KNOWLEDGE EXTRACTION IN AGRICULTURE USING MACHINE LEARNING ALGORITHMS

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of

Master of Technology in Civil Engineering with Specialization in "Water Resources and Environmental Engineering"

by

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DEPARTMENT OF CIVIL ENGINEERING INDIAN INSTITUTE OF SCIENCE, BANGALORE JUNE 2018

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DECLARATION

I certify that

- a. the work contained in this report is original and has been done by me under the guidance of my supervisor.
- b. the work has not been submitted to any other Institute for any degree or diploma.
- c. I have followed the guidelines provided by the Institute in preparing the report.
- d. I have conformed to the norms and guidelines given in the Ethical Code of Conduct of the Institute.
- e. Whenever I have used materials (data, theoretical analysis, figures, and text) from other sources, I have given due credit to them by citing them in the text of the report and giving their details in the references. Further, I have taken permission from the copyright owners of the sources, whenever necessary.
- f. I hereby declare that I am the sole author of this thesis. I authorize Indian Institute of Science to lend this thesis to other institutions or individuals for the purpose of scholarly research.

CERTIFICATE

This	is	to	certify	that	the	Disse	rtation	Report	entitled	l, "KN	OWI	LEDGE
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for the	e av	varc	d of the	degre	e of	Master	of Te	chnology	in Civil	Engin	eerin	g with
Specia	aliz	atio	n in "	Water	Reso	ources	and E	Environm	ental En	gineeri	ng"	of the
Institu	ite											

Supervisor
Date:

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Chapter 1

Introduction

Machine Learning algorithms are being widely used nowadays in all fields of science wherever huge amount of data is generated and agriculture is also not an exception for this. Farmers in many parts of India are largely dependent on timely rainfall for harvest and subsequent profits. Uncertainty surrounding this phenomenon has also haunted them since the beginning of civilization. Over time however, this uncertainty had reduced significantly as farmers back in the day could almost accurately plant crops based on previous experience with weather conditions. This wisdom has been passed on from one generation of farmers to the other. Gradual onset of global warming and climate changes over the last century has slowly-yet steadily put this wisdom out of use. As for rain-fed farmers preparing for agriculture, soil-water equation is fragile and any delay in rainfall could easily destroy the harvest. When age old systems fail, look to the future.

One of the fastest growing areas under the discipline of "artificial intelligence" is machine learning. And this technology is being deployed across modern agriculture to create solutions with greater accuracy and at unprecedented scale. Of the millions of combinations, advanced software greatly narrows the search. Machine learning can be used draw conclusions from various sets of raw data. Researchers in modern agriculture are testing their theories at greater scale and helping make more accurate, real-time predictions. Modern agriculture has the potential to discover even more ways to conserve water, use nutrients and energy more efficiently, and adapt to climate change. With the advent of technology, numerous advancements have taken place so that now we are in a place where we can measure field soil moisture using Remote Sensing satellites. The main goal in this study is to derive some meaningful relation from the variation between relative soil moisture obtained from the satellite data and field soil moisture obtained from 'Berambadi' Region.

Chapter 2

Literature Review

Though we can rely on moisture data given by satellite to a certain extent, we cannot rely on it completely as it is affected by many factors and it may not give the actual soil moisture. H. McNairna,*, C. Duguayb, B. Briscoc, T.J. Pultza examined the effect of soil and crop residue characteristics on polarimetric radar response. This study examines the sensitivity of linear polarizations and polarimetric parameters to conditions present on agricultural fields during the period of preplanting and postharvest. The co-polarizations signature plots are also discussed. Results indicate that the dominant scattering mechanism from these fields varies depending on the type and amount of residue cover, and whether the crop had been harvested. Radar parameters most sensitive to volume and multiple scattering perform best at characterizing these surface conditions. The scattering mechanisms associated with standing senesced vegetation, no-till fields, and tilled fields varied. Double-bounce, multiple, and volume scattering were all present in standing vegetation, while for no-till fields multiple scattering dominated. The pedestal height was also unique for each of these classes, with larger pedestals associated with standing crops and no-till fields. This confirms the sensitivity of pedestal height to multiple and volume scattering.

Jun Wen, Zhongbo Su examined that the radar backscattering coefficient is mainly determined by surface soil moisture, vegetation and land surface roughness under a given configuration of the satellite sensor. It is observed that the temporal variations of the three variables are different, the variation of vegetation and roughness are at the longer temporal scales corresponding to climate and cultivation practices, while soil moisture varies at a shorter temporal scale in response to weather forcing. Relative soil moisture is a function of field soil moisture and saturation capacity of the soil. The results show that the estimated relative soil moisture corresponds closely to vegetation and land surface roughness.

B.J. Choudury, T.J. Schmugge, R.W. Newton and A.Chang studied the effect of surface roughness on the brightness temperature of a moist terrain through the modification of Fresnel reflection coefficient and using the radiative transfer equation. The modification involves introduction of a single parameter to characterize the roughness. It is shown that this parameter depends on both

the surface height variance and the horizontal scale of the roughness. Model calculations are in good quantitative agreement with the observed dependence of the brightness temperature on the moisture content in the surface layer.

- J.R. Wang, P.E. O'Neill, T.J. Jackson, E.T. Engman conducted experiment on remote sensing of soil moisture content was conducted over bare fields with microwave radiometers at the frequencies of 1.4 GHz, 5 GHz, and 10.7 GHz. Three bare fields with different surface roughnesses and soil textures were prepared for the experiment. Ground truth acquisition of soil temperatures and moisture contents for 5 layers down to the depths of 15 cm was made concurrently with radiometric measurements. The experimental results show that the effect of surface roughness is to increase the soils' brightness temperature and to reduce the slope of regression between brightness temperature and moisture content. The slopes of regression for soils with different textures are found to be comparable, and the effect of soil texture is reflected in the difference of regression line intercepts at brightness temperature axis.
- L. Breiman Bagging predictors is a method for generating multiple versions of a predictor and using these to get an aggregated predictor. The aggregation averages over the versions when predicting a numerical outcome and does a plurality vote when predicting a class. The multiple versions are formed by making bootstrap replicates of the learning set and using these as new learning sets. Tests on real and simulated data sets using classification and regression trees and subset selection in linear regression show that bagging can give substantial gains in accuracy. The vital element is the instability of the prediction method. If perturbing the learning set can cause significant changes in the predictor constructed, then bagging can improve accuracy.

Thus, it is seen that the relative soil moisture determined by the satellites cannot be blindly correlated with the field soil moisture measured manually even though the saturation capacity of the soil is known. The main factors that lie in between the correlation of relative soil moisture and field soil moisture are the type of crop, crop coverage or crop growth basically how much the crop has covered the field at a given instance and also to the soil class based on texture and type of soil to which it belongs.

Chapter 3

Approach and Methodology

The field soil moisture data is obtained from 112 sites, from each site manually. These are the sites where the surface soil moisture data is available for year 2016 and 2017.



Image Showing 112 sites where soil moisture is measured routinely

Out of the 112 sites, 92 sites fall on the Berambadi region of Gundlupet Taluk and 20 sites fall in Vaddagare region of Koratagere Taluk.

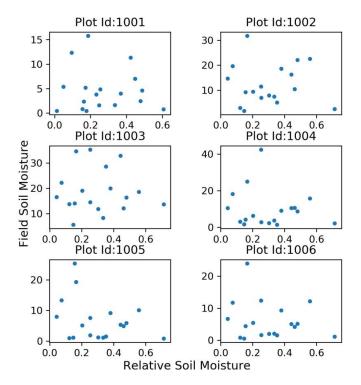
Each site is given a Plot ID for analysis purpose. The GPS coordinates of all the 112 sites are listed in the table below:

Plot_Id	Latitude	Longitude	Plot_Id	Latitude	Longitude
1001	11.79922	76.668	1057	11.78055	76.55742
1002	11.79856	76.65578	1058	11.7807	76.55765
1003	11.79863	76.65544	1059	11.78117	76.55781
1004	11.79923	76.65604	1060	11.78136	76.55815
1005	11.79984	76.656	1061	11.78165	76.56029
1006	11.79986	76.65602	1062	11.78109	76.56032
1007	11.79728	76.65138	1063	11.77904	76.55967
1008	11.79809	76.65148	1064	11.77926	76.55979
1009	11.79844	76.65142	1065	11.7787	76.56049
1010	11.79927	76.65085	1066	11.77832	76.56054
1011	11.787	76.63294	1067	11.77797	76.56057
1012	11.78756	76.63284	1068	11.77771	76.5606
1013	11.78752	76.6326	1069	11.77713	76.56074
1014	11.7875	76.63216	1070	11.74682	76.59141
1015	11.78108	76.62736	1071	11.74689	76.5917

1016	11.77725	76.62684	1072	11.74646	76.501.60
		70.02007	1072	11./4040	76.59168
1017	11.7624	76.62413	1073	11.74611	76.59158
1018	11.76174	76.62406	1074	11.74571	76.59169
1019	11.76173	76.62377	1075	11.74298	76.59072
1020	11.76173	76.62354	1076	11.74327	76.59087
1021	11.75631	76.60838	1077	11.74382	76.59097
1022	11.75692	76.60808	1078	11.74978	76.58994
1023	11.75693	76.60837	1079	11.74981	76.59027
1024	11.75613	76.59836	1080	11.74996	76.5918
1025	11.76326	76.59971	1081	11.74967	76.59184
1026	11.76336	76.59979	1082	11.72205	76.77913
1027	11.75485	76.58993	1083	11.77626	76.56072
1028	11.75639	76.58618	1084	11.73057	76.78211
1029	11.75696	76.58621	1085	11.73088	76.78255
1030	11.75735	76.58667	1086	11.73107	76.78261
1031	11.76143	76.58652	1087	11.73156	76.78283
1032	11.76101	76.58652	1088	11.7305	76.78417
1033	11.76069	76.58655	1089	11.73321	76.79298
1034	11.76132	76.58789	1090	11.73319	76.79266
1035	11.76166	76.58801	1091	11.73318	76.7923
1036	11.76118	76.58812	1092	11.73217	76.78549
1037	11.7607	76.58531	1093	11.73271	76.78565
1038	11.76074	76.58531	1094	11.73299	76.78532
1039	11.76127	76.58556	1095	11.73435	76.78511
1040	11.76129	76.5858	1096	11.73442	76.78544
1041	11.76101	76.58595	1097	11.73601	76.78595
1042	11.76172	76.57917	1098	11.73629	76.78589
1043	11.76088	76.57921	1099	11.73549	76.78456
1044	11.76086	76.57944	1100	11.7357	76.78471
1045	11.76213	76.57811	1101	11.73586	76.78471
1046	11.76885	76.56762	1102	11.57372	76.78369
1047	11.769	76.56771	1103	11.78131	76.62754
1048	11.77918	76.58606	1104	11.76464	76.62472
1049	11.77825	76.58636	1105	11.76534	76.62481
1050	11.77766	76.58646	1106	11.76518	76.62397
1051	11.77808	76.58685	1107	11.76144	76.62363
1052	11.77931	76.60627	1108	11.75825	76.5869
1053	11.77863	76.60614	1109	11.758	76.58597
1054	11.77993	76.55673	1110	11.76232	76.57731
1055	11.7799	76.55658	1111	11.77346	76.56834
1056	11.78011	76.55695	1112	11.77403	76.56823

While reviewing the literature, it is noted that relative soil moisture is a function of Field Soil Moisture (FSM) and saturation capacity of the soil. Hence, at a particular site, the relative soil moisture should have given a proper correlation with field soil moisture, but it has not.

Here, 'Relative Soil Moisture' (RSM) refers to the soil moisture data obtained through satellite which is provided by VATI project of 'Aapah innovations'. 'Field Soil Moisture' (FSM) refers to soil moisture measured from the site manually.



Plot showing Field Soil Moisture vs Relative Soil Moisture (for 6 sites)

But, when scatter plots of 'relative soil moisture' vs 'field soil moisture' are made, it does not show a good correlation. And, this leads to further thought why such variation is shown.

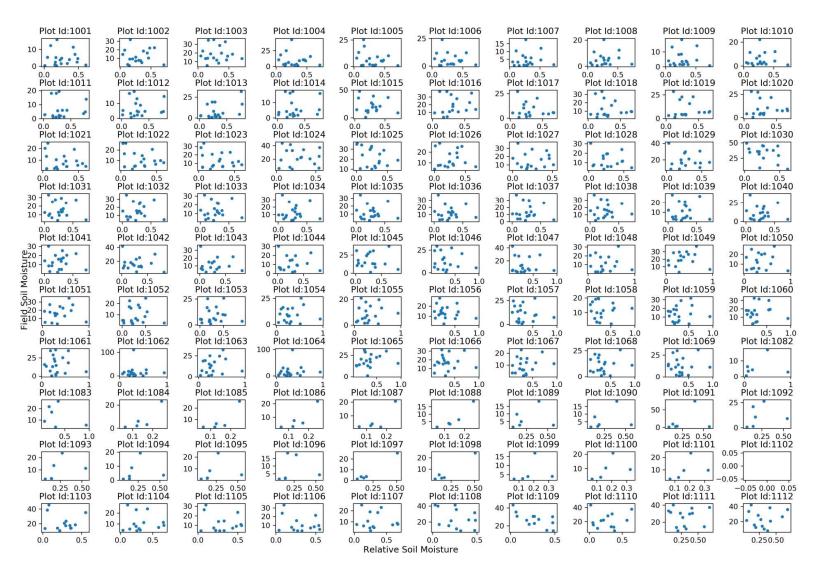
Plot_ID	Correlation	Plot_ID	Correlation	Plot_ID	Correlation	Plot_ID	Correlation
1001	-0.066	1029	-0.099	1057	-0.092	1085	0.850
1002	-0.004	1030	-0.468	1058	-0.016	1086	0.881
1003	-0.030	1031	-0.088	1059	0.135	1087	0.816
1004	-0.127	1032	0.009	1060	0.101	1088	0.936

1005	-0.308	1033	0.010	1061	-0.057	1089	0.223
1006	-0.169	1034	-0.032	1062	-0.007	1090	0.300
1007	0.038	1035	-0.071	1063	0.176	1091	0.342
1008	0.059	1036	-0.075	1064	0.082	1092	0.194
1009	-0.016	1037	-0.084	1065	0.197	1093	0.438
1010	0.016	1038	-0.036	1066	0.088	1094	0.190
1011	0.088	1039	0.014	1067	0.238	1095	0.232
1012	0.082	1040	-0.058	1068	0.110	1096	0.092
1013	0.456	1041	-0.023	1069	0.030	1097	0.987
1014	0.103	1042	-0.178	1070		1098	0.973
1015	-0.142	1043	-0.104	1071		1099	0.262
1016	0.145	1044	-0.042	1072		1100	0.479
1017	-0.174	1045	-0.058	1073		1101	0.465
1018	-0.131	1046	-0.156	1074		1102	
1019	-0.089	1047	-0.115	1075		1103	-0.138
1020	-0.063	1048	0.028	1076		1104	-0.040
1021	-0.182	1049	0.090	1077		1105	-0.190
1022	-0.209	1050	0.043	1078		1106	-0.282
1023	-0.239	1051	0.144	1079		1107	-0.093
1024	-0.058	1052	0.083	1080		1108	-0.355
1025	-0.357	1053	0.072	1081		1109	-0.700
1026	-0.009	1054	0.109	1082	0.217	1110	0.068
1027	-0.023	1055	0.131	1083	-0.338	1111	0.007
1028	-0.172	1056	-0.217	1084	0.860	1112	0.096

Table showing correlation between 'relative soil moisture' and 'field soil moisture' for each site

From the correlation table, it is seen that most of the sites have very poor correlation, mostly having R^2 values of less than 0.1. Thus, to bring a good result, just comparing between these two is not sufficient, but it is required to bring other parameters which cause this problem.

It is seen in the literature review that relative soil moisture measured using satellite gets affected by various factors such as the type of crop, crop coverage or crop growth basically how much the crop has covered the field at a given instance and also to the soil class based on texture and type of soil to which it belongs.



Field Soil Moisture vs Relative Soil Moisture Scatter Plot (for all 112 sites)

The compiled data used for understanding the relation between relative soil moisture data obtained from satellite and field soil moisture consists of crop type and soil class. The data needed for analysis is defined and organized in a manner to feed into machine learning algorithms.

The software utilized for extracting and organizing data are (i) Quantum GIS, commonly called as QGIS – an open source software, extended its capability with "PyQGIS", (ii) Geospatial Data Abstraction Library, in short "GDAL", for making pixel level calculations on the satellite data obtained and the programming language used is Python.

Crop Type:

The type of crop that is grown in farmer's field is available along with date. Frequency of data available is approximately twice a month for year 2016 and 2017. Total number of types of crop available from all 112 sites is 51.

No	Type	No	Туре	No	Type
1	No_Crop	18	Sunflower	35	Potato
2	Maize	19	Sugarcane	36	Maize+CountryBean
3	Chickpea	20	Garlic	37	CountryBean+Maize
4	Mariegold	21	Beetroot+Banana	38	Turmeric+Onion
5	Ragi	22	Banana	39	Pumkin
6	Groundnut+Marieg old	23	Watermelon+Banana+PolythynPla stic	40	HorseGram+CountryB
7	Cotton	24	Banana+Watermelon	41	CountryBean+Sunflow er
8	FieldBean	25	Ginger	42	Onion+Turmeric+Bana na
9	CountryBean	26	Weed	43	Watermelon
10	Sunflower+Maize	27	Cabbage	44	Banana+Beetroot
11	Sorghum	28	Garlic+Cabbage	45	Sunflower+Sorghum
12	HorseGram	29	Beetroot	46	Maize+Beetroot
13	Onion+Turmeric	30	Onion	47	Onion+Beans
14	Turmeric	31	Maize+Mariegold	48	Chilly+Beans
15	Groundnut	32	Toor+Chilly	49	Sorghum+Pulses
16	Beans	33	Chilly+Turmeric	50	Onion+Toor
17	Tomato	34	Chilly	51	Toor

Since the number of classes are way too many, it is decided to reduce the number of soil classes based on plant leaf coverage area and its height of growth. Keeping this in mind, the plants are divided into 9 classes.

	Less coverage	Medium coverage	Dense coverage
Short	1	2	3
Medium	4	5	6
Tall	7	8	9

Crop_Type	Crop Class	Crop_Type	Crop Class	Crop_Type	Crop Class
No_Crop	1	Onion	2	CountryBean	6
Weed	1	Toor+Chilly	2	HorseGram+CountryBean	6
Pumkin	1	Chilly+Turmeric	2	CountryBean+Sunflower	6
Watermelon	1	Chilly	2	Sunflower+Maize	7
Ragi	2	Potato	2	Sorghum	7
Cotton	2	Turmeric+Onion	2	Sunflower	7
FieldBean	2	Onion+Beans	2	Maize+CountryBean	8
HorseGram	2	Chilly+Beans	2	CountryBean+Maize	8
Onion+Tur meric	2	Onion+Toor	2	Sunflower+Sorghum	8
Turmeric	2	Toor	2	Sorghum+Pulses	8
Groundnut	2	Beetroot	3	Sugarcane	9
Beans	2	Mariegold	4	Beetroot+Banana	9
Tomato	2	Maize+Mariegold	4	Banana	9
Garlic	2	Maize	5	Watermelon+Banana+Polythy nPlastic	9
Ginger	2	Groundnut+Marie gold	5	Banana+Watermelon	9
Cabbage	2	Maize+Beetroot	5	Onion+Turmeric+Banana	9
Garlic+Cab bage	2	Chickpea	6	Banana+Beetroot	9

Relative Soil Moisture:

The relative soil moisture is obtained with respect to GPS coordinates of sites from the moisture data files which are present in 'GeoTiff' format. The tool used for extracting relative soil moisture from 'GeoTiff' files is 'Geospatial Data Abstraction Library' available in the PyQGIS console. The code snippet used is as follows:

Code Snippet

import pickle import numpy as np import pandas as pd import os, os.path from datetime import datetime, timedelta

```
from pandas import ExcelWriter
from openpyxl import load workbook
from osgeo import gdal, osr
from qgis.core import QgsRasterLayer
basepath = 'D:\MASTERS-PROJECT\\'
subBasepath = basepath + 'MTECH-PROJ-Prob 1 VATI vs Field Moisture\\'
in file = subBasepath + 'Soil Moisture Berambadi 1617 CropAge out.xlsx'
out file = subBasepath + 'Soil Moisture Berambadi 1617 CropAge VATI out.xlsx'
sm folder = 'D:\MASTERS-PROJECT\sm VATI\\'
SM ML df = pd.read excel(in file, sheet name='SM ML values')
SM ML Dates df = SM ML df[['Date']]
SM ML Dates df.drop duplicates(subset=['Date'], keep='first', inplace=True)
SM ML Dates df.reset index(drop=True, inplace=True)
# print (SM_ML_Dates_df)
sm VATI LatLon DF = SM ML df[['Plot Id', 'Latitude', 'Longitude']]
sm VATI LatLon DF.drop duplicates(subset=['Plot Id'], keep='first', inplace=True)
sm_VATI_LatLon_DF.reset_index(drop=True, inplace=True)
for index, SM ML Dates df row in SM ML Dates df.iterrows():
  date_dfval = SM_ML_Dates_df_row['Date']
  date = str(date dfval)
  date = datetime.strptime(date, '%Y-%m-%d %H:%M:%S')
  date = date.strftime('%Y%m%d')
  file fullPath = sm folder + date + '.tif'
  if(os.path.isfile(file_fullPath)):
    # print (date)
    raster ds = gdal.Open(file fullPath)
    rlayer = QgsRasterLayer(file fullPath)
    geoTrans = raster ds.GetGeoTransform()
    ulX = geoTrans[0]
    ulY = geoTrans[3]
    pxUnitX = geoTrans[1]
    pxUnitY = geoTrans[5] # this value is -ve
    prj = raster ds.GetProjectionRef()
    srs = osr.SpatialReference(wkt=prj)
    EPSG num = srs.GetAttrValue('authority', 1)
    crsSrc = QgsCoordinateReferenceSystem(4326)
                                                    # WGS 84
    crsDest = QgsCoordinateReferenceSystem(int(EPSG_num)) # WGS 84 / UTM zone 43N
    xform = QgsCoordinateTransform(crsSrc, crsDest)
```

```
sm VATI nparray = np.array([])
    for index, sm VATI LatLon DF row in sm VATI LatLon DF.iterrows():
      pt gps = QgsPoint(float(sm VATI LatLon DF row['Longitude']),
float(sm VATI LatLon DF row['Latitude']))
      pt meter = xform.transform(pt gps)
      # print (pt meter)
      sm = rlayer.dataProvider().identify(pt meter, QgsRaster.IdentifyFormatValue)
      sm val = sm.results()[1]
      # print (sm val)
      sm_VATI_nparray = np.append(sm_VATI_nparray, sm_val)
    sm_VATI_LatLon_DF['sm_VATI'] = sm_VATI_nparray
    # print (sm VATI LatLon DF.head())
    for index, sm VATI LatLon DF row in sm VATI LatLon DF.iterrows():
      Plot Id val = sm VATI LatLon DF row['Plot Id']
      SM ML df.loc[(SM ML df]'Plot Id'] == Plot Id val) & (SM ML df]'Date'] == date dfval),
'sm VATI'] = sm VATI LatLon DF row['sm VATI']
writer = ExcelWriter(out file)
SM ML df.to excel(writer,'SM ML values')
writer.save()
print ("done totally")
```

Maximum relative soil moisture:

As saturation capacity is a property of soil at a site, maximum relative soil moisture can be defined as one property of site where the value of relative soil moisture in any time does not exceed the maximum relative soil moisture. Code Snippet used is as follows:

Code Snippet

```
import numpy as np
import pandas as pd
import os
from datetime import datetime, timedelta
from osgeo import gdal, osr
from qgis.core import QgsRasterLayer
from pandas import ExcelWriter

basepath = 'D:\MASTERS-PROJECT\\'
subBasepath = basepath + 'MTECH-PROJ-Prob_1_VATI_vs_Field_Moisture\\'
in_file = subBasepath + 'Soil_Moisture_Berambadi_1617_CropAge_VATI_out.xlsx'
out_file = subBasepath + 'Soil_Moisture_Berambadi_1617_CropAge_VATI_withMinMaxRSM_out.xlsx'
sm_folder = 'D:\MASTERS-PROJECT\sm_VATI\\'
```

```
SM ML df = pd.read excel(in file, sheet name='SM ML values')
RSM minmax DF = SM ML df[['Plot Id', 'Latitude', 'Longitude']]
RSM minmax DF.drop duplicates(subset=['Plot Id'], keep='first', inplace=True)
RSM minmax DF.reset index(drop=True, inplace=True)
# print (RSM max DF.shape[0])
rsm Max npArray = np.zeros(RSM minmax DF.shape[0])
rsm Min npArray = np.zeros(RSM minmax DF.shape[0])
folder = os.listdir(sm folder)
fldr len = len(folder)
for ij, each file in enumerate(folder):
  if (ij \% 30 ==0):
    print (ij, "completed")
  if '.tif' in each file and '.xml' not in each file:
    file fullPath = sm folder + each file
    # print (file fullPath)
    for index, row in RSM minmax DF.iterrows():
       # print (index)
       rlayer_rsm = QgsRasterLayer(file_fullPath)
       rsm_ds = gdal.Open(file fullPath)
       prj = rsm_ds.GetProjectionRef()
       srs = osr.SpatialReference(wkt=prj)
       EPSG_num = srs.GetAttrValue('authority', 1)
       crsSrc = QgsCoordinateReferenceSystem(4326)
                                                       # WGS 84
       crsDest = QgsCoordinateReferenceSystem(int(EPSG_num)) # WGS 84 / UTM zone 43N
       xform = QgsCoordinateTransform(crsSrc, crsDest)
       pt gps = QgsPoint(float(row['Longitude']), float(row['Latitude']))
       pt meter = xform.transform(pt gps)
       RSM = rlayer rsm.dataProvider().identify(pt meter, QgsRaster.IdentifyFormatValue)
       if (RSM.isValid()):
         if not RSM.results()[1] == None:
           rsm val = RSM.results()[1]
           if(rsm Max npArray[index] < rsm val):
              rsm Max npArray[index] = rsm val
           if(rsm Min npArray[index] > rsm val):
             rsm Min npArray[index] = rsm val
RSM minmax DF['min RSM'] = rsm Min npArray
RSM_minmax_DF['max_RSM'] = rsm_Max_npArray
```

```
SM_ML_df['min_RSM'] =
SM_ML_df['Plot_Id'].map(RSM_minmax_DF.set_index('Plot_Id')['min_RSM'])
SM_ML_df['max_RSM'] =
SM_ML_df['Plot_Id'].map(RSM_minmax_DF.set_index('Plot_Id')['max_RSM'])

print ("writing to excel")
writer = ExcelWriter(out_file)
SM_ML_df.to_excel(writer,'SM_ML_values')
writer.save()
print ("done totally")
```

Soil Class:

The soil classes are available as vector file, ie., dbase file. Hence, the easiest approach that is followed is to get the soil class of all sites based on nearest neighbor algorithm. The major classes of the soil has been defined in terms of locations and the description and soil type is mentioned according. To feed into machine learning algorithms, The soil types are mapped to integer types accordingly.

Soil_Type	Int_Typ
	e
Clay	1
Gravelly_Sandy_Clay	2
Gravelly_Sandy_Clay_Lo	3
am	
Sandy_Clay	4
Sandy_Clay_Loam	5

Table showing soil types and corresponding mapped integer types for ML algorithms

	Soil Name	Description	Soil_Type	Int_Typ e
ARK	Annurke	well drained, have dark reddish brown to very dusky	Sandy_Cla	4
BMB	ri soils Beeman abeedu soils	moderately well drained, have very dark greyish brown to dark grey and very dark brown clayey soils	Clay	1
BMD	Beramb adi soils	well drained, dark brown to dark greyish brown clayey soils	Clay	1
BRG	Bargi soils	well drained, have very dark brown to very dark grayish brown clay soils	Clay	1
DRH	Devarah alli soils	well drained, have dark red to reddish brown and dusky red gravelly sandy clay loam to sandy clay soils	Gravelly_S andy_Clay _Loam	3
GPR	Gopalap	well drained, have dark brown to dark reddish brown	Gravelly_S	3

	ura soils	and reddish brown gravelly sandy clay loam to sandy	andy_Clay	
		clay soils	_Loam	
HDR	Hindupu	well drained, have dark reddish brown to dusky red	Sandy_Cla	5
	r soils	sandy clay loam to sandy clay soils	y_Loam	
HGH	Honneg	well drained, have very dark brown to brown and dark	Sandy_Cla	5
	audanah	reddish brown sandy clay loam soils	y_Loam	
	alli soils			
HPR	Hullipur	well drained, have dark brown to very dark brown	Gravelly_S	3
	a soils	gravelly sandy clay loam to sandy clay soils	andy_Clay	
			_Loam	
KDH	Kalligau	well drained, have dark red to dark reddish brown and	Sandy_Cla	4
	danahall	dark brown sandy clay to clay soils	y	
	i soils			
KLP	Kallipur	well drained, have dark reddish brown to dark red	Gravelly S	3
	a soils	gravelly sandy clay loam to sandy clay soils	andy_Clay	
			_Loam	
KNG	Kanniga	well drained, have dark reddish brown to dark red	Gravelly_S	3
	la soils	gravelly sandy clay loam to sandy clay soils	andy Clay	
			Loam	
MDH	Maddin	well drained, have dark reddish brown gravelly sandy	Gravelly_S	2
	ahundi	clay soils	andy Clay	
	soils			
MGH	Magoon	well drained, have very dark brown to dark brown	Gravelly_S	3
	ahalli	gravelly sandy clay loam soils	andy_Clay	
	soils		_Loam	
SPR	Shivapu	well drained, have dark reddish brown gravelly sandy	Gravelly_S	3
	ra soils	clay loam to sandy clay soils	andy_Clay	
			_Loam	

Table showing classes and corresponding classification and description

The code snippet used for extracting soil class is as follows:

Code Snippet

```
import numpy as np
import pandas as pd
from pandas import ExcelWriter

basepath = 'D:\MASTERS-PROJECT\\'
subBasepath = basepath + 'MTECH-PROJ-Prob_1_VATI_vs_Field_Moisture\\'
in_file = subBasepath + 'Soil_Moisture_Berambadi_1617_CropAge_VATI_withMinMaxRSM_out.xlsx'
out_file = subBasepath +
'Soil_Moisture_Berambadi_1617_CropAge_VATI_withMinMaxRSM_SoilClass_out.xlsx'
soil_class_file = subBasepath + 'Soil_Classes.xlsx'
soil_class_df = pd.read_excel(soil_class_file, sheet_name='soil_classes')
soil_class_df = soil_class_df[['longitude','latitude','Int_Type']]
# print (soil_class_df)

SM_ML_df = pd.read_excel(in_file, sheet_name='SM_ML_values')
```

```
sm Soil Class LatLon DF = SM ML df[['Plot Id', 'Latitude', 'Longitude']]
sm Soil Class LatLon DF = sm Soil Class LatLon DF.drop duplicates(subset=['Plot Id'], keep='first')
sm Soil Class LatLon DF.reset index(drop=True, inplace=True)
# print (sm Soil Class LatLon DF.shape)
soil found class nparray = np.empty(shape=sm Soil Class LatLon DF.shape[0])
soil found class nparray[:] = np.nan
# print (soil found class nparray.shape)
count = 1
for i, SM row in sm Soil Class LatLon DF.iterrows():
  sm longitude = SM row['Longitude']
  sm latitude = SM row['Latitude']
  left extent arry = np.array([])
  right extent arry = np.array([])
  for j, Class row in soil class df.iterrows():
     if sm longitude >= Class row['longitude']:
       left extent arry = np.append(left extent arry, j)
    if sm longitude <= Class row['longitude']:
       right extent arry = np.append(right extent arry, j)
  if (left_extent_arry.shape[0] != 0):
    left extent j = left extent arry.max()
  else:
    left_extent_j = None
  if (right extent arry.shape[0] != 0):
     right_extent_j = right_extent_arry.min()
  else:
    right extent_j = None
  # print (sm longitude, left extent j, right extent j)
  if (left extent j != None and right extent j != None):
     top extent arry = np.array([])
     bottom extent arry = np.array([])
     for jk, Class row in soil class df.iterrows():
       if (right extent j \ge jk \ge left extent j):
          if sm latitude >= Class row['latitude']:
            bottom extent arry = np.append(bottom extent arry, jk)
         if sm latitude <= Class row['latitude']:
            top extent arry = np.append(top extent arry, jk)
    if (top extent arry.shape[0] != 0):
       LT extent jk = top extent arry.min()
     else:
       LT extent jk = None
     if (bottom extent arry.shape[0] != 0):
       RT extent jk = bottom extent arry.max()
```

```
else:
    RT_extent_jk = None

# taking left top value for soil
    if (LT_extent_jk != None and RT_extent_jk != None):
        soil_found_class_nparray[i] = int(soil_class_df['Int_Type'].iloc[int(LT_extent_jk)])
    else:
        soil_found_class_nparray[i] = np.nan

sm_Soil_Class_LatLon_DF['Int_Type'] = soil_found_class_nparray

SM_ML_df['Soil_Class'] =

SM_ML_df['Plot_Id'].map(sm_Soil_Class_LatLon_DF.set_index('Plot_Id')['Int_Type'])

print ("writing to excel")

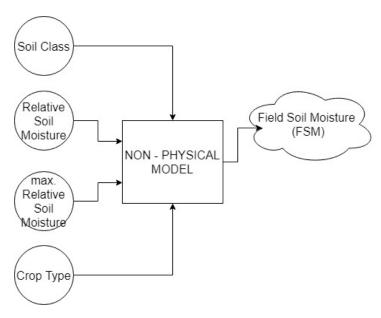
writer = ExcelWriter(out_file)

SM_ML_df.to_excel(writer,'SM_ML_values')
```

Thus, the different features that can be used in machine learning are (i) crop type, (ii) maximum relative soil moisture and (iii) soil class along with relative soil moisture obtained from satellite data.

Methodology

It is general practice to use physical model. In this study, a non physical model is used to analyze this problem. The dataset to be fed to this model consists of around 5200 data points.

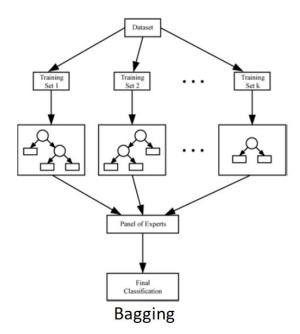


Non-Physical Model

This model has four inputs which are soil class, relative soil moisture, maximum relative soil moisture and crop type. And the output of the model is Field Soil Moisture. To train this model, bagging regressor, artificial neural networks and tensorflow custom machine learning regressor are used and discussed.

Bagging Regressor:

BAGGING is coined from 'Bootstrap AGGregatING'. Bagging regressor is an ensemble meta-estimator that fits base regressors each on random subsets of the original dataset and then aggregate their individual predictions (either by voting or by averaging) to form a final prediction. Such a meta-estimator can typically be used as a way to reduce the variance of a black-box estimator by introducing randomization into its construction procedure and then making an ensemble out of it.



Given a set D of d tuples, at each iteration i, a training set D_i of d tuples is sampled with replacement from D. A classifier model M_i is learned for each training set D_i . Regression can be applied to the prediction of continuous values by taking the average value of each prediction for a given test tuple. The code snippet used for bagging regressor is as follows:

import pickle import numpy as np import pandas as pd from pandas import ExcelWriter

```
import matplotlib.pyplot as plt
import itertools
from sklearn.model selection import train test split
from sklearn.ensemble import BaggingRegressor
def load data(in file):
  SM ML df = pd.read excel(in file, sheet name='SM ML values')
  reqd data arr = ['Plot Id', 'Crop Type', 'Field SM', 'rsm VATI', 'max RSM', 'Soil Class']
  SM ML df = SM ML df[reqd data arr]
  SM_ML_df.replace(0, np.nan, inplace=True)
  SM ML df.replace(-np.inf, np.nan, inplace=True)
  SM ML df = SM ML df.dropna(axis=0, how='any')
  return SM ML df
def replace df with crop classes and MaptoInt (basepath, SM ML df):
  # Replacing with crop classes
  crop class file = basepath + 'd crop classes.xlsx'
  crop_class_df = pd.read_excel(crop_class_file, sheet name='crop_classes')
  # print (crop class df)
  replacing dict = {}
  for index, each row in crop class df.iterrows():
      print (each row, type(each row))
    replacing_dict[each_row['Crop_Type']] = 'class' + str(each_row['Crop_Class'])
  # print (replacing dict)
  SM_ML_df["Crop_Type"] = SM_ML_df["Crop_Type"].str.strip().replace(replacing_dict)
  # print (SM ML df)
  # Forming Dictionary for crop Type and replacing with integer in Crop Type Column
  Crop Type nparray = SM ML df['Crop Type'].str.strip().unique()
  # print (Crop_Type_nparray)
  int toCrop type dict = dict(enumerate(Crop Type nparray))
  crop type toInt dict = {y:x for x,y in int toCrop type dict.items()}
  # print (int toCrop type dict)
  SM ML df["Crop Type"] = SM ML df["Crop Type"].str.strip().map(crop type toInt dict)
  # print (SM ML df)
  return SM ML df
def make data ready(SM ML df):
  X = SM ML df[['Crop Type', 'rsm VATI', 'Soil Class']]
  y = SM ML df[['Field SM']]
  X train, X test, y train, y test = train test split(X, y, test size=0.1)
  X train, X test, y train, y test = X train.values, X test.values, y train.values.flatten(),
y test.values.flatten()
  return (X_train, X_test, y_train, y_test)
def bagging(X train, X test, y train, y test):
```

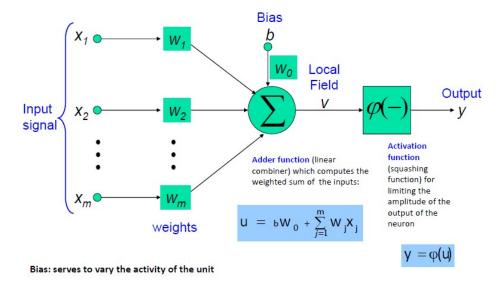
```
clf = BaggingRegressor()
  clf.fit(X train, y train)
  score = clf.score(X test, y test)
  return (clf, score)
def plot y vs y predicted(clf, X test, y test):
  y_predict = clf.predict(X_test)
  v = [0, 40, 0, 40]
  plt.axis(v)
  plt.scatter(y_test, y_predict)
  plt.xlabel("Y Actual")
  plt.ylabel("Y_Predicted")
  plt.show()
def main func():
# basepath = 'C:\\Users\\soi\\Documents\\MTECH-PROJ-Phase-2\\'
# basepath = 'C:\\Users\\rukmangadan\\Documents\\MTECH-PROJ-Phase-2\\'
  basepath = 'C:\\Users\\theorist\\Documents\\MTECH-PROJ-Phase-2\\'
  in_file = basepath + 'd_soil_moisture_comparison_data.xlsx'
  SM ML df = load data(in file)
  SM ML df = replace df with crop classes and MaptoInt (basepath, SM ML df)
  X train, X test, y train, y test = make data ready(SM ML df)
  clf, score = bagging(X train, X test, y train, y test)
  print(score)
  plot y vs y predicted(clf, X test, y test)
  plot_y_vs_y_predicted(clf, X_train, y_train)
```

Artificial Neural Networks:

A neural network is a set of connected input/output units (neurons) where each connection has a weight associated with it. During the learning phase, the network learns by adjusting the weights that enable it to predict the correct class label of the input samples.

Neural networks are built out of a densely interconnected set of simple units (neurons).

The neuron



- Each neuron takes a number of real-valued inputs.
- Produces a single real-valued output.
- Inputs to a neuron may be the outputs of other neurons.
- A neuron's output may be used as input to many other neurons.

Artificial Neural Networks can also be used to learn complex pseudo random number generator. The code snippet used for artificial neural networks is as follows:

```
import tensorflow as tf
import numpy as np
import pandas as pd
from sklearn.model selection import train test split
import matplotlib.pyplot as plt
def load data(in file):
  SM ML df = pd.read excel(in file, sheet name='SM ML values')
  reqd data arr = ['Plot Id', 'Crop Type', 'Field SM', 'rsm VATI', 'max RSM', 'Soil Class']
  SM ML df = SM ML df[reqd data arr]
  SM ML df.replace(0, np.nan, inplace=True)
  SM ML df.replace(-np.inf, np.nan, inplace=True)
  SM ML df = SM ML df.dropna(axis=0, how='any')
  return SM ML df
def replace df with crop classes and MaptoInt (basepath, SM ML df):
  # Replacing with crop classes
  crop class file = basepath + 'd crop classes.xlsx'
  crop class df = pd.read excel(crop class file, sheet name='crop classes')
  # print (crop class df)
```

```
replacing dict = {}
  for index, each row in crop class df.iterrows():
     print (each row, type(each row))
    replacing dict[each row['Crop Type']] = 'class' + str(each row['Crop Class'])
# print (replacing dict)
  SM ML df["Crop Type"] = SM ML df["Crop Type"].str.strip().replace(replacing dict)
  # print (SM ML df)
  # Forming Dictionary for crop Type and replacing with integer in Crop Type Column
  Crop Type nparray = np.sort(SM ML df['Crop Type'].str.strip().unique())
# print (Crop Type nparray)
  int toCrop type dict = dict(enumerate(Crop Type nparray))
  crop type toInt dict = \{y:(x+1) \text{ for } x,y \text{ in int toCrop type dict.items()}\}
# print (int toCrop type dict)
# print(crop type toInt dict)
  SM ML df["Crop Type"] = SM ML df["Crop Type"].str.strip().map(crop type toInt dict)
# print (SM ML df)
# print(SM ML df['Crop Type'].unique())
# print(SM ML df]'Soil Class'].unique())
  return SM ML df
def make data ready(SM ML df):
  X = SM_ML_df[['Crop_Type', 'rsm_VATI', 'max_RSM', 'Soil_Class']]
  y = SM ML df[['Field SM']]
  X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.1)
  X train, X test, y train, y test = X train.values, X test.values, y train, y test
  return (X train, X test, y train, y test)
# basepath = 'C:\\Users\\soi\\Documents\\MTECH-PROJ-Phase-2\\'
basepath = 'C:\\Users\\rukmangadan\\Documents\\MTECH-PROJ-Phase-2\\'
# basepath = 'C:\\Users\\theorist\\Documents\\MTECH-PROJ-Phase-2\\'
in file = basepath + 'd soil moisture comparison data.xlsx'
SM ML df = load data(in file)
SM ML df = replace df with crop classes and MaptoInt (basepath, SM ML df)
# print(SM ML df)
X train, X test, y train, y test = make data ready(SM ML df)
def tnsrflw(train input, y train, test input, optimizer type, epochs):
  train output = y train.values.flatten()
  A = tf.placeholder("float", [None, 4])
  Y = tf.placeholder("float", [None, 1])
  layer 1 = \text{tf.layers.dense}(A, 256)
  layer 2 = \text{tf.layers.dense(layer 1, 256)}
  layer 3 = \text{tf.layers.dense(layer } 2,256)
```

```
layer 4 = \text{tf.layers.dense(layer } 3,256)
  layer 5 = \text{tf.layers.dense(layer 4, 256)}
  pred = tf.layers.dense(layer 5, 1)
  cost = tf.reduce max(tf.square(pred - Y))
  optimizer = optimizer type.minimize(cost)
  init = tf.global variables initializer()
  sess = tf.Session()
  sess.run(init)
  step = 0
  total steps = train input.shape[0] * epochs
  for epoch in range(epochs):
     for (x, y) in zip(train input, train output):
       sess.run(optimizer, feed_dict=\{A: [[x[0],x[1],x[2],x[3]]\}, Y: [[y]]\})
       if(step % (total steps/4) == 0):
          print("Step", step, "of", total steps, ":")
          print ("Cost: ",sess.run(cost,
feed dict={A:np.transpose([train input[:,0],train input[:,1],train input[:,2],train input[:,3]]),
Y:np.transpose([train output])}),"\n")
       step+=1
  print("Step", total steps, "of", total steps, ":")
  print ("Cost: ",sess.run(cost,
feed_dict={A:np.transpose([train_input[:,0],train_input[:,1],train_input[:,2],train_input[:,3]]),
Y:np.transpose([train output])}),"\n")
  y pred test = sess.run(pred,
feed dict={A:np.transpose([test input[:,0],test input[:,1],test input[:,2],test input[:,3]])})
  y pred train = sess.run(pred,
feed dict={A:np.transpose([train input[:,0],train input[:,1],train input[:,2],train input[:,3]])})
  sess.close()
  return y pred test, y pred train
optimizer type = tf.train.AdamOptimizer(0.001)
epochs = 1000
y pred test, y pred train = tnsrflw(X train, y train, X test, optimizer type, epochs)
def plot_y_vs_y_predicted(y_actual, y_pred):
  y actual val = y actual.values.flatten()
  v = [0, 40, 0, 40]
  plt.axis(v)
  plt.scatter(y actual val, y pred)
  plt.xlabel("Y_Actual")
  plt.ylabel("Y_Predicted")
  plt.show()
```

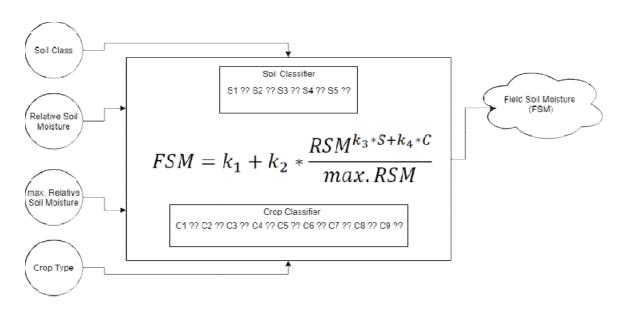
```
def number of points statistics(y_test, y_pred_test, y_train, y_pred_train):
  y test val = y test.values.flatten()
  y train val = y train.values.flatten()
  no_of_points_above = 0
  no of points matching = 0
  no of points below = 0
  for Y1, Y2 in zip(y_test_val, y_pred_test):
     if(0.7 * Y2 < Y1 \text{ and } Y1 < 1.3 * Y2):
       no of points matching += 1
    elif (Y1 < Y2):
       no_of_points_above += 1
    elif (Y2 < Y1):
       no of points below += 1
  for Y1, Y2 in zip(y_train_val, y_pred_train):
     if(0.7 * Y2 < Y1 \text{ and } Y1 < 1.3 * Y2):
       no of points matching += 1
     elif (Y1 < Y2):
       no of points above += 1
    elif (Y2 < Y1):
       no of points below += 1
  print("no_of_points_matching: ", no_of_points_matching)
  print("no of points above: ", no of points above)
  print("no_of_points_below: ", no_of_points_below)
number of points statistics(y test, y pred test, y train, y pred train)
print("Test Data Graph:")
plot y vs y predicted(y test, y pred test)
print("Trained Data Graph:")
plot y vs y predicted(y train, y pred train)
```

Tensorflow Machine Learning Custom Regressor:

Tensorflow has a custom regressor module wherein one can input the regressor functions along with variables and the corresponding training dataset for the model to train itself. Also, it has option of controlling flow of data for training based on conditions. The cost function for this model will be simple RMSE (Root Mean Square Error) between the predicted and actual values. The optimizer used for reducing RMSD (Root Mean Square Deviation) is Gradient Descent Optimizer.

Regression ML Model:

Since the dataset comprises of five soil classes and nine crop classes, 13 tensorflow variables will be kept for each class of S & C, ie., S1, S2, S3, S4, S5 for soil classes and C1, C2, ...,C9 for crop classes.



Machine Learning Model

The Field Soil Moisture (FSM) can be computed using

$$FSM = k_1 + k_2 * \frac{RSM^{k_3*S + k_4*C}}{max.RSM}$$

where

 $k_1, k_2, k_3, k_4 \rightarrow$ constants of regression model

 $S \rightarrow$ coefficient corresponding to type of soil

 $C \rightarrow$ coefficient corresponding to type of crop

RSM → Relative Soil Moisture obtained from the satellite data

max.RSM → maximum RSM for the field point

The code snippet used for Tensorflow ML regressor is as follows:

```
import tensorflow as tf
import numpy as np
import pandas as pd
from sklearn.model selection import train test split
import matplotlib.pyplot as plt
def load data(in file):
  SM ML df = pd.read excel(in file, sheet name='SM ML values')
  reqd data arr = ['Plot Id', 'Crop Type', 'Field SM', 'rsm VATI', 'max RSM', 'Soil Class']
  SM_ML_df = SM_ML_df[reqd_data_arr]
  SM ML df.replace(0, np.nan, inplace=True)
  SM ML df.replace(-np.inf, np.nan, inplace=True)
  SM ML df = SM ML df.dropna(axis=0, how='any')
  return SM ML df
def replace df with crop classes and MaptoInt (basepath, SM ML df):
  # Replacing with crop classes
  crop class file = basepath + 'd crop classes.xlsx'
  crop class df = pd.read excel(crop class file, sheet name='crop classes')
  # print (crop class df)
  replacing dict = {}
  for index, each row in crop class df.iterrows():
     print (each row, type(each row))
    replacing dict[each row['Crop Type']] = 'class' + str(each row['Crop Class'])
# print (replacing dict)
  SM ML df["Crop Type"] = SM ML df["Crop Type"].str.strip().replace(replacing dict)
  # print (SM ML df)
  # Forming Dictionary for crop Type and replacing with integer in Crop Type Column
  Crop_Type_nparray = np.sort(SM_ML_df['Crop_Type'].str.strip().unique())
# print (Crop Type nparray)
  int toCrop type dict = dict(enumerate(Crop Type nparray))
  crop type toInt dict = \{y:(x+1) \text{ for } x,y \text{ in int toCrop type dict.items()}\}
# print (int toCrop type dict)
# print(crop type toInt dict)
  SM ML df["Crop Type"] = SM ML df["Crop Type"].str.strip().map(crop type toInt dict)
# print (SM ML df)
# print(SM ML df['Crop Type'].unique())
# print(SM ML df['Soil Class'].unique())
  return SM ML df
def make data ready(SM ML df):
  X = SM_ML_df[['Crop_Type', 'rsm_VATI', 'max_RSM', 'Soil_Class']]
  y = SM ML df[['Field SM']]
  X train, X test, y train, y test = train test split(X, y, test size=0.1)
  X_train, X_test, y_train, y_test = X_train.values, X_test.values, y_train, y_test
```

```
return (X train, X test, y train, y test)
def tnsrflw(train input, y train, test input, optimizer type, epochs):
  train output = y train.values.flatten()
  k1 = tf. Variable(tf.random normal([1]))
  k2 = tf.Variable(tf.random normal([1]))
  k3 = tf.Variable(tf.random normal([1]))
  k4 = tf.Variable(tf.random normal([1]))
  k5 = tf.Variable(tf.random_normal([1]))
  c1 = tf. Variable(tf.random_normal([1]))
  c2 = tf.Variable(tf.random normal([1]))
  c3 = tf.Variable(tf.random_normal([1]))
  c4 = tf. Variable(tf.random_normal([1]))
  c5 = tf.Variable(tf.random_normal([1]))
  c6 = tf. Variable(tf.random_normal([1]))
  c7 = tf.Variable(tf.random normal([1]))
  c8 = tf.Variable(tf.random_normal([1]))
  c9 = tf. Variable(tf.random_normal([1]))
  s1 = tf.Variable(tf.random normal([1]))
  s2 = tf.Variable(tf.random normal([1]))
  s3 = tf.Variable(tf.random normal([1]))
  s4 = tf.Variable(tf.random normal([1]))
  s5 = tf.Variable(tf.random_normal([1]))
  A = tf.placeholder("float")
  B = tf.placeholder("float")
  C = tf.placeholder("float")
  D = tf.placeholder("float")
  Y = tf.placeholder("float")
  s2 s1 = tf.where(tf.logical and(1.9<D,D<2.1),x=s2,y=s1)
  s3 \ s2 = tf.where(tf.logical and(2.9 < D,D < 3.1),x = s3,y = s2 \ s1)
  s4 	ext{ s3} = tf.\text{where}(tf.logical and}(3.9 < D, D < 4.1), x = s4, y = s3 	ext{ s2})
  s = tf.where(tf.logical and(4.9 < D,D < 5.1),x=s5,y=s4 s3)
  c2 c1 = tf.where(tf.logical and(1.9<A,A<2.1),x=c2,y=c1)
  c3 c2 = tf.where(tf.logical and(2.9 < A, A < 3.1),x=c3,y=c2 c1)
  c4\_c3 = tf.where(tf.logical\_and(3.9 < A, A < 4.1), x = c4, y = c3\_c2)
  c5 c4 = tf.where(tf.logical and(4.9 < A, A < 5.1), x = c5, y = c4 c3)
  c6 c5 = tf.where(tf.logical and(5.9<A,A<6.1),x=c6,y=c5 c4)
  c7 c6 = tf.where(tf.logical and(6.9<A,A<7.1),x=c7,y=c6 c5)
  c = tf.where(tf.logical and(7.9 < A, A < 8.1), x = c8, y = c7 c6)
  pred = k1 + k2 * tf.pow(B, k3 * s + k4 * c) / tf.pow(C, k5)
  cost = tf.reduce max(tf.square(pred - Y))
```

```
optimizer = optimizer type.minimize(cost)
  init = tf.global variables initializer()
  sess = tf.Session()
  sess.run(init)
  step = 0
  total_steps = train_input.shape[0] * epochs
  for epoch in range(epochs):
     for (x, y) in zip(train input, train output):
         print(int(x[3]))
       sess.run(optimizer, feed_dict=\{A:x[0],B:x[1],C:x[2],D:x[3],Y:y\})
       if(step % (total steps/4) == 0):
          print("Step", step, "of", total steps, ":")
          k = sess.run([k1, k2, k3, k4, k5])
          s = sess.run([s1, s2, s3, s4, s5])
          c = sess.run([c1, c2, c3, c4, c5, c6, c7, c8])
          print (k[0], k[1], k[2], k[3], k[4])
          print (s[0], s[1], s[2], s[3], s[4])
          print (c[0], c[1], c[2], c[3], c[4], c[5], c[6], c[7])
          print ("Cost: ",sess.run(cost, feed dict=\{A:x[0],B:x[1],C:x[2],D:x[3],Y:y\}),"\n")
       step+=1
  print("Step", total steps, "of", total steps, ":")
  k = sess.run([k1, k2, k3, k4, k5])
  s = sess.run([s1, s2, s3, s4, s5])
  c = sess.run([c1, c2, c3, c4, c5, c6, c7, c8])
  print (k[0], k[1], k[2], k[3], k[4])
  print (s[0], s[1], s[2], s[3], s[4])
  print (c[0], c[1], c[2], c[3], c[4], c[5], c[6], c[7],"\n")
  y_pred_test = np.array([])
  for tst_inpt in test_input:
    y pred test = np.append(y pred test, sess.run(pred,
feed dict={A:tst inpt[0],B:tst inpt[1],C:tst inpt[2],D:tst inpt[3]}))
  y pred trn = np.array([])
  for trn_inpt in train_input:
    y_pred_trn = np.append(y_pred_trn, sess.run(pred,
feed dict={A:trn inpt[0],B:trn inpt[1],C:trn inpt[2],D:trn inpt[3]}))
  sess.close()
  return y_pred_test, y_pred_trn
def plot y vs y predicted(y actual, y pred):
  y_actual_val = y_actual.values.flatten()
  v = [0, 40, 0, 40]
  plt.axis(v)
  plt.scatter(y_actual_val, y_pred)
```

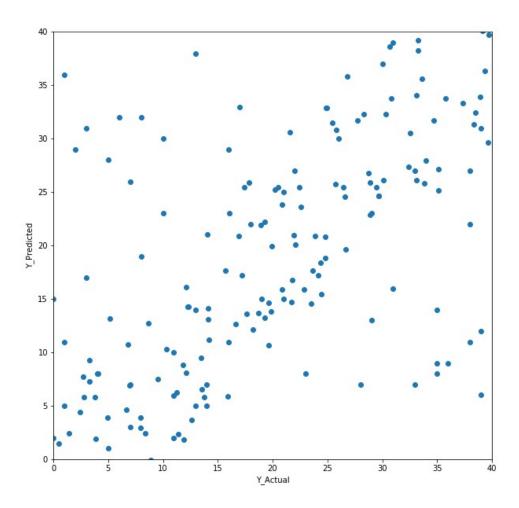
```
plt.xlabel("Y Actual")
  plt.ylabel("Y Predicted")
  plt.show()
def number of points statistics(y test, y pred test, y train, y pred trn):
  y test val = y test.values.flatten()
  y_train_val = y_train.values.flatten()
  no of points above = 0
  no of points matching = 0
  no\_of\_points\_below = 0
  for Y1, Y2 in zip(y_test_val, y_pred_test):
     if(0.7 * Y2 < Y1 \text{ and } Y1 < 1.3 * Y2):
       no of points matching += 1
    elif (Y1 < Y2):
       no of points above += 1
    elif (Y2 < Y1):
       no of points below += 1
  for Y1, Y2 in zip(y train val, y pred trn):
     if(0.7 * Y2 < Y1 \text{ and } Y1 < 1.3 * Y2):
       no of points matching += 1
    elif (Y1 < Y2):
       no_of_points_above += 1
    elif (Y2 < Y1):
       no of points below += 1
  print("no of points matching: ", no of points matching)
  print("no_of_points_above: ", no_of_points_above)
  print("no of points below: ", no of points below)
# basepath = 'C:\\Users\\soi\\Documents\\MTECH-PROJ-Phase-2\\'
basepath = 'C:\\Users\\rukmangadan\\Documents\\MTECH-PROJ-Phase-2\\'
# basepath = 'C:\\Users\\theorist\\Documents\\MTECH-PROJ-Phase-2\\'
in file = basepath + 'd soil moisture comparison data.xlsx'
SM ML df = load data(in file)
SM ML df = replace df with crop classes and MaptoInt (basepath, SM ML df)
# print(SM ML df)
X train, X test, y train, y test = make data ready(SM ML df)
optimizer type = tf.train.AdamOptimizer(0.001)
epochs = 100
y_pred_test, y_pred_trn = tnsrflw(X_train, y_train, X_test, optimizer_type, epochs)
number_of_points_statistics(y_test, y_pred_test, y_train, y_pred_trn)
print("Test Data Graph:")
plot y vs y predicted(y test, y pred test)
print("Trained Data Graph:")
plot_y_vs_y_predicted(y_train, y_pred_trn)
print(y_test)
```

Chapter 4

Results and Discussions

Bagging Regressor:

Bagging Regressor gives an average correlation of 0.65. Bagging regressor can also give average results if the dataset has a complex structure. To test if the dataset has a complex structure, Artificial Neural Networks (ANNs) are used.

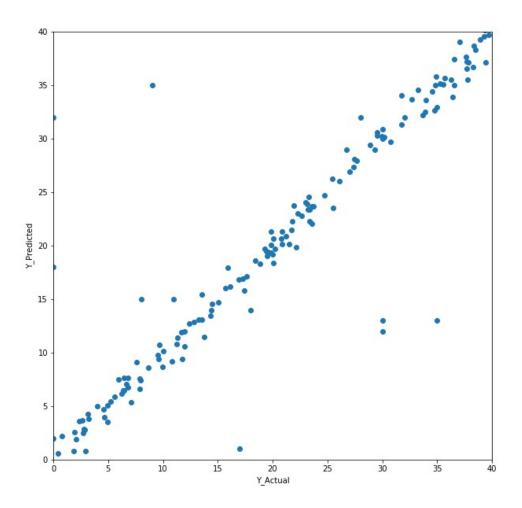


Scatter plot of Bagging Regressor Prediction

- It is far better than a single classifier derived from total dataset.
- For noisy data, it works average only.

Artificial Neural networks:

Artificial Neural Networks gives correlation of around 0.92. The results are of high accuracy. This means that a complex structure is found in the dataset.

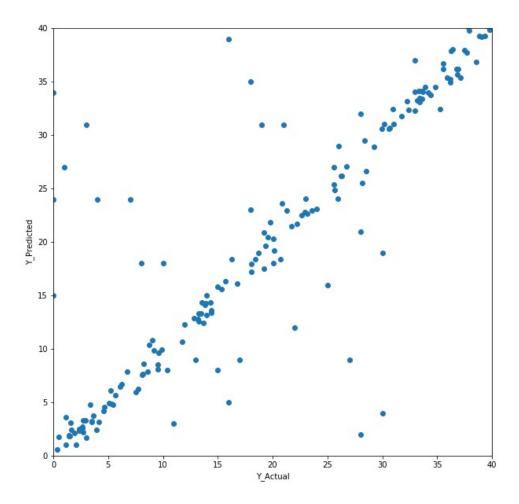


Scatter plot of ANN Prediction

- Prediction accuracy is generally high.
- robust, works when training examples contain errors or noisy data
- parameters are best determined empirically and longer training time
- difficult to understand the learned function (weights)
- not easy to incorporate domain knowledge

Regression ML Model:

Artificial Neural Networks has shown that there is a complex structure. Hence, the custom regressor model is tried and regression ML model gives correlation of around 0.86.



For the custom regression model,

$$FSM = k_1 + k_2 * \frac{RSM^{k_3*S + k_4*C}}{max.RSM}$$

the values of coefficients are found to be

Constants of regression model:

Constant	Value
k1	0.539
k2	0.876
k3	0.32
k4	0.84

Coefficients of Soil Class:

Soil Class	Coefficient	Value
1	s1	-0.22715
2	s2	-0.27834
3	s3	-0.32364
4	s4	-0.46348
5	s5	-0.39676

Coefficients of Crop Class:

Crop Class	Coefficient	Value
1	c1	2.065574
2	c2	2.328851
3	c3	2.414203
4	c4	2.475283
5	c5	2.439513
6	c6	2.055184
7	c7	2.406972
8	c8	2.342806
9	c9	2.843768

Keeping the tolerance \pm 0.5 % of the predicted values, around 20% of the data is showing different values other than the actual values. Banana and Sugarcane which have been classified as tall and more dense is showing higher values. And whichever is showing lesser values, belongs to tall and less dense sunflower and maize plants.

Chapter 5

Conclusion

- Thus we are able achieve good correlation between relative soil moisture and field soil moisture to a greater extent which did not make any sense before
- The algorithms could be used for prediction of future values of field moisture content from satellite data.
- Using machine learning, we could extract many interesting features from the datasets also.

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