

Module 2

Scale Space for Biological Image Segmentation

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First Approach

- Create a *scale space* via *area morphology* (connected filters)
- Cluster vectors in the scale space to extract segments

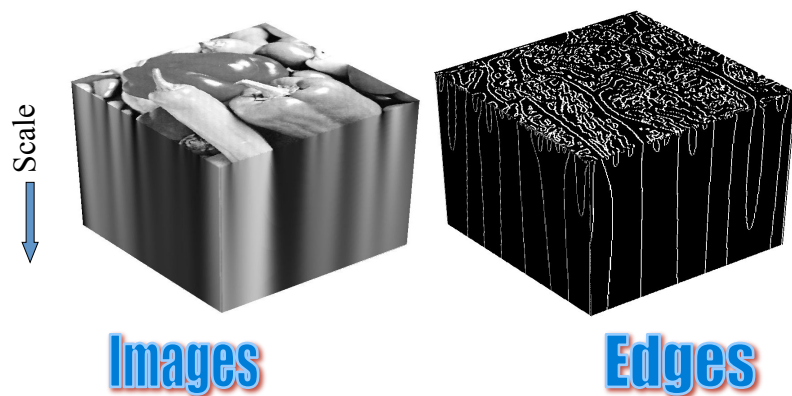


Objective

- The goal of the work is to investigate segmentation procedures that can be used for biological imagery
- Ability to specify the minimum-sized segments
- Provide segments that minimize classification error
- Provide segments that minimize intra-object classification error



Scale-space Generation from Linear Filtering

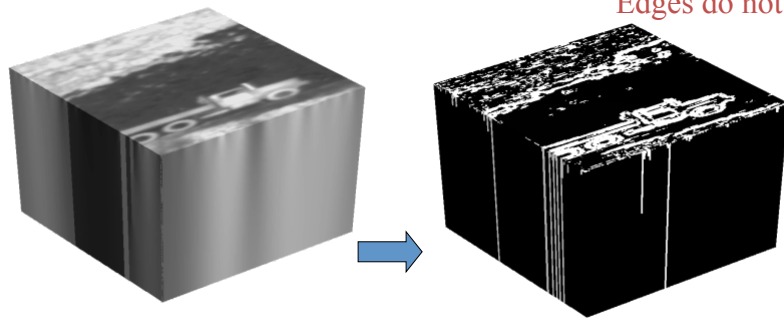


- Notice Edge Movement -- Feature Drift as scale increases
- Difficult to use in multi-scale image analysis tasks



Scale-space from Anisotropic Diffusion

- Diffusion/smoothing is inhibited where the local gradient magnitude is large...



- Causality is maintained -- no new features are created with increased scale
- Can be used in multi-scale tasks such as coarse-to-fine searches



Area Morphology

- **Area morphology** is based on the manipulation of connected components within the image level sets according to their area
- Let \mathbf{I} represent an image with level sets $\mathbf{B}(\mathbf{I}, t)$:
- Within a particular level set \mathbf{B} , we have a connected component of 1's at (x, y) represented by $\mathbf{C}_{\mathbf{B}}(x, y)$

$$(x, y) \in \mathbf{B}(\mathbf{I}, t) \text{ if } I(x, y) \geq t$$



Area Open and Close Operators

- For a particular level set \mathbf{B} , the area open and close operators are defined by

$$(x, y) \in \overset{a}{\circ}(\mathbf{B}) \text{ if } |\mathbf{C}_{\mathbf{B}}(x, y)| \geq a$$

$$(x, y) \in \overset{a}{\bullet}(\mathbf{B}) \text{ if } |\mathbf{C}_{\mathbf{B}}^c(x, y)| \geq a$$

Area open-close (AOC) is simply the concatenation of area open and close



Area Open-Close Scale Space

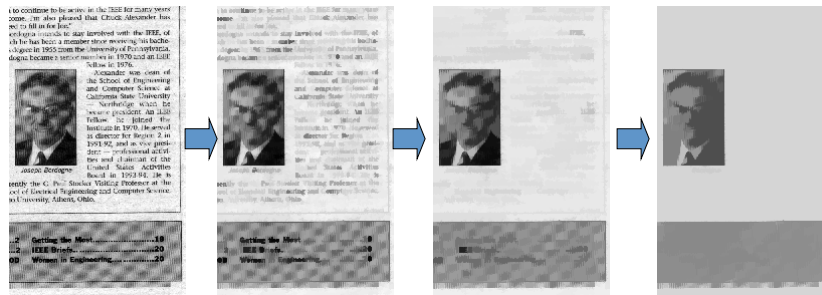
- For an image, the AOC is computed by stacking the processed level sets

$$I(x, y) = \sum_{i=0}^{K-1} 1_{(x,y) \in L(I,i)}$$

- The scale space is created recursively
- The AOC scale space maintains the **fidelity**, **causality**, **strong causality** and **Euclidean invariance** properties
- Fast algorithms** exist to compute the AOC (queue, tree and pyramid-based)



Non-bio Area Open-Close Scale Space Example



8-bit, 292x176
scan of 'The
Institute'



Clustering

- Let the 1-D signal $\mathbf{I}(x, y)$ represent the scale space evolution of $I(x, y)$
- $\mathbf{I}(x, y)$ is a scale space vector -- we cluster the scale space vectors to segment the image
- The distance between two scale space vectors is defined by

$$d(\mathbf{I}(x_1, y_1), \mathbf{I}(x_2, y_2)) = \left[\sum_{\Omega_S} |I_s(x_1, y_1) - I_s(x_2, y_2)|^p \right]^{1/p}$$



Fuzzy c-Means Clustering

Minimize: $J_m(U, \mu) = \sum_{\Omega} \sum_{i=1}^C (u_i(x, y))^m \|d_i(x, y)\|^2$

Sum over Scales Sum over Classes Class Membership Distance of scale space vector to cluster center

Update Memberships:

$$u_i(x, y) = 1 / \left[\sum_{j=1}^C \left(\frac{d_i(x, y)}{d_j(x, y)} \right)^{2/(m-1)} \right]$$

Update Cluster Centers:

$$\mu_i = \frac{\sum_{\Omega} (u_i(x, y))^m \mathbf{I}(x, y)}{\sum_{\Omega} (u_i(x, y))^m}$$



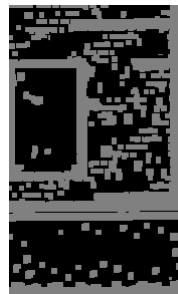
Clustering Results



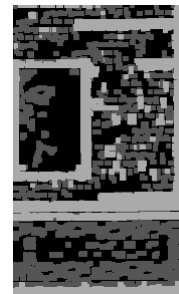
Using AOC
scale space
2 Classes



Using AOC
scale space
3 Classes



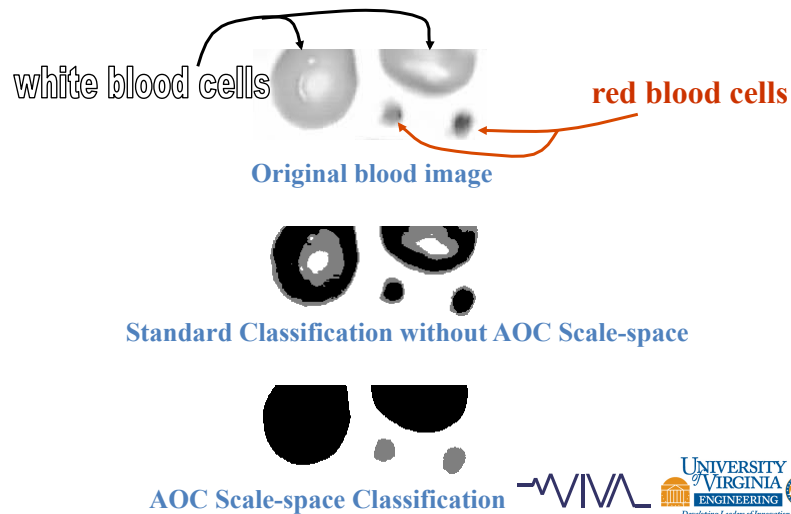
Using open
scale space
2 Classes



Using open
scale space
3 Classes



Cellular Example of Intra-object Error



Second Approach

- Use a partial differential equation (PDE)-driven diffusion to encourage intra-region smoothing and
 - Discourage inter-region smoothing
- This diffusion can be used to generate space space



Diffusion

- Diffusion is a mathematical model for several physical processes: the migration of bacteria, heat transfer, etc.
- The same partial differential equations (PDEs) may also be used for signal / image smoothing:

The M -dimensional signal

$$\frac{\partial I(\mathbf{x})}{\partial t} = \text{div}[c(\mathbf{x})\nabla I(\mathbf{x})]$$

time = scale

local gradient

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Motivation

- Benefits of the Diffusion Technique
 - Diffusion can be **efficiently implemented** using locally connected units on a parallel processor
 - Intra-region smoothing vs. inter-region smoothing (edge and **feature preservation**)
 - Control of feature **scale** to create a *scale-space* -- a family of signals that vary from coarse to fine



Diffusion on Digital Imagery

- The diffusion PDE must be discretized for implementation on digital images

New Image Intensity at iteration $t+1$

$$[I(\mathbf{x})]_{t+1} \leftarrow \left[I(\mathbf{x}) + \Delta T \sum_{p=1}^{\Omega} c_p(\mathbf{x}) \nabla I_p(\mathbf{x}) \right]_t$$

Time step ΔT Diffusion direction p Diff. Coef. in p^{th} direction $c_p(\mathbf{x})$ Simple difference in p^{th} direction $\nabla I_p(\mathbf{x})$

For 2-D images, there are $\Omega=4$ directions of diffusion (N, S, E, W)



The Diffusion Coefficient

- If the diffusion coefficient is constant at all image locations, isotropic diffusion (Gaussian smoothing) is enacted

– **Problem:** isotropic diffusion does not preserve edges



- If the diffusion coefficient is allowed to vary with the local image gradient magnitude, we have **anisotropic diffusion**

– **Benefit:** edges can be preserved or even enhanced



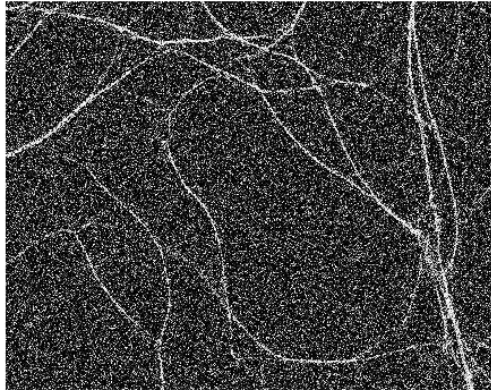
Form: typically a non-increasing function of image gradient magnitude...

$$c_p(\mathbf{x}) = f(|\nabla I_p(\mathbf{x})|)$$



An example on a noisy image of axons

Iteration = 1



Original

$$c_p(\mathbf{x}) = \exp \left\{ - \left[\frac{\nabla I_p(\mathbf{x})}{k} \right]^2 \right\}$$

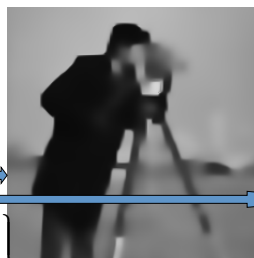
Traditional
Anisotropic
Diffusion

Preserves Noise, Small Details

Anisotropic
Diffusion with
Gradient
Prefilter

$$c_p(\mathbf{x}) =$$

$$\exp \left\{ - \left[\frac{\nabla S_p(\mathbf{x})}{k} \right]^2 \right\}$$



$$\uparrow S = I * G(\sigma)$$



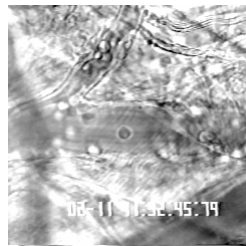
$$\uparrow S = (I \circ B) \cdot B$$

Morphological

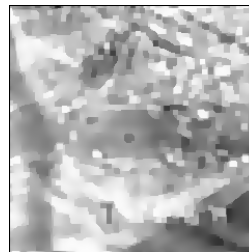


Image Enhancement

- We know the scale and shape of the leukocytes (roughly)
- We can exploit that knowledge in removing noise and clutter – using **morphological anisotropic diffusion**



Input

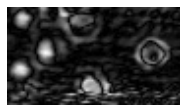
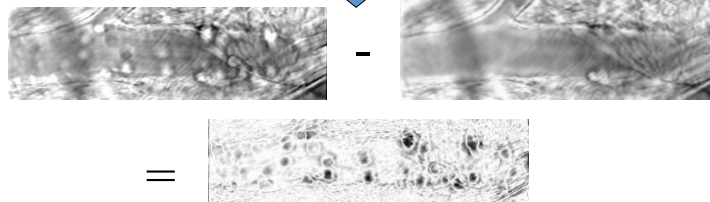


After Diffusion w/ Morph.
Diffusion coef. 



Background Subtraction

- Subtract background image from each registered frame to reveal foreground objects (leukocytes)



Original Subimage After Background Sub.

After Diffusion w/ Morph diffusion coef.



Anisotropic diffusion with signal-dependent noise

- Previous AD assumes additive noise that is independent of signal
- What to do when noise is signal-dependent?
- Base diffusion coefficient on Standard Deviation / Mean instead of Gradient magnitude...
- Let $q(x,y) = \sigma/\mu$ – the coef. of variation!
- Called SRAD: speckle reducing anisotropic diffusion



Diffusion Coefficient

$$c(q) = \frac{1}{1 + \left[q^2(x,y;t) - q_0^2(t) \right] / \left[q_0^2(t) (1 + q_0^2(t)) \right]}$$

Instantaneous Coef. Of Variation (ICOV)

ICOV of fully developed speckle

Gradient

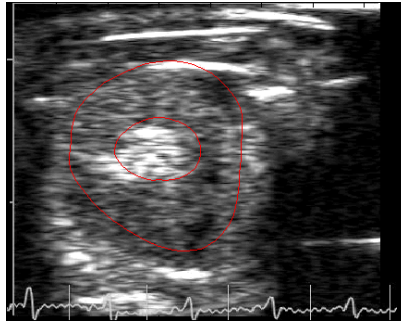
$$q(x,y) = \sqrt{\frac{\left| (1/2) |\nabla I(x,y)|^2 - (1/16) (\nabla^2 I(x,y))^2 \right|}{\left[I(x,y) + (1/4) \nabla^2 I(x,y) \right]^2}}$$

Derived from coefficient of variation

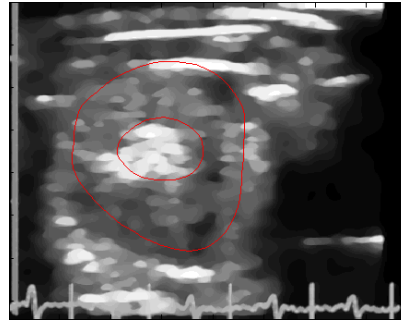
Laplacian



Enhancement via SRAD can improve segmentation results



**Image
segmentation
fails due to weak
bottom left edge**



SRAD improves contrast,
intraregion homogeneity



END

- Onward to graphs!



Intra-object Classification Error

$$e_s(x_1, y_1) = \left| \left\{ (x_2, y_2) : (x_2, y_2) \in O_s(x_1, y_1), (x_2, y_2) \in \gamma_{c_2}, (x_1, y_1) \in \gamma_{c_1}, c_1 \neq c_2 \right\} \right|$$

Members of same object
(member of the same
connected component
within an image level set)

Members of different
classes

$$e = \frac{\sum_{\Omega_s} \sum_{\Omega} e_s(x, y)}{|\Omega_s| |\Omega|}$$

Errors summed over all
scales and positions (and
normalized)

Example	Scale Space Fuzzy c- means	Scale Space k- means	Fuzzy c- means	k- means	Bayesian Classifier
1	133.58	139.64	171.62	167.77	168.10
2	125.5	115.95	174.74	174.74	173.84
3	365.55	399.84	416.30	419.95	463.93
4	122.1	120.55	159.98	158.99	143.23
5	169.98	168.78	211.7	209.53	188.89

