

question 3

1. A vector's degree of freedom depends upon the independent basis vector. Hence a vector having n independent basis has n degree of freedom

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1 We take a cross product of \vec{a} and \vec{b} . With the right hand rule we know that the resulting cross vector of \vec{a} and \vec{b} will be a vector orthogonal to \vec{a} and \vec{b} . Let's assume the resulting vector of $\vec{a} \times \vec{b}$ to be \vec{d} . For \vec{c} to be parallel to vector \vec{a} and \vec{b} the vector \vec{c} has to be perpendicular to \vec{d}

Hence the constraint equation for \vec{c} is $\vec{c} \cdot \vec{d} = 0$

$$\text{or } \vec{c} \cdot (\vec{a} \times \vec{b}) = 0$$

Degree of Freedom = \vec{c} has two degree of freedoms as it can move in two directions perpendicular to \vec{d}

2 Similar to previous answer for previous question for vector \vec{c} to be perpendicular, \vec{c} has to be parallel to \vec{d} . Hence $\vec{c} \times (\vec{a} \times \vec{b}) = 0$

Degree of Freedom = \vec{c} has one degree of freedom as it can only move in the direction of \vec{d} which is perpendicular to $(\vec{a} \times \vec{b})$

