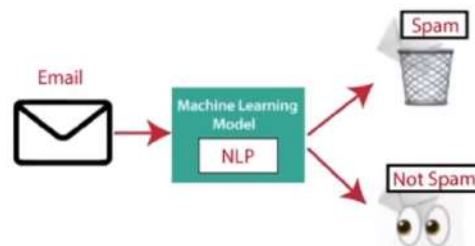


NLU vs NLG

NLU	NLG
NLU is the process of reading and interpreting language.	NLG is the process of writing or generating language.
It produces non-linguistic outputs from natural language inputs.	It produces constructing natural language outputs from non-linguistic inputs.

Applications of NLP

- Machine Translation
- Sentiment analysis
- Spelling correction
- Spam Detection
- Speech Recognition
- Chatbot



Role of NLP and Phases

- NLP help to communicate with intelligent system.
- Helps to control computer with voice commands.
- Helps human to communicate with machines.

- **Phases:**

- Lexical Analysis
- Syntactic Analysis
- Semantic Analysis
- Discourse Integration
- Pragmatic Analysis



Phases

1. Lexical Analysis:

- This is the first phase of NLP. This phase scans the source code as a stream of characters and converts it into meaningful lexemes. It divides the whole text into paragraphs, sentences, and words.

2. Syntactic Analysis:

- It is used to check grammar, word arrangements, and shows the relationship among the words.
- **Example:** Mumbai goes to the Delhi.
- In the real world, Agra goes to the Poonam, does not make any sense, so this sentence is rejected by the Syntactic analyzer.

Phases

3. Semantic Analysis:

- Concerned with the meaning representation. It mainly focuses on the literal meaning of words, phrases, and sentences.

4. Discourse Integration:

- It depends upon the sentences that precedes it and also invokes the meaning of the sentences that follow it.

5. Pragmatic Analysis:

- Pragmatic is the fifth and last phase of NLP. It helps you to discover the intended effect by applying a set of rules that characterize cooperative dialogues.
- **For Example:** "Open the door" is interpreted as a request instead of an order.

Machine translation

- Machine translation is the process of using artificial intelligence to automatically translate text from one language to another without human involvement.
- Modern machine translation goes beyond simple word-to-word translation to communicate the full meaning of the original language text in the target language.

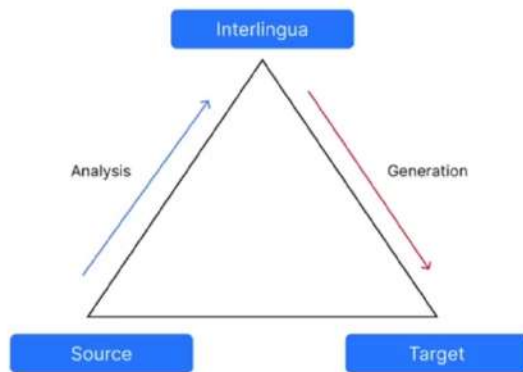
- **Types of MT Systems:**

- Bilingual MT System
- Multilingual MT System



Approaches Machine translation

- Direct MT Approach
- Interlingua Approach
- Transfer Approach
- Empirical MT Approach



Approaches Machine translation

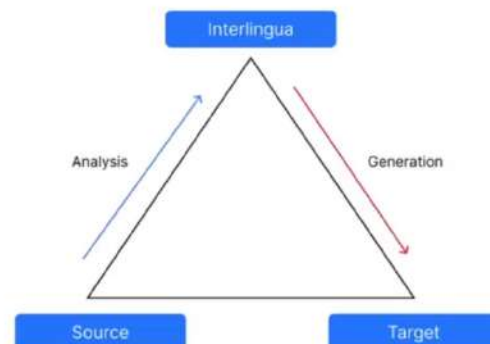
Direct MT Approach:

- It is less popular but the oldest approach of MT.
- SL to TL (directly).

SL → Source Language
TL → Target Language

Interlingua Approach:

- SL to IL called Interlingua
- Then translate IL to TL.



Approaches Machine translation

~~Transfer~~ Approach:

- 1st----> SL texts to abstract SL-oriented representations.
- 2nd---> SL-oriented representations to equivalent TL-oriented representations.
- 3rd----> Final text is generated.

Empirical MT Approach:

- This is an emerging approach for MT.
- It uses large amount of data.
- Raw data consists of the text and their translations.
- Analogy-based, example-based, memory machine translation techniques use empirical MT approach.

Process of Machine translation





Speech recognition

Speech recognition

- Speech recognition speech recognition is the process that enables a computer to recognize and responds to its spoken words and then convert them in a format that the machine understands.
- Speech recognition is widely used in digital assistants, smart speaker, smart homes and automation for a variety of services, products and solutions.



Algorithms for Speech recognition

- **Natural language processing(NLP)**
- **Hidden Markov models**
 - Markov chain model is useful for observable events such as text inputs.
 - Hidden Markov models allow us to incorporate hidden events, such as part of speech tags into a probabilistic model.
- **Neural networks**
 - A neural network is a series of algorithms that endeavors to recognize underlying relationships in a set of data through a process that mimics the way the human brain operates.
 - In this sense, neural networks refer to systems of neurons, either organic or artificial in nature.

Applications of Speech recognition

- Automotive
- Technology
- Healthcare
- Sale
- Security





Robot



Robot

- Robot are the artificial agents acting in real world environment.
- Robots are aimed at manipulating the objects by perceiving moving and doing repetitive functions without getting bored, distracted.

Robotics

- Robotics is a branch of AI which is composed of electrical engineering, mechanical engineering and computer science for designing, construction and application of robots.



Components of Robot

- Power supply
- Actuators
- Electric motors (AC/DC)
- Pneumatic air muscles
- Muscle wires
- Piezo Motors and ultrasonic motors
- Sensors.



Robot Locomotion and Types

- Locomotion is the mechanism that makes a robot capable of moving in its environment.
- **There are various types of locomotion:**
 - 1. Legged the locomotion
 - 2. Wheeled the locomotion
 - 3. Slip locomotion





Motion of Mobile Robot

Motion of Mobile Robot

- **Terrestrial:**
 - Terrestrial robots move on the ground.
 - Wheeled robots are most common type of robots in this category.
- **Airborne**
 - Robotic helicopters, robotically controlled parachutes have been deployed.
- **Aquatic**
 - This type of robots operates in water, either at the surface or underwater.
- **Space**
 - Robots are designed to operate in the microgravity of outer space, typically for space station maintenance.