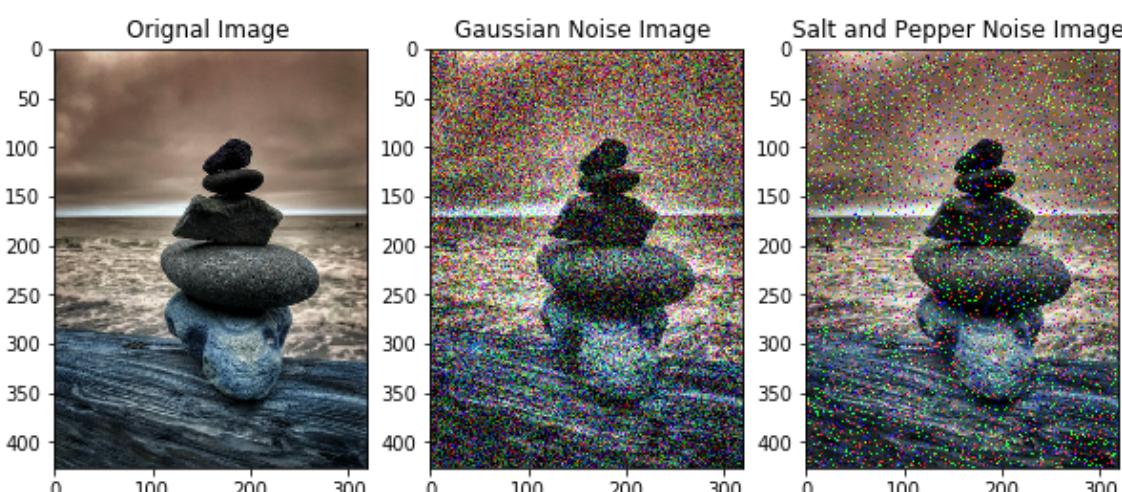
```
ax=plt.subplot(131)
```

C:\Users\uzair\Documents\MuhammadUzair-Azhar\helper_functions.py:235: MatplotlibDeprecationWarning: Adding an axes using the same arguments as a previous axes currently reuses the earlier instance. In a future version, a new instance will always be created and returned. Meanwhile, this warning can be suppressed, and the future behavior ensured, by passing a unique label to each axes instance.

```
ax=plt.subplot(132)
```

C:\Users\uzair\Documents\MuhammadUzair-Azhar\helper_functions.py:239: MatplotlibDeprecationWarning: Adding an axes using the same arguments as a previous axes currently reuses the earlier instance. In a future version, a new instance will always be created and returned. Meanwhile, this warning can be suppressed, and the future behavior ensured, by passing a unique label to each axes instance.

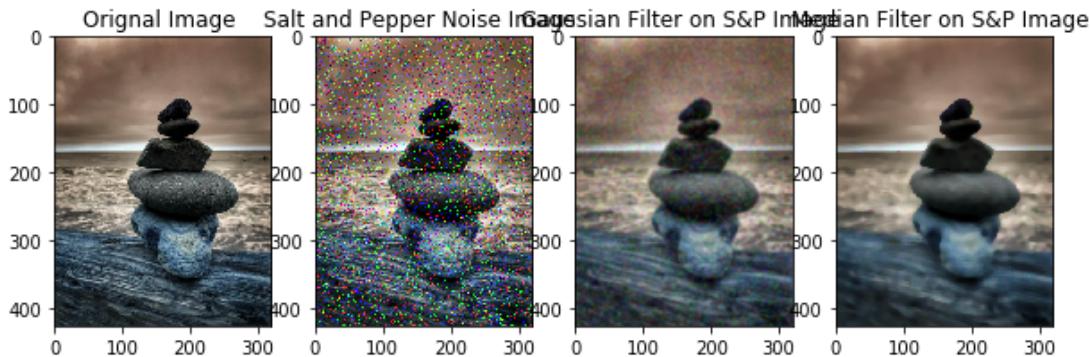
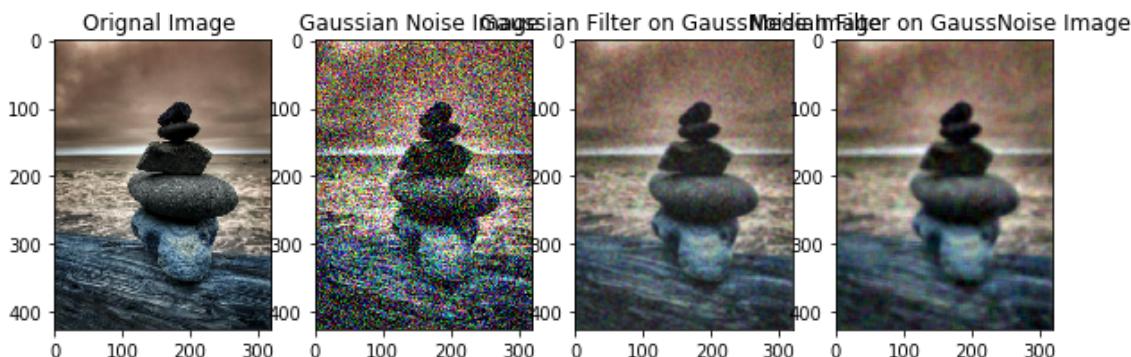
```
ax=plt.subplot(133)
```



In [48]:

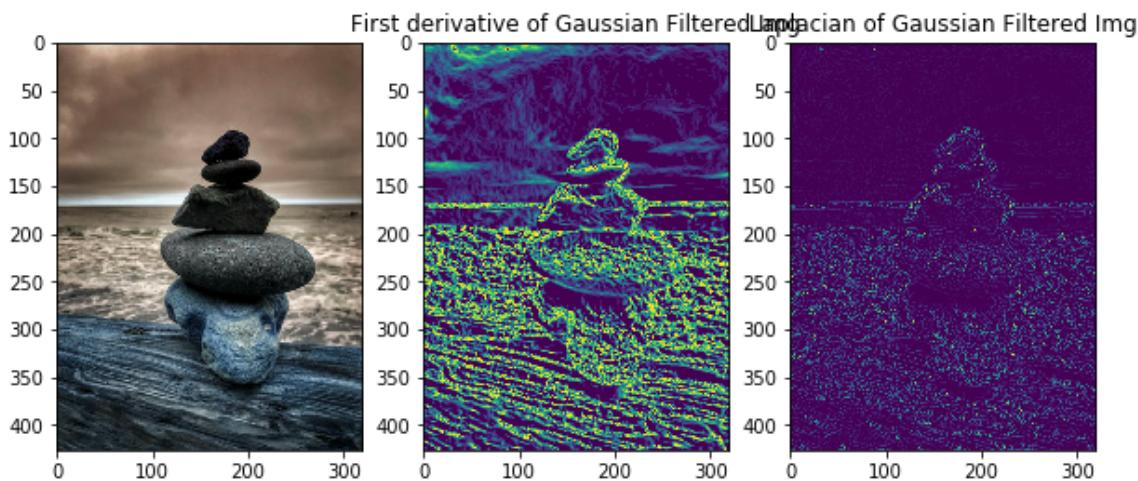
#2.54

```
gaussianFilter_and_medianFilters(images,sp_noise_images,gauss_noise_images)
```

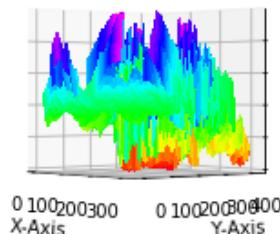


In [10]:

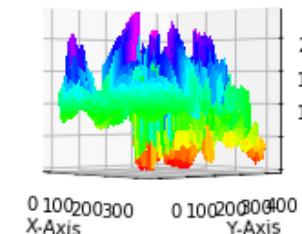
```
#2.55
# here mesh plots of all images has been generated and plotted that includes
#1)Gaussian Filter
#2) First deriv of Gaussian Filter
#3)Second deriv of Gaussian Filter
mesh_plots(images)
```



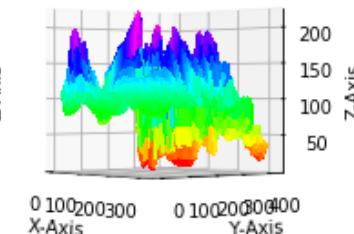
Gauss Filter Window 5x5



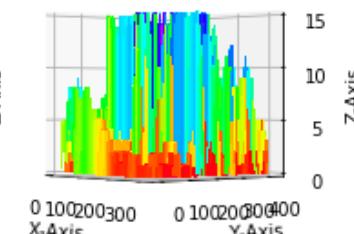
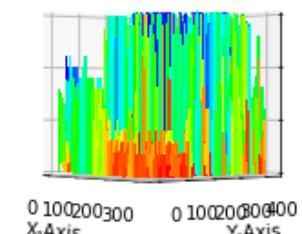
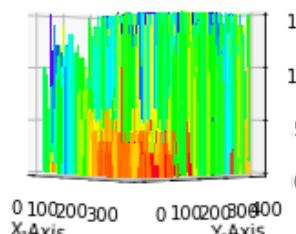
Gauss Filter Window 15x15



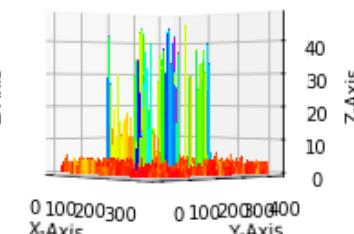
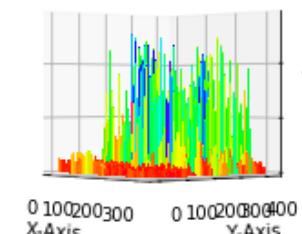
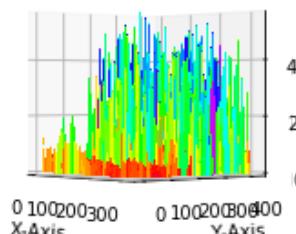
Gauss Filter Window 29x29

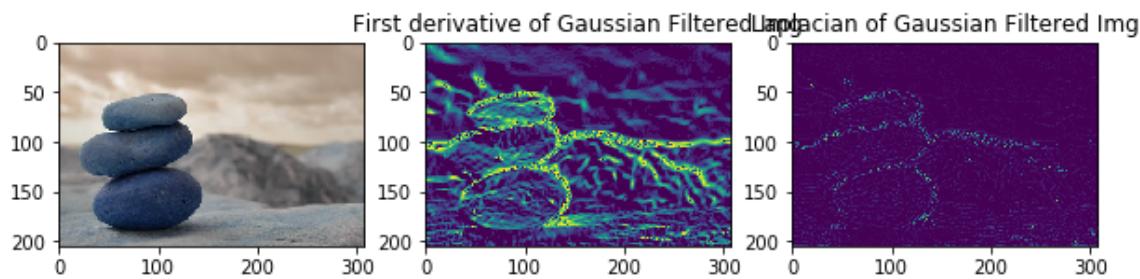


Deriv of Gauss Filter Window 1x1 | Deriv of Gauss Filter Window 3x3 | Deriv of Gauss Filter Window 5x5

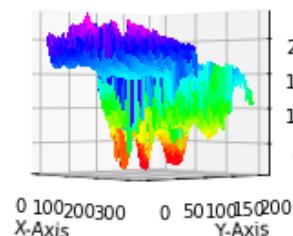


Laplacian Gauss Filter Window | Laplacian of Gauss Filter Window | Laplacian of Gauss Filter Window 29x29

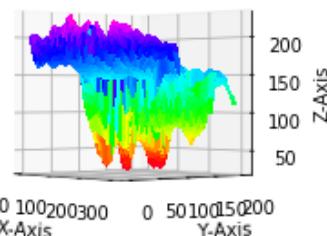




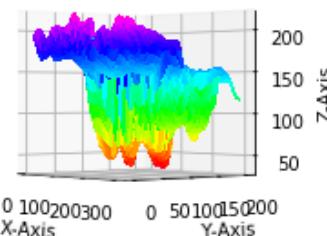
Gauss Filter Window 5x5



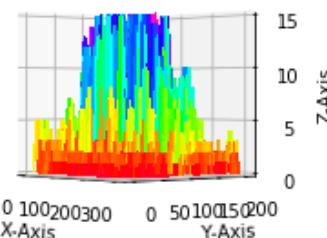
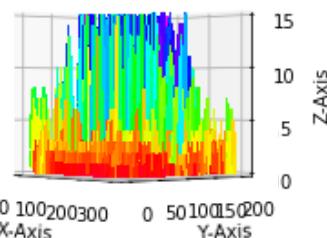
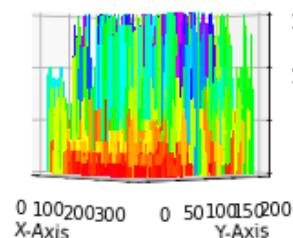
Gauss Filter Window 15x15



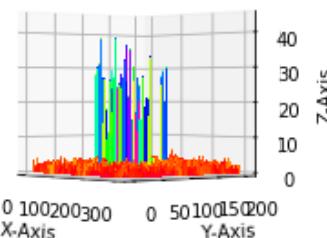
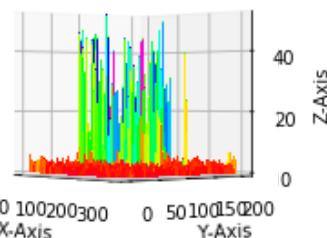
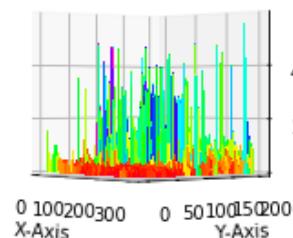
Gauss Filter Window 29x29



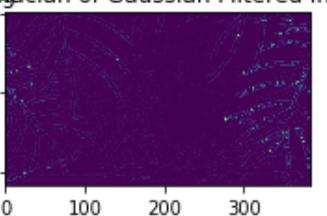
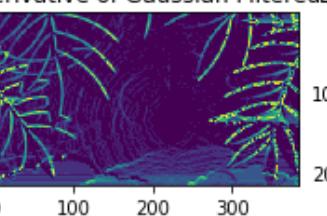
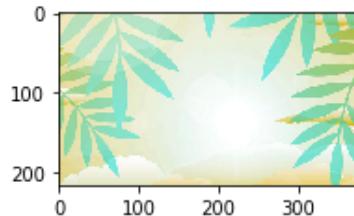
Deriv of Gauss Filter Window 1x1 Deriv of Gauss Filter Window 3x3 Deriv of Gauss Filter Window 5x5

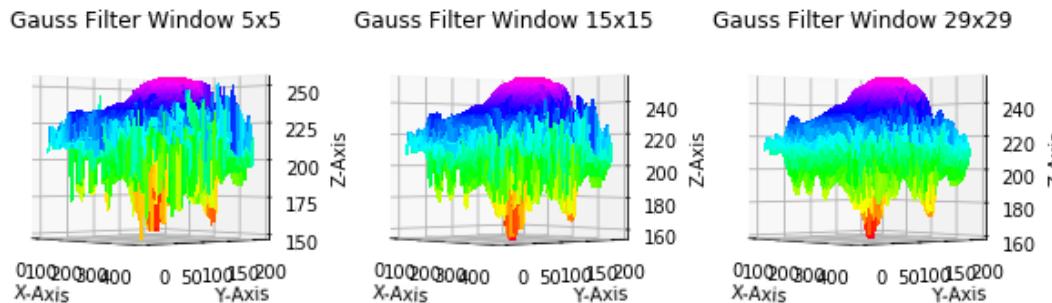


Laplacian Gauss Filter Window 5x5 Laplacian of Gauss Filter Window 15x15 Laplacian of Gauss Filter Window 29x29

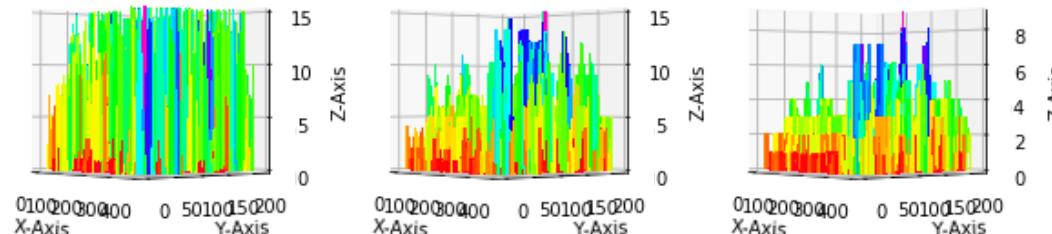


First derivative of Gaussian Filtered Img Laplacian of Gaussian Filtered Img

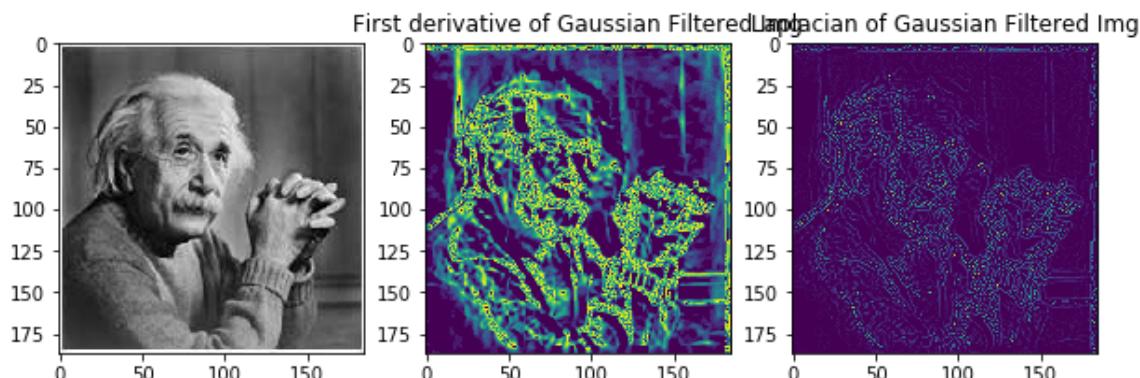
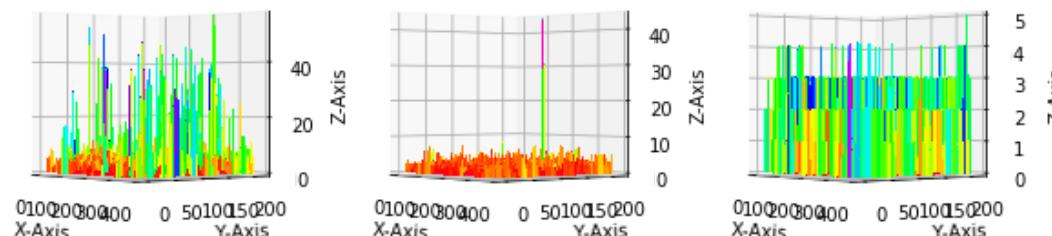


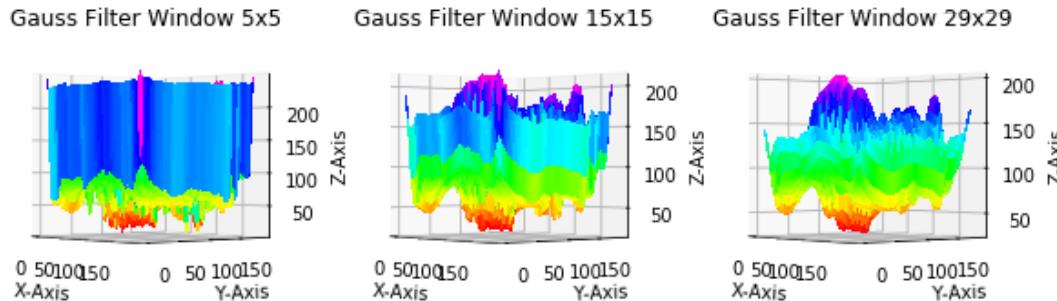


Deriv of Gauss Filter Window 1x1 Deriv of Gauss Filter Window 3x3 Deriv of Gauss Filter Window 5x5

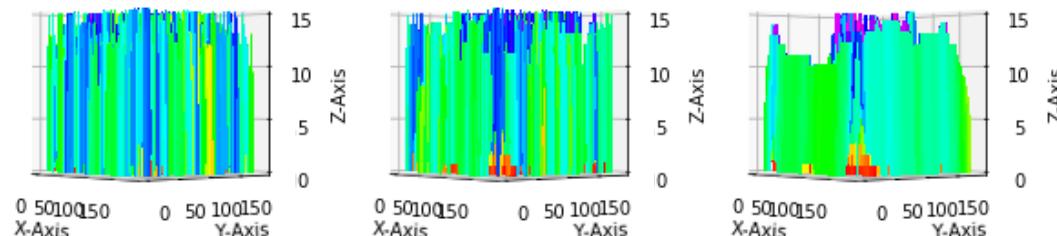


Laplacian Gauss Filter Window Laplacian of Gauss Filter Window Laplacian of Gauss Filter Window 29x29

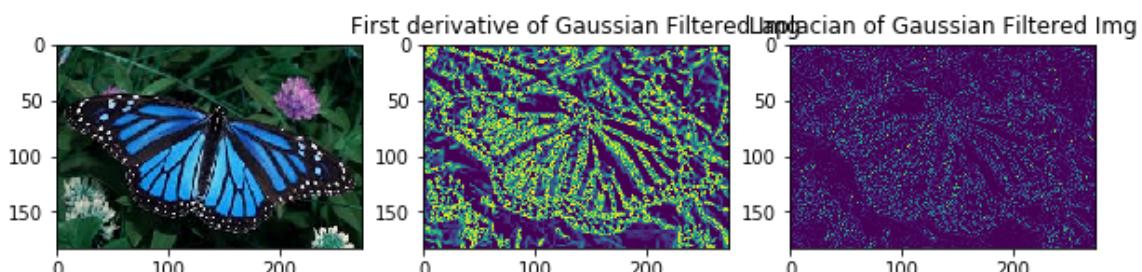
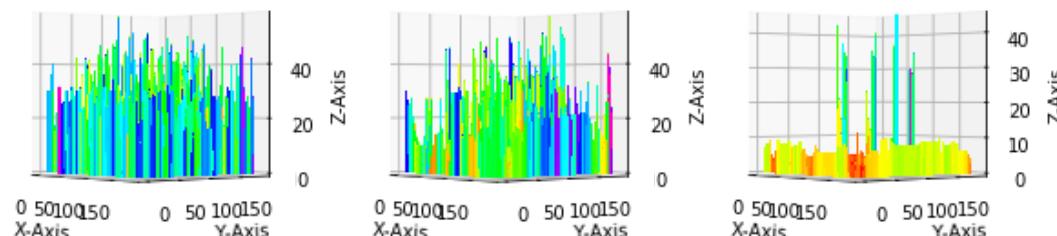


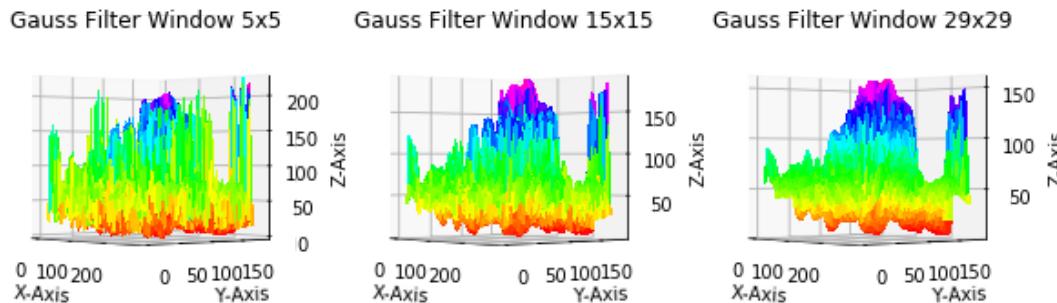


Deriv of Gauss Filter Window 1x1Deriv of Gauss Filter Window 3x3Deriv of Gauss Filter Window 5x5

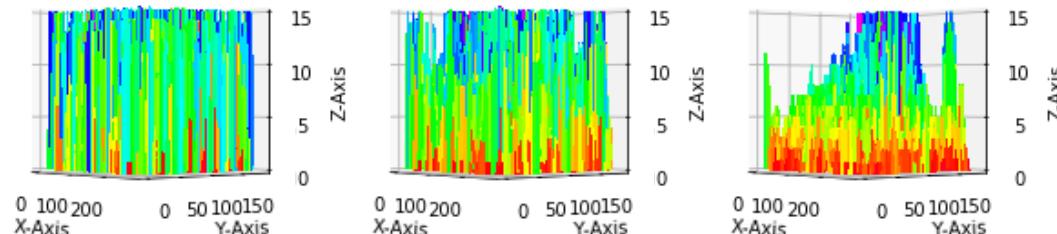


Laplacian Gauss Filter WindowLaplacian of Gauss Filter WindowLaplacian of Gauss Filter Window 29x29

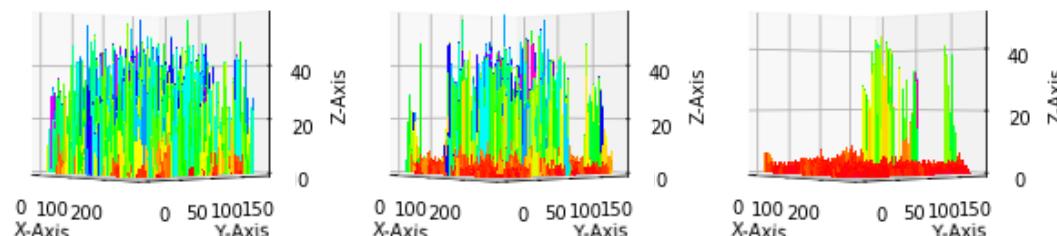




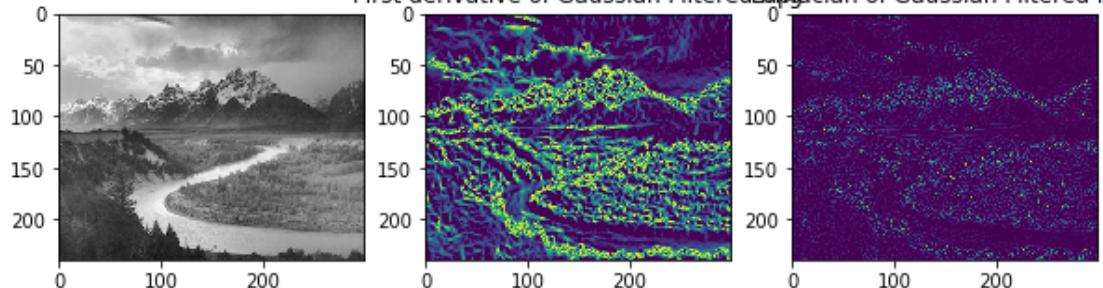
Deriv of Gauss Filter Window 1x1 Deriv of Gauss Filter Window 3x3 Deriv of Gauss Filter Window 5x5

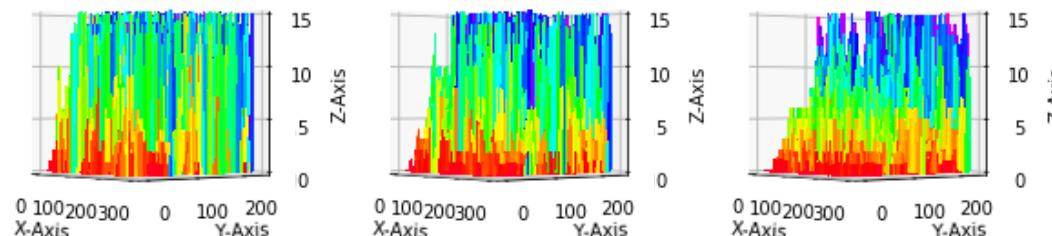
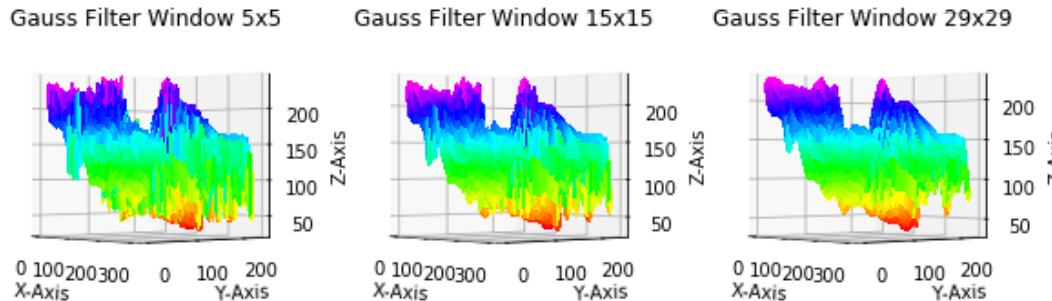


Laplacian Gauss Filter Window Laplacian of Gauss Filter Window Laplacian of Gauss Filter Window 29x29

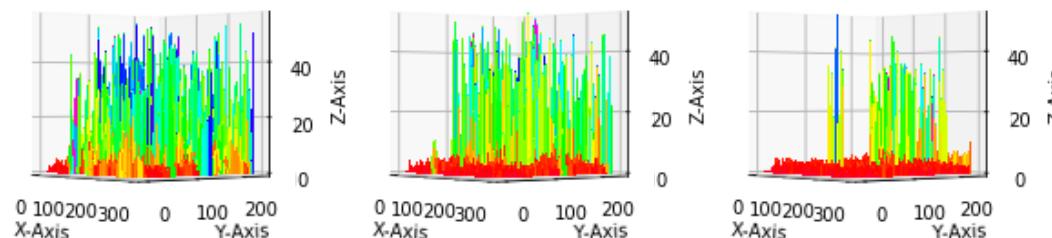


First derivative of Gaussian Filtered Img Laplacian of Gaussian Filtered Img

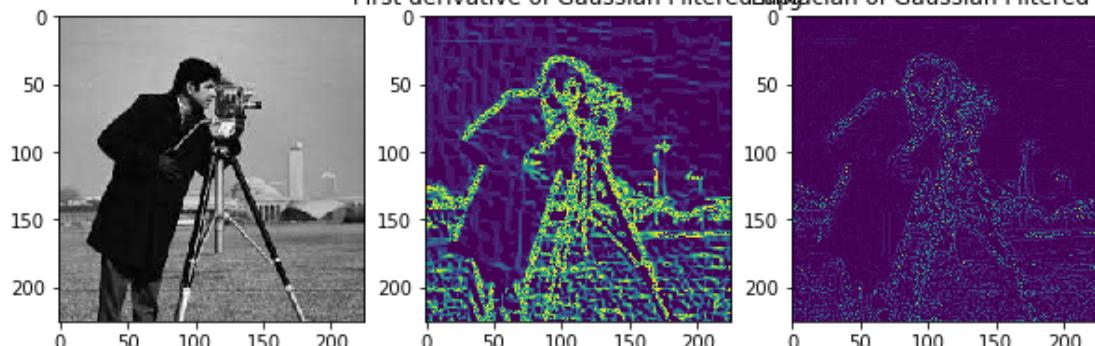


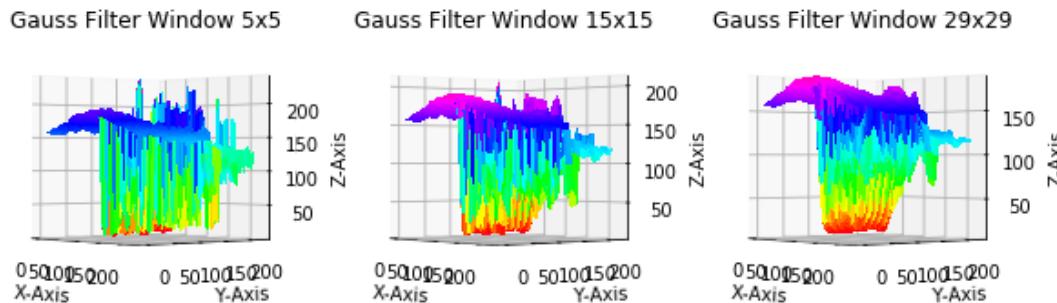


Laplacian Gauss Filter Window 5x5Laplacian of Gauss Filter Window 15x15Laplacian of Gauss Filter Window 29x29

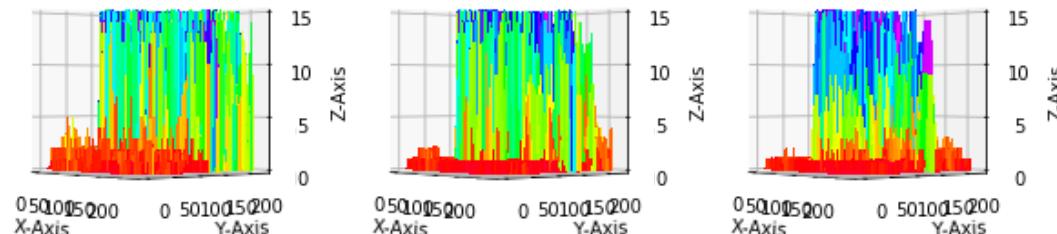


First derivative of Gaussian Filtered ImgLaplacian of Gaussian Filtered Img

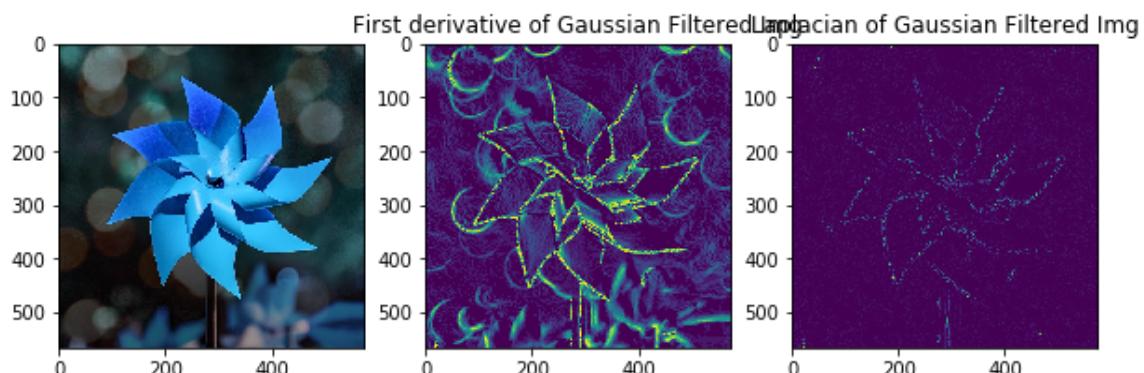
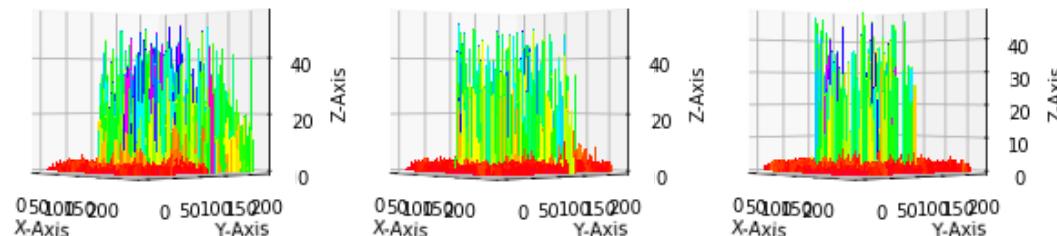


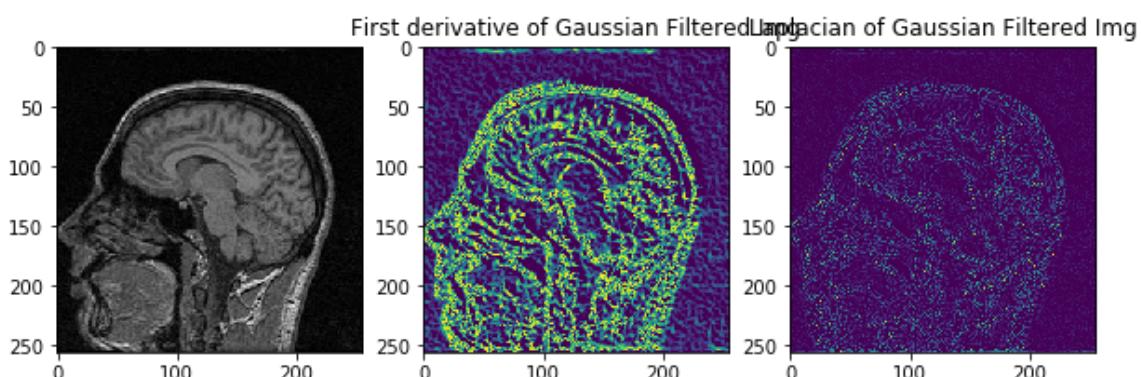
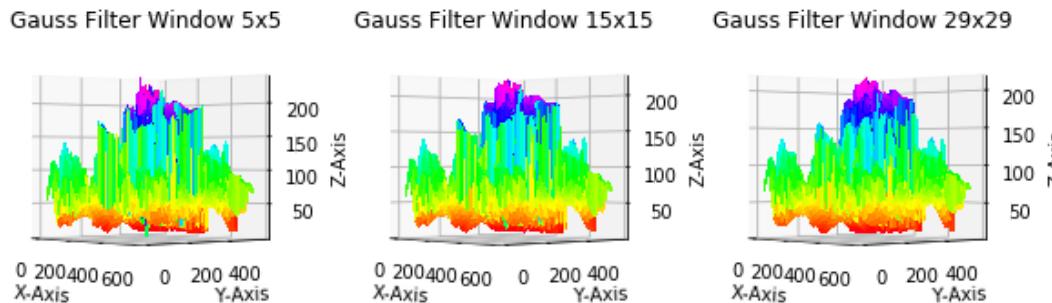


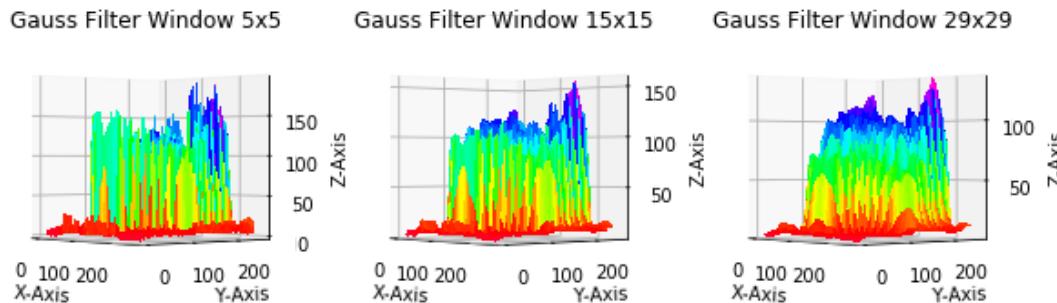
Deriv of Gauss Filter Window 1x1Deriv of Gauss Filter Window 3x3Deriv of Gauss Filter Window 5x5



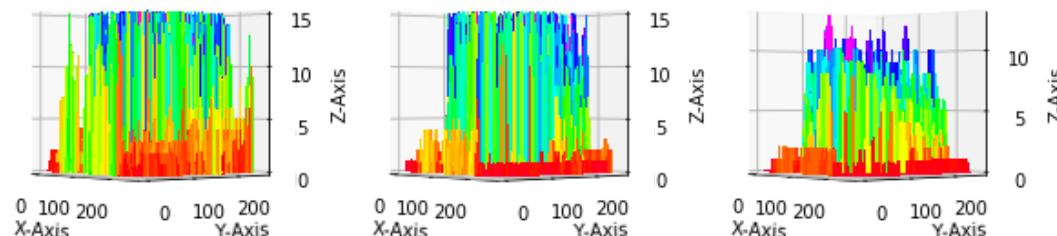
Laplacian Gauss Filter WindowLaplacian of Gauss Filter WindowLaplacian of Gauss Filter Window 29x29



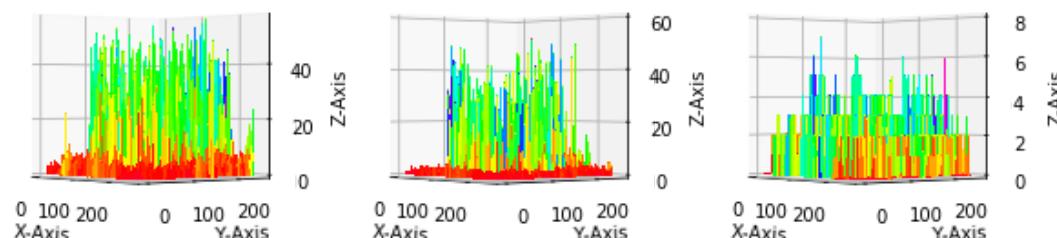




Deriv of Gauss Filter Window 1x1 Deriv of Gauss Filter Window 3x3 Deriv of Gauss Filter Window 5x5

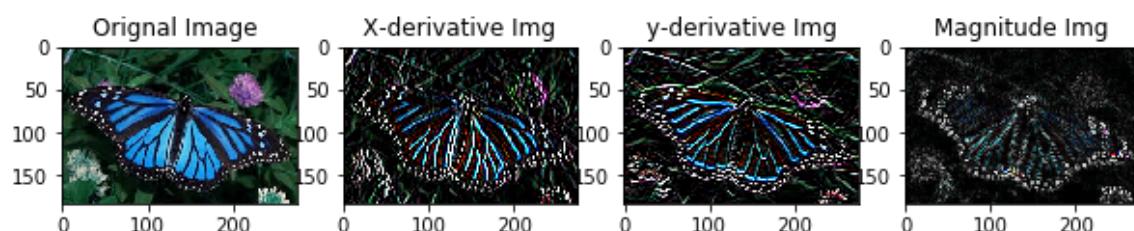
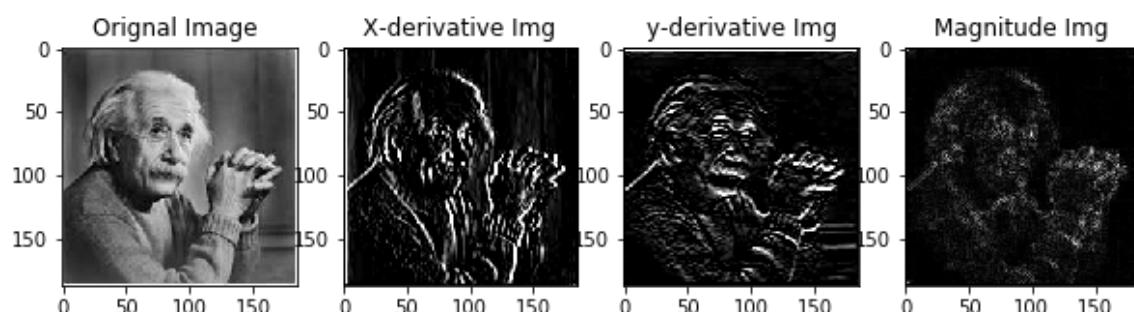
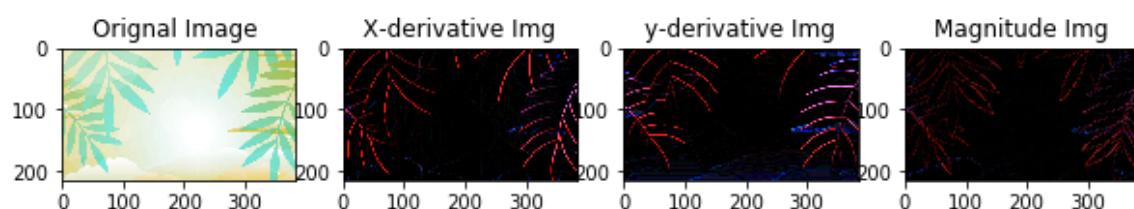
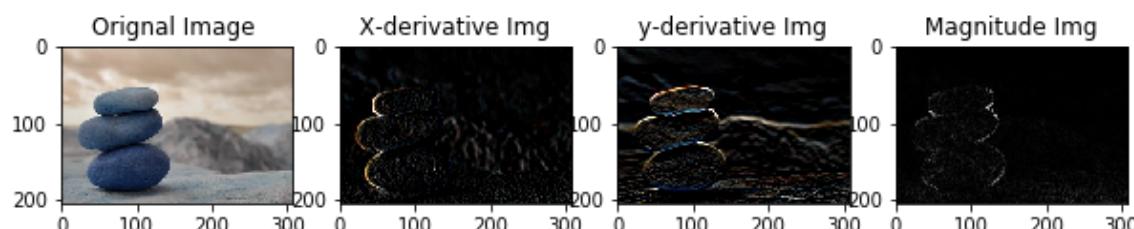
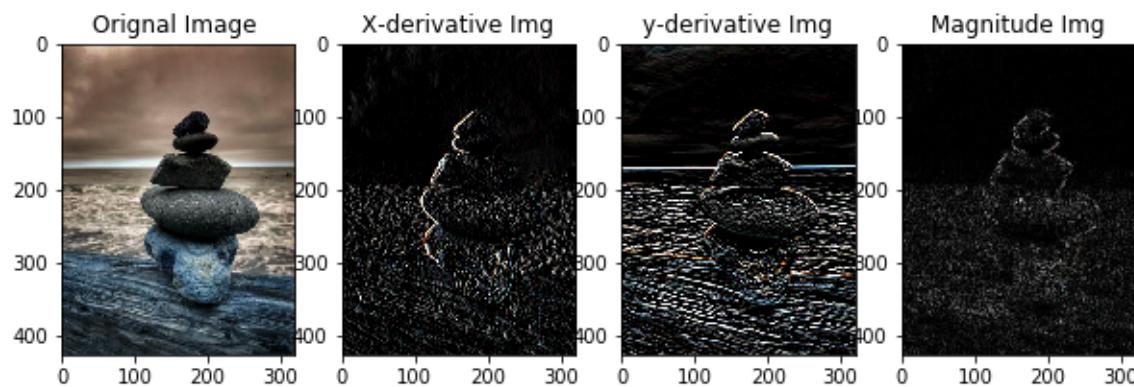


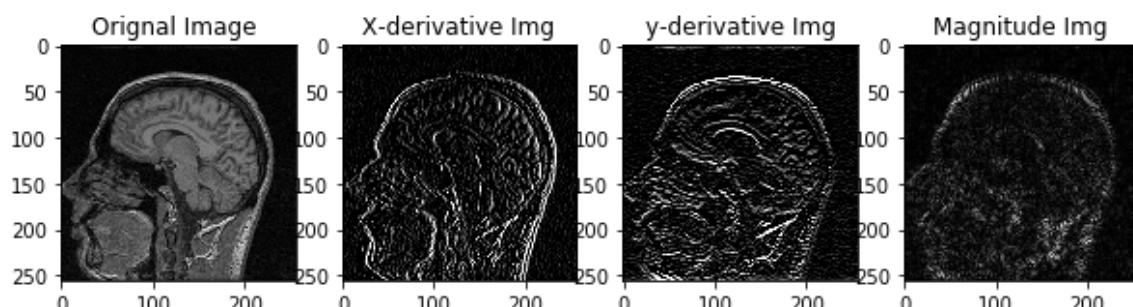
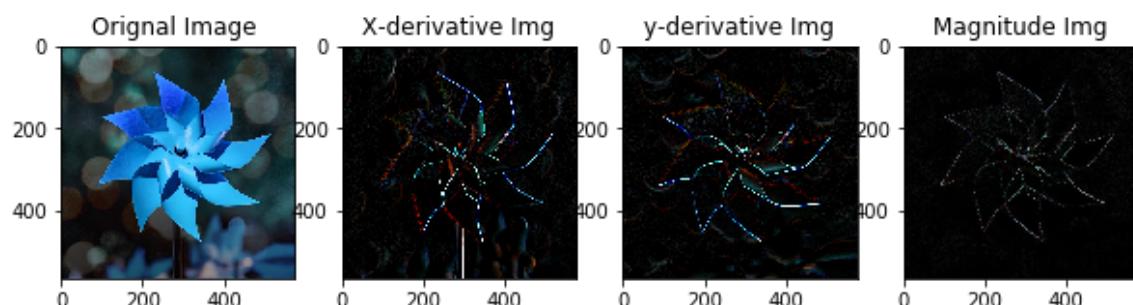
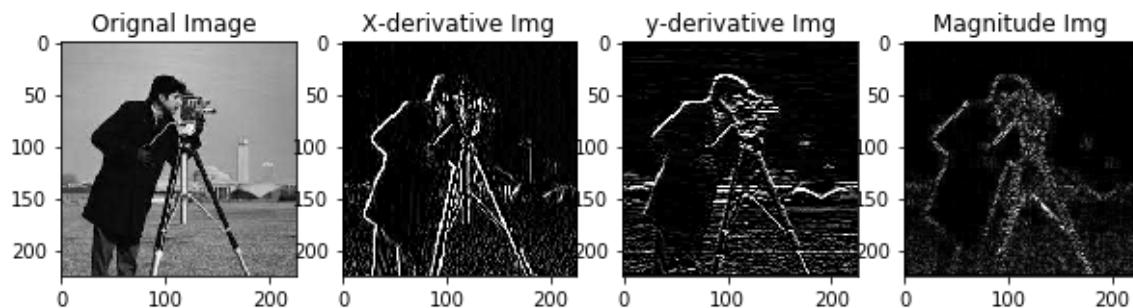
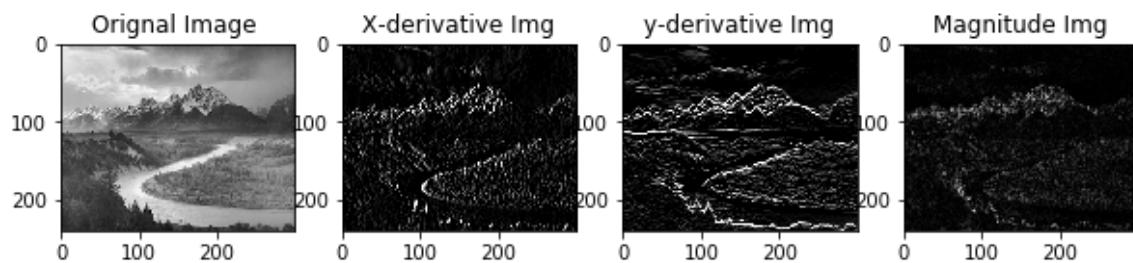
Laplacian Gauss Filter Window Laplacian of Gauss Filter Window Laplacian of Gauss Filter Window 29x29



In [11]:

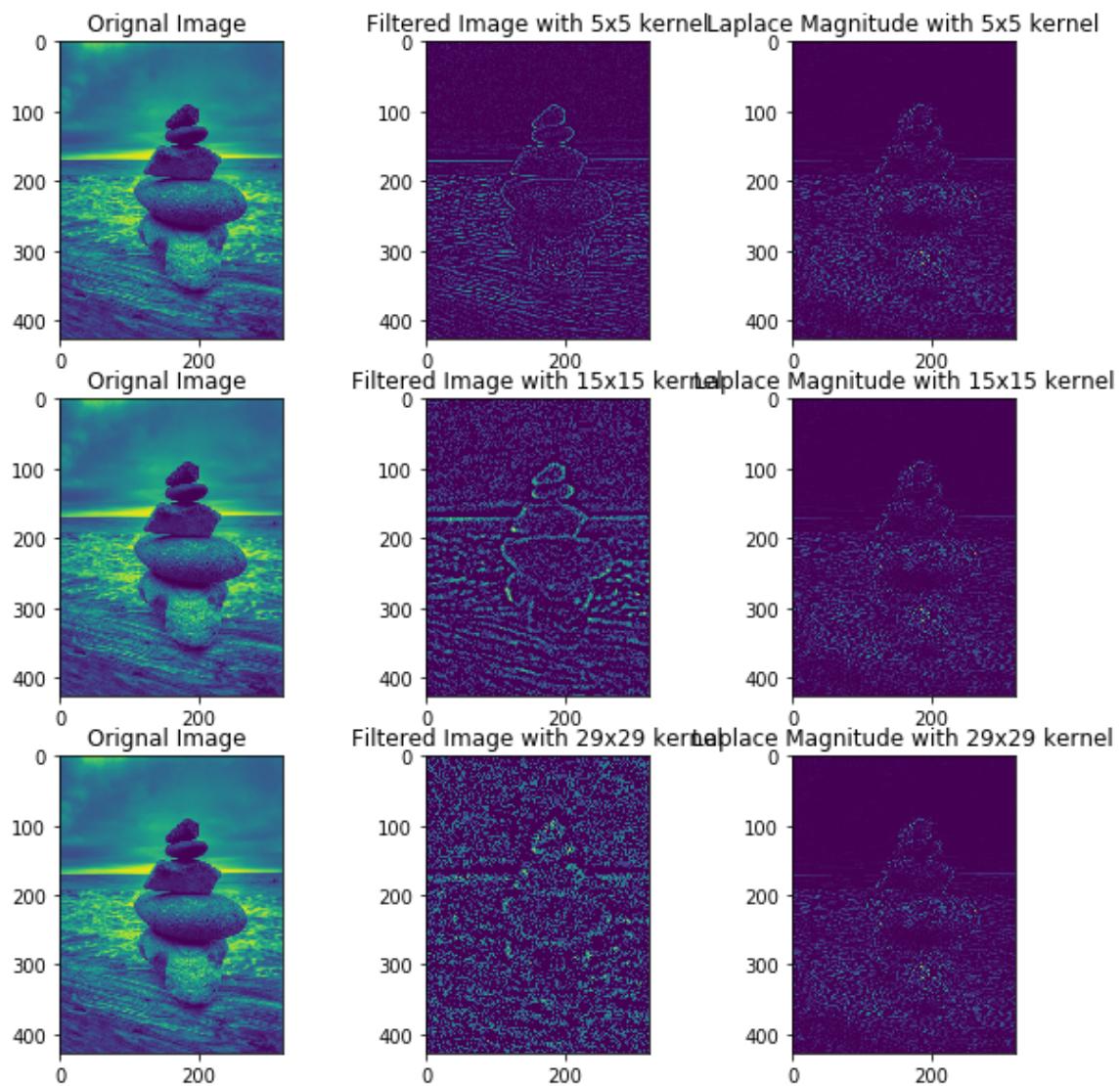
```
#2.61
# Here sobel filter has been applied on all images and plotted
sobel(images)
```

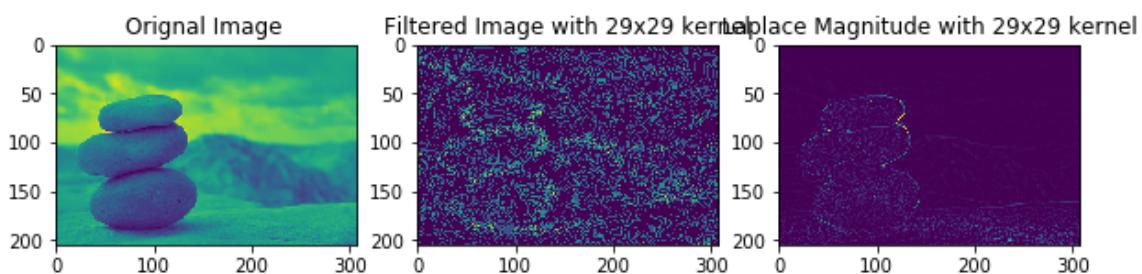
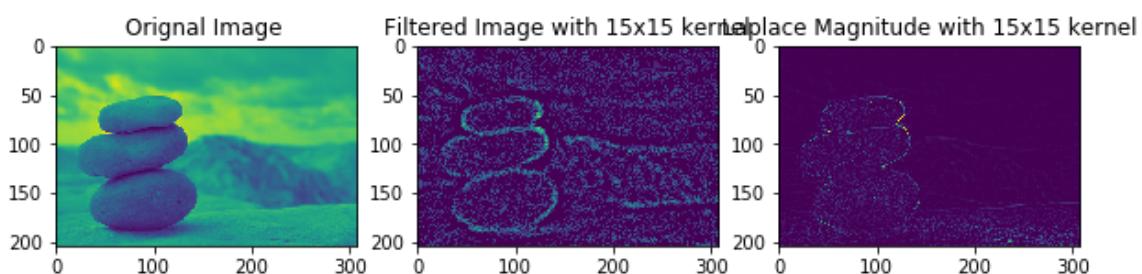
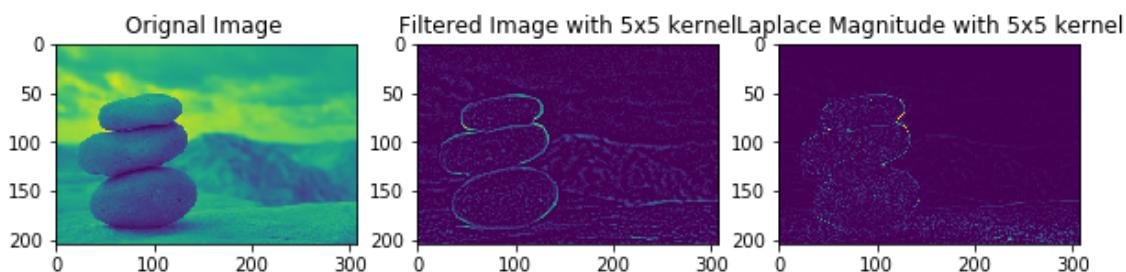


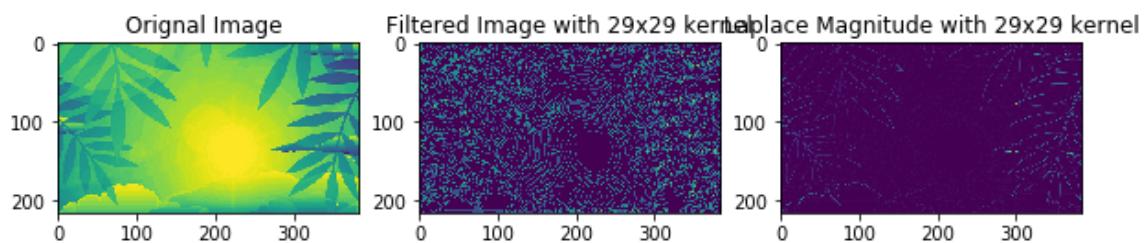
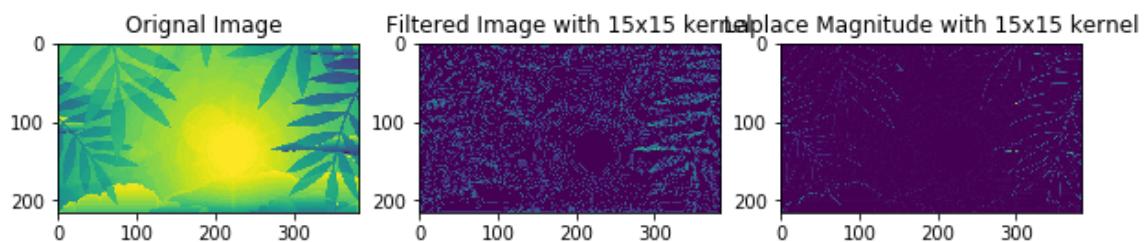
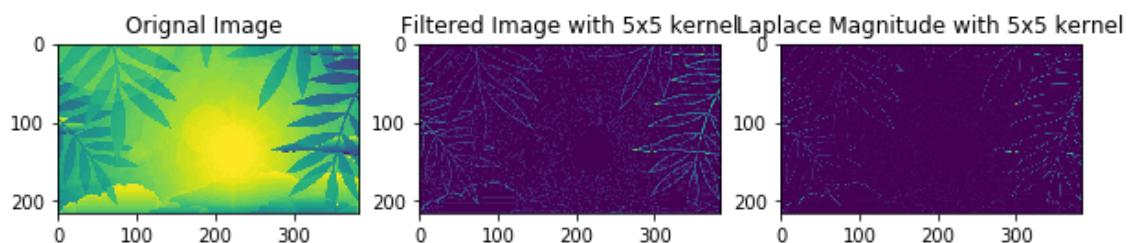


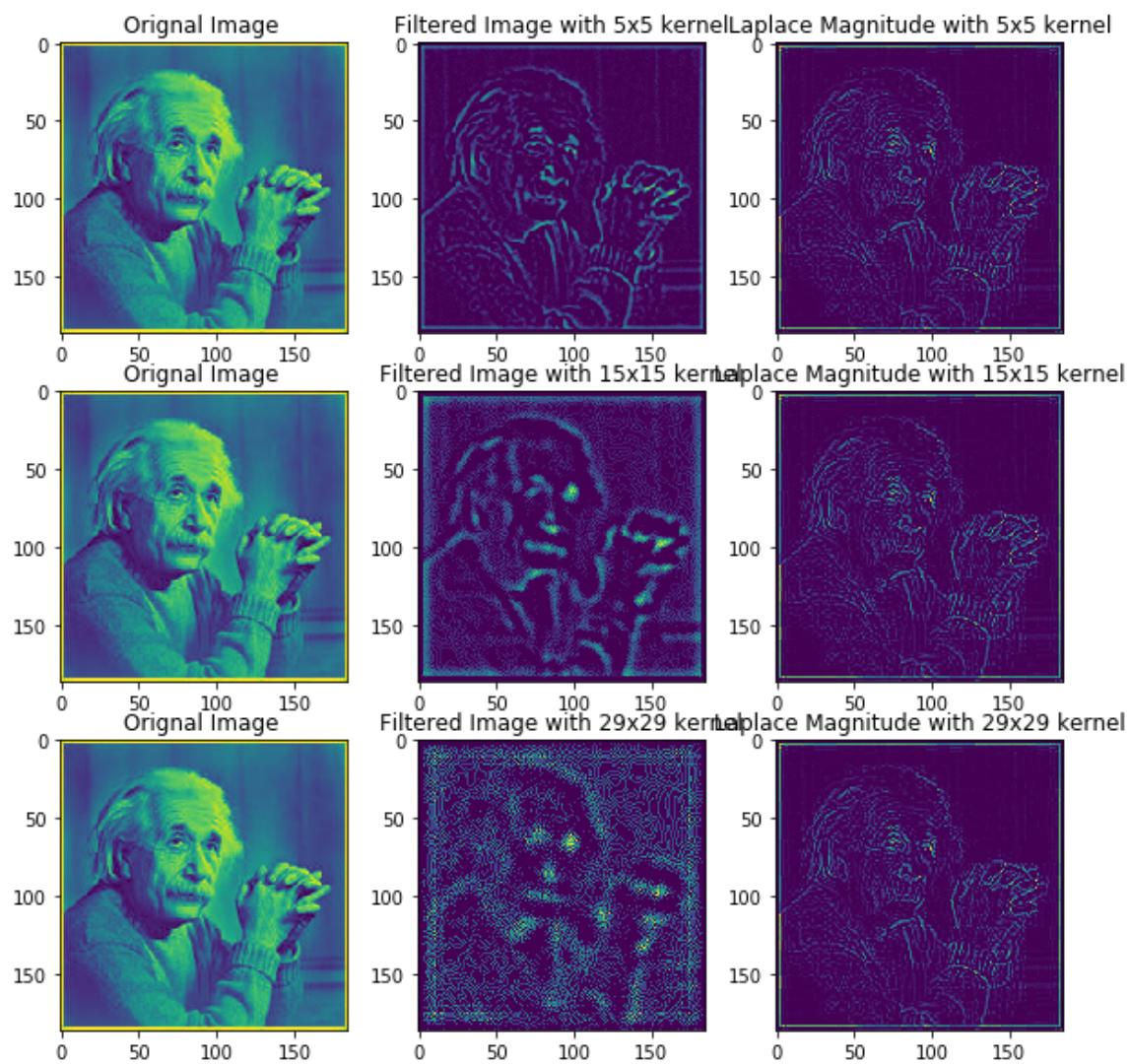
In [12]:

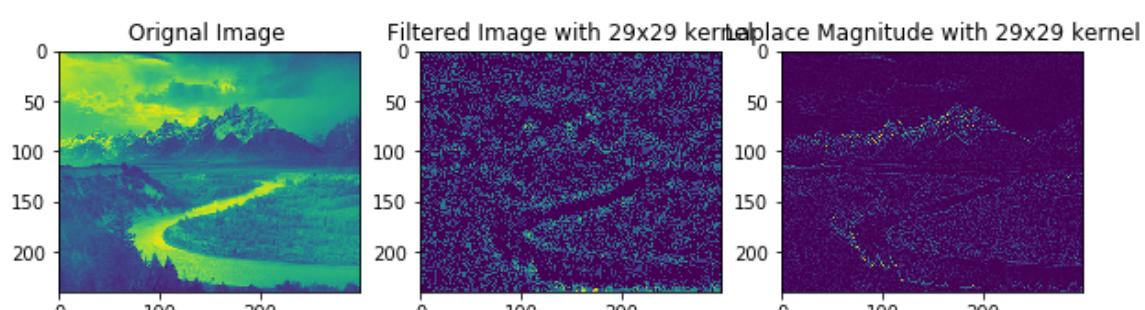
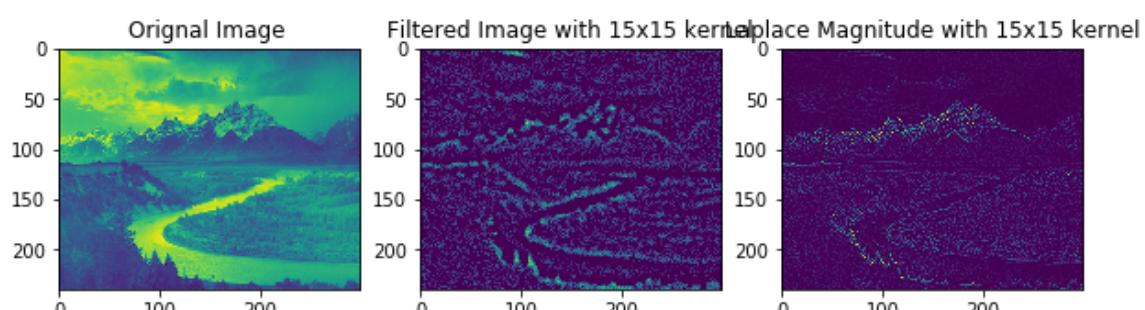
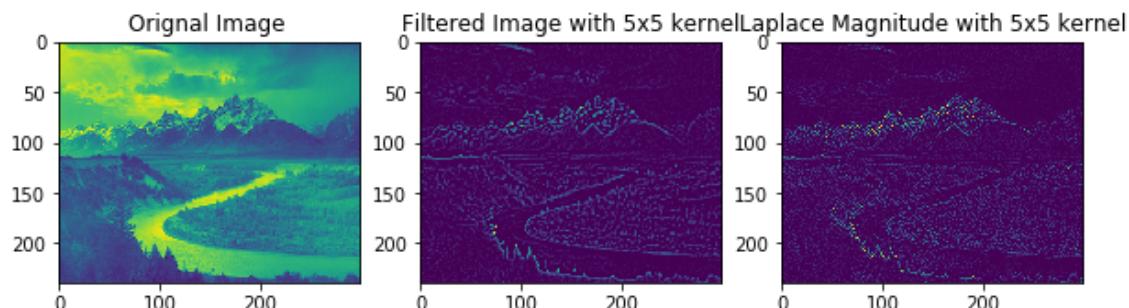
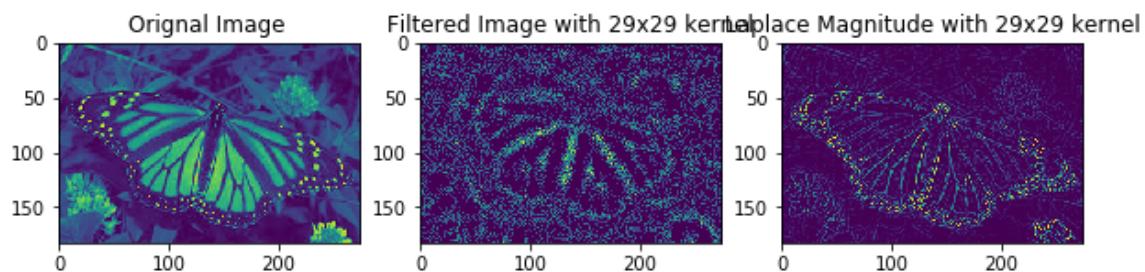
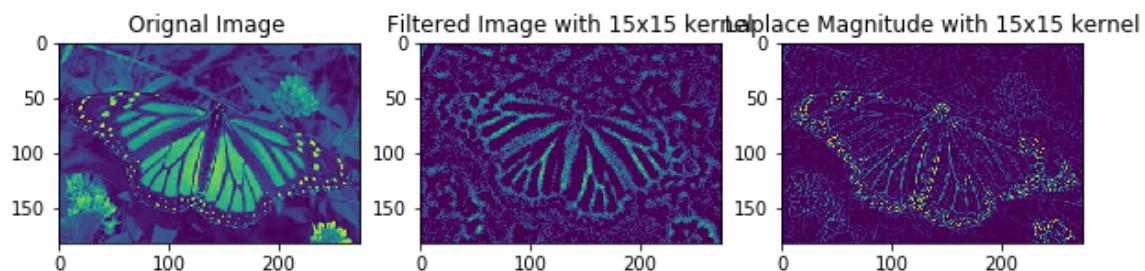
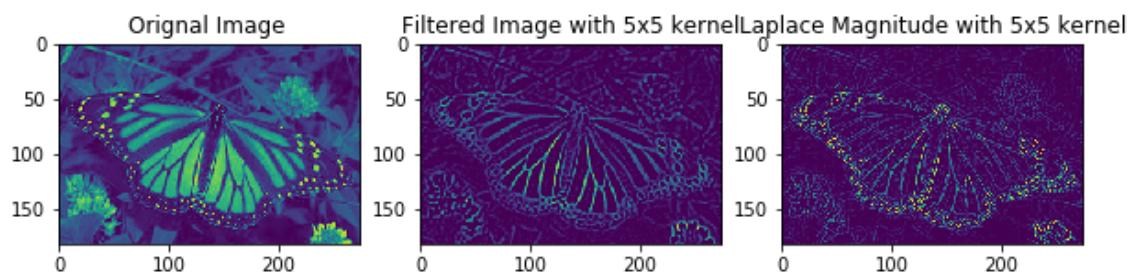
```
#2.62
# Here Laplacian filter has been applied on all images and plotted
laplacian(images)
```

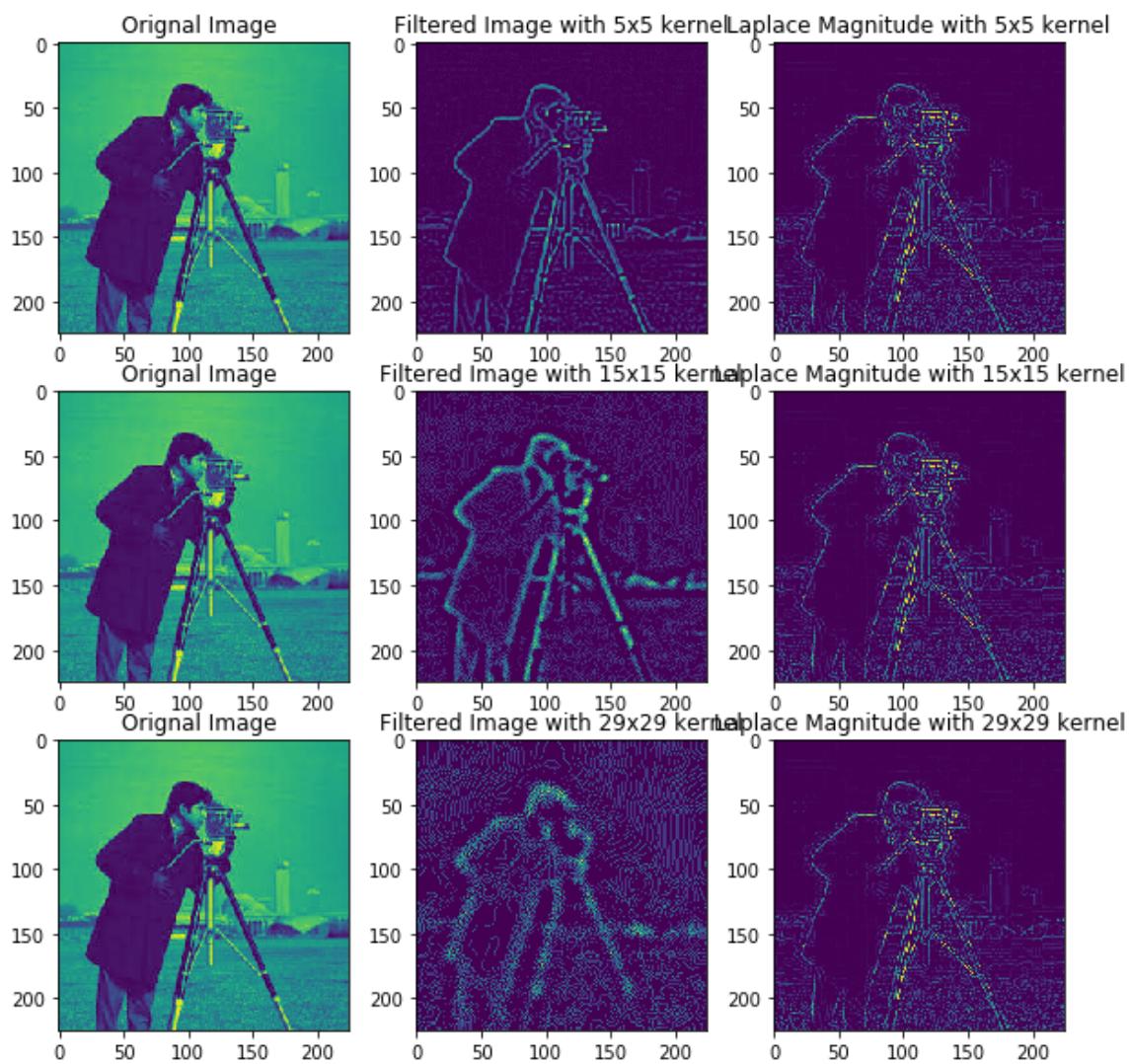


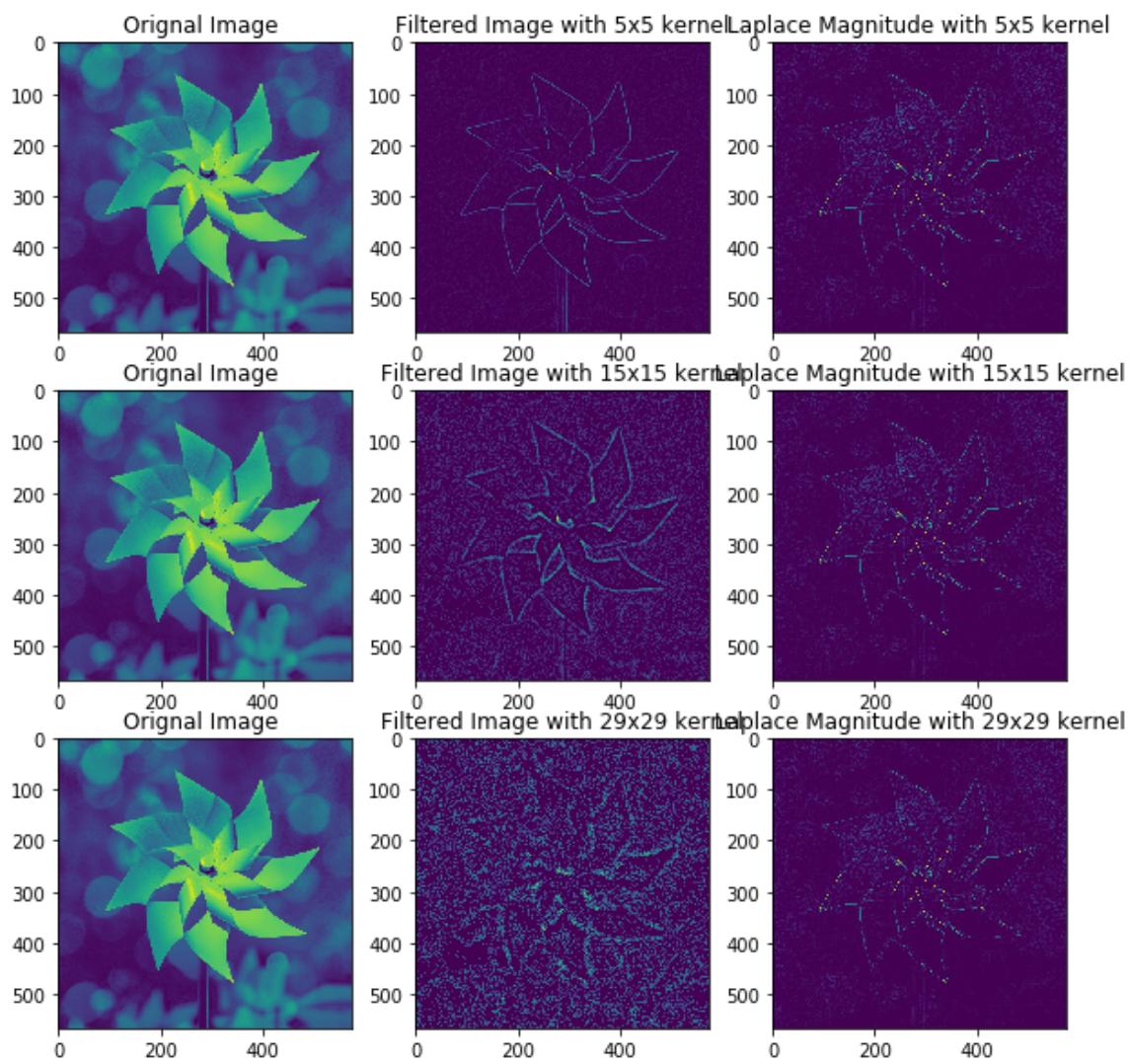


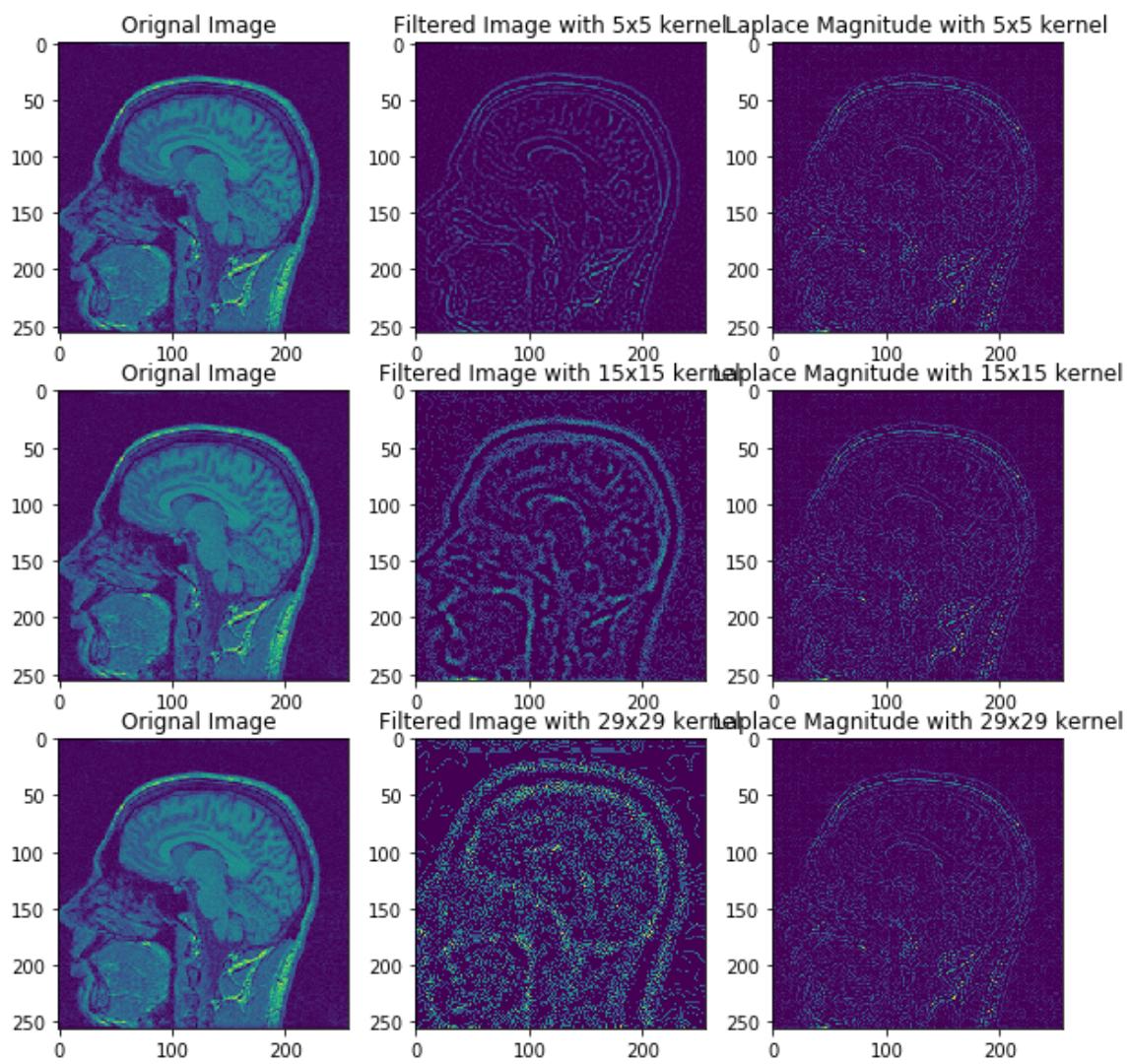






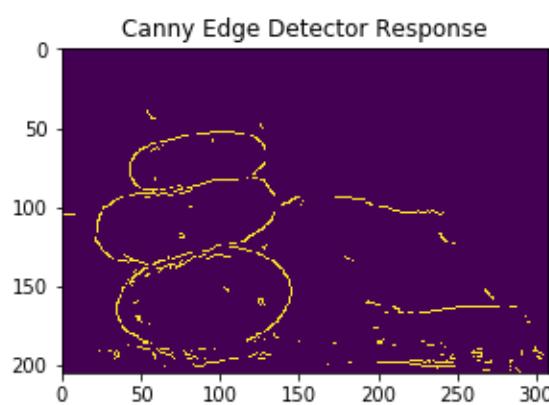
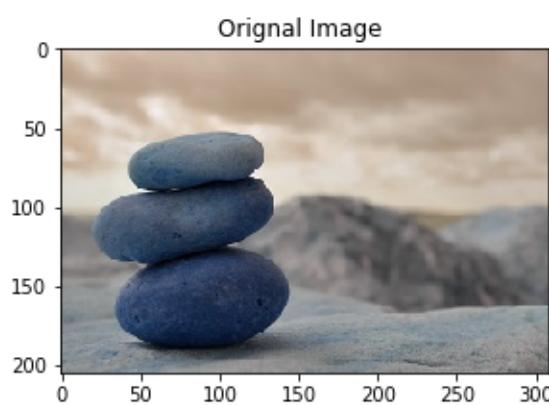
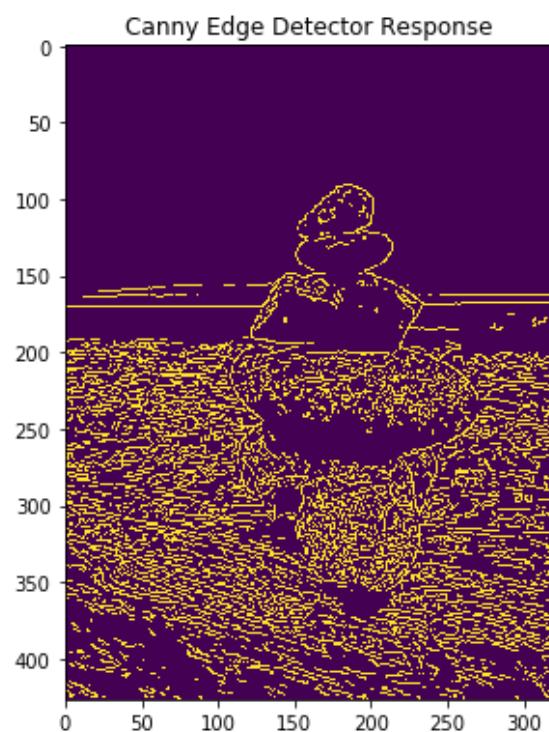


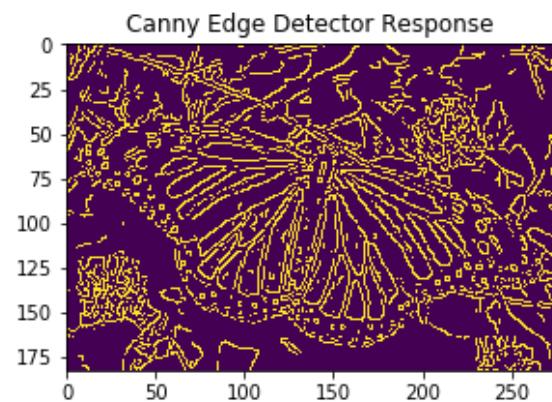
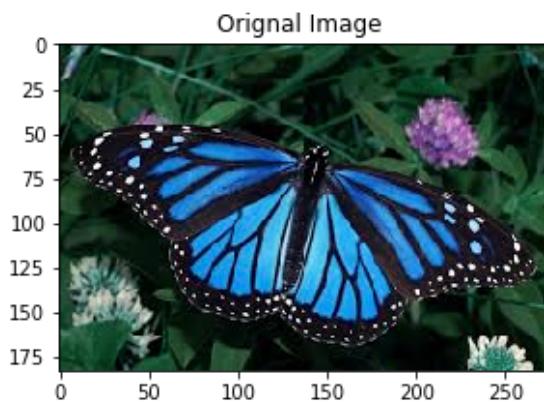
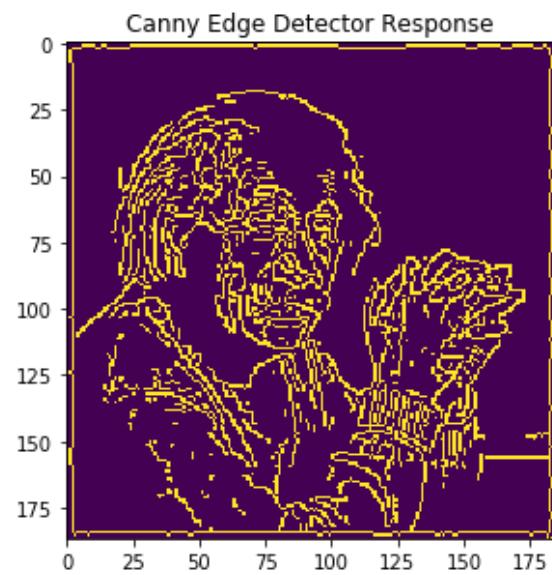
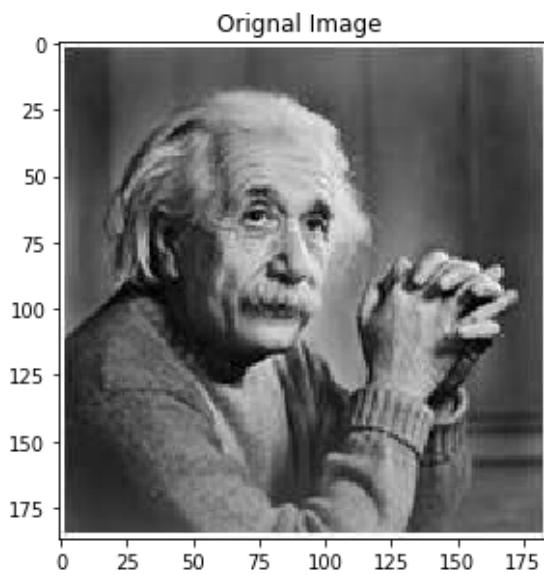
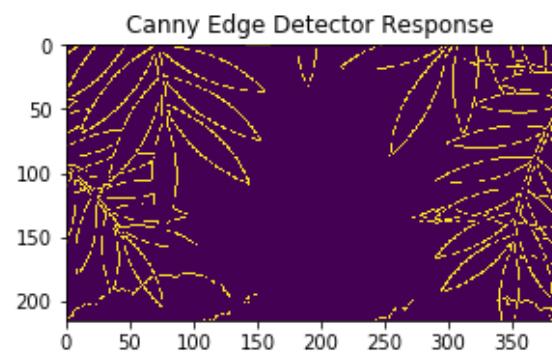
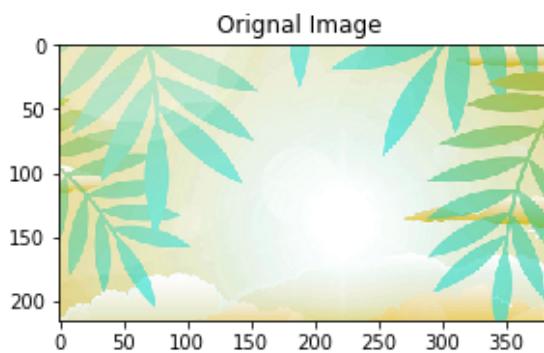


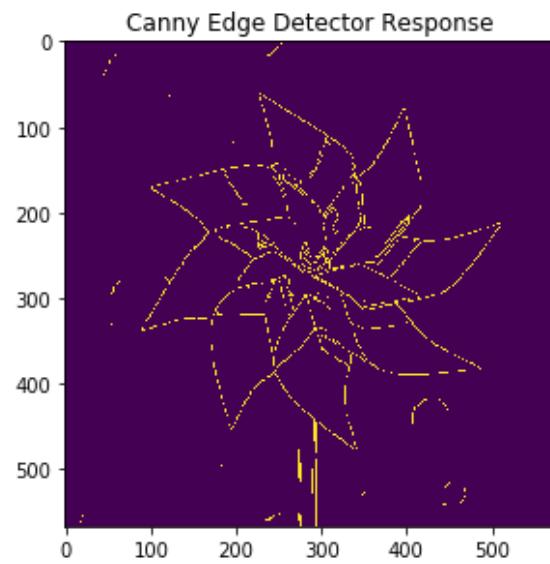
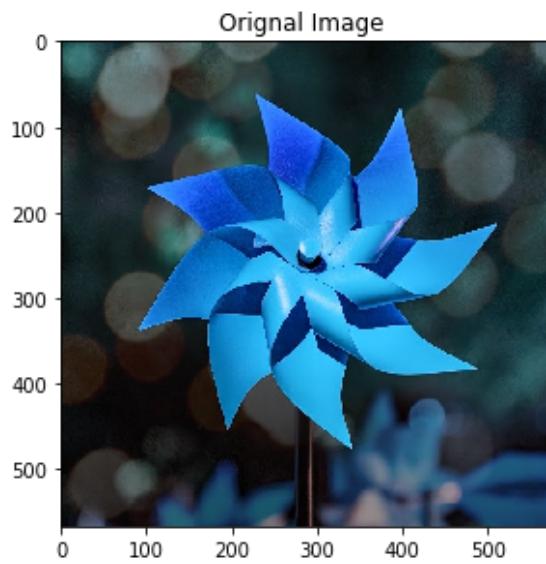
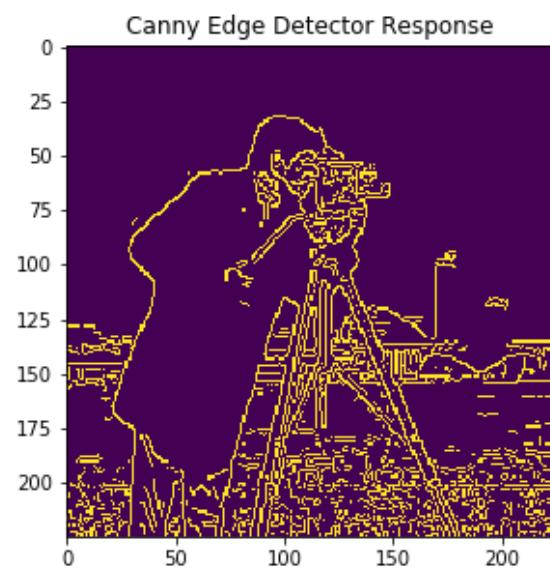
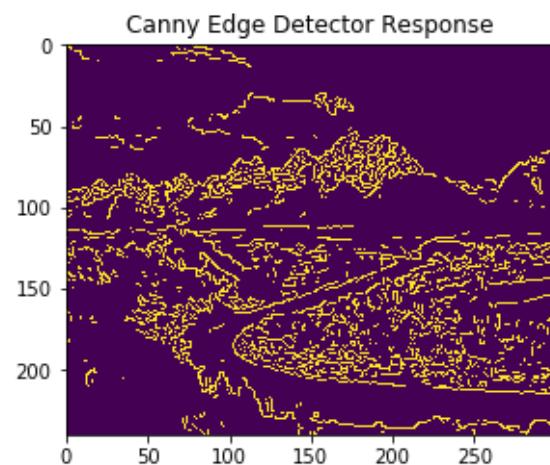
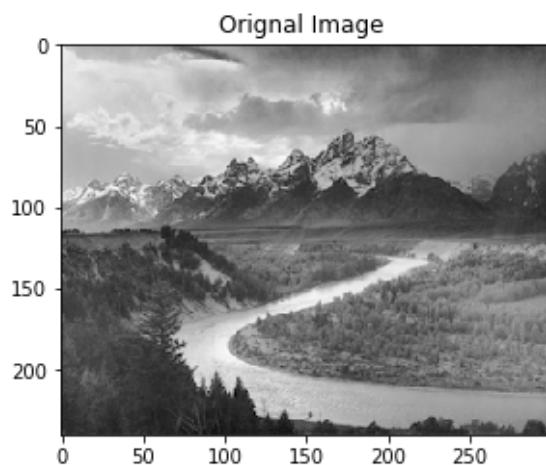


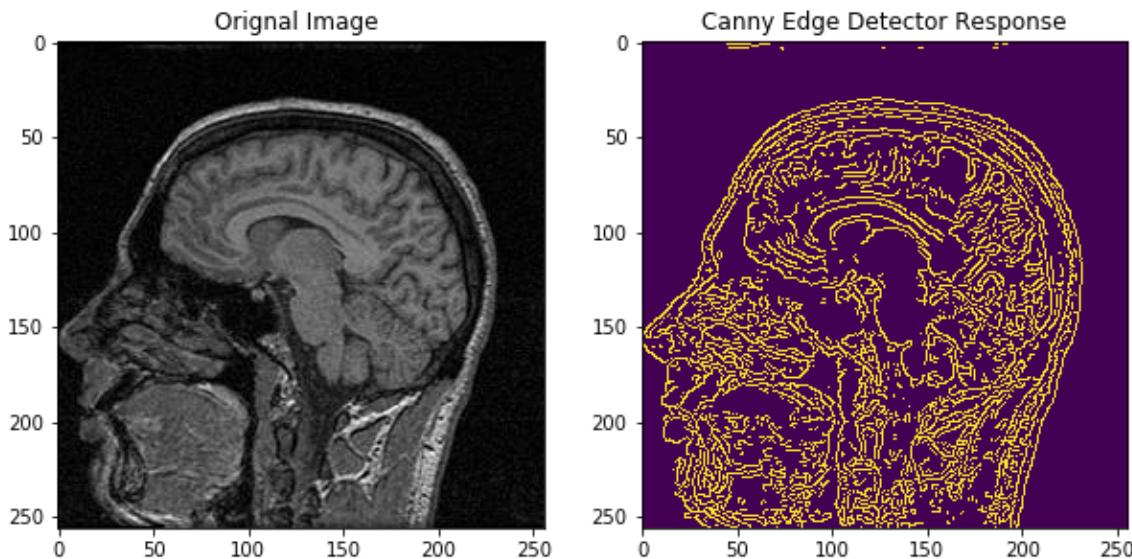
In [13]:

```
#2.63
## Here canny edge detector has been applied using built in lib on all images and plotted
canny(images)
```









In []:

```
#Bonus Task
# here live webcam video will open and on it, canny edge will apply with min threshold
one 1 and max threshold of 90
import cv2
cap = cv2.VideoCapture(0)
while True:
    ret, img = cap.read()

    grayimg = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
    blurimg = cv2.GaussianBlur(grayimg, (5, 5), 0)
    canny_det = cv2.Canny(blurimg, 1, 90)
    ret, mask = cv2.threshold(canny_det, 90, 255, cv2.THRESH_BINARY)
    cv2.imshow('Live Webcam feed', mask)

    if cv2.waitKey(1) == 3:
        break
cap.release()
cv2.destroyAllWindows()
```

In []: