# Foundations of Intelligent Systems Project 2: The Metal Part Sort-R Professor: Richard Zanibbi

Students: Ghodratollah Aalipour ga5481@rit.edu Akash Venkatachalam av2833@rit.edu

## **Algorithms:**

Multi-layer perceptron is a group of interconnected nodes which resembles the structure of neurons of present in human brain. A decision tree is a group of nodes arranged in tree-like structure which uses a top-down approach for classifying. Both of them infer a function from the given training dataset and hence be called supervised learning. The multi-layer perceptron takes a longer time for training and classifying the training dataset; it is bit slower. On the other hand, decision tree will work relatively faster for the same given set. A multi-layer perceptron can model nonlinear functions and so it will be more accurate. Nevertheless, a decision tree can only model functions that are parallel to the axis split of the data. In multi-layer perceptron, if the data arrives in a stream then we can do an incremental update with stochastic gradient descent. However, it cannot be performed in a decision tree because it uses batch-learning algorithm. Multi-layer perceptron can handle binary data better than a decision tree but it cannot handle categorical values.

We expect the Multi-layer perceptron (MLP) to perform better than the decision trees because of the nonlinear regions that MLP can model when compared with only linear function model produced by decision trees.

#### Data:

In the given training dataset, we have four classes. Class 1 is a representation for Bolt, class 2 for nut, class 3 for ring, class 4 for scrap. As represented in Figure 1, the class 1 is in red dots, class 2 is green stars, class 3 is blue squares, class 4 is black triangles. It can be seen that some

of class 4 triangles are placed in blue square region as well as in green star region. To explain in detail, class 1 occurs mostly when eccentricity is more than 0.8. Class 2 occurs when rotational symmetry is more than 0.3 and eccentricity is less than 0.2. Class 3 occurs when rotational symmetry is less than 0.3 and eccentricity is less than 0.2. Class 4 occurs when eccentricity is between 0.2 and 0.8.

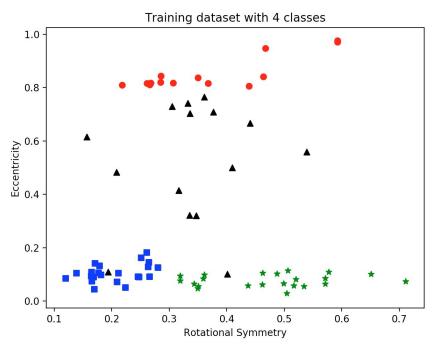


Figure 1: Plot of training dataset

The training dataset has three attributes: symmetry, eccentricity and class. The values of both symmetry and eccentricity varies from 0 to 1. The class values varies from 1 to 4. In the given training dataset, there are 15 data points in class 1, 22 in class 2, 22 in class 3 and 15 in class 4.

### **Results:**

## **Multi-Layer Perceptron:**

For training the MLP, we used 3 layers with 5 nodes in the hidden layers. The following figures shows the classification regions produced by different number of training epochs like 0, 10, 100, 1000, 10000.

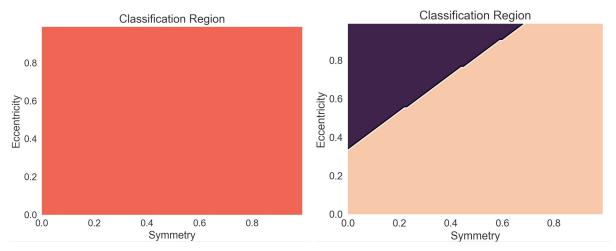


Figure 2: Classification region for 0 epoch

Figure 3: Classification region for 10 epoch

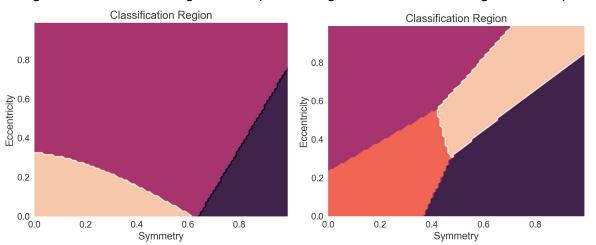


Figure 4: Classification region for 100 epoch Figure 5: Classification region for 1000 epoch

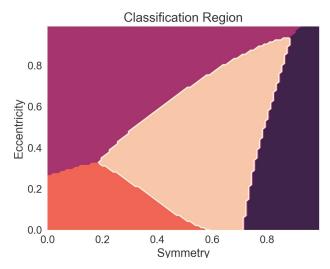


Figure 6: Classification region for 10000 epoch

The following figure shows the learning curve (SSE vs Epoch) for the trained MLP from 0 to 10000 epochs. It can be seen that the SSE gradually decreases as the number of epochs increases.

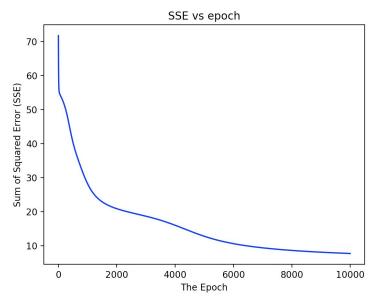


Figure 7: SSE vs Epoch plot

The following table shows the recognition rate and the profit for each epoch.

Table 1: Table showing recognition rate and profit for each epoch

Epochs	Recognition Rate (%)	Profit (in cents)*
0	25	-5
10	30	-8
100	55	71
1000	80	187
10000	95	199

<sup>\*</sup> Negative profit indicates a loss