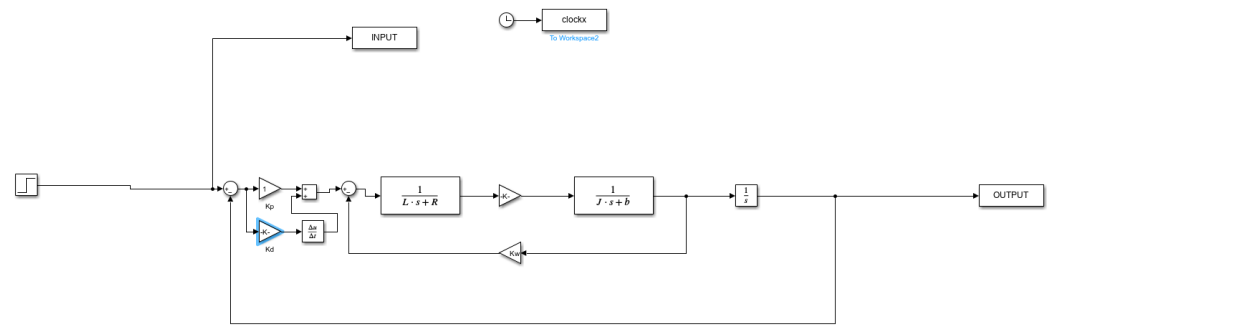


# **ASSIGNMENT 2**

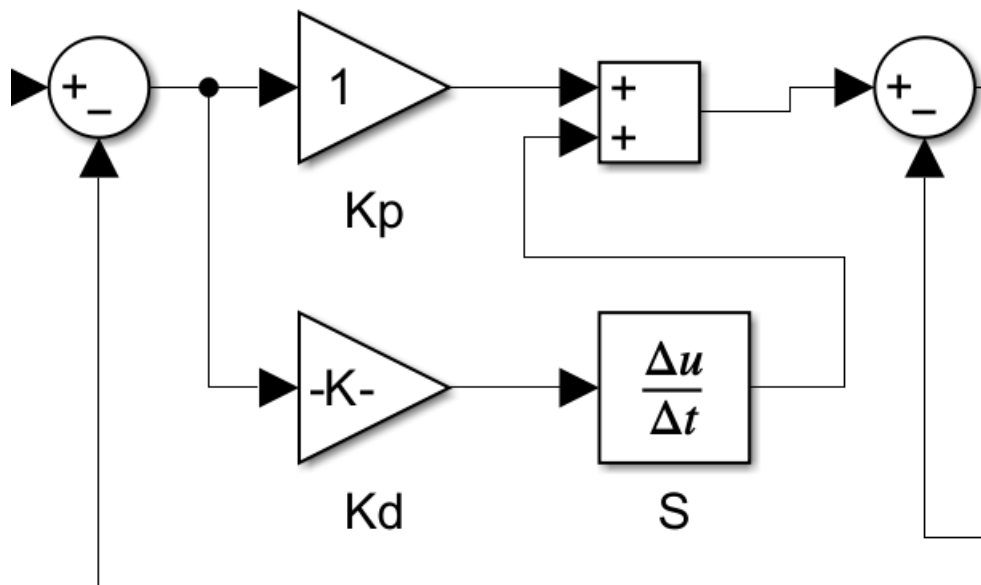
**BY VISHRUT CHAWLA**

**1228622241**

## The Simulink block diagram



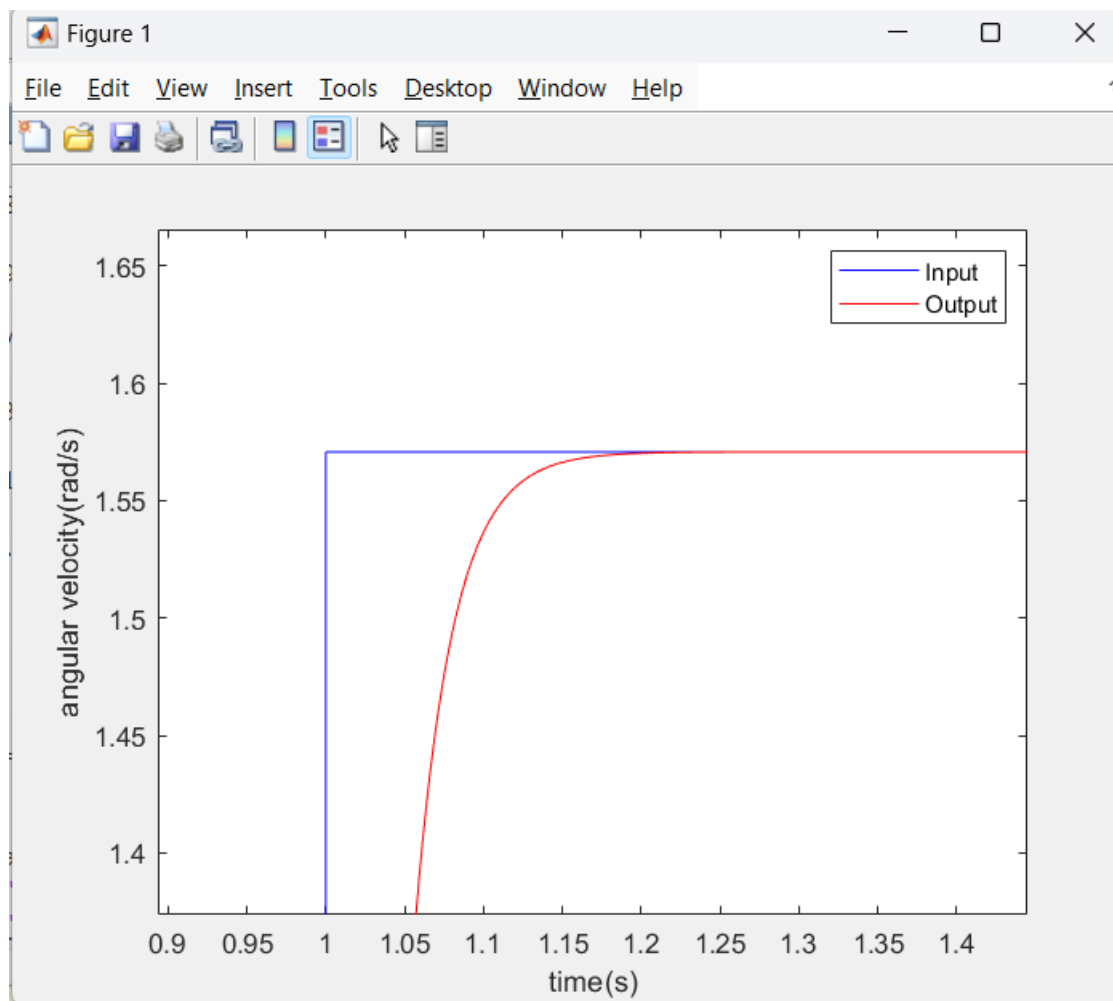
To simulate the PD controller( $K_p + K_d S$ )



**For values  $K_p=1$**

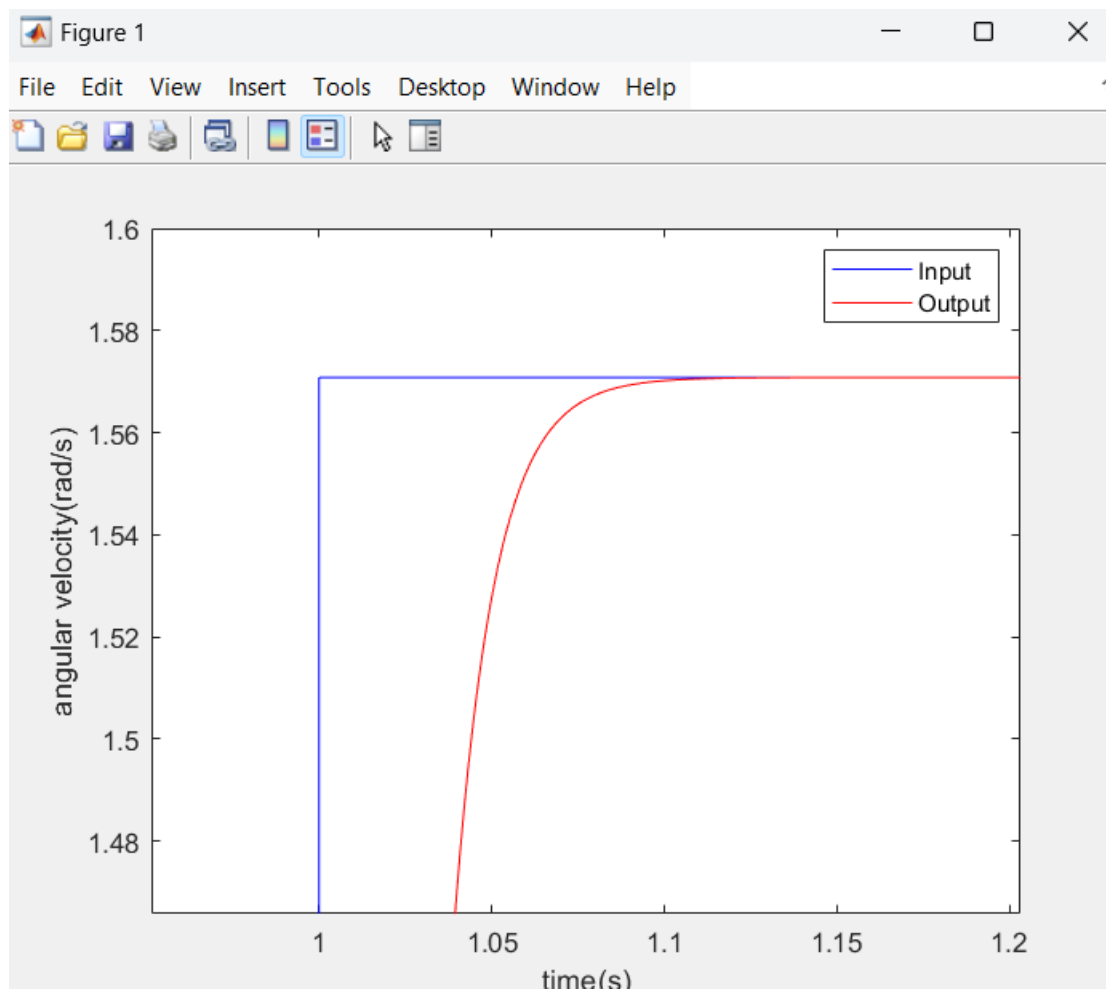
**$K_d$  value taken is = 0.000001**

**Graph**



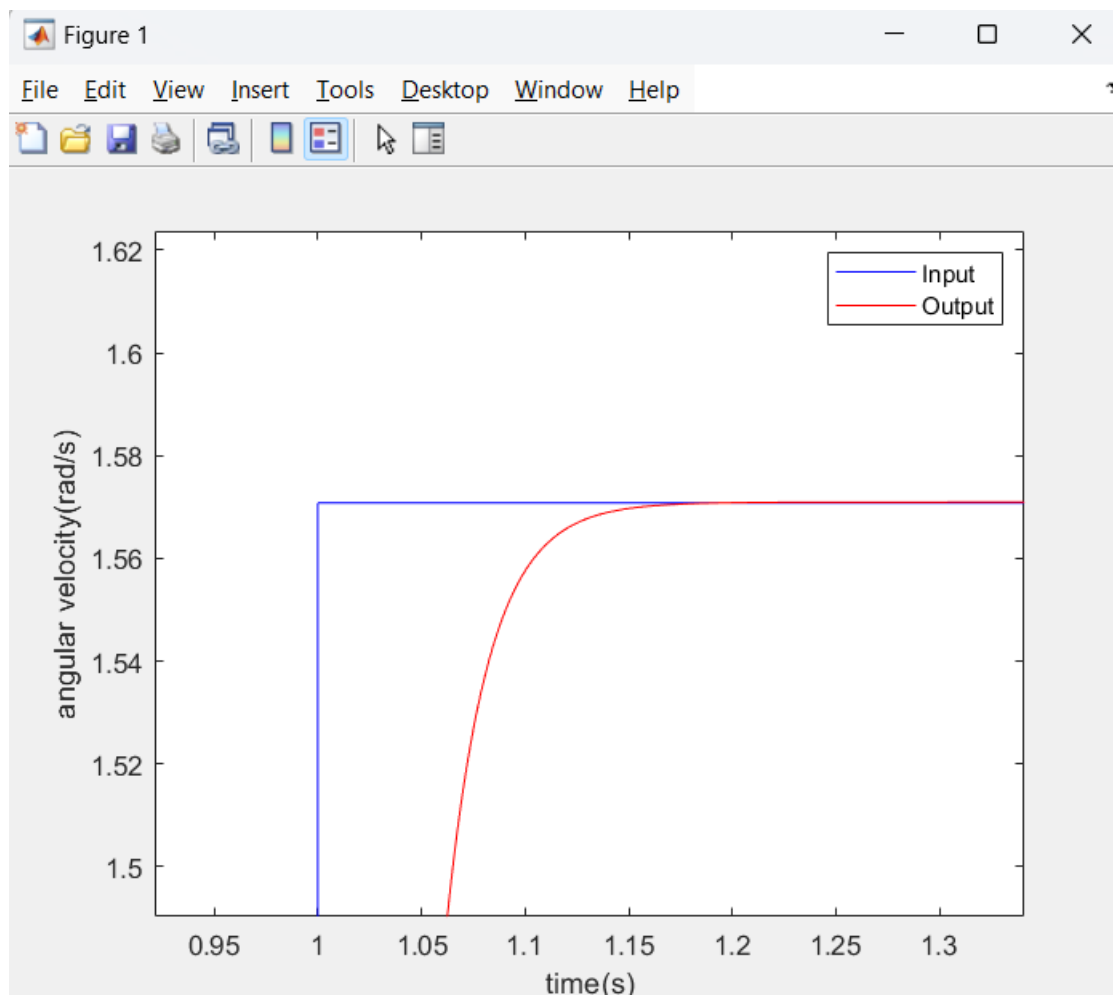
**For  $K_p=2$**

**$K_d=0.005$**



**For  $K_p=5$**

**$K_d=0.08$**



**For  $K_p=10$**

**$K_d=0.22$**

