Consider the following problems: (1) Numerical linear Algebra: x solves Ax = by solves  $(A+\Delta A)y=b$ how big can 1x-yll be for a small change DA? (2) Optimization:  $z = \underset{z \in \mathbb{R}^d}{\operatorname{argmin}} f(z)$ , for some function f $y = \operatorname{argmin} f(x_0) + \nabla f(x_0)^T(x_0-x_0)$ + 1 (z-20) 72 (20) (z-20) ZERd how big can 11x-y11 be for a small 11x-x011?? 3 statistics:  $\theta(P) = \underset{\theta \in \mathbb{M}}{\operatorname{arg min}} \int \ell(\theta; x) dP(x)$  $\theta(P_n) = \underset{\theta \in \mathbb{W}}{\operatorname{argmin}} \int \ell(\theta; x) dP_n(x)$ how big can  $\|\theta(P) - \theta(P_n)\|$  be for a small  $\|P_n - P\|$ ? All these problems fall under the concept of perturbation analysis or sensitivity analysis.

Variational analysis provides us with tools to derive perturbation bounds.

In real analysis, we go from sequences to limits to

Continuity to differentiation. In variational analysis, one considers liminf/limsupss more carefully and study functions that are not Continuous but semi-continuous, functions that are not differentiable but semi-differentiable.

In a way, variational analysis stems from ideas in convex analysis where smoothness may not be present but regularity exists.

Some Examples of Perturbation bounds:

Ax = b

$$Ax = b$$

$$(A+DA)y = b+Ob \Rightarrow (A+DA)y = Ax + Db$$

$$\Rightarrow A'(A+DA)y = x + A'Db$$

$$\Rightarrow A'(A+DA)y = x + A'Db$$

$$\Rightarrow A'(A+DA)J = x + A'Db$$

$$\Rightarrow (I + A'DA)Y = x + A'Db$$

$$\Rightarrow (A'DA)Y - A'Db$$

$$\Rightarrow (I + ADA) y - A^{1}Ob$$

$$\Rightarrow x - y = (A^{1}OA) y - A^{1}Ob$$

$$\Rightarrow x-y = (\vec{A}\Delta A)x + (\vec{A}\Delta A)(y-x) - \vec{A}\Delta b$$

$$\Rightarrow ||x-y|| \leq ||\vec{A}\Delta A||_{op} \cdot ||x|| + ||\vec{A}\Delta A||_{op} \cdot ||x-y|| + ||\vec{A}\Delta b||_{op} \cdot ||x-y||_{op} \cdot ||x-y||_{op}$$

In numerical linear algebra, this bound is presented

In numerical linear algebra, this bound is presented as 
$$\frac{K(A) \, \varepsilon}{1 - K(A) \, \varepsilon} \quad \text{where} \quad K(A) = \|A^{\dagger}\|_{op} \|A\|_{op}$$

$$\varepsilon = \frac{\|\Delta A\|_{op}}{\|A\|_{op}} \|A\|_{op}$$
Tabilism: To relative change in A is small,

E = 1/2 All op 1/2 1/6/1

Intuition: If relative change in A is small, relative change in x is small.

 $A = \Sigma = \mathbb{E}[XX^T]$ Application: Take  $A+DA = \hat{Z} = \hat{A}\hat{Z}X_iX_i^T$ b= 7= E(XY)  $b+\Delta b=\hat{\Gamma}=\frac{1}{12}\sum_{i}^{n}X_{i}Y_{i}$ . Provides model-free bounds for Estimation Error in linear regrethion.

Example 2: Optimization (Kantorovich's theorem).  $x = \operatorname{argmin} f(z)$ argmin  $f(z_0) + \nabla f(z_0)^T (x-x_0) + \frac{1}{2} (x-x_0)^T \nabla_2 f(z_0)(x-z_0)$  $\Delta f(x) = 0$ and  $\nabla f(z_0) + \nabla_2 f(z_0)(y-z_0) = 0$ . Kantorovich Theorem: Def(20) is non-singular, whenever 1/2-2011, = 3L'  $\| (D_2 f(Z_0))^T \nabla f(Z_0) \|_2 \leq \frac{2}{9L}$ and there exists a unique solution

 $x \in \mathcal{B}(z_0, \frac{3}{2} \| (z_0 f(z_0))^T \nabla f(z_0) \|_2)$  satisfying  $\nabla f(a) = 0$  and  $\| \chi - \chi_0 - (Q_2 f(Z_0))^T \nabla f(Z_0) \|_{2} \le \frac{9L}{4} \| (Q_2 f(Z_0))^T \nabla f(Z_0) \|_{2}^{2}$ 

Application: (Asymp. Normality of MLE)

Suppose 
$$X_1,...,X_n$$
 iid  $P_{\Theta_0}$ .

Set  $L_n(\Theta) = -\sum_{i=1}^n log P_{\Theta}(X_i)$ .

If  $\nabla_2 L_n(\Theta_0)$  is non-singular (smbirical Fisher information is

If 
$$\nabla_2 L_n(\theta_0)$$
 is non-singular (empirical Fisher information is non-singular) at the truth of the truth o

 $\|\nabla L_n(\theta_0)\|$  is small,

then there exists a unique solution to  $DL_n(\theta)=0$ in the nod of the such that  $\|\hat{\theta} - \theta_o - (\nabla_2 \ln(\theta_o)) \nabla \ln(\theta_o)\|_2 \leq \|(\nabla_2 \ln(\theta_o)) \nabla \ln(\theta_o)\|_2$ 

and 
$$\|\nabla L_n(\theta_0)\|$$
 is small,  
then there exists a unique solution to  $\nabla L_n(\theta) = 0$   
in the nbd of  $\theta_0$  such that  
in the nbd of  $\theta_0$  such that  
 $\|\hat{\theta} - \theta_0 - (\nabla_2 L_n(\theta_0))^T \nabla L_n(\theta_0)\|_2 \leq \|(\nabla_2 L_n(\theta_0))^T \nabla L_n(\theta_0)\|_2$ 

$$\Rightarrow \sqrt{n}(\hat{\theta}-\theta_0) \stackrel{d}{\rightarrow} N(0,\vec{z}(\theta)).$$

Example 3: (Hjort and Pollard (2011, arxiv: 1107.3806)) Suppose A(·) is a convex function and  $\propto E$  argmin  $A(\theta)$ .

Suppose B(·) is any function with

minimizer B: argmin B(0). C (f).

 $U(S) = \sup_{|\theta-\beta| \leq S} |A(\theta) - B(\theta)|$ Define and  $C(8) = \inf_{|\theta - \beta| = 8} B(\theta) - B(\beta)$ .

Then for any 8>0 such that  $U(S) \leq \frac{1}{2}C(S),$ 

We have  $|\alpha - \beta| \leq 8$ .

The proof only relies on the definition of convexity. The principle is general. Uniform Convergence and curvature imply clarence of Solutions.

Take any point  $\theta = \beta + lu$  for some l > 8and  $u \in S^{d-1}$ . ( $\|\theta-\beta\|>8$ ). We shall show that  $A(\theta) > A(\beta)$  which implies that any minimizer of A(·) cannot be outside B(B,8). Convexity of A() implies  $(1-\frac{5}{\lambda})A(\beta)+\frac{5}{\ell}A(\theta)\geq A(\beta+\delta u).$  $(\underline{s})(A(\theta)-A(\beta)) \geq A(\beta+\delta u)-A(\beta)$  $= B(\beta + \delta u) - B(\beta)$ + { A(B+SU) - B(B+SU)}  $-\left\{A(\beta)-B(\beta)\right\}$  $\geq C(8) - 2U(8)$  $A(\theta) - A(\beta) > 0$  whenever  $U(8) \subset \frac{1}{2}C(8)$ .

In all these problems, there are certain restrictions on uniquers of solutions. The results prevented cannot account for solution sets. They also cannot handle constraints very well. Suppose we have  $\propto_n = \operatorname{argmin} A(\Theta)$ 0 E Bn  $\beta_n = \operatorname{argmin} B(0)$ . Suppose the Converges to the in some sense. How close/far are xn & Bn? Several interesting problems fall into this category. 1) Grid search optimization 2) High-dimensional Dantzig type estimators.

We can always write these as unconstrained problems by introducing the "optimization indicator" function.

For any set (i) define  $\delta_{\mathbf{P}}(\mathbf{e}) = \begin{cases} 0 & \text{if } \mathbf{e} \in \mathbf{E} \\ \infty & \text{if } \mathbf{e} \notin \mathbf{E} \end{cases}$ then OFIRd  $\beta_n = \underset{\theta \in \mathbb{R}^d}{\operatorname{argmin}} A(\theta) + \delta_{\mathbb{Q}}(\theta).$ But uniform convergence cannot be expected. Additionally, these functions are non-smooth around the boundary of On & A. Epi-convergence was introduced as a way to tackle such problems. This is also referred to as 17-Convergence or Masco convergence. A function  $f: \mathbb{R}^d \to \overline{\mathbb{R}}$  is lower semicontinuous liminf  $f(x) \ge f(x_0)$ . 72-30 Equivalently, liminf =  $f(x_0)$ .

A function of is upper semicontinuous at the if  $limsup f(x) = f(x_0).$ A sequence of functions {fn}n>1 is said to epi-converge to a function f if 4 NOERd 1) & sequences {xn}nz1, xn > x0, liminf fo(xn) > f(xb) for some sequence (yn), yn-> 20, limsup  $f_n(y_n) \leq f(x_0)$ .  $n\to\infty$  (or  $\epsilon_{\ell} = ).$ 

Thm: Epi-convergence implies convergence of argmin. If  $x_n \in \operatorname{argmin} f_n$  and  $x^*$  is  $\infty$ limit point of  $\{x_n\}$ , then  $x^* \in argmin f$ of: let {yn} be any sequence such that  $f(y_n) \rightarrow i n^p f(x)$ . By (1) liminf  $f_n(x_n) \ge f(x^*)$  $r \to \infty$   $\lim_{n \to \infty} f_n(x_n) \leq \lim_{n \to \infty} f_n(y_n) \leq \inf_{x} f(x)$   $\lim_{n \to \infty} f_n(x_n) \leq \lim_{n \to \infty} f(x) \leq \inf_{x} f(x)$  Study of Consistency versus asy. distributions:

Suppose  $\chi \in argmin, f(g)$ ĕ€Rd y e argmin 9(0) oerRd

then

r(x-y)= u = x=y+4

Solves

 $u \in \underset{8 \in \mathbb{R}^d}{\operatorname{argmin}} f(y + \frac{u}{r}) - f(y)$ 

Hence, studying Local convergence of F implies some understanding of asymptotic dist. of u.