ML Term Project Report

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Decision Tree Algorithm:

根據 information gain 找到當前最好的 feature 去 split samples,分割完後再 recursively 的往左右的 child node 去找最好切割的 feature,並且設置停止條件,當深度達到 max depth 或當前 node 只有一種類別或當前 node 沒有 instances。

Implementation:

```
class Node:
    def __init__(self, feature=None, threshold=None, left=None, right=None, *, value=None)
        self.feature = feature
        self.threshold = threshold
        self.left = left
        self.right = right
        self.value = value

def is_leaf(self):
    return self.value is not None
```

is leaf 回傳 true or false 根據 node 的 value 是否為 None

```
class DecisionTree:
    def __init__(self, max_depth=None, min_samples_split=5, split_criterion="entropy"):
         self.max_depth = max_depth
         self.min_samples_split = min_samples_split
         self.split_criterion = split_criterion
         self.root = None
         self.classes = None
        self.deepest = 0
   def _build_tree(self, X, y, depth=0, parent_samples=0):
    self.n_samples, self.n_features = X.shape
       self.classes = len(np.unique(y))
       if(depth > self.deepest): self.deepest = depth
        # randomly select features to consider for split
       rnd_feats = np.random.choice(self.n_features, self.n_features, replace=False)
        # find best split based on selected features
       score, best_feat, best_thresh = self._best_split(X, y, rnd_feats)
         # Check if reach stop criteria
       if self._is_finished(depth, parent_samples) or score == 0:
           most_common_Label = np.argmax(np.bincount(y))
            return Node(value=most_common_Label)
        # create children nodes and continue building tree recursively
       left_idx, right_idx = self._create_split(X[:, best_feat], best_thresh)
       left_child = self._build_tree(X[left_idx, :], y[left_idx], depth + 1, self.n_samples)
       right_child = self._build_tree(X[right_idx, :], y[right_idx], depth + 1, self.n_samples)
       return Node(best_feat, best_thresh, left_child, right_child)
```

呼叫_best_split 找最好的 feature, threshold,再判斷是否觸碰到停止條件,若是則把當前 node 中最多 instances 的類別當作這個 node 的 class,若非則切割 instance 並繼續往左右 recursively _build_tree。

```
def _best_split(self, X, y, features):
    split = {'score':- 1, 'feat': None, 'thresh': None}

for feat in features:
    X_feat = X[:, feat]
    thresholds = np.unique(X_feat)
    for thresh in thresholds:
        score = self._information_gain(X_feat, y, thresh)

    if score > split['score']:
        split['score'] = score
        split['feat'] = feat
        split['thresh'] = thresh

return split['score'], split['feat'], split['thresh']
```

Loop 所有 features 和所有 features value 當作 threshold 去計算 information gain, 紀錄最佳的 infromation gain 所用的 feature 和 threshold

```
def _is_finished(self, depth, parent_samples):
    """Check if stop to grow or not."""
    if (self.max_depth is not None and depth >= self.max_depth
        or self.classes == 1
        or self.n_samples < self.min_samples_split
        or self.n_samples == parent_samples
        or self.n_samples == 0):
        return True
    return False</pre>
```

若深度達到最大深度、當前 node 只剩一個類別、當前 node 沒有 instance,或當前 node instances 和 parent node instances 一樣多就達到停止條件。

```
def _create_split(self, X, thresh):
    """Create a split in the data based on a given threshold."""
    left_idx = np.argwhere(X <= thresh).flatten()
    right_idx = np.argwhere(X > thresh).flatten()
    return left_idx, right_idx

def _split_criterion(self, y):
    proportions = np.bincount(y) / len(y)
    if(self.split_criterion == 'gini'):
        value = 1 - np.sum([p* pf or p in proportions if p > 0])
    else:
        value = -np.sum([p* np.log2(p) for p in proportions if p > 0])
    return value

def _information_gain(self, X, y, thresh):
    """Calculate the information gain from splitting on a given feature and threshold."""
    left_idx, right_idx = self._create_split(X, thresh)
    n, n_left, n_right = len(y), len(left_idx), len(right_idx)

if n_left == 0 or n_right == 0:
        return 0

parent_loss = self._split_criterion(y)
    child_loss = (n_left / n) * self._split_criterion(y[left_idx]) + (n_right / n) * self._split_criterion(y[right_idx])
    return parent_loss - child_loss
```

_create_split 根據 threshold 切割 instances

_split_criterion 根據 self.split_criterion 判斷計算 gini 或 entropy。

_information_gain 計算 parent node 和 child nodes 的 entropy 或 gini index 來計算 infromation gain

```
def fit(self, X, y):
    self.root = self._build_tree(X, y)

def _predict_one(self, x, node):
    if node.is_leaf():
        return node.value
    if x[node.feature] <= node.threshold:
            return self._predict_one(x, node.left)
        return self._predict_one(x, node.right)

def predict(self, X):
    return [self._predict_one(x, self.root) for x in X]

def getdeepest(self):
    return self.deepest</pre>
```

fit: 開始 build tree 並 assign root node。

_predict_one, predict: 根據預測傳進來的 instance feature 去走一遍 path 得到

prediction class •

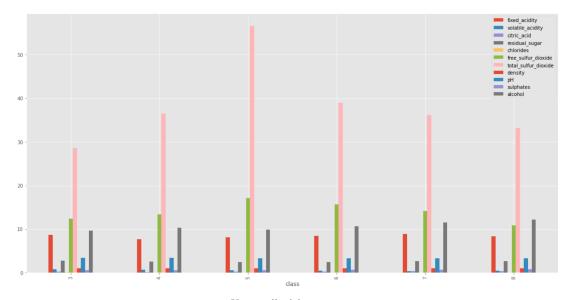
getdeepest: 回傳最深走到第幾層。

- Dataset 1

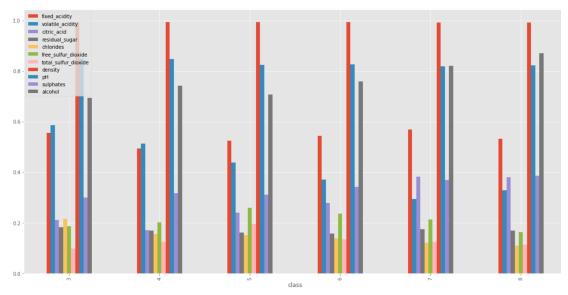
Data Preprocessing:

 Normalize Feature & Remove Outlier 使用 IQR, 把落在 upper bound 和 lower bound 外的 instance remove,但 因為資料本來就不多而且很不平衡,所以有額外設定 threshold 去決定 是否要 remove

2. Impute Missing Value 使用 KNN imputer 並根據距離去找最近的 5 個 neighbors 去補值



Unnormalized data



Normalized data

Experiment Result:

1. Without Data Preprocessing

train Accuracy: 0.7341153470185728 0 0 0 8 90 87 19 1] 0 0 2 7 85 83 25 3 Accuracy: 0.5414634146341464 6 53 25 1 2 26 47 8 0] 0] Classification Report: precision recall f1-score 0.00 0.00 0.61 0.54 0.53 0.40 0.45 0.50 accuracy eighted avg 0.54 205

2. Add Data Preprocessing

```
rain Accuracy: 0.8636363636363636
pred: [ 0 0 0 2 6 89 75 23 3]
label: [ 0 0 0 1 6 84 82 23 2]
Accuracy: 0.5353535353535354
Confusion Matrix:
                    0]
1]
      2 55 22
                    0]
            1 0
                               recall f1-score
               precision
                                                     support
                                 0.00
                                             0.00
                                 0.49
                      0.39
                                                          198
   macro avg
```

實驗發現即使做了 data preprocessing,prediction 也沒有取得明顯的進步,並且 也和沒做 data preprocessing 時一樣在 $0.48\sim0.64$ 的 accuracy,推測可能是 Data Preprocessing 做的不夠完整,可能有 irrelevent feature 之類的影響。也有使用迴圈去看不同 hyper parameter 的 performance,但基本上也只是在差不多的區間有 小小的浮動。

- Dataset 2

Data Preprocessing:

基於 demo 的 code,把 phrase 切成單字並移除 stop words(大量出現但不助於情感分析的單詞),再轉換成 one hot encoded 的 list 並 padding 成最長的 phrase。有移除 missing value 的資料。

Experiment Result:

```
Train Accuracy: 0.837590235990268
Accuracy: 0.5376852222667201
    409 390 210 89
534 1767 1530 421
    354 1851 8763 1556 209]
145 494 2114 2074 441]
43 130 290 597 413]
 lassification Report:
                     precision
                                          recall f1-score
                             0.28
                                            0.40
                                                            0.39
                                                                           4364
                             0.38
                                                                            1473
      accuracy
                                                                          24970
                             0.42
                                                            0.42
                                                                          24970
    macro avg
pred: [ 1485 4632 12907 4737 1209]
label: [ 1132 4364 12733 5268 1473]
```

這個 dataset 資料雖然比較充足,但也是不平衡,Accuracy 比上一個 dataset 浮動的要來的小很多,基本上都在 $0.52 \sim 0.54$ 的區間。

Conclusion:

雖然 dataset1 有做了滿多資料前處理,但 Accuracy 還是這麼低,不太確定問題是出在哪裡,或是可能這就是 DT 的極限(?)。至於 dataset2 我有點不太知道該怎麼進行處理所以就只有處理 missing value,原本有想要試試 random forest,但一直遇到各種 error,就放棄了。