Neural Networks image recognition - ConvNet

- Add random noise (see below on size parameter on <u>np.random.normal</u> (https://numpy.org/doc/stable/reference/random/generated/numpy.random.normal.html))
 to the images in training and testing. **Make sure each image gets a different noise feature added to it. Inspect by printing out several images. Note the size parameter should match the data. **
- 2. Compare the accuracy of train and val after N epochs for MLNN with and without noise.
- 3. Vary the amount of noise by changing the scale parameter in np.random.normal by a factor. Use .1, .5, 1.0, 2.0, 4.0 for the scale and keep track of the accuracy for training and validation and plot these results.
- 4. Compare these results with the previous week where we used a MultiLayer Perceptron (this week we use a ConvNet).

Neural Networks - Image Recognition ¶

```
In [1]:
    import keras
    from keras.datasets import mnist
    from keras.models import Sequential
    from keras.optimizers import RMSprop
    from keras.layers import Dense, Dropout, Flatten
    from keras.layers import Conv2D, MaxPooling2D
```

2023-07-25 09:46:48.944877: I tensorflow/core/platform/cpu_feature_gu ard.cc:182] This TensorFlow binary is optimized to use available CPU instructions in performance-critical operations.

To enable the following instructions: AVX2 FMA, in other operations, rebuild TensorFlow with the appropriate compiler flags.

```
In [5]: import numpy as np
import matplotlib.pyplot as plt
```

Conv Net

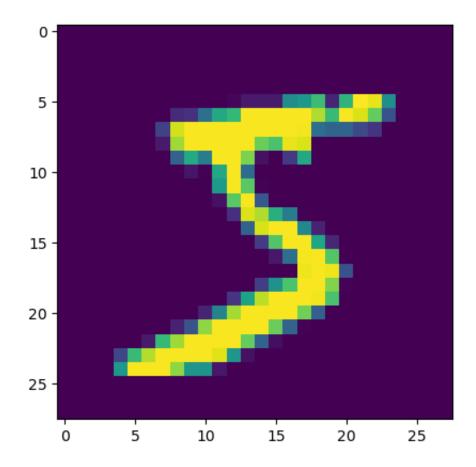
Trains a simple convnet on the MNIST dataset. Gets to 99.25% test accuracy after 12 epochs (there is still a lot of margin for parameter tuning).

```
In [35]: # input image dimensions
         img_rows, img_cols = 28, 28
         # the data, shuffled and split between train and test sets
         (x_train, y_train), (x_test, y_test) = mnist.load_data()
         if backend.image_data_format() == 'channels_first':
             x train = x train.reshape(x train.shape[0], 1, img rows, img cols)
             x_test = x_test.reshape(x_test.shape[0], 1, img_rows, img_cols)
             input_shape = (1, img_rows, img_cols)
         else:
             x_train = x_train.reshape(x_train.shape[0], img_rows, img_cols, 1)
             x_test = x_test.reshape(x_test.shape[0], img_rows, img_cols, 1)
             input_shape = (img_rows, img_cols, 1)
         x_train = x_train.astype('float32')
         x_test = x_test.astype('float32')
         x train /= 255
         x test /= 255
         print('x_train shape:', x_train.shape)
         print(x train.shape[0], 'train samples')
         x_train shape: (60000, 28, 28, 1)
         60000 train samples
         10000 test samples
In [36]: # Noise Add
         x train noise = x train + np.random.normal(scale = 0.1, size = (60000),
         np.shape(x train noise)
```

Out[36]: (60000, 28, 28, 1)

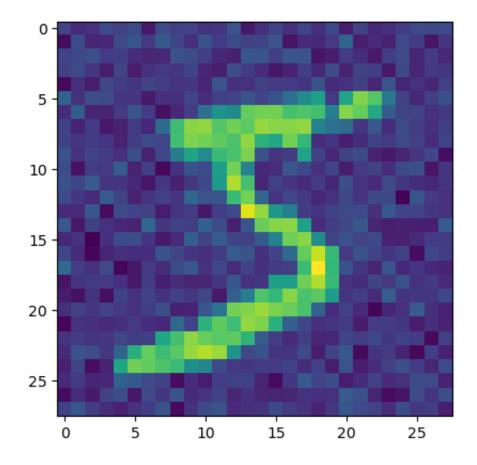
In [37]:

Out[37]: <matplotlib.image.AxesImage at 0x7fd7b427e2c0>



In [38]:

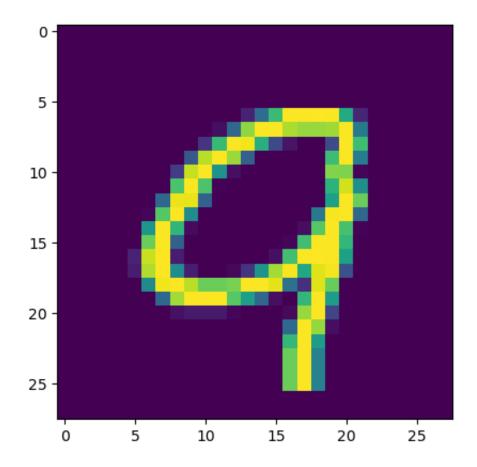
Out[38]: <matplotlib.image.AxesImage at 0x7fd6ff0ffe80>



```
In [42]: x_train_noise = x_train + np.random.normal(scale = 0.5, size = (60000,
Out[42]: (60000, 28, 28, 1)
```

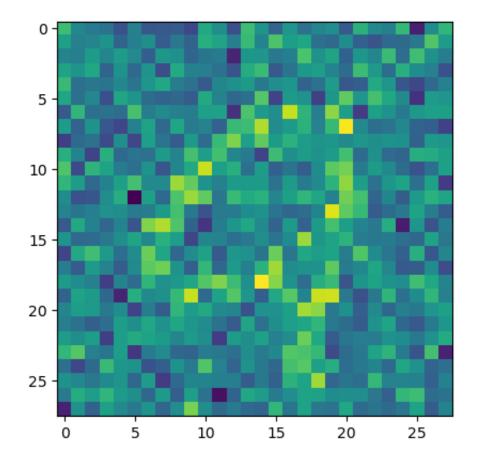
In [43]:

Out[43]: <matplotlib.image.AxesImage at 0x7fd7f3e2a3b0>



In [44]:

Out[44]: <matplotlib.image.AxesImage at 0x7fd7970a3df0>

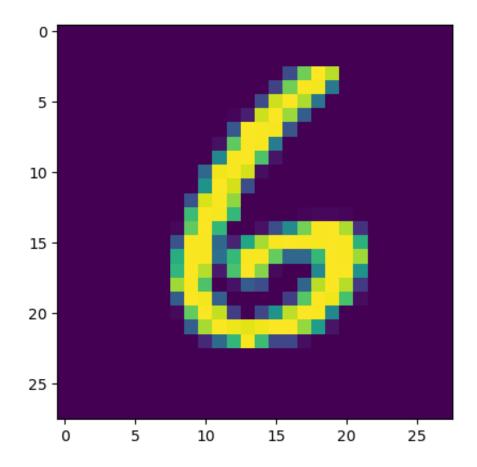


In [45]: x_train_noise = x_train + np.random.normal(scale = 1.0, size = (60000,

Out[45]: (60000, 28, 28, 1)

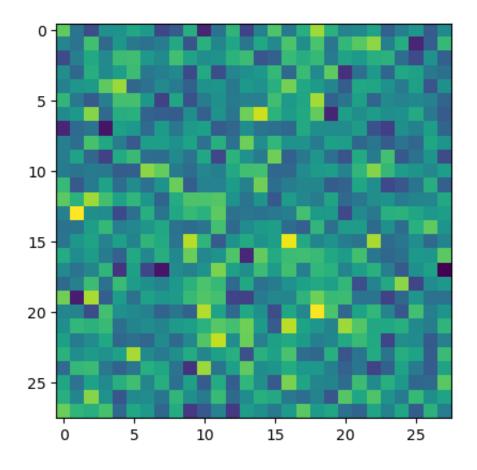
In [46]:

Out[46]: <matplotlib.image.AxesImage at 0x7fd75e470c40>



In [47]:

Out[47]: <matplotlib.image.AxesImage at 0x7fd6ae6be650>

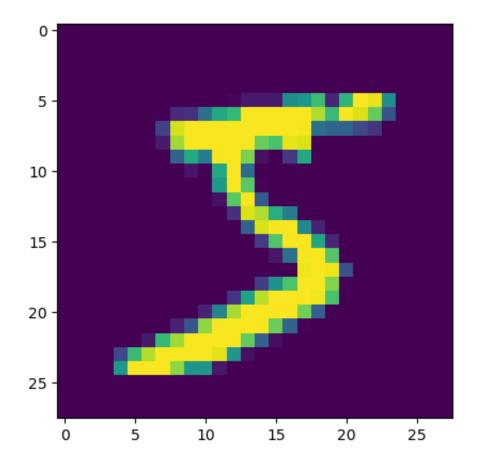


```
In [21]: # Noise Multiply
    x_train_noise = x_train * np.random.normal(scale = 0.1, size = (60000,
    np.shape(x_train_noise)
```

Out[21]: (60000, 28, 28, 1)

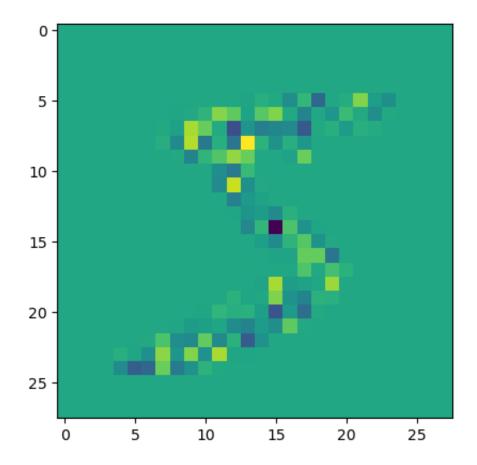
In [22]:

Out[22]: <matplotlib.image.AxesImage at 0x7fd7d5144760>



In [23]:

Out[23]: <matplotlib.image.AxesImage at 0x7fd7d51b1b40>

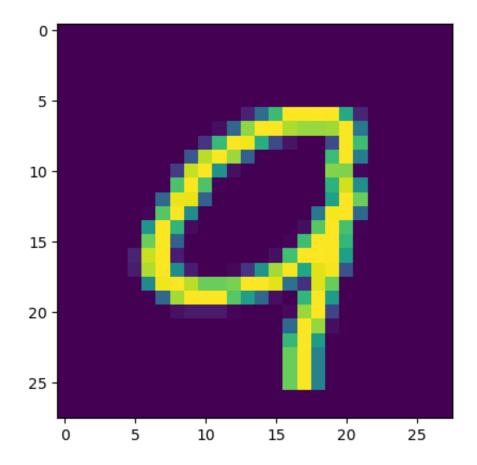


In [24]: x_train_noise = x_train * np.random.normal(scale = 0.5, size = (60000,
Out[24]: (60000, 28, 28, 1)

http://localhost:8888/notebooks/SU23%20Week%2011/asnmt_bowman.ipynb

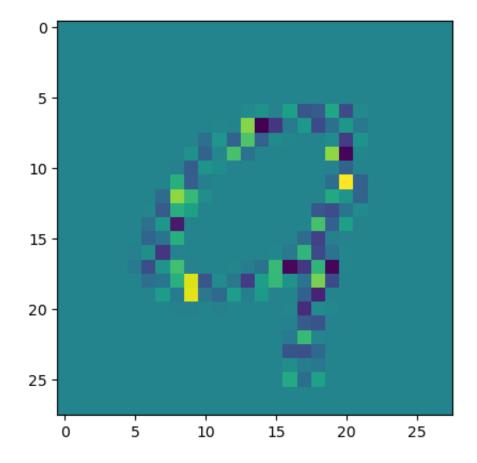
In [25]:

Out[25]: <matplotlib.image.AxesImage at 0x7fd7bdb329e0>



In [26]:

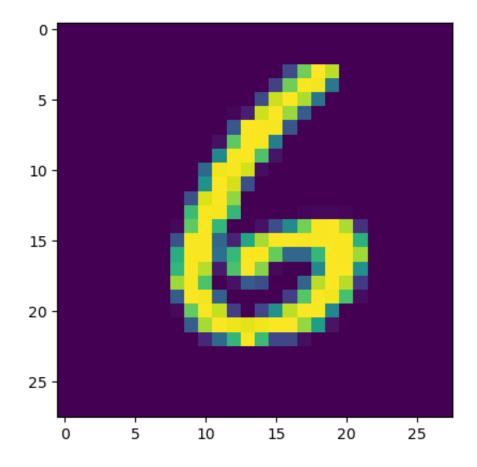
Out[26]: <matplotlib.image.AxesImage at 0x7fd7bdba3640>



In [27]: x_train_noise = x_train * np.random.normal(scale = 1.0, size = (60000,
Out[27]: (60000, 28, 28, 1)

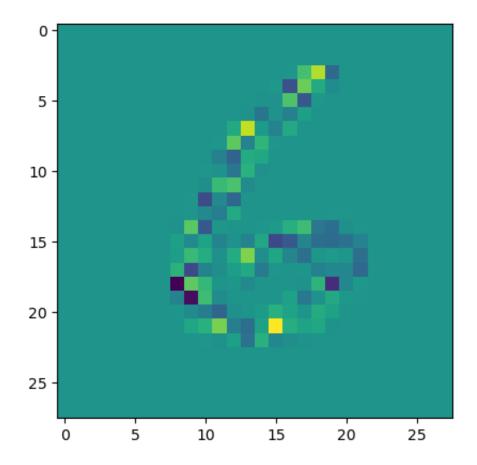
In [28]:

Out[28]: <matplotlib.image.AxesImage at 0x7fd7b41dc400>



In [29]:

Out[29]: <matplotlib.image.AxesImage at 0x7fd7b4250cd0>



```
In [ ]: |batch_size = 128
         num classes = 10
         epochs = 12
         # convert class vectors to binary class matrices
         y train = keras.utils.to categorical(y train, num classes)
         y_test = keras.utils.to_categorical(y_test, num_classes)
         model = Sequential()
         model.add(Conv2D(32, kernel_size=(3, 3),
                          activation='relu',
                          input shape=input shape))
         model.add(Conv2D(64, (3, 3), activation='relu'))
         model.add(MaxPooling2D(pool_size=(2, 2)))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(128, activation='relu'))
         model.add(Dropout(0.5))
         model.add(Dense(num classes, activation='softmax'))
         model.compile(loss=keras.losses.categorical crossentropy,
                       optimizer=keras.optimizers.Adadelta(),
                       metrics=['accuracy'])
         model.fit(x_train, y_train,
                   batch size=batch size,
                   epochs=epochs,
                   verbose=1,
                   validation_data=(x_test, y_test))
         score = model.evaluate(x_test, y_test, verbose=0)
         print('Test loss:', score[0])
         Epoch 1/12
         141/469 [======>.....] - ETA: 19s - loss: 2.3113 -
         accuracy: 0.1060
In [31]: # For Loop of Scales with addition of noise
         np.random.seed(7) # Set for reproducibility
         scales = [0.1, 0.5, 1.0, 2.0, 4.0]
         batch_size = 128
         num_classes = 10
         epochs = 12
         scores = []
         plt.figure(figsize=(12, 8))
         # convert class vectors to binary class matrices
         y_train = keras.utils.to_categorical(y_train, num_classes)
         v test = keras utils to categorical(v test num classes)
```

```
y_ccsc - Nordstatttstto_cdtcgorfcat(y_ccst, ndm_ctdsscs/
model = Sequential()
model.add(Conv2D(32, kernel_size=(3, 3),
                 activation='relu',
                 input_shape=input_shape))
model.add(Conv2D(64, (3, 3), activation='relu'))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(128, activation='relu'))
model.add(Dropout(0.5))
model.add(Dense(num classes, activation='softmax'))
model.compile(loss='categorical_crossentropy',
              optimizer="adam",
              metrics=['accuracy'])
history = model.fit(x train, y train,
                    batch size=batch size,
                    epochs=epochs,
                    verbose=0, # processes faster when not set to verb
                    validation_data=(x_test, y_test))
plt.plot(history.history['accuracy'], label='No Noise')
model.summary()
score_baseline = model.evaluate(x_test, y_test, verbose=0)
print(score_baseline)
for scale in scales:
   x train noise = x train + np.random.normal(scale = scale, size = (
   x_test_noise = x_test + np.random.normal(scale = scale, size = (10)
   model.compile(loss='categorical_crossentropy',
              optimizer="adam",
              metrics=['accuracy'])
   history = model.fit(x_train_noise, y_train,
                    batch_size=batch_size,
                    epochs=epochs,
                    verbose=0,
                    validation_data=(x_test_noise, y_test))
   plt.plot(history.history['accuracy'], label=f'{scale} noise scale'
   model.summary()
```

```
score = model.evaluate(x_test_noise, y_test, verbose=0)
print(score)
scores.append(score)

plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.title('Accuracy vs. Epochs for Different Scales of Noise')
plt.legend()
plt.show()
printout = [item for sublist in zip(scales, scores) for item in sublise
```

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 26, 26, 32)	320
conv2d_1 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 12, 12, 64)	0
dropout (Dropout)	(None, 12, 12, 64)	0
flatten (Flatten)	(None, 9216)	0
dense (Dense)	(None, 128)	1179776
dropout_1 (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.028407897800207138, 0.9918000102043152]

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 26, 26, 32)	320
conv2d_1 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d (MaxPooling2</pre>	(None, 12, 12, 64)	0

D)		
dropout (Dropout)	(None, 12, 12, 64)	0
flatten (Flatten)	(None, 9216)	0
dense (Dense)	(None, 128)	1179776
dropout_1 (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.03660549968481064, 0.9919999837875366]

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 26, 26, 32)	320
conv2d_1 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 12, 12, 64)	0
dropout (Dropout)	(None, 12, 12, 64)	0
flatten (Flatten)	(None, 9216)	0
dense (Dense)	(None, 128)	1179776
dropout_1 (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.11334235966205597, 0.9729999899864197]

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 26, 26, 32)	320

conv2d_1 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 12, 12, 64)	0
dropout (Dropout)	(None, 12, 12, 64)	0
flatten (Flatten)	(None, 9216)	0
dense (Dense)	(None, 128)	1179776
dropout_1 (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.5325009226799011, 0.8461999893188477]

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 26, 26, 32)	320
conv2d_1 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 12, 12, 64)	0
dropout (Dropout)	(None, 12, 12, 64)	0
flatten (Flatten)	(None, 9216)	0
dense (Dense)	(None, 128)	1179776
dropout_1 (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

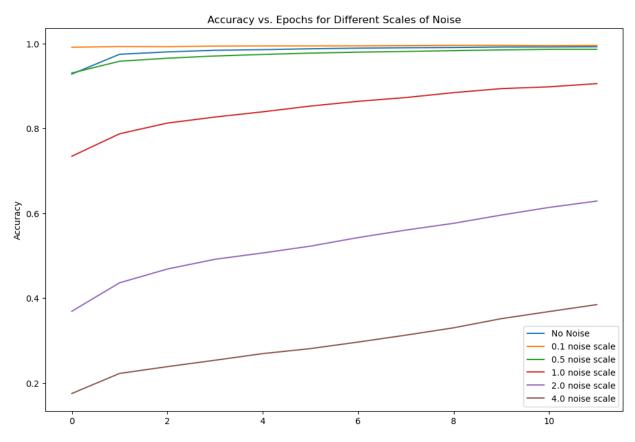
[1.5234874486923218, 0.5058000087738037]

Model: "sequential"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 26, 26, 32)	320
conv2d_1 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d (MaxPooling2 D)</pre>	(None, 12, 12, 64)	0
dropout (Dropout)	(None, 12, 12, 64)	0
flatten (Flatten)	(None, 9216)	0
dense (Dense)	(None, 128)	1179776
dropout_1 (Dropout)	(None, 128)	0
dense_1 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB) Trainable params: 1199882 (4.58 MB) Non-trainable params: 0 (0.00 Byte)

[2.1445717811584473, 0.2538999915122986]



Epochs

Noise Scale, Loss, Accuracy: No Noise [0.028407897800207138, 0.991800 0102043152] [0.1, [0.03660549968481064, 0.9919999837875366], 0.5, [0.11334235966205597, 0.9729999899864197], 1.0, [0.5325009226799011, 0.8 461999893188477], 2.0, [1.5234874486923218, 0.5058000087738037], 4.0, [2.1445717811584473, 0.2538999915122986]]

The model without noise is able to achieve a 99.2% accuracy with a 0.028 loss. For the added noise we can see that with a scale of 0.1 the accuracy is still 99.2% with a loss of 0.037. Noise scale of 0.5 has an accuracy of 97.3% and a loss of 0.113. Noise scale 1.0 has an accuracy of 84.6% and a loss of 0.532. Noise scale 2.0 has an accuracy of 50.6% and a loss of 1.523. Finally the noise scale of 4.0 has an accuracy of 25.4% and a loss of 2.145. When compared to the Multi-Layer Perceptron models from the last assignment we can see that the ConvNet model is overall less susceptiable noise the added noise and still declines in performance as the scale of the noise increases. Generally we can see a 1-5% improvement in model accuracy performance over the Perceptron model with noise introduced. From the human eye perspective the ConvNet performance is shocking given how quickly the images degrade in to visual noise when it is added. It is additionally impressive that the Convolution Net model is able to achieve superior accuracy in only 12 epochs versus the Perceptron's 20. I suspect given equal epochs the ConvNet could achieve even higher accuracy.

```
In [34]: # For Loop of Scales with multiplication of noise.
         np.random.seed(7) # Set for reproducibility
         scales = [0.1, 0.5, 1.0, 2.0, 4.0]
         batch_size = 128
         num classes = 10
         epochs = 12
         scores = []
         plt.figure(figsize=(12, 8))
         # convert class vectors to binary class matrices
         y_train = keras.utils.to_categorical(y_train, num_classes)
         y_test = keras.utils.to_categorical(y_test, num_classes)
         model = Sequential()
         model.add(Conv2D(32, kernel_size=(3, 3),
                           activation='relu',
                           input_shape=input_shape))
         model.add(Conv2D(64, (3, 3), activation='relu'))
         model.add(MaxPooling2D(pool size=(2, 2)))
         model.add(Dropout(0.25))
         model.add(Flatten())
         model.add(Dense(128, activation='relu'))
```

```
model_add(Dropout(0.5))
model.add(Dense(num_classes, activation='softmax'))
model.compile(loss='categorical_crossentropy',
              optimizer="adam",
              metrics=['accuracy'])
history = model.fit(x_train, y_train,
                    batch size=batch size,
                    epochs=epochs,
                    verbose=0, # processes faster when not set to verb
                    validation_data=(x_test, y_test))
plt.plot(history.history['accuracy'], label='No Noise')
model.summary()
score baseline = model.evaluate(x test, y test, verbose=0)
print(score_baseline)
for scale in scales:
    x train noise = x train * np.random.normal(scale = scale, size = (
    x_{test_noise} = x_{test} * np.random.normal(scale = scale, size = (10))
    model.compile(loss='categorical crossentropy',
              optimizer="adam",
              metrics=['accuracy'])
    history = model.fit(x train noise, y train,
                    batch_size=batch_size,
                    epochs=epochs,
                    verbose=0.
                    validation_data=(x_test_noise, y_test))
    plt.plot(history.history['accuracy'], label=f'{scale} noise scale'
    model.summary()
    score = model.evaluate(x_test_noise, y_test, verbose=0)
    print(score)
    scores.append(score)
plt.xlabel('Epochs')
plt.ylabel('Accuracy')
plt.title('Accuracy vs. Epochs for Different Scales of Noise')
nlt.ledend()
```

plt.show()
printout = [item for sublist in zip(scales, scores) for item in sublis

Model: "sequential_2"

Layer (type)	Output Shape	Param #
conv2d_4 (Conv2D)	(None, 26, 26, 32)	320
conv2d_5 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 12, 12, 64)	0
dropout_4 (Dropout)	(None, 12, 12, 64)	0
flatten_2 (Flatten)	(None, 9216)	0
dense_4 (Dense)	(None, 128)	1179776
dropout_5 (Dropout)	(None, 128)	0
dense_5 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.02853526547551155, 0.9926000237464905]

Model: "sequential_2"

Layer (type)	Output Shape	Param #
conv2d_4 (Conv2D)	(None, 26, 26, 32)	320
conv2d_5 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 12, 12, 64)	0
dropout_4 (Dropout)	(None, 12, 12, 64)	0
flatten_2 (Flatten)	(None, 9216)	0
dense_4 (Dense)	(None, 128)	1179776
dropout_5 (Dropout)	(None, 128)	0
dense_5 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.06564854085445404, 0.9815000295639038]

Model: "sequential_2"

Layer (type)	Output Shape	Param #
conv2d_4 (Conv2D)	(None, 26, 26, 32)	320
conv2d_5 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 12, 12, 64)	0
dropout_4 (Dropout)	(None, 12, 12, 64)	0
flatten_2 (Flatten)	(None, 9216)	0
dense_4 (Dense)	(None, 128)	1179776
dropout_5 (Dropout)	(None, 128)	0
dense_5 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.06569663435220718, 0.9829999804496765]

Model: "sequential_2"

Layer (type)	Output Shape	Param #
conv2d_4 (Conv2D)	(None, 26, 26, 32)	320
conv2d_5 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 12, 12, 64)	0
dropout_4 (Dropout)	(None, 12, 12, 64)	0
flatten_2 (Flatten)	(None, 9216)	0
dense_4 (Dense)	(None, 128)	1179776

dropout_5 (Dropout)	(None, 128)	0
dense_5 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.07121571153402328, 0.9842000007629395]

Model: "sequential_2"

Layer (type)	Output Shape	Param #
conv2d_4 (Conv2D)	(None, 26, 26, 32)	320
conv2d_5 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 12, 12, 64)	0
dropout_4 (Dropout)	(None, 12, 12, 64)	0
flatten_2 (Flatten)	(None, 9216)	0
dense_4 (Dense)	(None, 128)	1179776
dropout_5 (Dropout)	(None, 128)	0
dense_5 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.07189298421144485, 0.9846000075340271]

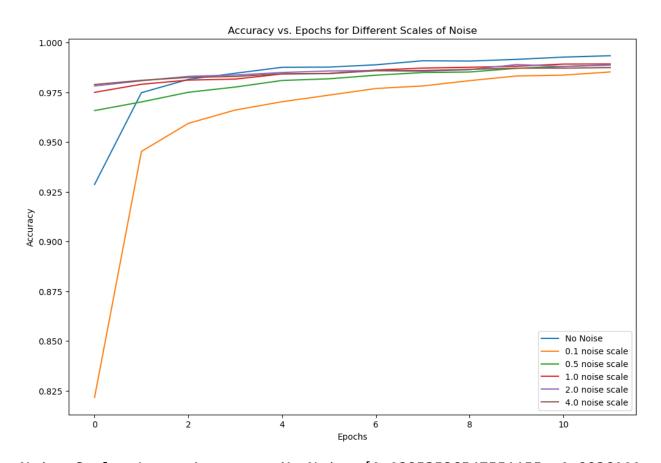
Model: "sequential_2"

Layer (type)	Output Shape	Param #
conv2d_4 (Conv2D)	(None, 26, 26, 32)	320
conv2d_5 (Conv2D)	(None, 24, 24, 64)	18496
<pre>max_pooling2d_2 (MaxPoolin g2D)</pre>	(None, 12, 12, 64)	0

dropout_4 (Dropout)	(None, 12, 12, 64)	0
<pre>flatten_2 (Flatten)</pre>	(None, 9216)	0
dense_4 (Dense)	(None, 128)	1179776
dropout_5 (Dropout)	(None, 128)	0
dense_5 (Dense)	(None, 10)	1290

Total params: 1199882 (4.58 MB)
Trainable params: 1199882 (4.58 MB)
Non-trainable params: 0 (0.00 Byte)

[0.06756246089935303, 0.9861000180244446]



Noise Scale, Loss, Accuracy: No Noise [0.02853526547551155, 0.9926000 237464905] [0.1, [0.06564854085445404, 0.9815000295639038], 0.5, [0.06569663435220718, 0.9829999804496765], 1.0, [0.07121571153402328, 0.9842000007629395], 2.0, [0.07189298421144485, 0.9846000075340271], 4.0, [0.06756246089935303, 0.9861000180244446]]

I didn't think to try multiplying the noise in to the data until the image printouts were so rough in the ConvNet shape. I went back and tried the Multi-Layer Perceptron model with the multiplied noise and got similar results to the ConvNet. Indeed the comparison between the Perceptron and the ConvNet with multiplied noise mirror the results of the added noise. The ConvNet performs ~7-10% better than the Perceptron for accuracy once noise is introduced. The additional characteristic I noted is that both models start off with worse performance at the lowest scale of noise multiplied and then improve as the noise scale gets larger. Finally both models perform nearly indentically regardless of noise scaling when the noise is multiplied.