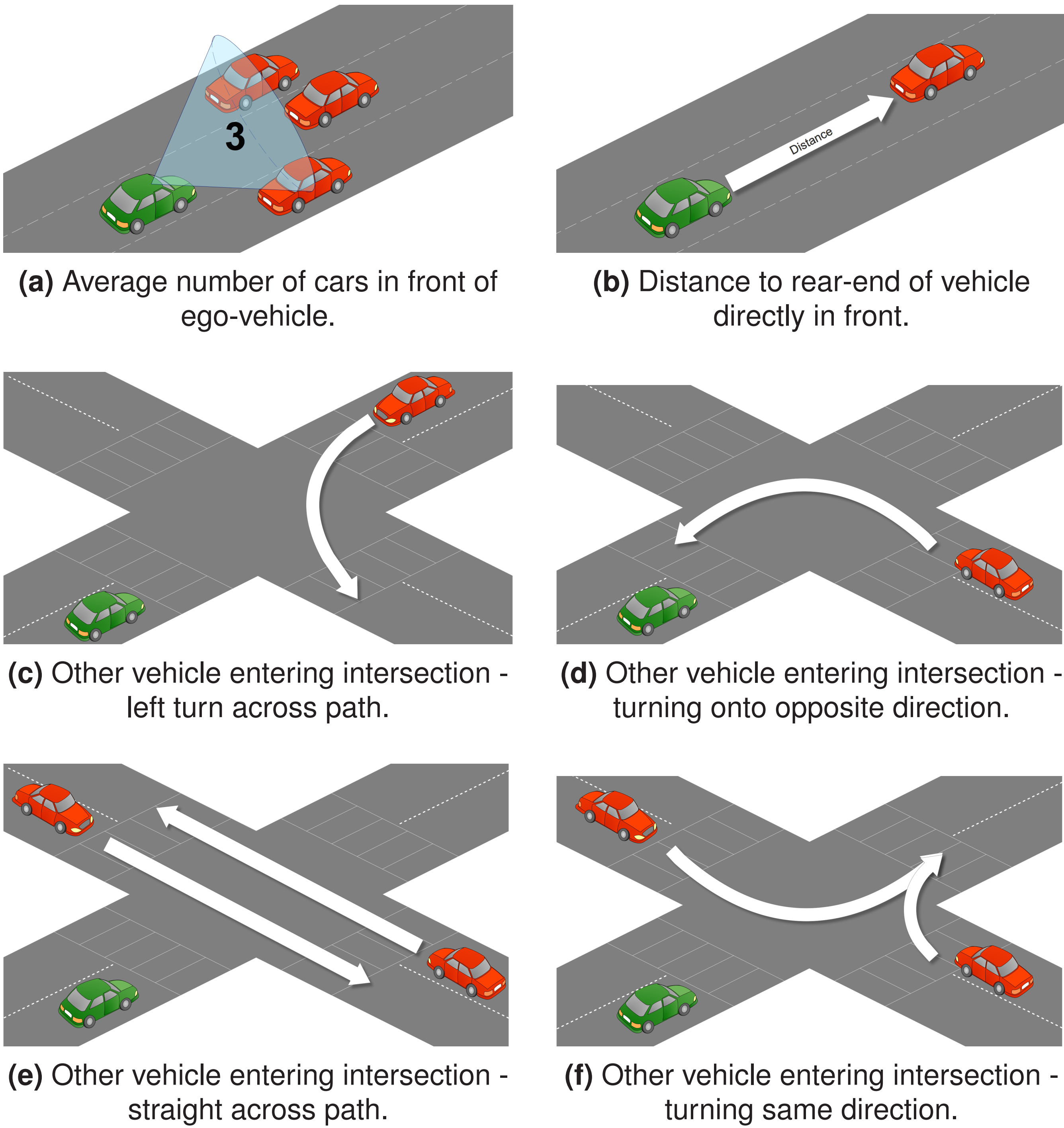


## Introduction



**Figure 1:** Drive events that can be automatically detected by the method proposed in this paper. Green car is ego vehicle. Red cars are other vehicles.

## Proposed Method

## Results

## Conclusion

## Acknowledgment

We would like to thank Ravi K. Satzoda, Mohan M. Trivedi, Andreas Møgelmoose, and Thomas B. Moeslund for their guidance. Additionally, we would like to thank the reviewers from *Intelligent Vehicles Symposium 2015* for their comments.

## References