Math computing

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NCERT 9.7.1.5

This question is from class 9 ncert chapter 7.triangles

- 1. Line l is the bisector of an angle $\angle A$ and B is any point on l. BP and BQ are perpendiculars from B to the arms of $\angle A$. Show that:
 - (a) $\triangle APB \cong \triangle AQB$
 - (b) BP = BQ or B is equidistant from the arms of $\angle A$.

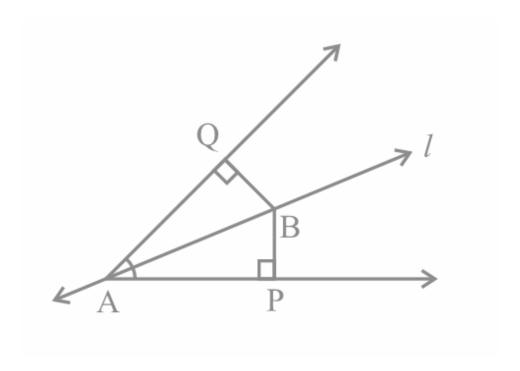


Figure 1: $\triangle AQB$ and $\triangle APB$

1. Finding foot of perpendiculars P,Q using Eigen Approach:

Assuming that the point A be the intersection point of two tangents of a circle with centre B and radius r. Let consider P,Q be the points of contact of two tangents to the circle.

Symbol	Value	Description
A	$\begin{pmatrix} 0 \\ 0 \end{pmatrix}$	coordinates of vertex A
В	$\begin{pmatrix} 3 \\ 3 \end{pmatrix}$	centre of circle B
r	2	radius of circle

Table 1: parameters for eigen approach

(a) let ,consider h = A and u = -B

$$\mathbf{h} = \mathbf{A} \tag{1}$$

$$\mathbf{u} = -\mathbf{B} \tag{2}$$

$$\mathbf{h} = \begin{pmatrix} a \\ b \end{pmatrix} \tag{3}$$

$$\mathbf{u} = \begin{pmatrix} c \\ d \end{pmatrix} \tag{4}$$

$$\mathbf{V} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \tag{5}$$

$$\mathbf{f} = \|u\|^2 - r^2 \tag{6}$$

(b) finding the circle equation:

$$gh = h^{T}Vh + 2u^{T}h + f$$
 (7)

$$\mathbf{gh} = \begin{pmatrix} a & b \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} + 2 \begin{pmatrix} c & d \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} + f \tag{8}$$

(9)

(c) from Table 1 and (1),

$$\mathbf{h} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \tag{10}$$

$$\mathbf{u} = \begin{pmatrix} -3\\ -3 \end{pmatrix} \tag{11}$$

$$r = 2 \tag{12}$$

(d) on substituting these in (6) and (8) we get,

$$\mathbf{f} = 14.000000 \tag{13}$$

$$\mathbf{gh} = \begin{pmatrix} 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} -3 & -3 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + 14.0 \tag{14}$$

$$gh = 14.000000 (15)$$

(e) Finding the sigma matrix:

$$\Sigma = (\mathbf{V}\mathbf{h} + \mathbf{u})(\mathbf{V}\mathbf{h} + \mathbf{u})^{T} - \mathbf{g}\mathbf{h}\mathbf{V}$$
(16)

$$\Sigma = \begin{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} + \begin{pmatrix} c \\ d \end{pmatrix} \end{pmatrix} \begin{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} + \begin{pmatrix} c \\ d \end{pmatrix} \end{pmatrix}^{T} - \mathbf{gh} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
(17)

on substituting we get

$$\Sigma = \begin{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -3 \\ -3 \end{pmatrix} \end{pmatrix} \begin{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -3 \\ -3 \end{pmatrix} \end{pmatrix}^{T} - 14.0 \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
(18)

$$= \begin{pmatrix} -5.000000 & 9.000000 \\ 9.000000 & -5.000000 \end{pmatrix} \tag{19}$$

(f) Finding eigen values and eigen vectors for (19), we get

$$\lambda = \begin{pmatrix} 4 \\ -14 \end{pmatrix} \tag{20}$$

$$\lambda_1 = 4 \tag{21}$$

$$\lambda_2 = -14 \tag{22}$$

$$\mathbf{P} = \begin{pmatrix} -0.707107 & -0.707107 \\ -0.707107 & 0.707107 \end{pmatrix}$$
 (23)

(g) Finding The direction vectors of the tangents from a point h to the circle

$$\mathbf{m} = \mathbf{P} \begin{pmatrix} \sqrt{|\lambda_2|} \\ \pm \sqrt{|\lambda_1|} \end{pmatrix} \tag{24}$$

$$= \begin{pmatrix} -0.707107 & -0.707107 \\ -0.707107 & 0.707107 \end{pmatrix} \begin{pmatrix} \sqrt{|-14|} \\ \pm \sqrt{|4|} \end{pmatrix}$$
 (25)

on solving we get

$$\mathbf{m_1} = \begin{pmatrix} -4.059965 \\ -1.231538 \end{pmatrix} \tag{26}$$

$$\mathbf{m_2} = \begin{pmatrix} -1.231538 \\ -4.059965 \end{pmatrix} \tag{27}$$

(h) Finding the contact points

$$\mathbf{x} = \mathbf{h} + \mu \mathbf{m} \tag{28}$$

Here

$$\mu = -\frac{\mathbf{m}^{\mathbf{T}} \left(\mathbf{V} \mathbf{h} + u \right)}{\mathbf{m}^{\mathbf{T}} \mathbf{V} \mathbf{m}}$$
 (29)

$$\mu = -\frac{\mathbf{m}^{T} (\mathbf{V} \mathbf{h} + u)}{\mathbf{m}^{T} \mathbf{V} \mathbf{m}}$$

$$\mu_{1} = -\frac{\mathbf{m}_{1}^{T} (\mathbf{V} \mathbf{h} + u)}{\mathbf{m}_{1}^{T} \mathbf{V} \mathbf{m}_{1}}$$

$$\mu_{2} = -\frac{\mathbf{m}_{2}^{T} (\mathbf{V} \mathbf{h} + u)}{\mathbf{m}_{2}^{T} \mathbf{V} \mathbf{m}_{2}}$$
(30)

$$\mu_{2} = -\frac{\mathbf{m_{2}^{T}} \left(\mathbf{Vh} + u \right)}{\mathbf{m_{2}^{T}} \mathbf{Vm_{2}}}$$
(31)

$$\mu_{1} = -\frac{\left(-4.059965 - 1.231538\right) \left(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -3 \\ -3 \end{pmatrix}\right)}{\left(-4.059965 - 1.231538\right) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -4.059965 \\ -1.231538 \end{pmatrix}}$$
(32)

$$\mu_{\mathbf{2}} = -\frac{\left(-1.231538 - 4.059965\right) \left(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -3 \\ -3 \end{pmatrix}\right)}{\left(-1.231538 - 4.059965\right) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} -1.231538 \\ -4.059965 \end{pmatrix}}$$
(33)

on solving we get,

$$\mu_1 = -0.881917 \tag{34}$$

$$\mu_2 = -0.881917 \tag{35}$$

(i) now for contact points P and Q

$$\mathbf{P} = \mathbf{h} + \mu_1 \mathbf{m_1} \tag{36}$$

$$\mathbf{Q} = \mathbf{h} + \mu_2 \mathbf{m_2} \tag{37}$$

$$\mathbf{P} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -0.881917 \end{pmatrix} \begin{pmatrix} -4.059965 \\ -1.231538 \end{pmatrix}$$
(38)
$$\mathbf{Q} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \begin{pmatrix} -0.881917 \end{pmatrix} \begin{pmatrix} -1.231538 \\ -4.059965 \end{pmatrix}$$
(39)

$$\mathbf{Q} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + (-0.881917) \begin{pmatrix} -1.231538 \\ -4.059965 \end{pmatrix} \tag{39}$$

$$\mathbf{P} = \begin{pmatrix} 3.580552\\ 1.086114 \end{pmatrix} \tag{40}$$

$$\mathbf{Q} = \begin{pmatrix} 1.086114 \\ 3.580552 \end{pmatrix} \tag{41}$$

(j) As the lines BP and BQ are radius of circle, so the lengths of BP and BQ are equal

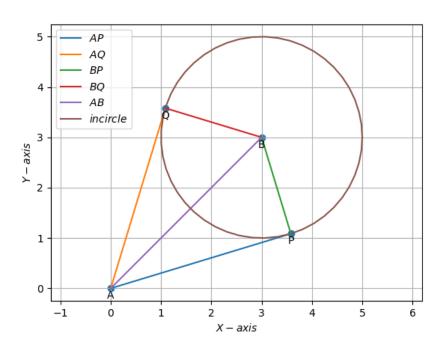


Figure 2: Contact points P and Q