## Universal transceiver control interface – TCI

### Version 1.0

#### Introduction

This document describes TCI interface, what can you do with it and how can you do that. This document may be of interest to programmers, who will implement this interface in their software and devices.

TCI – Transceiver Control Interface is the network interface for control, data transfer and synchronization between a transceiver/receiver, logger, digital software, skimmer, other software and external power amplifier, band filters, antenna switch, radio station controller and other devices.

TCI was created as an advanced alternative to old-fashioned COM-port interface and audio cables. It utilizes full duplex web-socket protocol, which works above TCP connection providing data exchange between server and client, and cross-platform capabilities. Transceiver works as a server, all other software and devices as clients. Server and clients may work inside the same PC (SDR-software-server, logger etc. – clients) and/or in separate physical devices, connected via local network (classical transceiver, power amplifier, antenna switch, BPF-filters etc.).

TCI interface has main commands to control a transceiver (CAT-system analogue), receives CW macroses from clients and transmits them on the air, passes transceiver's IQ stream to clients, receives spots from skimmers and Internet clusters, receives/transmits audio signal for digital mode operation\*.

\* Will be added in the new TCI release.

TCI uses an extensible architecture; thus, it can be enriched with new functionality, preserving efficiency of old functions. You can add a certain functionality to the TCI interface, which corresponds to specific needs of any software developer or hardware manufacturer (of receivers, transceivers, power amplifiers, antenna switches etc.). TCI has a server/client identifier; thus, clients can detect an assigned name for a transceiver/receiver (server), this function will help other manufacturers to preserve names of their devices in implemented TCI.

We created TCI interface to unify data exchange between different devices and various software. Modern transceivers and software should be connected via the unified interface – TCI.

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## **Description**

Any command is the ASCII line, which contents name of the command and list of arguments corresponding to this command. There are some reserved characters, which cannot be part of the command name and its arguments.

List of reserved characters: «:», «,», «;».

Command structure:

- 1. Name of the command;
- 2. Separating character between command name and arguments «:»;
- **3.** Separating character between arguments «,»;
- **4.** End of the command character «:».

If there are no arguments in the command, then after the name of the command should go end of the command character «;». If the command is incorrect, it is ignored. Letter case (capitalization) is irrelevant.

ExpertSDR2 software works as a server, which can have several clients connected simultaneously, they will be synced between each other via server. When client is connected to the ExpertSDR2, it receives ExpertSDR2 status: firstly, it receives *Read only* commands, then different parameters like frequency, modulations, etc.

When any parameter is changed in the ExpertSDR2 (server), it informs each connected client, so clients do not have to send continuous requests to a server, any change will be reported to every client. If a client will change its state, server will set it for itself and send it to every other client, so server works as a synchronizer. All clients connected to a server will be automatically synced. This way of operation allows to minimize network load, by lessening the traffic.

TCI protocol offers CW operation with line commands.

There are two types of commands:

- 1. Macros:
- 2. Message.

Macros – this is a list of characters, which has no rules, but abides to "change of speed" and "abbreviation transfer" commands.

Message – special command, which consists of three parts:

- 1. Text before callsign;
- 2. Callsign;
- 3. Text after callsign.

When transmitting the message, you can transmit the rest of your callsign after transmitting the message with only part of callsign, also you can change transmitting speed in the middle of the message and use abbreviations.

If you need to insert some abbreviation inside the text, it will look like:

ANY TEXT | SK | OTHER TEXT

All characters, which are put between vertical brackets, will be transmitted together.

If you need to decrease transmitting speed, use this character «<», to increase speed use «>». Speed change step 5 wpm, e.g.

#### ANY TEXT>TEXT+5WPM<TEXT-5WPM>>>TEXT+15WPM

Text commands may contain reserved characters, that is why they should be replaced with the other characters, which will be converted back on the server end:

- 1. Character «:» should be replaced with «^»;
- 2. Character «,» should be replaced with «~»;
- **3.** Character «;» should be replaced with «\*».

Command to send macros looks like:

```
cw_macros:arg1,arg2;
arg1 - periodic number of the software transceiver;
arg2 - text to be sent before the callsign;
To send this line «+5wpmTU -5wpmRA6LH +10wpm599 004 SK» the command will be:
cw_macros:0,>TU <RA6LH >>599 004 |SK/;
```

Command to send CW message with opportunity to send callsign twice or to enter full callsign in the middle of transmission:

```
cw_msg:arg1,arg2,arg3,arg4;
arg1 - periodic number of the software transceiver;
arg2 - text before callsign;
arg3 - callsign;
arg4 - text after callsign;

Example:
To transmit «TU RA6LH 599 004» command will be:
cw_msg:0,TU,RA6LH,599 004;
If you need to repeat the callsign «TU RA6LH RA6LH 599 004», command will be:
cw_msg:0,TU,RA6LH$2,599 004;
If there is no text before callsign «RA6LH RA6LH 599 004», instead of text use special character "_":
```

If while sending the message you don't know full callsign and you'll need to add it (send it again), probably not once, command will be: cw\_msg:arg1;

Example:

```
cw_msg:0,_,RA6$2,599 004;
```

cw\_msg:0,\_,RA6LH\$2,599 004;

### cw\_msg:RA6L;

## cw\_msg:RA6LH;

If callsign "addition" was late, it came through after callsign transmission was finished, then this command is ignored.

Also, TCI supports order of transmitted CW messages, if you'll enter several cw\_msg commands one-by-one, they will be transmitted one-by-one, in this case callsign addition will be applied to currently sent callsign.

Commands is divided on three types:

- Read only;
- Read/Write;
- Write only.

## List of commands:

VFO_LIMITS	Receiver's frequency tuning limits	
Set		Arguments:
Read	To be sent after connection;	
Answer	VFO_LIMITS:arg1,arg2;	arg1 — bottom frequency limit, Hz.
Type	Read only	
Example	VFO_LIMITS:10000,30000000;	arg2 — top frequency limit, Hz.

IF_LIMITS	IF filter frequency limits (in ESDR2	IF filter frequency limits (in ESDR2 only for VFOA)	
Set			
Read	To be sent after connection;	Arguments:	
Answer	IF_LIMITS:arg1,arg2;		
Type	Read only	<i>arg1</i> — bottom frequency limit, Hz.	
	IF_LIMITS:-48000,48000;		
Example		arg2 — top frequency limit, Hz.	
	IF_LIMITS:-96000,96000;		

TRX_COUNT	Number of receivers (transceivers) in the radio		
Set			
Read	To be sent after connection;	A	
Answer	TRX_COUNT:arg1;	Arguments:	
Type	Read only	and number of receivers/transcoivers (physical)	
Example	TRX_COUNT:2; TRX_COUNT:8;	arg I — number of receivers/transceivers (physical or software).	

CHANNEL_CO	CHANNEL_COUNT Number of additional receiver channels (slices) in one receiver (A/B/C)		
Set			
Read	To be sent after connection;		
Answer	CHANNEL_COUNT:arg1;	Arguments:	
Type	Read only		
	CHANNEL_COUNT:2;	<i>arg1</i> — number of receiver channels (slices).	
Example			
	CHANNEL_COUNT:3;		

DEVICE	Name of the device	Name of the device	
Set			
Read	To be sent after connection;		
Answer	DEVICE:arg1;	Arguments:	
Type	Read only		
	DEVICE:SunSDR2;	arg1 — name of the device.	
Example			
	DEVICE:ColibriDDC;		

RECEIVE_ONLY Determine device as a receiver or transceiver		
Set		
Read	To be sent after connection;	
Answer	RECEIVE_ONLY:arg1;	Arguments:
Type	Read only	
	RECEIVE_ONLY:true;	<i>arg1</i> — number of receive channels.
Example		
	RECEIVE_ONLY:false;	

MODULATIONS_LIST List of supported mode types			
Set			
Read	To be sent after connection;	Arguments:	
Answer	MODULATIONS LIST:arg1, arg2,,argN;		
Туре	Read only	Mode type to be sent as a name.	
	MODULATIONS_LIST:AM,LSB,USB,FM;		
Example			
	RECEIVE_ONLY:AM,SAM,LSB,USB,CW,NFM,WFM,	;	

TX_ENABLE	Permission to use transmitter	
Set		Arguments:
Read	To be sent while operating device	
Answer	TX_ENABLE:arg1, arg2;	arg1 — periodic number of receiver/transmitter.
Type	Read only	
Example	TX_ENABLE:0,true;	arg2 — transmission permitted (true)/transmission prohibited (false).

READY	To be sent after initialization commands while connecting	
Set		
Read	To be sent after connection;	
Answer	READY;	
Type	Read only	
Example		

TX_FOOTSWITCH	PTT footswitch signal	
Set	TX_FOOTCWITCH:arg1,arg2; Arguments:	
Type	Read only	
	TX_FOOTCWITCH:0,true;	arg1 — periodic number of receiver.
Example	TX FOOTCWITCH: 0 false:	arg2 — footswitch state (pressed (true), not pressed (false))

START	Start ExpertSDR2	
Set	START;	
Type	Read / Write	Arguments:
Example	START;	-

STOP	Stop ExpertSDR2	
Set	STOP;	
Type	Read / Write	Arguments:
Example	STOP;	

DDS	Tuning of the RX's center freque	Tuning of the RX's center frequency (center of the panorama)	
Set	RXFREQ:arg1,arg2;		
Read	RXFREQ:arg1;		
	RXFREQ:arg1,arg2;	Arguments:	
Answer			
		arg1 — receiver's periodic number.	
Type	Read / Write		
	RXFREQ:0,7200050;	arg2, arg5 — tuning frequency, Hz.	
Example			
	RXFREQ:1;		

IF	IF filter tuning in panorama bar	ndwidth
Set	IF:arg1,arg2,arg3;	A manyon and a
Read	IF:arg1,arg2;	Arguments:
Answer	IF:arg1,arg2,arg3;	gral receiver's periodic number
Type	Read / Write	arg I — receiver's periodic number.
	IF:0,0,-12000;	arg2 — channel's periodic number (A / B).
Example <i>IF:0,0,23000; IF:1,0;</i>	IF:0,0,23000;	Arg3 — new tuned frequency in respect to DDS
	<i>IF:1,0;</i>	(center of the panorama), Hz.

RIT_ENABLE	Enable RIT	
Set	RIT_ENABLE:arg1,arg2;	
Read	RIT_ENABLE:arg1;	
Answer	RIT_ENABLE:arg1,arg2;	Arguments:
Туре	Read / Write	
	RIT_ENABLE:0,true;	arg1 — receiver's periodic number.
Example	RIT_ENABLE:0,false; RIT_ENABLE:1;	arg2 — enable indicator.

MODULATION	Set mode type	
Set	MODULATION:arg1,arg2;	Arguments:
Read	MODULATION:arg1;	riguments.
Answer	MODULATION:arg1,arg2;	<i>arg1</i> — receiver's periodic number.
Type	Read / Write	
	MODULATION:0,LSB;	arg2 — mode type (line).
Example	MODULATION:0,CW;	List of supported mode types:
	MODULATION:1;	AM / SAM / DSB / LSB / USB / CW / NFM / WFM / SPEC / DIGL / DIGU / DRM

RX_ENABLE	Enable software receivers	
Set	RX_ENABLE:arg1,arg2;	
Read	RX_ENABLE:arg1;	
Answer	RX_ENABLE:arg1,arg2;	Arguments:
Type	Read / Write	
	RX_ENABLE:1,true;	<i>arg1</i> — receiver's periodic number.
Example	RX_ENABLE:2,false; RX_ENABLE:1;	arg2 — enable indicator.

XIT_ENABLE	Enable XIT	
Set	XIT_ENABLE:arg1,arg2;	
Read	XIT_ENABLE:arg1;	
Answer	XIT_ENABLE:arg1,arg2;	Arguments:
Туре	Read / Write	
	XIT_ENABLE:0,true;	arg1 — receiver's periodic number.
Example	XIT_ENABLE:0,false;	arg2 — enable indicator.
	XIT_ENABLE:1;	

SPLIT_ENABLE	Enable SPLIT mode	
Set	SPLIT_ENABLE:arg1,arg2;	
Read	SPLIT_ENABLE:arg1;	
Answer	SPLIT_ENABLE:arg1,arg2;	Arguments:
Type	Read / Write	
	SPLIT_ENABLE:0,true;	arg1 — receiver's periodic number.
	SPLIT_ENABLE:0,false; SPLIT_ENABLE:1;	arg2 — enable indicator.

RIT_OFFSET	Tune RIT offset	
Set	RIT_OFFSET:arg1,arg2;	
Read	RIT_OFFSET:arg1;	
Answer	RIT_OFFSET:arg1,arg2;	Arguments:
Type	Read / Write	
	RIT_OFFSET:0,500;	arg1 — receiver's periodic number.
Example	RIT_OFFSET:0,-200; RIT_OFFSET:1;	arg2 — offset frequency, Hz.

XIT_OFFSET	Tune XIT offset	
Set	XIT_OFFSET:arg1,arg2;	
Read	XIT_OFFSET:arg1;	
Answer	XIT_OFFSET:arg1,arg2;	Arguments:
Type	Read / Write	
	XIT_OFFSET:0,500;	arg1 — receiver's periodic number.
Example	XIT_OFFSET:0,-200; XIT_OFFSET:1;	arg2 — offset frequency, Hz.

RX_CHANNEL	Enable additional receive channels	
Set	RX_CHANNEL:arg1,arg2,arg3;	
Read	RX_CHANNEL:arg1,arg2;	Arguments:
Answer	RX_CHANNEL:arg1,arg2,arg3;	
Type	Read / Write	arg1 — receiver's periodic number.
	RX_CHANNEL:0,1,true;	
		arg2 — channel's periodic number.
Example	RX_CHANNEL:0,1,false;	
		<i>arg3</i> — enable indicator.
	RX_CHANNEL:1, 1;	

RX_FILTER_BAND	Adjust IF filter width	
Set	RX_FILTERL_BAND:arg1,arg2,arg3;	
Read	RX_FILTER_BAND:arg1,arg2;	Arguments:
Answer	RX_FILTER_BAND:arg1,arg2,arg3;	_
Type	Read / Write	arg1 — receiver's periodic number.
	RX_FILTER_BAND:0,30,2700;	
		arg1 — bottom frequency limit, Hz.
Example	RX_FILTER_BAND:0,-2900,-70;	
		arg2 — top frequency limit, Hz.
	RX_FILTER_BAND:1;	

RX_SMETER	Signal level (S-Meter) in filter bandwidt	th
Set	RX_SMETER:arg1,arg2,arg3;	
Read	RX_SMETER:arg1,arg2;	Arguments:
Answer	RX_SMETER:arg1,arg2,arg3;	
Type	Read / Write	arg1 — receiver's periodic number.
	RX_SMETER:0,0,-72;	
		arg2 — channel's periodic number.
Example	RX_SMETER:0,1,-63;	
		arg3 — signal level.
	RX_SMETER:1,0;	

CW_MACROS_SPEED Set CW speed for macros		
Set	CW_MACROS_SPEED:arg1;	
Read	CW_MACROS_SPEED;	
Answer	CW_MACROS_SPEED:arg1;	
Type	Read / Write	Arguments:
	CW_MACROS_SPEED:30;	CW and WDM
Example	CW_MACROS_SPEED:42;	arg1 — CW speed, WPM.
	CW_MACROS_SPEED;	

CW_MACROS_DELAY Set delay between "turn to TX" and "start of macros transmission"		
Set	CW_MACROS_DELAY:arg1;	
Read	CW_MACROS_DELAY;	
Answer	<pre>CW_MACROS_DELAY:arg1;</pre>	
Type	Read / Write	Arguments:
	CW_MACROS_DELAY:100;	
		<i>arg1</i> — delay before start of transmission, ms.
Example	CW_MACROS_DELAY:150;	
	CW_MACROS_DELAY;	

TRX	Switch between RX/TX modes	
Set	TRX:arg1,arg2, arg3;	
Read	TRX:arg1;	
Answer	TRX:arg1,arg2;	Argumenter
Type	Read / Write	Arguments:
	TRX:0,true;	arg1 — receiver's periodic number.
	TRX:0,true,mic;	arg2 — enable indicator.
Example	TRX:0,true,vac;	arg3 — source of the signal (unnecessary)
	TRX:0,false;	(mic – mic signal, vac – signal from VAC)
	TRX:1;	

For common use, the TRX command might have two arguments, in this case server will automatically determine the source of the input signal for transmission. When you select DIGL/DIGU modes the transceiver will automatically enable VAC and use the signal from it. In all other cases will be used signal from the mic. If you need to manually determine the source of the signal, you should use the third argument: mic – mic signal, vac – signal from VAC.

IQ_START	Start IQ signal output	
Set	IQ_START:arg1;	Arguments:
Type	Read / Write	
Example	IQ_START:0;	arg1 — receiver's periodic number.

IQ_STOP	Stop IQ signal output	
Set	IQ_STOP:arg1;	Arguments:
Type	Read / Write	
Example	IQ_STOP:0;	arg1 — receiver's periodic number.

IQ_SAMPLERATE Set IQ signal sample rate		
Set	IQ_SAMPLERATE:arg1;	
Read		Arguments:
Answer		
Туре	Read / Write	arg1 — sample rate, Hz.
	IQ_SAMPLERATE:48000;	
		Supported sample rates:
Example	IQ_SAMPLERATE:96000;	
		48 / 96 / 192 kHz
	IQ_SAMPLERATE:192000;	

SPOT	Send spot to ExpertSDR2 to display	
Set	SPOT:arg1,arg2,arg3,arg4;arg5	Arguments:
Read		
Answer		arg1 — callsign.
Type	Write only	
Example	SPOT:RN6LHF,CW,16711680,ANY_TEXT;	Arg4 — color ARGB.  Arg4 — additional text.
Color is coded	d with 32-bit characterless number 0x00FF0000 ->	· 16711680

SPOT_DELETE	Delete spot	
Set	SPOT:arg1;	Arguments:
Read		
Answer		arg1 — callsign.
Type	Write only	
Example	SPOT_DELETE:IT8TY;	

Reception of IQ signal happens via binary websocket connection, packet structure looks like this:

```
typedef struct
  quint32 receiver;
                        //!< receiver's periodic number
  quint32 sampleRate; //!< sample rate</pre>
                        //!< always equals 4 (float 32 bit)
  quint32 format;
  quint32 codec;
                        //!< compression algorithm (not implemented yet), always 0
                        //!< check sum (not implemented yet), always 0
  quint32 crc;
                        //!< length of data field
  quint32 length;
  quint32 type;
                        //!< type of data stream
  quint32 reserv[9];
                        //!< reserved
  float data[4096];
                        //!< data field
}DataStream;
```

Type of data stream is determined with the following numeration:

# List of software with TCI support:

```
- SDC
```

- LogHX

## Conclusion

TCI interface will gradually develop, in time it will be added with new commands and functionality. Follow the updates of TCI interface.