# Multiple View Geometry: Exercise Paper 1

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# Exercise 1

**a**)

Since number of vectors matches the dimension of  $\mathbb{R}^3$  we can form a matrix if  $det(A) \neq 0$  they are linearly independent

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

 $\det(A) = 1$  Hence the vectors are linearly independent, since they are linearly independent they span  $\mathbb{R}^3$ , and since they are linearly independent and span  $\mathbb{R}^3$  they form basis in  $\mathbb{R}^3$ 

b)

$$\begin{cases} 2a+1b=0\\ 1a+1b=0, & a,b\in\mathbb{R} \iff \begin{cases} a=-b\\ 2a=-b, & a,b\in\mathbb{R} \end{cases}$$

So a = b = 0 and vectors are linearly independent, but since dim(span(v1,v2))  $\leq$  2, while dim( $\mathbb{R}^n$ ) = n

**c**)

The four vectors are linearly dependent, but we can form matrix where rows of matrix are linearly independent hence span  $\mathbb{R}^3$ , but since four vectors are not linearly independent they can not form basis in  $\mathbb{R}^3$ 

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

## Exercise 2

**a**)

By counterexample we have:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \times \begin{bmatrix} 1 & 2 & 3 \\ 2 & 0 & 4 \\ 3 & 4 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 0 & 8 \\ 9 & 12 & 15 \end{bmatrix}$$

The first two matrix are members of the set and since resulting matrix is not member of set it is not closed under multiplication hence not a group

b)

Since det(I) = 1, the set does not have identity element, hence not a group

**c**)

We can prove that it is a subgroup of GL if A and B are in  $G_3$  and  $AB^{-1}$  in  $G_3$ .  $\det(AB^{-1}) = \det(A)\det(B)^{-1} = \det(A)\frac{1}{\det(B)} \ge 0$ 

## Exercise 3

We know that in  $\mathbb{R}^3$  we have at most three linearly independent vectors, without loss of generality we have  $v_1=a_2v_2+a_3v_3+a_4v_4+a_5v_5$ , than we can write  $\|v_1\|=< v1, v1>=< v_1, a_2v_2+a_3v_3+a_4v_4+a_5v_5>=a_2< v_1, v_2>+a_3< v_1, v_3>+a_4< v_1, v_4>+a_5< v_1, v_5>=0+0+0+0=0$  and that contradicts assumtion about non zero vectors

#### Exercise 4

SO(n) - special orthogonal group, O(n)- general orthogonal group, GL(n) - general linear group, SL(n)- special linear group, SE(n) - special euclidean group, E(n) - euclidean group, A(n) - affine group

### Exercise 5

We have  $\lambda_a < v_a, v_b > = <\lambda_a v_a, v_b > = < A v_a, v_b > = < v_a, A^t v_b > = < v_a, A v_b > = < v_a, \lambda_b v_b > = \lambda_b < v_a, v_b >$  and since  $v_a$  and  $v_b$  are not orthogonal we have equal eigenvalues

# Exercise 6

For a symmetric matrix A, it can be diagonalized as  $A = VDV^t$ , where  $V = [v_1, \cdots, v_n]$  is the matrix of orthonormal eigenvectors and  $D = \text{diag}(\lambda_1, \cdots, \lambda_n)$  is the diagonal matrix of eigenvalues. So we can decompose our expression as

$$(c^tV^t)VDV^t(Vc) = c^tDc = \sum_{i=1} c_i^2 \lambda_i$$

The minimum is achieved when weight  $c_i$  put on smallest eigenvalue

# Exercise 7

## Exercise 8

**a**)

A is  $m \times n$ , U is  $m \times m$ , S is  $m \times n$  and V is  $n \times n$ 

b)

Both matrix diagonalization but Eigenvalue decomposition is only applied to quadratic matrices

**c**)

The columns of V are eigenvectors of  $A^tA$ , the columns of U are eigenvalues  $AA^t$ 

d)

The number of non-zero singular values is equal to the rank of A