

Generative AI and LLM

Flow-based generative models
Normalizing Flows
CS5202

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2/17/2026

Lecture Plan

- Flow-based generative models
 - Normalizing Flows

Flow-based generative models

- A flow-based generative models are constructed by a sequence of invertible transformations.

Flow based generative models

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Search Wikipedia

Search

8 languages

Contents

hide

(Top)

Method

Derivation of log likelihood

Training method

Variants

Planar Flow

Nonlinear Independent Components Estimation (NICE)

Real Non-Volume Preserving (Real NVP)

Generative Flow (Glow)

Masked Autoregressive Flow (MAF)

Continuous Normalizing Flow (CNF)

Flows on manifolds

Differential volume ratio

Flow-based generative model

ArticleTalk

ReadEditView historyTools

From Wikipedia, the free encyclopedia

A **flow-based generative model** is a **generative model** used in **machine learning** that explicitly models a **probability distribution** by leveraging **normalizing flow**,^{[1][2][3]} which is a statistical method using the **change-of-variable** law of probabilities to transform a simple distribution into a complex one.

The direct modeling of likelihood provides many advantages. For example, the negative log-likelihood can be directly computed and minimized as the **loss function**. Additionally, novel samples can be generated by sampling from the initial distribution, and applying the flow transformation.

In contrast, many alternative generative modeling methods, such as **variational autoencoders** (VAEs), **generative adversarial networks** (GANs), or diffusion models, do not explicitly represent the likelihood function.

Method

[edit]

Let z_0 be a (possibly multivariate) **random variable** with distribution $p_0(z_0)$.

For $i = 1, \dots, K$, let $z_i = f_i(z_{i-1})$ be a sequence of random variables transformed from z_0 . The functions f_1, \dots, f_K should be invertible, i.e. the **inverse function** f_i^{-1} exists. The final output z_K models the target distribution.

Part of a series on

Machine learning and data mining

Paradigms

[show]

Problems

[show]

Supervised learning

(classification • regression)

[show]

Clustering

[show]

Dimensionality reduction

[show]

Structured prediction

[show]

Anomaly detection

[show]

Neural networks

[show]

Reinforcement learning

[show]

Learning with humans

[show]

Model diagnostics

[show]

Mathematical foundations

[show]

Journals and conferences

[show]

Related articles

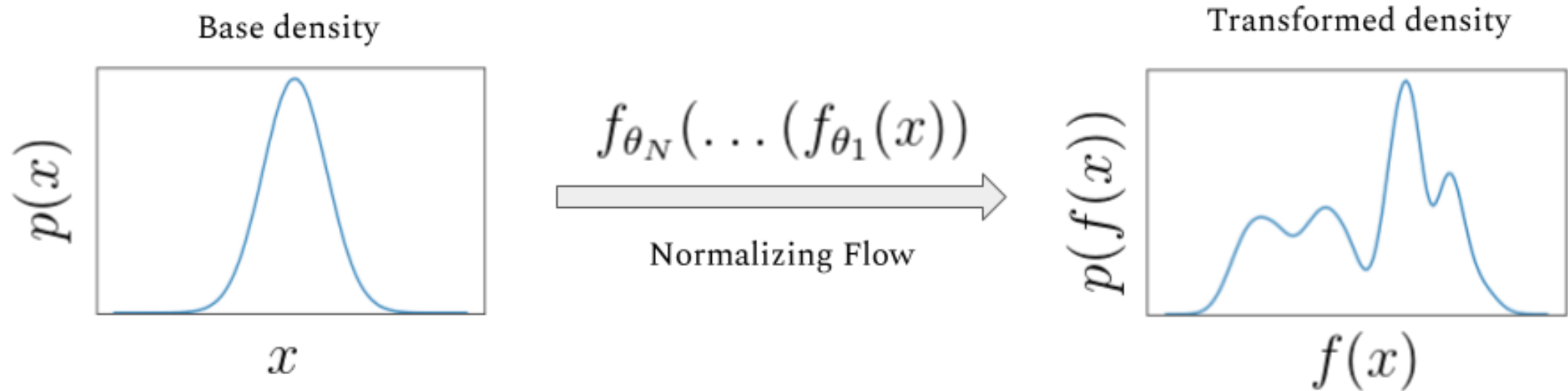
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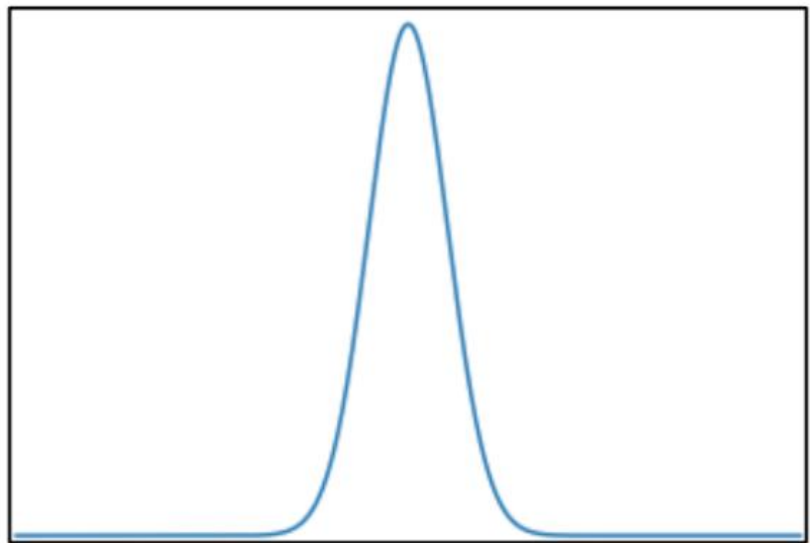
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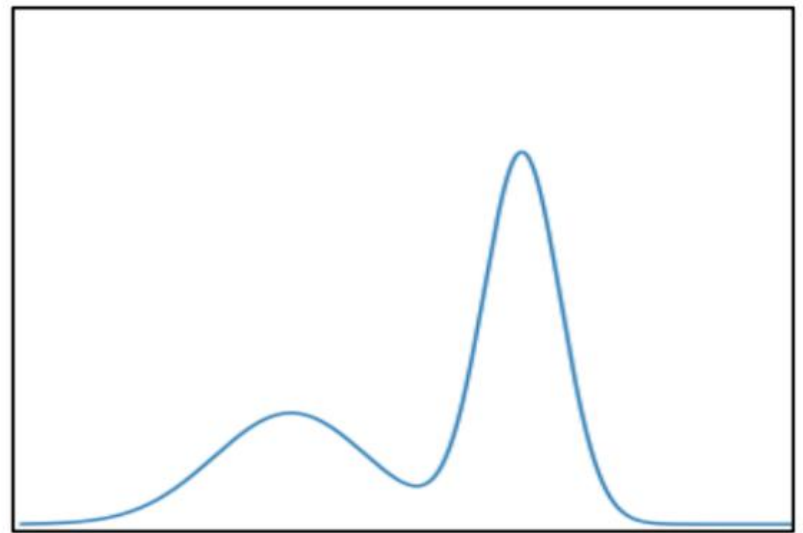
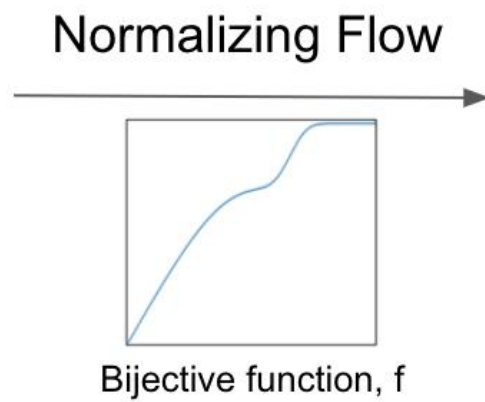
Normalizing flows

Normalizing flows learn an *invertible* mapping $f: X \rightarrow Z$, where X is our data distribution and Z is a chosen latent-distribution.



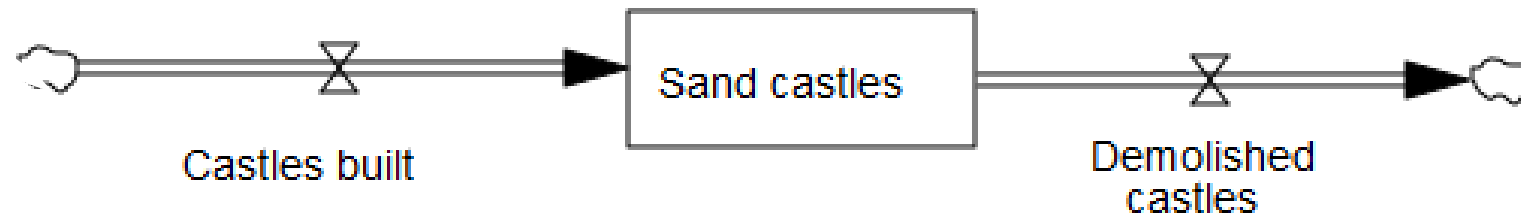


Base distribution, \mathbf{Z}



Target distribution, \mathbf{Y}

Normalizing flows



Sandcastles

How to create a sandcastle:

Step 1: Take a sandcastle

Step 2: Destroy the sandcastle

Step 3: Remember how you destroyed the sandcastle

Step 4: Reverse the process

Key Idea

Once you know how to reconstruct sandcastles, you can start with some different “sand”, apply this process, and end up with a different “sandcastle”



Why Normalizing Flows?

- NFs optimize the exact log-likelihood of the data, $\log(p_x)$
 - VAEs optimize the _____
 - GANs _____
- NFs infer exact latent-variable values z , which are useful for downstream tasks
 - The VAE infers a distribution over _____ values
 - GANs _____
- Potential for memory savings, with NFs gradient computations scaling constant to their depth
 - Both VAE's and GAN's gradient computations scale _____ to their depth
- NFs require only an encoder to be learned
 - VAEs require _____
 - GANs require _____

Why Normalizing Flows?

- **NFs optimize the exact log-likelihood of the data, $\log(p_x)$**
 - VAEs optimize the lower bound (ELBO)
 - GANs learn to fool a discriminator network
- **NFs infer exact latent-variable values z , which are useful for downstream tasks**
 - The VAE infers a distribution over latent-variable values
 - GANs do not have a latent-distribution
- **Potential for memory savings, with NFs gradient computations scaling constant to their depth**
 - Both VAE's and GAN's gradient computations scale linearly to their depth
- NFs require only an encoder to be learned
 - VAEs require encoder and decoder networks
 - GANs require generative and discriminative networks

How to ensure that we can reverse?

- Use invertible mapping

Bijjective function

- Normalizing flows require:
- **$f: X \rightarrow Z$**

to be **bijjective** because:

- You must go forward (data \rightarrow latent)
- You must go backward (latent \rightarrow data)

Linear algebra basics

- Jacobian
- Change of variables

Jacobian Matrix

2.1 Jacobian matrix

Given a function of mapping a n -dimensional input vector \mathbf{x} to a m -dimensional output vector, $\mathbf{f} : \mathbb{R}^n \mapsto \mathbb{R}^m$, the matrix of all first-order partial derivatives of this function is called the Jacobian matrix \mathbf{J} , where one entry on the i -th row and j -th column is $\mathbf{J}_{ij} = \frac{\partial f_i}{\partial x_j}$.

$$\mathbf{J} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \cdots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \cdots & \frac{\partial f_m}{\partial x_n} \end{bmatrix}$$

[Source: flow based deep generative models report.pdf](#)

Jacobian matrix

$$\mathbf{z} = g(\mathbf{a}) = f^{-1}(\mathbf{a})$$

$$\mathbf{J}_{\mathbf{a}} g(\mathbf{a}) = \begin{bmatrix} \frac{\partial z_1}{\partial a_1} & \dots & \frac{\partial z_1}{\partial a_K} \\ \vdots & & \vdots \\ \frac{\partial z_K}{\partial a_1} & \dots & \frac{\partial z_K}{\partial a_K} \end{bmatrix}$$

Change of variables theorem

2.2 Change of variable theorem

Given some random variable $z \sim \pi(z)$ and an invertible mapping $x = f(z)$ (i.e., $z = f^{-1}(x) = g(x)$). Then, the distribution of x is

$$p(x) = \pi(z) \left| \frac{dz}{dx} \right| = \pi(g(x)) \left| \frac{dg}{dx} \right|.$$

The multivariate version takes the following form:

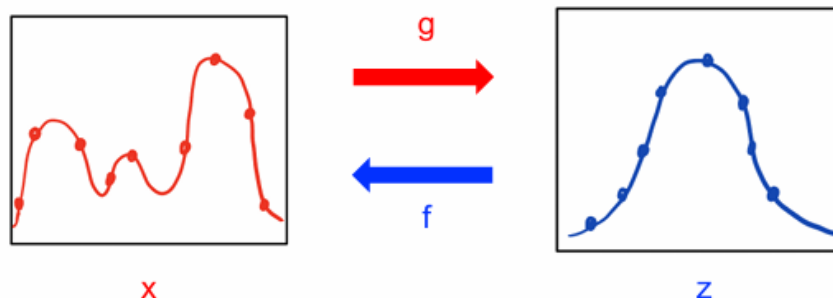
$$p(\mathbf{x}) = \pi(\mathbf{z}) \left| \det \frac{d\mathbf{z}}{d\mathbf{x}} \right| = \pi(g(\mathbf{x})) \left| \det \frac{dg}{d\mathbf{x}} \right|,$$

where $\det \frac{dg}{d\mathbf{x}}$ is the *Jacobian determinant* of g .

[Source: flow based deep generative models report.pdf](#)

Intuition/Math

Normalizing Flows – Log likelihood



Bijection (and invertibility) allow us to directly compute the likelihood:

$$\int p_x(x)dx = \int p_z(g(x))dz$$

In multiple dimensions,
we generalize to the
determinant of the
Jacobian

$$p_x(x) = p_z(g(x)) \left| \frac{dg(x)}{dx} \right| \rightarrow p_z(g(x)) |det. J(g(x))|$$

$$\log p_x(x) = \log p_z(g(x)) + \log |det. J(g(x))|$$

Intuitively

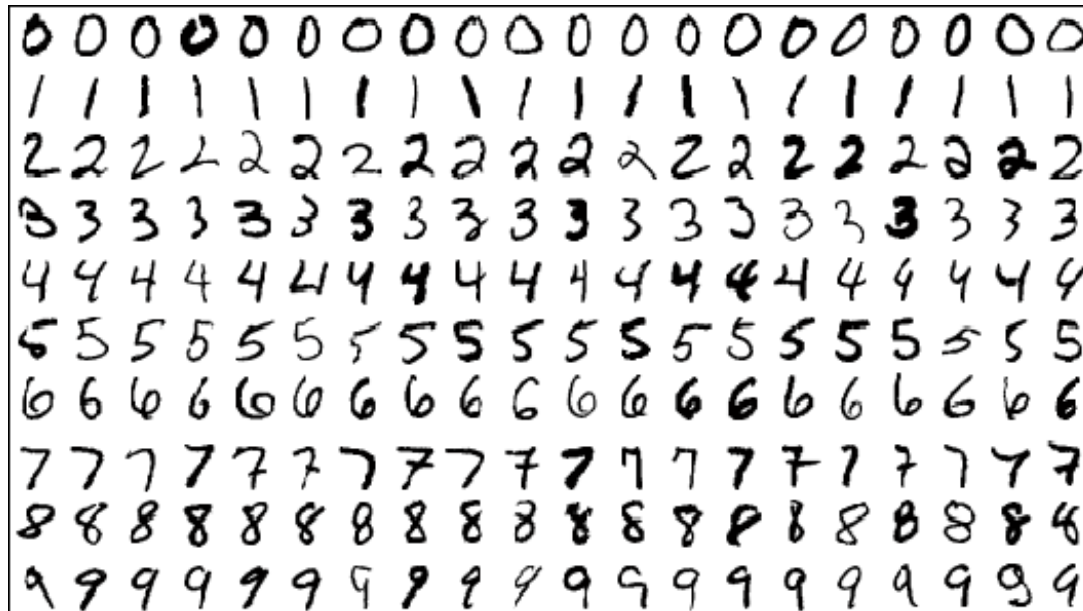
$z = g(x)$ determines
where a point in x -space
maps to z -space (where
to move grains of sand)

$|det. J(g(x))|$ describes
how much probability
mass (sand) gets moved
in a local neighborhood.

Math and Code

- [Going with the Flow: An Introduction to Normalizing Flows | Brennan Gebotys](#)

Implementation



[Tutorial 9: Normalizing Flows for Image Modeling — PyTorch Lightning 2.6.1 documentation](#)

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Downside of NFs

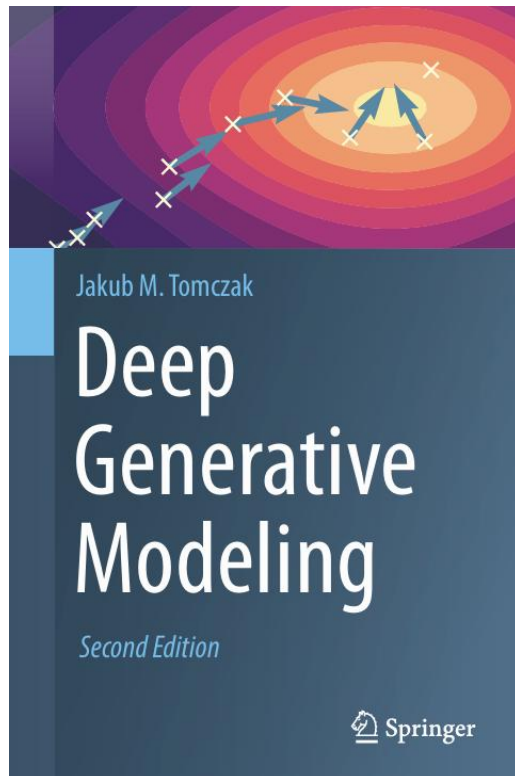
- The requirements of invertibility and efficient Jacobian calculations restrict model architecture
- NFs generative results are still behind VAEs and GANs

References

- https://hermandong.com/pdf/flow_based_deep_generative_models_report.pdf
- [Flow-based Deep Generative Models | Lil'Log](#)
- [Going with the Flow: An Introduction to Normalizing Flows | Brennan Gebotys](#)

Books and lecture notes

Deep Generative Modeling



GitHub

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