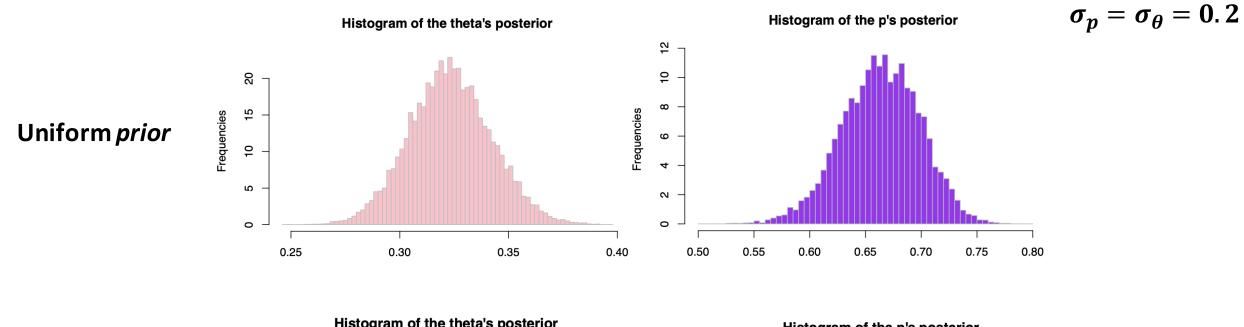
PROJET MCMC

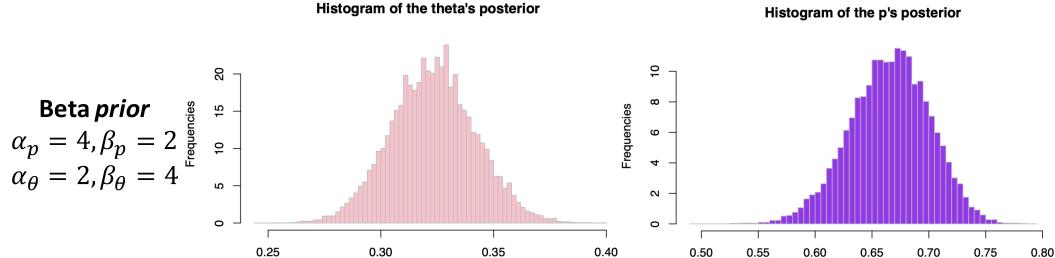
EM

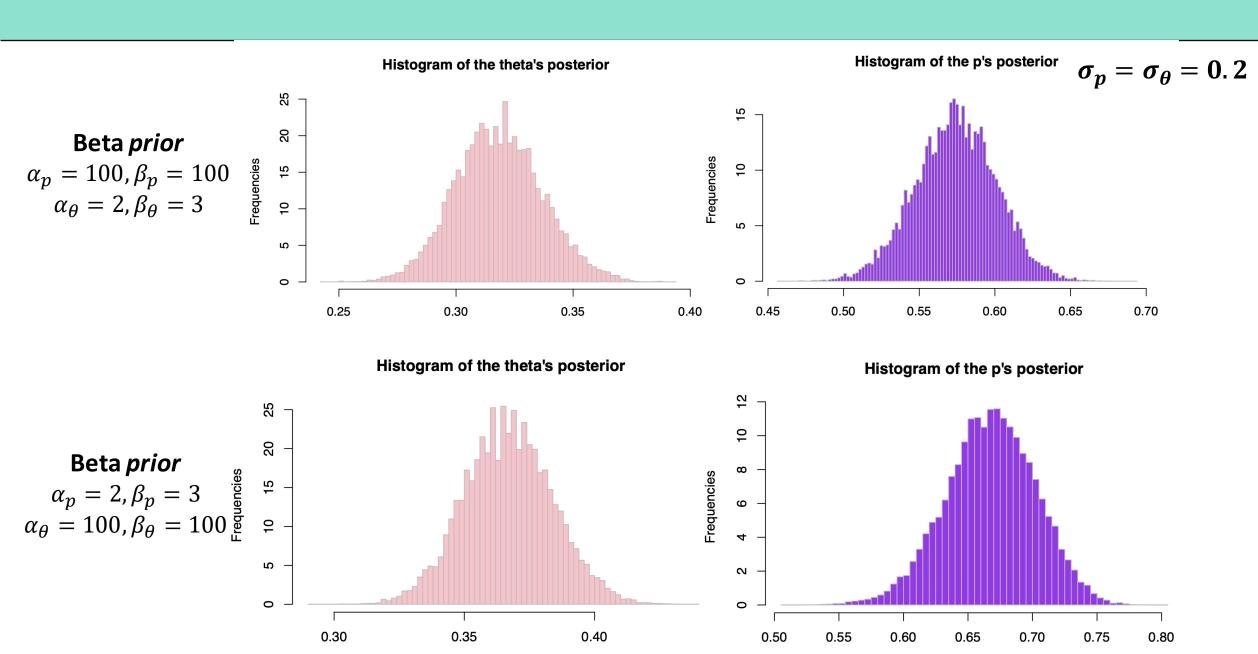
Proposal $\begin{array}{c} \textbf{distributions} \\ \theta_{new}^{(t)} \sim \mathcal{N}(\theta^{(t-1)}, \sigma_{\theta}) \end{array}$ $p_{new}^{(t)} \sim \mathcal{N}(p^{(t-1)}, p_{\theta})$

$$\begin{split} & - \text{Accept-Reject function} \\ & \rho \big(p_{new}, \theta_{new}, p^{(t-1)}, \theta^{(t-1)} \big) = \frac{\pi(p_{new}, \theta_{new} | x_{obs})}{\pi(p^{(t-1)}, \theta^{(t-1)} | x_{obs})} \\ & = \frac{\pi(p_{new}, \theta_{new})}{\pi(p^{(t-1)}, \theta^{(t-1)})} \frac{l(p_{new}, \theta_{new} | x_{obs})}{l(p^{(t-1)}, \theta^{(t-1)} | x_{obs})} \end{split}$$

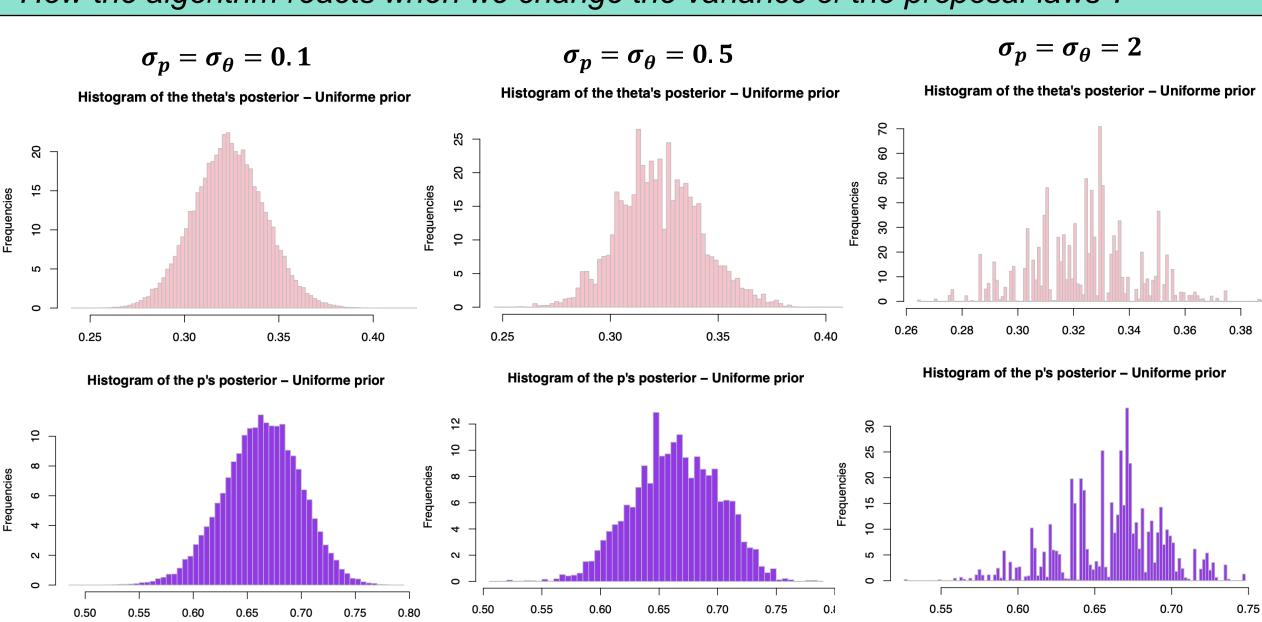
Shema? Ou calcul des prior







How the algorithm reacts when we change the variance of the proposal laws?



GIBBS SAMPLER

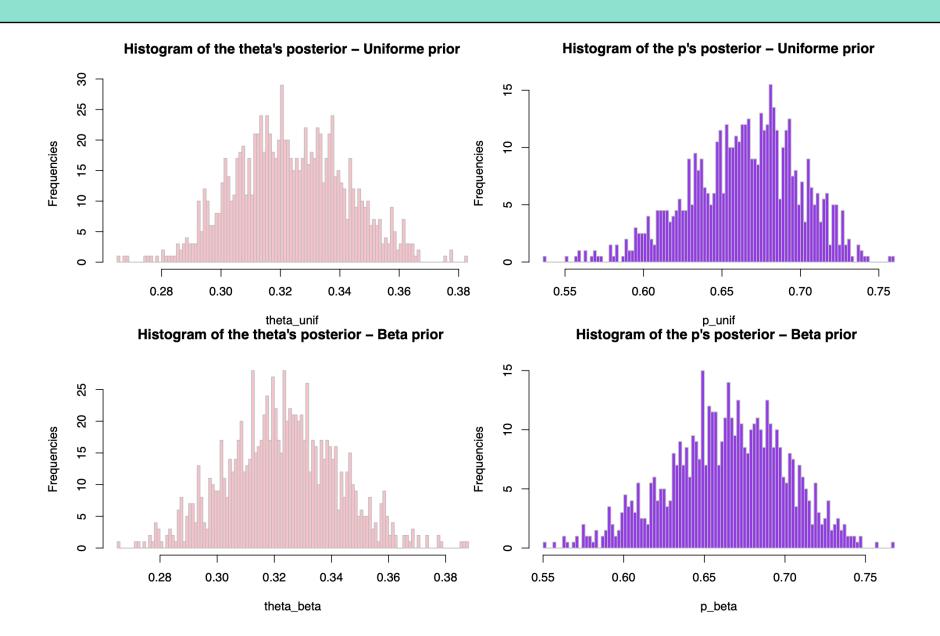
Conditional distribution of p, $\theta | (z, x_{obs})$

$$\pi(p,\theta|z,x_{obs}) = \pi(p,\theta)l(p,\theta|z,x_{obs})$$

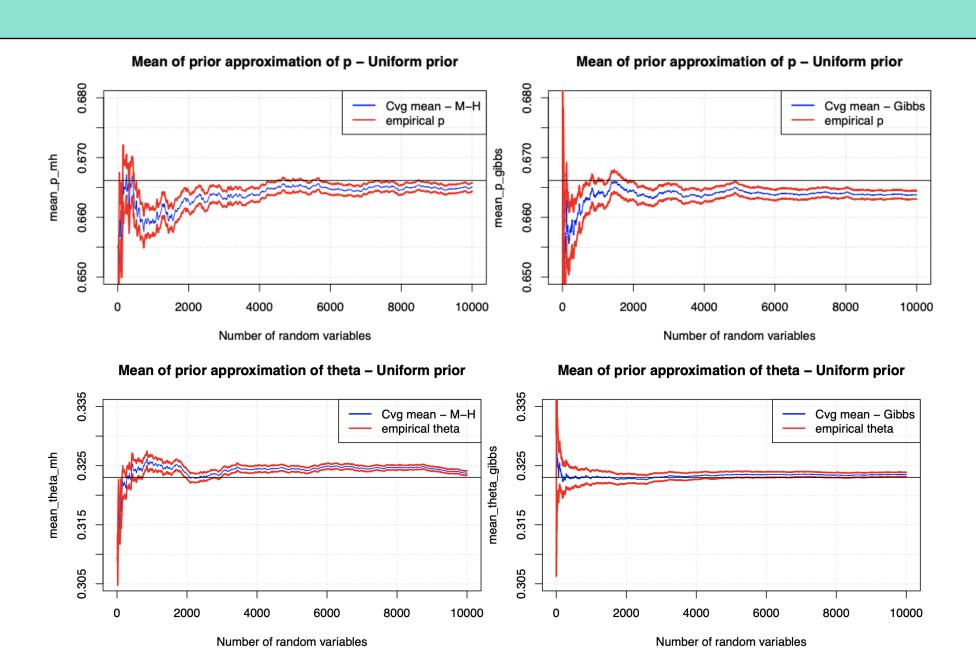
Conditional distribution of $z|(p, \theta, x_{obs})$

$$\mathbb{P}(Z_i = 1 | X_i = x_i, p, \theta) = \frac{p(1 - \theta)}{p(1 - \theta) + (1 - p)(1 - \theta)^2} \quad \text{si} \quad x_i = AA \qquad \mathbb{P}(Z_i = 0 | X_i = x_i, p, \theta) = \frac{(1 - p)(1 - \theta)^2}{p(1 - \theta) + (1 - p)(1 - \theta)^2} \quad \text{si} \quad x_i = AA \\
= \frac{p\theta}{p\theta + (1 - p)\theta^2} \quad \text{si} \quad x_i = aa \\
= 0 \quad \text{si} \quad x_i = aA \\
= 1 \quad \text{si} \quad x_i = aA$$

GIBBS SAMPLER



GIBBS SAMPLER



ABC: Approximate bayesian computation

Summarv

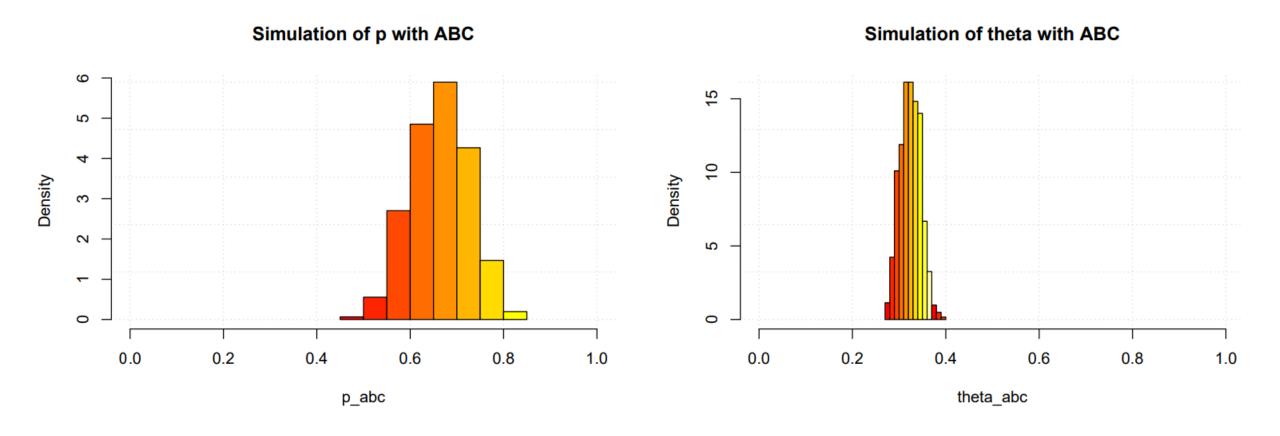
$$l(x|p,\theta) = ln(p_{AA}) \sum_{i=1}^{n} \mathbb{1}_{x_i = AA} + ln(p_{aa}) \sum_{i=1}^{n} \mathbb{1}_{x_i = aa} + ln(p_{aA}) \sum_{i=1}^{n} \mathbb{1}_{x_i = aA}$$

$$= ln(p_{AA}) N_{AA} + ln(p_{aa}) N_{aa} + ln(p_{aA}) (n - N_{AA} - N_{aa})$$

$$\begin{cases} N_{AA} = \sum_{i=1}^{n} \mathbb{1}_{x_i = AA} \\ N_{aa} = \sum_{i=1}^{n} \mathbb{1}_{x_i = aa} \end{cases}$$

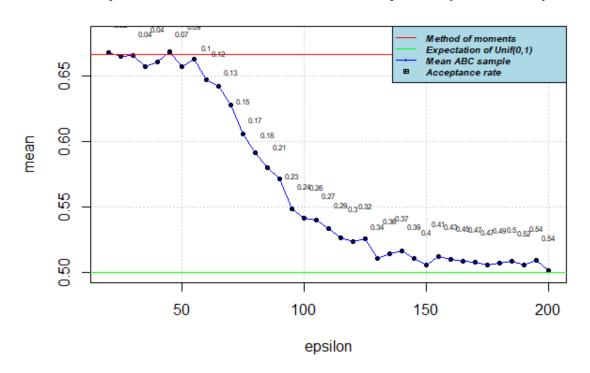
Algorithm 2: ABC i-th iteration $\begin{aligned} & \text{input: } \pi, \, (X_k^{obs})_{1 \leq k \leq n}, \, \epsilon \\ & 1 \, \left(p_i, \theta_i\right) \sim \pi \\ & 2 \, p_{AA,i} = p_i (1-\theta_i) + (1-p_i)(1-\theta_i)^2 \\ & 3 \, p_{aa,i} = p_i \theta_i + (1-p_i) \theta_i^2 \\ & 4 \, p_{aA,i} = 1 - p_{AA,i} - p_{aa,i} \\ & 5 \, \left(X_{i,k}^{new}\right)_{1 \leq k \leq n} \sim \mathcal{L}(p_{AA,i}, p_{aa,i}, p_{aA,i}) \\ & 6 \, N_i^{new} := \left(N_{AA,i}^{new}, N_{aa,i}^{new}\right) \\ & 7 \, \text{if} \, d(N_i^{new}, N^{obs}) \leq \epsilon \, \text{then} \\ & 8 \, \mid \, \text{return} \, (p_i, \theta_i) \, ; \\ & 9 \, \text{else} \\ & 10 \, \mid \, \text{return} \, \emptyset \, ; \end{aligned}$

ABC: First results (eps=15)

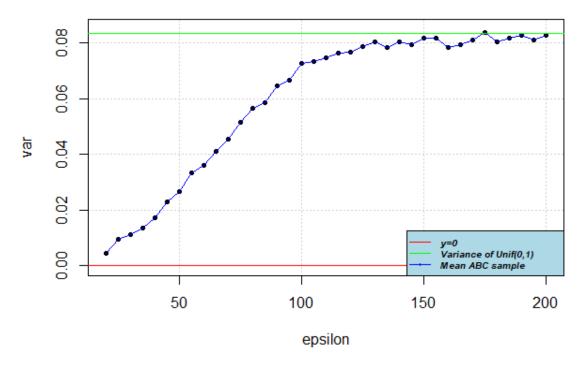


ABC: Parameter Epsilon

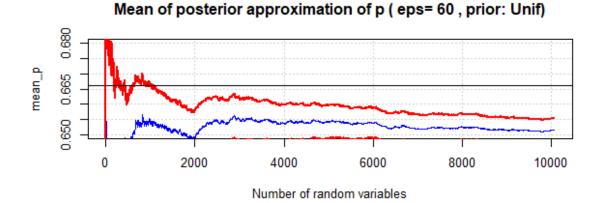
posterior's mean in function of epsilon (N= 10000)

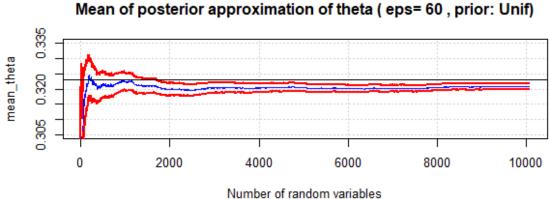


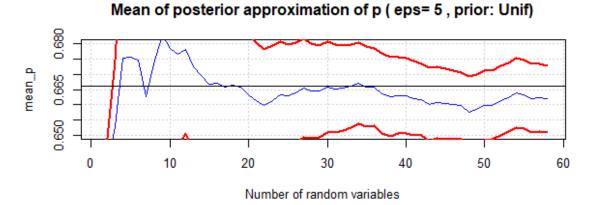
posterior's variance in function of epsilon (N= 10000)

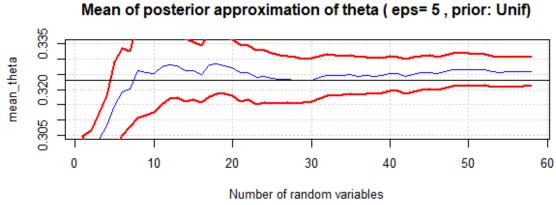


ABC: Poseterior Means



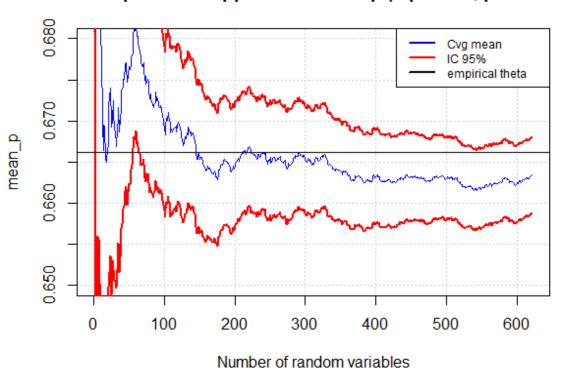




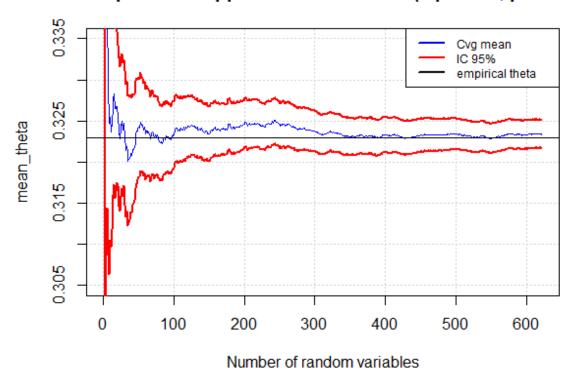


ABC: Poseterior Means

Mean of posterior approximation of p (eps= 15, prior: Unif)



Mean of posterior approximation of theta (eps= 15, prior: Unit

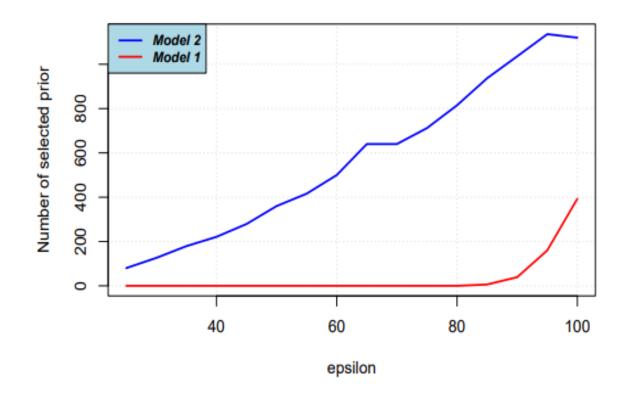


ABC: Model choice (1)

```
Algorithm 3: ABC model selection i-th iteration
    input: (X_k^{obs})_{1 \le k \le n}, \epsilon
 1 M_i \sim \mathcal{U}(\{1,2\})
 2 if M_i = 1 then
 \theta_i \sim \mathcal{U}([0,1])
 4 p_{AA,i} = (1 - \theta_i)^2
     p_{aa,i} = \theta_i^2
     p_{aA,i} = 1 - p_{AA,i} - p_{aa,i}
 7 else
 8 | (p_i, \theta_i) \sim \mathcal{U}^2([0, 1])
    p_{AA,i} = p_i(1 - \theta_i) + (1 - p_i)(1 - \theta_i)^2
    p_{aa,i} = p_i \theta_i + (1 - p_i)\theta_i^2
|\mathbf{11}| p_{aA,i} = 1 - p_{AA,i} - p_{aa,i}
|_{12} (X_{i,k}^{new})_{1 \leq k \leq n} \sim \mathcal{L}(p_{AA,i}, p_{aa,i}, p_{aA,i})
| {\bf 13} \ N_i^{new} := (N_{AA,i}^{new}, N_{aa,i}^{new}) |
14 if d(N_i^{new}, N^{obs}) \le \epsilon then
15 return M_i;
16 else
| \mathbf{return} \emptyset;
```

ABC: Model choice (2)





Model 1 Variable VS Model 2 Variables

