

FACULTY OF COMPUTER SCIENCE

Institute of Theoretical Computer Science

CHAIR OF AUTOMATA THEORY

Prof. Dr.-Ing. Franz Baader

Master's Thesis

A Tableau Algorithm for the Numerical Description Logic \mathcal{ALCSCC}

Ryny Khy

Matriculation Number: 4751049 born on 30. November 1994 in Landshut

supervised by Dr.-Ing. Stefan Borgwardt Filippo De Bortoli M.Sc. reviewed by Dr.-Ing. Stefan Borgwardt Prof. Sebastian Rudolph

December 5, 2020

Declaration of Authorship

Author: Ryny Khy

Matriculation Number: 4751049

Title: A Tableau Algorithm for the Numerical Description Logic \mathcal{ALCSCC}

I hereby declare that I have written this final thesis independently and have listed all used sources and aids. I am submitting this thesis for the first time as a piece of assessed academic work. I understand that attempted deceit will result in the failing grade "not sufficient" (5.0).

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Abstract

In the research field of Description Logics (DLs) checking satisfiability of \mathcal{ALCQ} has been investigated thoroughly and is therefore well-known. The DL \mathcal{ALCSCC} extend \mathcal{ALCQ} with constraints over role successor using quantifier-free fragment (QF) of Boolean Algebra (BA) and Presburger Arithmetic (PA). Checking satisfiability of this DL has been proven to be decidable and PSpace-complete. We provide in this work a tableau algorithm for checking satisfiability of \mathcal{ALCSCC} and its correctness proof.

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Chapter 1

Introduction

1.1 Motivation

In traditional databases stored data objects do not have any relation with each other unless explicitly stated. However we can extract additional information about these objects if we use database systems which employ semantics. Imagine we want to add data entries for two people (Anna and Beth) to a traditional database. Anna is a teacher at the local school. Beth is a student of her class. In our database we save their names, the class that Beth attends as well as the class that Anna teaches. As we do not explicitly encode their student-teacher relationship the traditional database does not know about it. If we use an ontology-based system we can deduce this information by making use of semantics. These semantics are described by a set of rules (axioms). In our example one axiom would be that if a teacher teaches a class and students attend the same class, then there is a student-teacher relationship between the teacher and these students. By applying this axiom the ontology-based database can automatically deduce that Anna is the teacher of Beth. Popular use-cases for ontology-based systems are databases for biological and medical research [4]. As an example ontologies can be used to automatically fill in missing information about patients which are helpful in diagnostics. Another major use-case for ontologies is the Semantic Web, which is an extension of the World Wide Web with standards given by the World Wild Web Consortium (W3C)¹. These standards allow a more effective way of combining information from different sources.

An Ontology (in the field of computer science) can be viewed as formal representation of a certain domain of interest. The relationships between entities in an ontology-based database are formulated by a fragment of first-order logic (FOL). This fragment of FOL is called $Description\ Logic\ (DL)$ and is a family of knowledge representation systems. DLs mainly consist of concepts, which correspond to unary relations in FOL, and relations between the concepts, which

 $^{^1}$ https://www.w3.org/standards/semanticweb/, last accessed on December 5, 2020

correspond to binary relations in FOL. To create more complex (compound) concepts we can combine concepts by using operators like \sqcap , \sqcup , \sqsubseteq , \exists and \forall . For example the statement "All Humans who have children are parents" can be formalized in DL as $Human \sqcap \exists hasChild$. $\sqcap \sqsubseteq Parent$, where Human and Parent are concept names and hasChild is a role name. This statement can also be formalized with a a numerical restriction: $Human \sqcap \geq 1hasChild$. $\sqcap \sqsubseteq Parent$. A knowledge base consists of a TBox, which contains the axioms, and an ABox, which contains assertions about certain individual names (objects).

The process of determining whether some statement can be concluded from a set of information is called reasoning. Reasoning can be done by adding this statement in negated form (as an axiom or assertion) to the set of information (TBox or ABox) and then checking whether the updated knowledge base is now unsatisfiable. If it is unsatisfiable the statement can be concluded from the information set. Being able to check the satisfiability of DL statements is therefore a valuable tool to conduct reasoning in ontology systems. The DL \mathcal{ALCQ} [5][9] has been investigated thoroughly and therefore we know a lot about its satisfiability. This DL allows conjunctions (\square), disjunctions (\square), negations (\square) and number restrictions ($\subseteq nrC$ and $\supseteq nrC$, where n is a number, r a role name and C a concept name). In [5] Hollunder and Baader proved that checking satisfiability of a \mathcal{ALCQ} concept without a TBox is in PSpace and otherwise in ExpTime.

The DL \mathcal{ALCSCC} [1] extends \mathcal{ALCQ} with set constraints and cardinality constraints over role successors, which use the logic of QFBAPA (quantifier-free fragment of Boolean Algebra with Presburger Arithmetic)[7]. Instead of the quantifiers \exists and \forall we use set expressions (Boolean Algebra) and numerical constraints (Presburger Arithmetic). For example $Human \cap \geq 1$ has $Child. \cap \subseteq Parent$ is written in \mathcal{ALCSCC} as $Human \cap succ(|hasChild| \geq 1) \subseteq Parent$. This DL is more expressive than \mathcal{ALCQ} because every quantified restriction of the form $\leq nr.C$ or $\geq nr.C$ can be written in \mathcal{ALCSCC} as $succ(|r \cap C| \leq 1)$ or $succ(|r \cap C| \geq 1)$ respectively. However a constraint like succ(|r| = |s|) can not be formulated in \mathcal{ALCQ} [1]. Because of this extension checking satisfiability over \mathcal{ALCSCC} becomes more complicated. Nevertheless in [1] Baader has shown that the satisfiability problem for \mathcal{ALCSCC} is still PSpace-complete.

In this work we present a tableau algorithm for \mathcal{ALCSCC} . While a tableau algorithm leads to a runtime complexity worse than PSpace-complete the benefit of a tableau algorithm is that we gain a satisfied interpretation (a correct assignment without contradiction) of the concepts, which is also called witness. A tableau algorithm consists of completion rules which are applied to the assertions of the ABox. By applying these rules new assertions that can be derived from the original assertions are added to the ABox. If we can no longer apply any rules and the ABox contains a contradiction, then the ABox is unsatisfiable. Otherwise it is satisfiable. The main difficulty in creating the completion rules for \mathcal{ALCSCC} is that unlike in \mathcal{ALCQ} , the number of successor is not bounded. By adding role successors the cardinalities in a constraint can vary. For example if we have a constraint succ(|r| = |s|) then the bound for the number of s-successors is equal to the number of r-successors we already have. During a

tableau algorithm we can add, merge or replace r-successors which changes the bound for the number of s-successors. To deal with the changing cardinalities of \mathcal{ALCSCC} we transform the assertions with cardinalities to a QFBAPA formula and use a QFBAPA solver to determine whether the formula is satisfiable or not. If the formula is not satisfiable, there must be a contradiction. If the solver returns a solution, we add new assertions accordingly. Since we use a solver that is capable of returning every possible solution, there can be an infinite number of solutions. We can show that we can shorten each of these solutions to a bound number of role successors without losing any information.

1.2 Related Works

The tableau algorithm is a popular tool to solve the satisfiability problem for description logics. Hence a lot of research has been done trying to formulate tableau algorithms for different description logic languages. In [5] Hollunder and Baader present a tableau algorithm for checking the satisfiability of an ABox in the DL \mathcal{ALCQ} . This satisfiability problem is PSpace-hard. The presented algorithm consists of five rules which can be applied to the ABox in non-deterministic order. Two of these rules are decomposing rules for \sqcap and \sqcup . Furthermore there is a rule that decides whether a successor of an individual name also contributes in any other numerical assertion, which helps to determine the exact number of role successors. The last two rules add and replace individual names to the ABox according to the numerical restrictions. This is can lead to an endless loop of adding and replacing invidual names. To avoid endless loops the author introduces a concept of safeness, which has a similar purpose as blocking in other tableau algorithms: Individual names can only be replaced if they fullfill the safeness criteria. In [10] Tobies presented an optimized tableau algorithm for ALCQ, which runs in PSpace. This optimization is achieved by saving an integer which denotes the number of successors already introduced to satisfy a restriction $\geq n r.C$, instead of keeping all n possible successors.

In [6] Horrocks et al. published tableau algorithms for \mathcal{SHIF} concepts and \mathcal{SI} concepts. The DL \mathcal{SI} extends the DL \mathcal{ALC} with transitive and inverse role names. The DL \mathcal{SHIF} further extends \mathcal{SI} with role hierarchy and functional restriction. For both DLs the tableau algorithm has to have a blocking technique to avoid infinite chains of introducing elements with the same properties which can be caused by transitive or inverse roles. For \mathcal{SI} the tableau algorithm does not only look at the successors but also the predecessors of the considered individual names when dealing with a \forall -assertion. In case of \exists -assertions the algorithm first determines whether the considered individual name x is blocked or not. It is blocked if an ancestor (a non-direct predecessor) is blocked or if an ancestor has "similar" assertions as x. This algorithm runs in PSpace. For \mathcal{SHIF} the tableau algorithm has to ensure that the considered individual name x is not pair-wise blocked for any rule. Being pair-wise blocked means that for a predecessor y of x there are two ancestors of x, such that they behave "similar" to y and x. In [3] a DL called \mathcal{SHQ} (also known \mathcal{ALCQH}_{R^+} from the SI family

is presented. This DL does not have inverse roles, but a role hierarchy and numerical restrictions. The difficulty of creating a tableau algorithm for this DL is that with numerical restrictions an infinite chain of adding individual names can prevent the termination of the algorithm. Hence a blocking technique is also needed to ensure termination: An individual name x blocks another individual name y if x was introduced before y and if any assertion about x also holds for y. To deal with the number restrictions a reasoner about sets of linear inequations is used.

Regarding the DL \mathcal{ALCSCC} , which is considered in this work, Baader provides a solution for the satisfiability problem without a TBox in [1], which is PSpace-complete: For a part of the Abox we guess the values (true or false) of the top-level atoms (concepts). This can already lead to a *false* result, which would mean that the ABox is unsatisfiable. If not, then the ABox is formulated into a QFBAPA formula. Then the formula is extended with constraints over the *Venn regions* of the concepts. For the new formula we test whether it returns true or false with a satisfiability algorithm for QFBAPA. This satisfiability algorithm runs in NP. If the algorithm returns true we are done. If it returns false, we create a concept for every guessed Venn region. Then the algorithm is applied on these new concepts recursively. If it return false, the ABox is unsatisfiable, otherwise satisfiable.

Chapter 2

Preliminaries

In order to be able to follow the construction of the tableau algorithm for \mathcal{ALCSCC} this section provides a number of important definitions on QFBAPA and \mathcal{ALCSCC} .

2.1 QFBAPA

The logic QFBAPA [7] combines boolean algebra (BA) over a sets of symbols with Presburger arithmetic (PA). Terms in boolean algebra over a symbol set T are comprised of conjunctions (\cap) and/or disjunctions (\cup) of symbols. These symbols can also be used in negated form (s^{\neg} , $s \in T$). Terms in Presburger arithmetic are additions of natural numbers. In QFBAPA we construct set terms using boolean algebra and create cardinality terms over the cardinalities of those set terms with the help of Presburger arithmetic. As multiplications can be constructed as chained additions, we also allow multiplication in cardinality terms. QFBAPA allows the construction of inclusion and comparison constrains over set and cardinality terms. This is defined as:

Definition 1 (QFBAPA). Let T be a finite set of symbols

- \bullet set terms over T are:
 - empty set \emptyset and universal set \mathcal{U}
 - every set symbol in T
 - if s, t are set terms then so are $s \cap t$, $s \cup t$ and $s \cap t$
- \bullet set constraints over T are
 - $-s \subseteq t$ and $s \not\subseteq t$
 - -s = t and $s \neq t$

where s, t are set terms

- cardinality terms over T are:
 - every number $n \in \mathbb{N}$
 - -|s| if s is a set term
 - if k, l are cardinality terms then so are k+l and $n \cdot k$, $n \in \mathbb{N}$
- cardinality constraints over T are:
 - -k=l and $k \neq l$
 - $-k < l \text{ and } k \ge l$
 - $-k \le l$ and k > l
 - $n \ dvd \ k$ and $n \ \neg dvd \ k \ (n \ dvd \ k: n \ divides \ k)$

where k, l are cardinality terms and $n \in \mathbb{N}$

A QFBAPA formula ϕ consists of disjunctions (\vee) and/or conjunctions (\wedge) of (possible negated) cardinality constraints, where every set symbol is represented as a set variable.

Set constraints of the form $s \subseteq t$ can be expressed as cardinality constraints like $|s \cap t^{-}| \leq 0$. Analogously $s \not\subseteq t$ can be expressed as $|s \cap t^{-}| > 0$. Set constraints of the form s = t can be written as $|s \cap t^{-}| \leq 0$ and $|s^{-} \cap t| \leq 0$. Analogously for $s \neq t$. As all set constraints can be written as cardinality constraints we will not use them any further. For better readability we write $k \leq l$ instead of $l \geq k$, $k + 1 \leq l$ instead of k < l and $k \leq l$ and $l \leq k$ instead of k = l.

As an example for a QFBAPA formula consider the symbols $T = \{l, a, n, e, f\}$ and the constraints |l| = 2, |l| = |a|, $|e \cap f^{\neg}| = 0$, $|n \cap f^{\neg}| = 0$. A formula can be written as:

$$|l| = 2 \wedge |l| = |a| \wedge |e \cap f^{\neg}| = 0 \wedge |n \cap f^{\neg}| = 0$$
 (2.1)

To satisfy this formula we have to create a semantic that satisfies all cardinality constraints (since all constraints are connected with \land). In this case we need two elements which are in the semantic of l and therefore also two elements in the semantic of a.

The semantics of QFBAPA, called substitutions, are defined as follows:

Definition 2 (Substitutions of QFBAPA). A substitution σ over a symbol set T is a mapping that assigns

- \mathcal{U} to a finite set $\sigma(\mathcal{U})$
- every symbol a in T to $\sigma(a) \subseteq \sigma(\mathcal{U})$
- \emptyset to $\sigma(\emptyset) = \emptyset$
- $\sigma(s \cap t) := \sigma(s) \cap \sigma(t), \ \sigma(s \cup t) := \sigma(s) \cup \sigma(t)$
- $\sigma(s^{\neg}) := \sigma(\mathcal{U}) \setminus \sigma(s)$

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- $\sigma(|s|) := |\sigma(s)|$
- $\sigma(k+l) := \sigma(k) + \sigma(l), \ \sigma(n \cdot k) := n \cdot \sigma(k)$

Given cardinality terms k, l we say that σ satisfies

- $k \le l$ iff $\sigma(k) \le \sigma(l)$
- $n \, dv d \, l \, \text{iff} \, \exists m \in \mathbb{N} : n \cdot m = \sigma(l)$

The substitution σ is a solution of a QFBAPA formula ϕ if it evaluates the formula to \top . A QFBAPA formula is satisfiable if it has a solution σ and is unsatisfiable otherwise.

For our example (2.1) a possible solution σ is: Let $\sigma(\mathcal{U}) = \{ \text{leg 1, leg 2, arm1, arm 2, nose, ear1, ear2} \}$ and:

- $\sigma(l) = \{ \text{leg1}, \text{leg2} \}$
- $\sigma(n) = \{\text{nose}\}$
- $\sigma(a) = \{\text{arm1, arm2}\}$
- $\sigma(e) = \{\text{ear1, ear 2}\}$
- $\sigma(f) = \{\text{nose, ear1, ear2}\}\$

This interpretation satisfies the formula because $\sigma(|l|) = 2 = \sigma(|k|)$, $\sigma(|n \cap f^{\neg}|) = 0$ and $\sigma(|e \cap f^{\neg}|) = 0$.

Now we can interpret our formula as:

- we have 2 legs
- we have as many legs as arms
- nose and two ears are both in the same set hence they belong to a common body part (face)

In [7] Kuncak and Rincard show that checking satisfiability of QFBAPA formulas is a NP-complete problem.

2.2 ALCSCC

Next we define the parts and semantics of the description logic \mathcal{ALCSCC} [1]. Let \mathbf{C} be a set of concept names and \mathbf{R} a set of role names, such that \mathbf{C} and \mathbf{R} are disjoint.

Definition 3 (\mathcal{ALCSCC}). \mathcal{ALCSCC} concepts over \mathbf{C} and \mathbf{R} are defined inductively as:

- all concept names in C
- \bullet if C,D are \mathcal{ALCSCC} concepts over ${\bf C}$ and ${\bf R}$ then so are:

$$- \neg C$$

- $-C \sqcup D$
- $-C\sqcap D$
- if c is a QFBAPA cardinality constraint over a set T of role names in \mathbf{R} and \mathcal{ALCSCC} concepts over \mathbf{C} and \mathbf{R} then succ(c) is an \mathcal{ALCSCC} concept over \mathbf{C} and \mathbf{R}

An \mathcal{ALCSCC} ABox \mathcal{A} is a finite set of assertions of the form x:C and (x,y):r, where C is a \mathcal{ALCSCC} concept, $r\in\mathbf{R}$ and x,y are individual names. The set $I(\mathcal{A})$ is the set of individual names occurring in \mathcal{A} .

Regarding our QFBAPA example (2.1) we can now construct an ABox of specific individual names. Let $\mathbf{C} = \{Legs, Arms, Female\}$ and $\mathbf{R} = \{bodyParts\}$. A possible ABox, which states that an individual name Anna has two legs and two arms and is female, is:

$$\{Anna: succ(|Legs \cap bodyParts| = 2) \cap succ(|Legs| = |Arms|) \cap Female\}$$
 (2.2)

Similar to the substitutions for QFBAPA we now define the semantics for \mathcal{ALCSCC} which are called interpretations.

Definition 4 (Interpretations of \mathcal{ALCSCC}). An interpretation $\mathcal{I} = (\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ over an \mathcal{ALCSCC} ABox \mathcal{A} consists of a non-empty set $\Delta^{\mathcal{I}}$ and a mapping $\cdot^{\mathcal{I}}$ which maps:

- each individual name $x \in I(\mathcal{A})$ to $x^{\mathcal{I}} \in \Delta^{\mathcal{I}}$
- each concept name $A \in \mathbf{C}$ to $A^{\mathcal{I}} \subset \Delta^{\mathcal{I}}$
- each role name $r \in \mathbf{R}$ to $r^{\mathcal{I}} \subseteq \Delta^{\mathcal{I}} \times \Delta^{\mathcal{I}}$, such that every element in $\Delta^{\mathcal{I}}$ has a finite number of successors.

The set $r^{\mathcal{I}}(x)$ contains all elements y such that $(x,y) \in r^{\mathcal{I}}$ i.e. it contains all r-successors of x.

For compound concepts the mapping $\cdot^{\mathcal{I}}$ is extended inductively as follows

- $\top^{\mathcal{I}} = \Delta^{\mathcal{I}}$ and $\bot^{\mathcal{I}} = \emptyset^{\mathcal{I}}$
- $(C \sqcap D)^{\mathcal{I}} := C^{\mathcal{I}} \cap D^{\mathcal{I}}, (C \sqcup D)^{\mathcal{I}} := C^{\mathcal{I}} \cup D^{\mathcal{I}}$
- $(\neg C)^{\mathcal{I}} := \Delta^{\mathcal{I}} \backslash C^{\mathcal{I}}$
- $succ(c)^{\mathcal{I}} = \{x \in \Delta^{\mathcal{I}} | \text{the mapping } \mathcal{I}_x \text{ satisfies } c\}$

The mapping $\cdot^{\mathcal{I}_x}$ is a QFBAPA substitution that maps \emptyset to $\emptyset^{\mathcal{I}}$, \mathcal{U} to $\mathcal{U}^{\mathcal{I}_x} := \{\bigcup_{r \in \mathbf{R}} r^{\mathcal{I}}(x)\}$, every concept C occurring in c to $C^{\mathcal{I}_x} := C^{\mathcal{I}} \cap \mathcal{U}^{\mathcal{I}_x}$ and every role name r occurring in c to $r^{\mathcal{I}_x} := r^{\mathcal{I}}(x)$.

 \mathcal{I} is a model of \mathcal{A} iff

- $x: C \text{ iff } x^{\mathcal{I}} \in C^{\mathcal{I}}$
- $(x,y): r \text{ iff } (x^{\mathcal{I}},y^{\mathcal{I}}) \in r^{\mathcal{I}}$

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We can define a model \mathcal{I} of the ABox defined in (2.2) by setting $\Delta^{\mathcal{I}} = \{Anna^{\mathcal{I}}, Leg1^{\mathcal{I}}, Leg2^{\mathcal{I}}, Arm1^{\mathcal{I}}, Arm2^{\mathcal{I}}\}$ and

- $Female^{\mathcal{I}} = \{Anna^{\mathcal{I}}\}$
- $Leg^{\mathcal{I}} = \{Leg1^{\mathcal{I}}, Leg2^{\mathcal{I}}\}$
- $Arm^{\mathcal{I}} = \{Arm1^{\mathcal{I}}, Arm2^{\mathcal{I}}\}$
- $bodyPart^{\mathcal{I}} = \{(Anna, Leg1), (Anna, Leg2), (Anna, Arm1), (Anna, Arm2)\}$

By mapping Anna to $Anna^{\mathcal{I}}$, Leg1 to $Leg1^{\mathcal{I}}$ and so on we see that this interpretation satisfies the ABox: $Anna^{\mathcal{I}}$ is indeed in $succ(|Legs \cap bodyParts| = 2)^{\mathcal{I}}$ because $Leg1^{\mathcal{I}}$, $Leg2^{\mathcal{I}} \in bodyPart^{\mathcal{I}_{Anna}} \cap Leg^{\mathcal{I}_{Anna}}$. Analogously for the second succ-assertion.

Next we define the negated normal form (NNF) for \mathcal{ALCSCC} . By transforming all concepts into NNF we avoid nested negations e.g. $\neg(\neg(\neg(A \cup B)))$ which helps to formulate the rules for the tableau algorithm.

Definition 5 (Negation Normal Form). A \mathcal{ALCSCC} concept is in *negation* normal form (NNF) if the negation sign \neg only appears in front of a concept name or above a role name. Let C be an arbitrary \mathcal{ALCSCC} concept. With NNF(C) we denote the concept which is obtained by applying the the following rules on C until none of them are applicable anymore.

$1 \neg \top \to \bot$	$8 \neg (k \le l) \to l \le k$
$2 \neg \perp \rightarrow \top$	$9 \ \neg (n \ dvd \ k) \rightarrow n \ \neg dvd \ k$
$3 \neg \neg C \rightarrow C$	$10 \ \neg (n \ \neg dvd \ k) \rightarrow n \ dvd \ k$
$4 \neg (C \sqcap D) \rightarrow \neg C \sqcup \neg D$	$11 (s \cap t) \neg \to s \neg \cup t \neg$
$5 \neg (C \sqcup D) \rightarrow \neg C \sqcap \neg D$	$12 (s \cup t)^{\neg} \to s^{\neg} \cap t^{\neg}$
$6 \ C^{\neg} \rightarrow \neg C$	$13 \ (s \) \ \neg \rightarrow s$
$7 \neg succ(c) \rightarrow succ(\neg c)$	

The rule $C^{\neg} \to \neg C$ is necessary because C^{\neg} can be a result of s^{\neg} , where s is a set term. C^{\neg} can be transformed into $\neg C$: For every substitution σ for a concept C based on QFBAPA it holds that $\sigma(C^{\neg}) = \sigma(\mathcal{U}) \setminus \sigma(C)$ and for every interpretation \mathcal{I} based on \mathcal{ALCSCC} it holds that $(\neg C)^{\mathcal{I}} = \Delta^{\mathcal{I}} \setminus C^{\mathcal{I}}$. Since $\sigma(\mathcal{U}) \subseteq \Delta^{\mathcal{I}}$ we can conclude that every element in $\sigma(C^{\neg})$ is also in $(\neg C)^{\mathcal{I}}$. All rules used to obtain the NNF can be applied in linear time. For rules 1-5 this is shown in [5],[9]. For rules 6-11 this can be shown analogously because we only shift the negation signs. Rules 11, 12 and 13 work similarly to rules 4, 5 and 3 respectively.

Regarding the normal form we additionally replace every disjunction and conjunction in form as \sqcap and \sqcup in every succ(c) concept with \cap and \cup . We can do

this because for an arbitrary interpretation \mathcal{I} for each $x, y \in \Delta^{\mathcal{I}}$ it holds that $y \in (C \cap D)^{\mathcal{I}_x}$ iff $y \in (C \cap D)^{\mathcal{I}_x}$:

Next we define the size of an \mathcal{ALCSCC} concept C inductively over concepts, set terms and cardinality constraints. This definition is necessary for the termination proof.

- size(r) = size(C) = 1 if $r \in \mathbf{R}$, $C \in \mathbf{C}$
- size(n) = size(|k|) = 1 if $n \in \mathbb{N}$, k cardinality term
- $size(\neg C) = size(C) + 1$
- size(k) = size(k) + 1
- $size(C \sqcap D) = size(C \sqcup D) = size(C) + size(D) + 1$
- $size(k \cap l) = size(k \cup l) = size(k) + size(l) + 1$
- size(|k|) = size(k)
- $size(succ(c)) = \begin{cases} 1 + size(k) + size(l) & c = k \le l \\ 1 + size(l) & c = n \, dvd \, l \end{cases}$

Chapter 3

Tableau for ALCSCC

The tableau algorithm is a popular tool to check satisfiability. Even though the complexity of tableau algorithms can grow exponentially one advantage of them is that they do not only check if an Abox is satisfiable but also return an interpretation that satisfies this ABox (witness) if one exists. A tableau algorithm consists of completion rules that are used to iteratively add new assertions to the ABox that are derived from pre-existing assertions. These rules are exhaustively applied to the Abox until there are no more applicable rules. For some completion rules like the rule for disjunctions $(x: C \sqcap D)$, the algorithm can decide which assertion is added to the ABox (either x: C or x: D). If such a choice results in a clash the algorithm back tracks to the point of the decision and tries an alternative choice instead. If all choices end in a clash, then the ABox is unsatisfiable.

Before *clashes* can be defined we first need to introduce the concept of *induced* interpretations. Induced interpretations can be used to count the number of successors of any individual name after any rule application and hereby detect violated assertions.

Definition 6 (Induced Interpretation). An interpretation $\mathcal{I}(\mathcal{A})$ can be induced from an ABox \mathcal{A} through the following steps:

- for each individual name $x \in I(\mathcal{A})$ we introduce $x^{\mathcal{I}(\mathcal{A})}$ and add it to $\Delta^{\mathcal{I}(\mathcal{A})}$
- for each x:C such that C is a concept name we add $x^{\mathcal{I}(A)}$ to $C^{\mathcal{I}(A)}$
- for each (x, y): r such that r is a role name we add $(x^{\mathcal{I}(\mathcal{A})}, y^{\mathcal{I}(\mathcal{A})})$ to $r^{\mathcal{I}(\mathcal{A})}$

Definition 7 (Violated assertion). Let \mathcal{A} be an ABox and x be an individual name in $I(\mathcal{A})$. An assertion x : succ(c) is *violated* if $x^{\mathcal{I}(\mathcal{A})} \notin succ(c)^{\mathcal{I}(\mathcal{A})}$.

Violated assertions can sometimes be resolved by applying further completion rules. However if we find a violated assertion and can no longer apply any rules there is a clash. Aside from unresolvable violated assertions there are other kinds of situations that are also labelled as clashes. **Definition 8** (Clash). An ABox \mathcal{A} contains a *clash* if

- $\{x : \bot\} \subseteq \mathcal{A}$ or
- $\{x:C, x: \neg C\} \subseteq \mathcal{A}$ or
- $\{(x,y):r,(x,y):\neg r\}\subseteq \mathcal{A}$ or
- $x : succ(c) \in \mathcal{A}$ violated and no more rules are applicable

3.1 Transforming an ABox into a formula

One major difficulty of creating a tableau algorithm for \mathcal{ALCSCC} is its numerical arithmetic in the form of successor-assertions. The application of rules can change the number of successors which can in turn influence the number of successors that are demanded by certain constraints. Furthermore it introduces the problem of nested successor assertions.

Definition 9 (Nested Level). Let $\mathcal{A} = \{x : C\}$ be an ABox. An individual name lays in the *i*-th nested level if it is the *i*-th individual name in a role chain beginning from x, where the individual name x is in the 0th nested level. A direct successor of x is in the 1st nested level.

In some DLs we are able to describe the successor of a successor like $\exists r.(\exists r.C)$, such that the number of needed successors is fixed. However in \mathcal{ALCSCC} such boundaries can vary like in x:succ(|succ(|A|<|B|)|>|A|). The number of successors needed to satisfy succ(|A|<|B|) depends on how many successors x already has in x. By applying rules the number of successors for x in x can change. Hence we use a QFBAPA solver whenever we want to add successors for an individual name x. To do this we first collect all x successors regarding x and then transform them into a QFBAPA formula for the next nested level, which means we only consider the direct successors of x. We assume that the ABox is already in x and x regarding the direct successors of x are suggested in x regarding the following ABox:

Example 1.

$$\mathcal{A}=\{x:succ(1\leq|succ(|A|\leq|B\cap r|)|),x:succ(|A|\leq|B|),x:C\}$$
 with $\mathbf{C}=\{A,B,C\}$ and $\mathbf{R}=\{r\}$

In this example the first assertion states that x must have at least one successor y which in turn has at least as many successors in $B \cap r$ as in A. The individual names for $succ(|A| \leq |B| \cap r|)$ are on a different nested level than the ones for $succ(|A| \leq |B|)$. The second assertion states that x has at least as many successors in B as in A.

We start by gathering all succ-assertion regarding x and then transform the cardinality constraints into a formula by carrying out the following steps:

- replace all role names r with X_r
- replace all concepts names C with X_C
- replace all succ(c) with $X_{succ(c)}$
- \bullet connect all formulas with \wedge
- include the conjunct $\mathcal{U} = X_{r_1} \cup \cdots \cup X_{r_n}, r_1, \ldots, r_n \in \mathbf{R}$

We replace (compound) concepts and role names with set variables, so a solver can assign elements to them. The last step is important because sometimes it is not explicitly stated what kind of successor an individual name has. However a successor must always be "connected" to its predecessor by at least one role name. Through the last step we ensure that every element (successor) is assigned to a set variable, which represents a role name.

In our example we have five set variables: X_A , X_B , X_r , $X_{succ(|A| \leq |B \cap r|)}$ and \mathcal{U} . The QFBAPA formula for Example 1 is:

$$\phi = 1 \le |X_{succ(|A| \le |B \cap r|)}| \land |X_A| \le |X_B| \land \mathcal{U} = X_r \tag{3.1}$$

We can use the solver to get a possible solution, if there is one. We make two assumptions about the QFBAPA solver so we can use it in the tableau algorithm.

Assumption 1. We assume that every considered QFABAPA solver is correct which means

- it terminates for all QFBAPA formulas
- a formula is satisfiable iff it returns a solution

Assumption 2. Let ϕ be an arbitrary QFBAPA formula. We assume that every considered QFABAPA solver is able to return all possible solutions of ϕ .

3.2 Solution of a formula

Since we make Assumption 2 there can be infinitely many solutions. Actually Example 1 can have infinitely many solutions: We can always increase the amount of successors in B as long as we have fewer successors in A. However having that means that the tableau algorithm can work on an infinite space and/or might not terminate. Therefore we want to only consider solutions inside some pre-computed upper bounds. For an Integer Linear Programming (ILP) problem, which is described as a system of linear equalities, possible upper bounds are already investigated like in [8], which solution we are going to use. Therefore we want to transform our formula into a linear system of equalities of the form Ax = b, where A and b describe our cardinality constraints and x is the solution i.e. denotes the numbers of elements we have to assign to set variables to satisfy the formula.

First, we notice that every inequality in a QFBAPA formula can be rewritten as $n_1 \cdot |X_1| \pm \cdots \pm n_i \cdot |X_i| \leq I$, $\leq \in \{\leq, \geq, =\}$, where $n_1, \ldots, n_i, I \in \mathbb{Z}$ are a constants. The numbers n_1, \ldots, n_i are called *pre-factors*. Let $c = succ(|A| \leq |B \cap r|)$. We arrange ϕ in (3.1) into

$$\phi' = |X_c| \ge 1 \land |X_A| - |X_B| \le 0 \land |\mathcal{U} \cap X_r^{\neg}| = 0 \land |\mathcal{U}^{\neg} \cap X_r| = 0 \tag{3.2}$$

Then we change each inequalities into equalities by adding two slack variables I_1 and I_2 :

$$\phi'' = |X_c| - I_1 = 1 \land |X_A| - |X_B| + I_2 = 0 \land |\mathcal{U} \cap X_r^-| = 0 \land |\mathcal{U}^- \cap X_r| = 0$$
(3.3)

Right now it is not clear whether the set variables are overlapping or not which is a problem because for a system of linear equations the variables are always disjunct. Therefore we consider *Venn regions*, which are of the form $X_1^i \cap \cdots \cap X_k^i$. The subscript i denotes either 0 or 1. X_1^0 denotes X_1^- and X_1^1 denotes X_1 . Since we have 5 set variable, we have $2^5 = 32$ Venn regions. We already see that the number of Venn regions grows exponentially with the number of set variables. In [1] it is stated that there exists a number N, which is polynomial in the size of ϕ , such that at most N Venn regions are not empty if there exists a solution.

Lemma 1 (Lemma 3 from [1]). For every QFBAPA formula ϕ a number N, which is polynomial in the size of ϕ , can be computed in polynomial time such that for every solution σ of ϕ there exists a solution σ' of ϕ such that

- $|\{v|v \text{ is a Venn region and } \sigma'(v) \neq \emptyset\}| \leq N$
- $\{v|v \text{ is a Venn region and } \sigma'(v) \neq \emptyset\} \subseteq \{v|v \text{ is a Venn region and } \sigma'(v) \neq \emptyset\}$

Hence we guess (in non-deterministic polynomial time) a number N of Venn regions, which are non-empty. In Example 1 we can already guess that any Venn region within X_r^- or \mathcal{U}^- must be empty, because every element must be in \mathcal{U} and since $\mathcal{U}=X_r$ they must be all in X_r . Hence we can drop 24 Venn regions. Therefore we construct A and b such that instead of assigning elements to set variables we assign them to the remaining 8 Venn regions. That means for the vector x the entry x_k , $1 \leq k \leq 8$, denotes the number of elements in the k-th Venn region. Since we have four equations and two slack variables the matrix A has four rows and 10 columns with a_{ij} , $1 \leq i \leq 4$ and $1 \leq j \leq 10$, denoting the sum of the pre-factors of the set variables, in which the j-th Venn region is included, occurring in the i-th equation. Let the vectors for the Venn regions be in the following order:

- $v_1 = X_A \cap X_B \cap X_c \cap X_r \cap \mathcal{U} \cap I_1^{\neg} \cap I_2^{\neg}$
- $v_2 = X_A \cap X_B \cap X_c^{\neg} \cap X_r \cap \mathcal{U} \cap I_1^{\neg} \cap I_2^{\neg}$
- $v_3 = X_A \cap X_B \cap X_c \cap X_r \cap \mathcal{U} \cap I_1 \cap I_2$

- $v_4 = X_A \cap X_B \cap X_c \cap X_r \cap \mathcal{U} \cap I_1 \cap I_2$
- $v_5 = X_A \cap X_B \cap X_c \cap X_r \cap \mathcal{U} \cap I_1 \cap I_2$
- $v_6 = X_A \cap X_B \cap X_c \cap X_r \cap \mathcal{U} \cap I_1 \cap I_2$
- $v_7 = X_A \cap X_B \cap X_c \cap X_r \cap \mathcal{U} \cap I_1 \cap I_2$
- $v_8 = X_A^{\neg} \cap X_B^{\neg} \cap X_c^{\neg} \cap X_r \cap \mathcal{U} \cap I_1^{\neg} \cap I_2^{\neg}$

The last two vectors denote the slack variables

- $v_9 = X_A^{\neg} \cap X_B^{\neg} \cap X_c^{\neg} \cap X_r^{\neg} \cap \mathcal{U}^{\neg} \cap I_1 \cap I_2^{\neg}$
- $v_{10} = X_A^{\neg} \cap X_B^{\neg} \cap X_c^{\neg} \cap X_r^{\neg} \cap \mathcal{U}^{\neg} \cap I_1^{\neg} \cap I_2$

We create now the linear system of equation:

Note that $a_{2,1}$ and $a_{2,2}$ are 0 because the pre-factors of $|X_A|$ and $|X_B|$ in the second equation are 1 and -1 and the Venn regions v_1 and v_2 are included both in X_A and X_B . If $x_i = 0$, then the *i*-th Venn region is empty. The last two rows of A, which present the equations $|\mathcal{U} \cap X_r^{\neg}| = 0$ and $|\mathcal{U}^{\neg} \cap X_r| = 0$, are lines of zeros because we omit the Venn regions, in which $\mathcal{U} \cap X_r^{\neg}$ and $\mathcal{U}^{\neg} \cap X_r$ are included. However we do not loose information because the information is that those Venn regions must be empty.

Going back to the upper bound problem: The following result from [8] can be used to establish an upper bound for the solution of the *ILP* in NP:

Theorem 1 (Theorem 1 from [8]). Let $A \in \mathbb{Z}^m \times \mathbb{Z}^n$ be a matrix and $b \in \mathbb{Z}^m$ a vector. If $x \in \mathbb{N}^n$ is a solution of Ax = b, then there exists a solution x' such that all entries are integers between 0 and $n \cdot (m \cdot max_{i,j}\{|a_{ij}|, |b_i|\})^{2 \cdot m+1}$.

We take a look now in the proof of this theorem to understand how the solution is decreased. We distinguish between two cases. Let $M = m \cdot max_{i,j} \{|a_{ij}|\}^m$, $F = \{i|x_i > M\}$ and v_i be the *i*-th column of A

• If there exist integers α_i , for all $i \in F$, such that $\sum_{i \in F} \alpha_i \cdot v_i = 0$ and $\exists i : \alpha_i > 0$ then x' = x - d, $d_j = \alpha_j$ if $j \in M$ else $d_j = 0$, $1 \le j \le n$.

• Else: There must be a vector $h \in \{0, \pm 1, \pm 2, \dots \pm M\}^m$ such that $h^T v_i \ge 1, i \in F$. We premultiply A and b with h^T and show that x is already in the bound:

$$h^T A x = h^T b$$

Therefore we are able to set an upper bound a priori for the solutions the QFBAPA solver returns, which is important for the termination proof. In our example the upper bound for all x_i is $10 \cdot (4 \cdot max\{|1|, |-1|\})^{2 \cdot 4+1} = 2621440$, which means that we can discard any solution in which a Venn region has more than 2621440 elements.

3.3 The Tableau Algorithm

Finally we can present the tableau algorithm for an ABox in \mathcal{ALCSCC} . Before we handle the numerical arithmetic of \mathcal{ALCSCC} we want to decompose compound concepts first. That means we want to consider conjunctions and disjunctions first and then consider the transformation to a QFBAPA formula. Hence we divide the algorithm in two parts: a boolean part, where the decomposition of compound concepts takes place, and a numerical part, where a part of the ABox is transformed into a QFBAPA formula. In the second part we calculate an upper bound and let a solver return a possible solution within this bound, in case the ABox is satisfiable. The boolean part has a higher priority than the numerical part.

Definition 10 (Tableau for \mathcal{ALCSCC}). The completion rules for a \mathcal{ALCSCC} ABox \mathcal{A} in NNF are the following. Boolean part:

- \sqcap -rule: \mathcal{A} contains $x: C_1 \sqcap C_2$ but not both $x: C_1$ and $x: C_2$ $\rightarrow \mathcal{A} := \mathcal{A} \cup \{x: C_1, x: C_2\}$
- \sqcup -rule: \mathcal{A} contains $x:C_1\sqcup C_2$ but neither $x:C_1$ nor $x:C_2$ $\to \mathcal{A}:=\mathcal{A}\cup\{x:C_1\}$ or $\mathcal{A}:=\mathcal{A}\cup\{x:C_2\}$

Numerical part:

- successor-rule: \mathcal{A} contains for an individual name x at least one violated assertion of the form x: succ(c), this rule has not been applied for x yet and no boolean rules are applicable:
 - gather all assertions of the form x : succ(c) into a set S
 - transform S into a QFBAPA formula ϕ as in Section 3.1
 - calculate the upper bound as in Theorem 1

If the QFBAPA solver returns unsatisfiable, then $\mathcal{A} := \mathcal{A} \cup \{x : \bot\}$ If the QFBAPA solver returns satisfiable, then select one solution σ with in the upper bound. For each $e \in \sigma(\mathcal{U})$, we introduce a new individual name y_e and

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- if e \in X_C we set \mathcal{A} := \mathcal{A} \cup \{y_e : C\}

- if e \in X_{succ(c)} we set \mathcal{A} = \mathcal{A} \cup \{y_e : succ(c)\}

- if e \in X_r, r \in \mathbf{R}, we set \mathcal{A} := \mathcal{A} \cup \{(x, y_e) : r\}

- if e \notin X_C we set \mathcal{A} := \mathcal{A} \cup \{y_e : \neg C\}

- if e \notin X_{succ(c)} we set \mathcal{A} := \mathcal{A} \cup \{y_e : NNF(\neg succ(c))\}

- if e \notin X_r, r \in \mathbf{R}, we have \mathcal{A} := \mathcal{A} \cup \{(x, y_e) : \neg r\}
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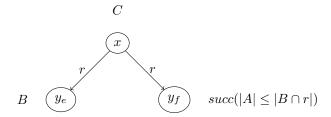
A complete ABox is an ABox to which no more rules of the tableau algorithm are applicable.

We present a possible run of this algorithm over the following ABox:

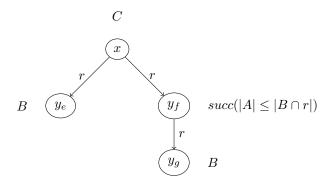
Example 2.

$$\mathcal{A} = \{x : succ(1 \le |succ(|A| \le |B \cap r|)|) \cap succ(|A| \le |B|) \cap C\}$$

We are able to apply to apply the □-rule and hence we apply them first and derive the ABox in Example 1. Then neither the \sqcap - nor the \sqcup -rule is applicable. Therefore we apply the *successor*-rule: We collect every *succ*-assertion regarding x to a set $\mathcal{S} := \{x : succ(1 \leq |succ(|A| \leq |B \cap r|)|), x : succ(|A| \leq |B|)\}$ and convert A to the QFBAPA formula in (3.1). The upper bound for that formula is 2621440 (see Section 3.2). If the formula have been unsatisfiable, we would add $x : \bot$ to our ABox. this would have led us to the end of the tableau algorithm because this "choice" is the only one possible since we do not have any disjunction. However since the formula is satisfiable we obtain a solution from the solver because of Assumption 1. We see that the formula is satisfiable with $X_{succ(|A| \leq |B \cap r|)} = \{f\}, X_A = \{\}, X_B = \{e\}$ and $X_r = \{e, f\}$. Since we have $\mathcal{U} = \{X_r\}$ every element must be in X_r i.e. every successor is a r-successor. The considered QFBAPA formula is capable of returning this solution because of Assumption 2. Obviously in this solution every Venn-region has less element than 2621440. We then introduce for e and f two individual names y_e and y_f and the assertion $y_e: X_B, (x, y_e): r, y_f: succ(|A| \leq |B \cap r|)$ and $(x, y_f): r$ to \mathcal{A} .



Then for y_f we have to apply the successor-rule because no boolean rule is applicable. Since $y_f: succ(|A| \leq |B \cap r|)$ is the only succ assertion we only have to add an r-successor of the concept B. We assume that the QFBAPA solver returns a solution $X_B = X_r = \{g\}$ and hereby introduce an individual name y_g and add $y_g: B$ and $(x, y_g): r$ to A.



In this procedure we do not add any assertions of individual names which are not freshly introduce. Hence if we applied all possible rules on the individual name x and we do not have a clash, then all assertions of x remains satisfied until the tableau algorithm ends. In the next chapter we provide a formal proof of the its correctness.

Chapter 4

Correctness

For the correctness proof of the tableau algorithm we have to show the following:

- For every input the tableau algorithm terminates.
- If no more rules are applicable on a clash-free ABox \mathcal{A} , then \mathcal{A} is satisfiable.
- If A is satisfiable, then the tableau algorithm terminates without a clash.

In all proofs we consider Assumption 1 and 2. First we prove that the algorithm always terminates.

4.1 Termination

We define a derived ABox as an ABox A_2 after a finite number of rule applications on an ABox A_1 . Each rule terminates:

- □- and □-rule: Obviously both rule terminates because we decompose finite compound concepts.
- successor-rule: Since ABoxes are finite we can only have a finite subset S of successor-assertions and therefore can always form a (finite) QFBAPA formula. By Assumption 1 the QFBAPA solver always terminates and we gain a finite solution. Therefore we always add a finite number of successor in this rule. Hence this rule application always terminates.

For the termination proof we map every ABox \mathcal{A} to an element $\Psi(\mathcal{A})$ of a set Q. Each $\Psi(\mathcal{A})$ consists of triples $\psi_{\mathcal{A}}(x)$ for each individual name x. Let \prec be an strict partial ordering, which is a irreflexive (if $a \prec b$ then $b \not\prec a$) and transitive (if $a \prec b$ and $b \prec c$ then $a \prec c$) relation (with a,b,c being comparable elements). If we show that \prec is well-founded, e.g. there is no infinite decreasing chain, and that for every ABox \mathcal{A}' , which is derivable from an ABox \mathcal{A} , we can only have $\Psi(\mathcal{A}') \prec \Psi(\mathcal{A})$ then the termination of the algorithm can be concluded.

Each triple in Q consists of a multiset of natural numbers and two natural

numbers. A multiset of natural numbers M is smaller than another multiset of natural numbers M' if we can obtain M from M' by replacing at least one number n of M' with a set of natural numbers, which are all smaller than n, or by deleting at least the number n. For example $M = \{2, 2, 2, 1, 5\}$ is smaller than $M' = \{2, 3, 5\}$ because the second entry $\{3\}$ of M' can be replaced by $\{2,2,1\}$. We say that the empty mutliset $\{\}$ is always smaller than any multiset of natural numbers. Since the multisets consist of natural numbers, which can be ordered by the strict partial order <, they can be ordered by \prec , too. A triple $T_1 = (x_1, x_2, x_3)$ is smaller than a triple $T_2 = (y_1, y_2, y_3)$ if T_1 is lexicographically smaller (from right to left) than T_2 which means that for the first $i \in \{1, 2, 3\}$ such that $x_i \neq y_i$ it holds that x_i is smaller than y_i . Again because we have triples of numbers they can be ordered by \prec , too. Therefore $\Psi(\mathcal{A}') \prec \Psi(\mathcal{A})$ if we can replace one triple $\psi_{\mathcal{A}}(x)$ in $\Psi(\mathcal{A})$ with at least one triple $\psi_{\mathcal{A}'}(x')$, such that $\psi_{\mathcal{A}}(x) \prec \psi_{\mathcal{A}'}(x')$ to obtain $\Psi(\mathcal{A}')$ or if we remove at least one triple $\psi_{\mathcal{A}}(x)$. Note that we assume earlier in Section 2.2 that each $C \sqcap D$ and $C \sqcup D$ in a cardinality term is replaced by $C \cap D$ and $C \cup D$ respectively. We describe now how the triples in Q looks like.

Definition 11. Let \mathcal{A} be a derived ABox. The multiset $\Psi(\mathcal{A})$ consists of triples. Each triple $\psi_{\mathcal{A}}(x)$ represent one individual name x:

- The first component $\psi_{\mathcal{A},1}(x)$ is the natural number $\max\{size(C)|x:C\in\mathcal{A}\}.$
- The second component $\psi_{\mathcal{A},2}(x)$ is a multiset which contains for each assertion $x:C\sqcap D\in\mathcal{A}$ for which the \sqcap -rule is applicable the natural number $size(C\sqcap D)$. Respectively for $x:C\sqcup D$.
- The third component $\psi_{A,3}(x)$ is the number 1 if the *successor*-rule is applicable, 0 otherwise.

For the ABox \mathcal{A} in Example 2 we have the following multiset:

$$\Psi(\mathcal{A}) = \{ \psi_{\mathcal{A}}(x) \} = \{ (7, \{7, 7\}, 0) \} \tag{4.1}$$

After the decomposing we got the ABox \mathcal{A}^1 , which is stated in Example 1.

$$\Psi(\mathcal{A}^1) = \{\psi_{\mathcal{A}^1}(x)\} = \{(7, \{\}, 2)\}$$
(4.2)

We can see that $\psi_{\mathcal{A}',2}(x) \prec \psi_{\mathcal{A},2}(x)$ because we do not have any conjunction anymore. Therefore he increment of the third entry does not matter. Hence $\psi_{\mathcal{A}'}(x) \prec \psi_{\mathcal{A}}(x)$ which means $\Psi(\mathcal{A}') \prec \Psi(\mathcal{A})$.

Then the successor-rule is applied and we add two new individual names y_e and y_f to obtain \mathcal{A}^2 , hence two new multisets have to be added.

$$\Psi(\mathcal{A}^2) = \{ \psi_{\mathcal{A}^2}(x), \psi_{\mathcal{A}^2}(y_e), \psi_{\mathcal{A}^2}(y_f) \} = \{ (7, \{\}, 0), (1, \{\}, 0), (3, \{\}, 1) \}$$
 (4.3)

We see that $\psi_{\mathcal{A}^2}(x)$, $\psi_{\mathcal{A}^2}(y_e)$ and $\psi_{\mathcal{A}^2}(y_f)$ are smaller than $\psi_{\mathcal{A}^1}(x)$ hence $\Psi(\mathcal{A}^2) \prec \Psi(\mathcal{A}^1)$.

We then apply the last successor-rule to y_f and gain

$$\Psi(\mathcal{A}^3) = \{ \psi_{\mathcal{A}^3}(x), \psi_{\mathcal{A}^3}(y_e), \psi_{\mathcal{A}^3}(y_f), \psi_{\mathcal{A}^3}(y_g) \} = \{ (7, \{\}, 0), (1, \{\}, 0), (3, \{\}, 0), (2, \{\}, 0) \}$$

$$(4.4)$$

The newly introduced triple $\psi_{\mathcal{A}^3}(y_g)$ is smaller then $\psi_{\mathcal{A}^2}(y_f)$, because $\psi_{\mathcal{A}^3,1}(y_g) < \psi_{\mathcal{A}^2,1}(y_f)$, and hence we have $\Psi(\mathcal{A}^3) \prec \Psi(\mathcal{A}^2) \prec \Psi(\mathcal{A}^1) \prec \Psi(\mathcal{A})$. We are now able to finally prove the termination of the algorithm.

Lemma 2. For any ABox $\mathcal{A} = \{x : C\}$ the tableau algorithm terminates

Proof. We show that if \mathcal{A}' is derivable from \mathcal{A} by a rule from Definition 3.3, then we have $\Psi(\mathcal{A}') \prec \Psi(\mathcal{A})$.

- \mathcal{A}' is obtained from \mathcal{A} by applying the \sqcap -rule on $x:C\sqcap D$: The first component remains unchanged because $size(C) \leq size(C\sqcap D)$ and $size(D) \leq size(C\sqcap D)$. We have $\psi_{\mathcal{A}',2}(x) \prec \psi_{\mathcal{A},2}(x)$ because the integer for $size(C\sqcap D)$ is removed (because we cannot apply this rule anymore after one application). In case C and/or D happens to be a disjunction or conjunction $\psi_{\mathcal{A}',2}(x)$ still becomes smaller because $size(C) < size(C) + size(D) + 1 = size(C\sqcap D)$ (respectively for size(D)). Hence $\psi_{\mathcal{A}'}(x) \prec \psi_{\mathcal{A}}(x)$. For any other individual name y, such that $y \neq x$, the triple $\psi_{\mathcal{A}}(y)$ remains unchanged.
- \mathcal{A}' is obtained from \mathcal{A} by applying the \sqcup -rule on $x:C\sqcap D$: similar to above
- \mathcal{A}' is obtained from \mathcal{A} by applying the successor-rule on x: succ(c): $\psi_{\mathcal{A},1}(x)$ remains unchanged because we do not add any assertion for x. We are able to apply this rule, because both \sqcap -rule and \sqcup -rule are not applicable on \mathcal{A} and we do not have applied this rule for x yet. Because we do not add assertions for x and do not decompose any disjunction or conjunction we know that $\psi_{\mathcal{A},2}(x)$ remains unchanged. We also know that $\psi_{\mathcal{A},3}(x)=1$ because we are able to apply the successor-rule on an assertion of x. Afterwards we have $\psi_{\mathcal{A}',3}(x)=0$. Therefore $\psi_{\mathcal{A}'}(x) \prec \psi_{\mathcal{A}}(x)$.

For every freshly introduced individual name y we have to add a triple $\psi_{\mathcal{A}'}(y)$ to $\Psi(\mathcal{A}')$. For each $y:C\in\mathcal{A}'$ we know that C must be part of a cardinality constraint c such that $x:succ(c)\in\mathcal{A}$ and therefore size(succ(c))>size(C). That means that $max\{size(C)|y:C\in\mathcal{A}'\}$ is always smaller then $max\{size(C)|x:C\in\mathcal{A}'\}$ by the definition of size(C). Therefore $\psi_{\mathcal{A}',1}(y)<\psi_{\mathcal{A}',1}(x)$ and hence $\psi_{\mathcal{A}'}(y)\prec\psi_{\mathcal{A}'}(x)$.

For any other individual name z, such that $z \neq x$ and z = y, the triple $\psi_{\mathcal{A}}(y)$ remains unchanged.

Hence in all three cases we can obtain $\Psi(\mathcal{A}')$ from $\Psi(\mathcal{A})$ by replacing $\psi_{\mathcal{A}}(x)$ with the smaller triple $\psi_{\mathcal{A}'}(x)$. For any newly introduced individual names we showed

that the new triples are always smaller than $\psi_{\mathcal{A}'}(x)$. Therefore $\Psi(\mathcal{A}') \prec \Psi(\mathcal{A})$. Because we work with natural numbers the ordering < over them is well-founded. Therefore we also know that \prec multisets over natural numbers is also well-founded [2](Theorem 2.5.5). Since the natural numbers and multisets of natural numbers can be ordered by a well-founded ordering, the triples after Definition 11, which are "lexicographical products of two terminating relation" [2](Theorem 2.4.2), can be ordered by a well-founded ordering as well. Therefore \prec over the multisets of these triples is well-founded, too [2](Theorem 2.5.5).

4.2 Soundness and Completeness

After we proved that the algorithm terminates, we continue with the correctness of the algorithm e.g. the algorithm terminates with a clash-free ABox iff the ABox is satisfiable.

We start with one direction of the *iff* statement.

Lemma 3 (Soundness). If the tableau algorithm is applied on an ABox $\mathcal{A} = \{x : C\}$ and terminates without a clash, then \mathcal{A} is satisfiable

Proof. Let \mathcal{A}' be the result after the algorithm terminated. From Lemma 2 we know that the tableau algorithm always terminates. Since we do not remove any assertion during the algorithm we have $\mathcal{A} \subseteq \mathcal{A}'$. Hence if an interpretation \mathcal{I} satisfies \mathcal{A}' then it also satisfies \mathcal{A} . Let $\mathcal{I}(\mathcal{A}')$ be the induced interpretation of \mathcal{A}' . We show that $\mathcal{I}(\mathcal{A}')$ indeed satisfies \mathcal{A}' by induction over concepts: For each concept name $C \in \mathbf{C}$ such that $x : C \in \mathcal{A}'$, we have $x^{\mathcal{I}(\mathcal{A}')} \in C^{\mathcal{I}(\mathcal{A}')}$ by the definition of induced interpretation. (induction base) We consider x : C where C is a compound concept (induction step):

- $C = \neg D$: Since \mathcal{A}' does not contain a clash, $x : C \in A$ implies $x : D \notin A$. D must be a concept name, because \mathcal{A}' is in NNF. Therefore by definition of induced interpretation and $x : D \notin A$ we have $x^{\mathcal{I}(\mathcal{A}')} \notin D^{\mathcal{I}(\mathcal{A}')}$ which implies $x^{\mathcal{I}(\mathcal{A}')} \in \Delta^{\mathcal{I}(\mathcal{A}')} \backslash D^{\mathcal{I}(\mathcal{A}')} = C^{\mathcal{I}(\mathcal{A}')}$.
- $C = D \sqcap E$: Since the algorithm terminated, the \sqcap -rule is not applicable anymore. That means that there is an individual name x, such that $\{x:D,x:E\}\subseteq \mathcal{A}'$. By the induction hypothesis we have $x^{\mathcal{I}(\mathcal{A}')}\in D^{\mathcal{I}(\mathcal{A}')}$ and $x^{\mathcal{I}(\mathcal{A}')}\in E^{\mathcal{I}(\mathcal{A}')}$. Therefore $x^{\mathcal{I}(\mathcal{A}')}\in D^{\mathcal{I}(\mathcal{A}')}\cap E^{\mathcal{I}(\mathcal{A}')}=C^{\mathcal{I}(\mathcal{A}')}$.
- $C = D \sqcup E$: Since the algorithm terminated, the \sqcup -rule is not applicable anymore. That means that there is an individual name x, such that $\{x : D, x : E\} \cap \mathcal{A}' \neq \emptyset$. By the induction hypothesis we have $x^{\mathcal{I}(\mathcal{A}')} \in D^{\mathcal{I}(\mathcal{A}')}$ or $x^{\mathcal{I}(\mathcal{A}')} \in E^{\mathcal{I}(\mathcal{A}')}$. Therefore $x^{\mathcal{I}(\mathcal{A}')} \in D^{\mathcal{I}(\mathcal{A}')} \cup E^{\mathcal{I}(\mathcal{A}')} = C^{\mathcal{I}(\mathcal{A}')}$.
- C = succ(c): Since \mathcal{A}' does not contain a clash, the QFBAPA solver must have returned a solution. If the solution is empty, then no individual names are needed to be introduced to satisfy x : C and we have $x^{\mathcal{I}(\mathcal{A}')} \in C^{\mathcal{I}(\mathcal{A}')}$. If the solution is not empty, then the induced interpretation is updated

by introducing a new element $y_e^{\mathcal{I}(\mathcal{A}')}$ for each $e \in \sigma(\mathcal{U})$ and hence also for each freshly introduced individual name y_e . For each $e \in X_C$ we have $y: C \in \mathcal{A}'$. By the induction hypothesis $y_e^{\mathcal{I}(\mathcal{A}')}$ must be in $C^{\mathcal{I}(\mathcal{A}')}$. For each $e \in X_r$ we have $(x,y): r \in \mathcal{A}'$. Since we also added (x,y): r to \mathcal{A}' , we must have $(x^{\mathcal{I}(\mathcal{A}')}, y^{\mathcal{I}(\mathcal{A}')}) \in r^{\mathcal{I}(\mathcal{A}')}$. Lastly for each $e \in X_{succ(d)}$ we have $y: succ(d) \in \mathcal{A}'$. Again by the induction hypothesis $y^{\mathcal{I}(\mathcal{A}')} \in succ(d)^{\mathcal{I}(\mathcal{A}')}$. Since the solution is correct, we know that $x^{\mathcal{I}(\mathcal{A}')} \in succ(c)^{\mathcal{I}(\mathcal{A}')}$.

Since we know that $\mathcal{I}(\mathcal{A}')$ satisfies \mathcal{A}' and that $\mathcal{A} \subseteq \mathcal{A}'$, $\mathcal{I}(\mathcal{A}')$ also satisfies \mathcal{A} .

We now proof that we can return any ABox such that we can induce every possible model within the pre-computed upper bound.

Lemma 4 (Completeness). If $\mathcal{A} := \{x : C\}$ is satisfiable then the tableau algorithm terminates without a clash.

Proof. By Lemma 1 we know that the algorithm always terminates. It remains to show that the algorithm terminates with a clash-free ABox. Since \mathcal{A} is satisfiable it does not contain a clash. Let $\mathcal{I} = (\Delta^{\mathcal{I}}, \mathcal{I})$ be an interpretation which satisfies \mathcal{A} . We show that if \mathcal{A}_i does not contain a clash and \mathcal{I} satisfies \mathcal{A}_i , then \mathcal{A}_{i+1} can be obtained from \mathcal{A}_i by applying a rule while maintaining clash-freeness and satisfiability by \mathcal{I} .

We already stated that \mathcal{I} satisfies the clash-free $\mathcal{A} =: \mathcal{A}_0$ (induction base). Let \mathcal{A}_i be a clash-free ABox which is satisfied by \mathcal{I} (induction hypothesis). We distinguish the cases based on the rules we apply on \mathcal{A}_i to obtain \mathcal{A}_{i+1} (induction step):

- we apply the \sqcap -rule on $x: C \sqcap D$: The interpretation \mathcal{I} satisfies $\mathcal{A}_{i+1} = \mathcal{A}_i \cup \{x: C, x: D\}$ because by the hypothesis \mathcal{I} already satisfies \mathcal{A}_i and hence also $x: C \sqcap D$. That means that $x^{\mathcal{I}} \in (C \sqcap D)^{\mathcal{I}}$ and therefore $\{x, C, x: D\} \cup \mathcal{A}_i$ is satisfied by \mathcal{I}
- we apply the \sqcup -rule on $x: C \sqcup D$: We have to show that either $\mathcal{A}_{i+1} = \mathcal{A}_i \cup \{x: C\}$ or $\mathcal{A}_{i+1} = \mathcal{A}_i \cup \{x: D\}$ is satisfied by \mathcal{I} . Again by the induction hypothesis \mathcal{A}_i is satisfied by \mathcal{I} and hence $x^{\mathcal{I}} = (C \sqcup D)^{\mathcal{I}}$. So either $x^{\mathcal{I}} \in C^{\mathcal{I}}$ and hence we choose $\mathcal{A}_{i+1} = \mathcal{A}_i \cup \{x: C\}$ or $x^{\mathcal{I}} \in D^{\mathcal{I}}$ and hence we choose $\mathcal{A}_{i+1} = \mathcal{A}_i \cup \{x: D\}$. In both cases \mathcal{I} satisfies \mathcal{A}_{i+1} .
- we apply the succ-rule on x: succ(c): We have to show that by this step we are able to add successors such that \mathcal{I} satisfies \mathcal{A}_{i+1} . In this step, we gather first all succ-assertions together in a set \mathcal{S} , formulate a QFBAPA formula $\phi(x)$ and let a solver return us all possible solutions within an upper bound. Because \mathcal{A}_i is satisfiable, \mathcal{S} is also satisfiable (subset of \mathcal{A}_i). Hence there have to be solutions which can be returned by the solver. We need to show that the solver is capable of returning a solution within our upper bound, such that \mathcal{A}_{i+1} is satisfied by \mathcal{I} . In case $x^{\mathcal{I}}$ has no successors, the empty solution must be a valid solution, which can be

returned from the solver. If \mathcal{I} is finite and the number of x's successors within each Venn region is within our upper bound, then we can create a solution σ induced by \mathcal{I} , which can be returned by our solver. In any other case we have to show that we can create a (finite) solution from \mathcal{I} , which the solver is able to return. We know that $x^{\mathcal{I}}$ must have a finite number of successors in \mathcal{I} . Therefore we can create a solution σ based on that: Let σ be an empty solution. For each $e \in \bigcup_{r \in \mathbf{R}} r^{\mathcal{I}}(x)$ we add e to $\sigma(\mathcal{U})$:

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- for each (x^{\mathcal{I}}, e) \in r^{\mathcal{I}} add e to \sigma(X_r)
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- for each $e \in C^{\mathcal{I}}$ add e to $\sigma(X_C)$
- for each $e \in succ(c)^{\mathcal{I}}$ add e to $\sigma(X_c)$

It is clear that if the solver returns this solution, then \mathcal{I} satisfies \mathcal{A}_{i+1} . If each Venn region of this solution has more elements than the calculated upper bound, we can reduce the number of successors by the following steps [8]: Convert the QFBAPA formula to a system of linear equations An = b like in Section 3.2. We know there has to be a solution, because \mathcal{S} is satisfiable. Let n be a solution to this system such that $n_k = |\{e|e \in \sigma(X_1^i) \cap \cdots \cap \sigma(X_m^i)\}|$, where $X_1^i \cap \cdots \cap X_m^i$ is the k-th Venn region. Then we can reduce n to n' like shown in Section 3.2. With the help of n' we create the new solution σ' by adding n'_k successors in the k-th Venn region. It holds that (\dagger) :

```
-\sigma^*(\mathcal{U}) \subseteq \sigma(\mathcal{U})
-\text{ for each } e \in \sigma^*(\mathcal{U}) \colon e \in \sigma^*(X_v) \text{ iff } e \in \sigma(X_m)
with m \in \mathbf{C} \cup \mathbf{R} \cup \{succ(c) | x : succ(c) \in \mathcal{A}_i\}
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The reason is the fact that we decrease the number of successors in specific Venn-regions to obtain n'.

The algorithm then creates individual names according to the solution σ' , which leads to the satisfaction of all succ-assertions of x. For each element $e \in \sigma'(\mathcal{U})$ we know that there is an individual name y_e such that:

$$- y_e : C \in \mathcal{A}_{i+1} \text{ iff } e \in \sigma'(X_C), C \in \mathbf{C}$$

$$- y_e : succ(c) \in \mathcal{A}_{i+1} \text{ iff } e \in \sigma'(X_{succ(c)})$$

$$- (x, y_e) : r \in \mathcal{A}_{i+1} \text{ iff } e \in \sigma'(X_r)$$

Because of the fact in (†) we can conclude

$$- y_e : C \in \mathcal{A}_{i+1} \text{ iff } e \in \sigma(X_C), C \in \mathbf{C}$$
$$- y_e : succ(c) \in \mathcal{A}_{i+1} \text{ iff } e \in \sigma(X_{succ(c)})$$
$$- (x, y_e) : r \in \mathcal{A}_{i+1} \text{ iff } e \in \sigma(X_r)$$

Since σ is induced by \mathcal{I} :

$$-y_e: C \in \mathcal{A}_{i+1} \text{ iff } e \in C^{\mathcal{I}}, C \in \mathbf{C}$$

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$$- y_e : succ(c) \in \mathcal{A}_{i+1} \text{ iff } e \in succ(c)^{\mathcal{I}}$$
$$- (x, y_e) : r \in \mathcal{A}_{i+1} \text{ iff } (x^{\mathcal{I}}, e) \in r^{\mathcal{I}}$$

Hence we can extend \mathcal{I} by $y_e^{\mathcal{I}} = e$ which satisfies \mathcal{A}_{i+1} .

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Chapter 5

Conclusion

The description logic \mathcal{ALCSCC} extends the well-known description logic \mathcal{ALCQ} with set constraints and cardinality constraints over role successors which are hard to deal with when checking satisfiability over \mathcal{ALCSCC} . We present a tableau algorithm which uses a QFBAPA solver to deal with the successors. It is shown that checking satisfiability for this DL is in PSpace, however the tableau algorithm runs in 2ExpSpace: We know that in each successor-rule application we can add in worse case exponential many successors as shown in Section 3.2. Each of the newly added successors is also capable of obtaining exponential many successors. The advantage of this approach is that we do not only return the statement about the satisfiability but also a satisfied interpretation, a model, for the concept.

For future works one can extend the algorithm for \mathcal{ALCSCC} concepts w.r.t. a TBox. In [1] it is stated that the satisfiability problem w.r.t. a TBox is in ExpTime. One approach can be to add all information we can concluded from the TBox first i.e. if we have $C \sqsubseteq D$ (says that every individual name in C is also in D) and x:C then x:D has to be added to the ABox, too. We have do the same for every freshly introduce individual name, too. One can also research for a tableau algorithm which does not use a QFBAPA solver. For that introducing blocking technique is most likely required because like in for \mathcal{ALCQ} and the \mathcal{SI} families endless loops of adding and merging (or replacing) individual names are possible. Another interesting area to do research on is the pre-computed upper bound. In this work the bound is exponentially large which is the reason for the ExpSpace complexity. If there exists a smaller upper bound one can run this algorithm in a smaller complexity.

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