

Introduction

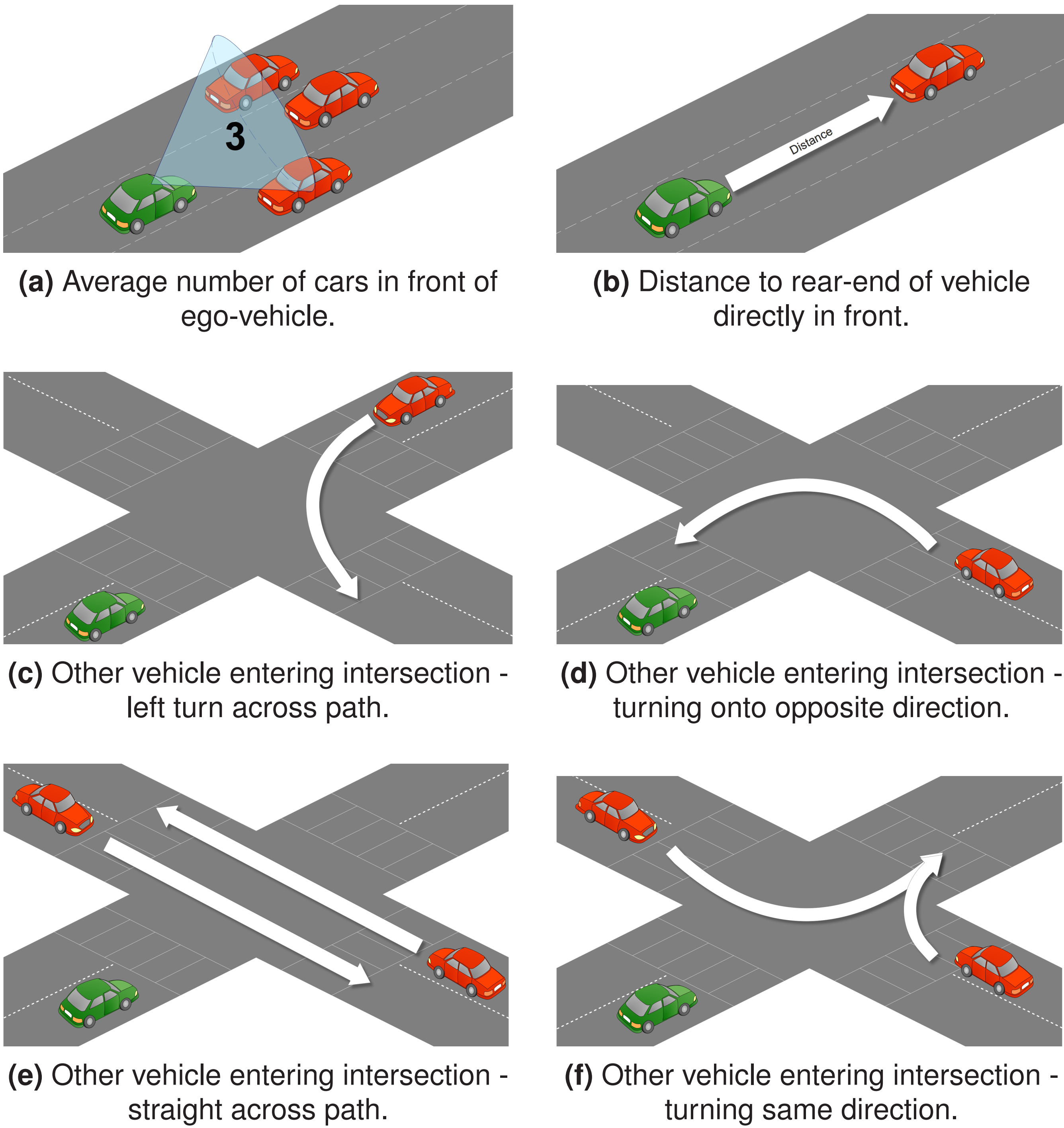


Figure 1: Drive events that can be automatically detected by the method proposed in this paper. Green car is ego vehicle. Red cars are other vehicles.

Proposed Method

Results

Conclusion

Acknowledgment

We would like to thank Ravi K. Satzoda, Mohan M. Trivedi, Andreas Møgelmoose, and Thomas B. Moeslund for their guidance. Additionally, we would like to thank the reviewers from *Intelligent Vehicles Symposium 2015* for their comments.

References