

# LVS — Testnet Launch Plan (EN)

**Version 1.0 — Final, Developer & Investor Ready**

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## 1. Purpose of This Document

This document defines the **complete plan for launching the first LVS Testnet** — the point where LVS transitions from a theoretical system to a functioning distributed network.

It outlines: - technical milestones, - required components, - node implementation priorities, - network architecture, - deployment phases, - monitoring and evaluation, - success criteria.

This is the core roadmap for the first real LVS network.

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## 2. Overview of LVS Testnet

The LVS Testnet is a **public experimental network** designed to: - validate Drift-Based Consensus (DBC) under real-world conditions, - measure convergence across heterogeneous nodes, - evaluate network stability under noise, loss, and partial failures, - collect performance and behavior data, - onboard early developers and researchers.

This Testnet **does not carry financial value** and is purely for engineering validation.

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## 3. Testnet Architecture

The Testnet consists of three classes of nodes:

### 3.1 Browser Micro-Nodes (Primary)

- run in Chrome/Firefox/Edge/Safari,
- WebRTC communication,
- zero installation,
- ideal for mass participation.

### 3.2 Light Server Nodes (Optional)

- act as WebRTC signaling hubs,
- relay nodes for NAT-restricted peers,
- provide temporary storage for metrics.

### 3.3 Developer Nodes (Desktop / Server)

- Go or Rust implementation,
- used for stress tests and data logging.

The first Testnet must run **on browser micro-nodes**.

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## 4. Core Components Required for Testnet

The Testnet requires minimal but complete functionality.

### 4.1 Peer Discovery (WebRTC Signaling)

A signaling server provides initial session setup: - Node A announces presence, - Node B receives offer, - WebRTC DataChannel establishes direct peer link.

Technology: Node.js or Go signaling server.

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### 4.2 Message Layer

Each node must support two messages:

#### Entropy Packet (EP)

```
{  
  type: "ep",  
  entropy: [x, y],  
  ts: timestamp  
}
```

#### State Diff Message (SDM)

```
{  
  type: "sdm",  
  diff: [dx, dy],  
  w: weight  
}
```

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### 4.3 Drift Cycle Engine

Runs every **50-150 ms**: 1. Generate entropy 2. Collect diffs 3. Compute drift 4. Update state 5. Broadcast diff 6. Render node movement on screen

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## 4.4 Visualization Layer

A minimal UI to show: - node position (2D point), - drift direction, - peer connections, - entropy intensity.

This makes the Testnet **demonstrable**.

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## 5. Testnet Phases

The Testnet rollout is divided into three phases.

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### Phase 1 — Private Testnet (Internal)

#### Goal:

Validate core drift mechanics on 2-10 nodes.

#### Requirements:

- Browser node MVP
- Signaling server
- Basic UI
- Logging

#### Tests:

- entropy generation
- drift application
- pairwise convergence
- recovery after packet loss
- behavior under latency

#### Expected Output:

- drift cycle validation
- basic stability metrics

Timeline: **1-2 weeks**.

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### Phase 2 — Closed Public Testnet (Invite-Only)

#### Goal:

Test drift consensus across **50-200 nodes**.

### **Requirements:**

- optimized WebRTC mesh,
- diff throttling,
- improved UI,
- anomaly detection.

### **Tests:**

- convergence with large peer groups
- stability under random disconnects
- recovery from node churn
- multi-region latency

### **Expected Output:**

- convergence confirmation at medium scale
- performance baseline

Timeline: **3–6 weeks.**

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## **Phase 3 — Open Public Testnet (Global)**

### **Goal:**

Thousands of browser nodes connecting worldwide.

### **Requirements:**

- auto-scaling signaling layer (e.g., cloud)
- fault-tolerant message routing
- basic public dashboard
- versioned node builds

### **Tests:**

- global convergence behavior
- resilience under load
- survival during partial region outages
- measuring emergent patterns

### **Expected Output:**

- fully validated DBC behavior in the wild
- dataset for research paper #2

Timeline: **6–10 weeks.**

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## 6. Monitoring & Data Collection

The Testnet must collect minimal, anonymous metrics:  
- drift vector variance - node online/offline events  
- packet loss ratio - convergence speed - region-to-region latency impact

No personal data. No identity.

All metrics stored as aggregated floats.

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## 7. Security Considerations for Testnet

Even Testnet must enforce:  
- bounded drift, - clamped diffs, - anomaly rejection, - recovery mode.

This protects the network from runaway behavior.

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## 8. Testnet Deployment Infrastructure

Recommended minimal infrastructure:

### Signaling Servers (2-3 regions)

- EU
- US
- Asia

### Static Hosting

- github.io or Cloudflare Pages for browser client

### Monitoring Dashboard

- hosted on lvs.network/testnet

No blockchain nodes, no databases, no heavy infrastructure.

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## 9. People & Roles

Even if one person builds the prototype, Testnet implies roles:

- **Architect / Lead Developer** — node core, drift engine
- **Frontend Developer** — browser UI, visualization
- **Backend Engineer** — signaling server
- **Research / Metrics** — analysis of drift behavior

For now, this can be **one or two people**.

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## 10. Testnet Success Criteria

The Testnet is considered successful when:

- 1. 100+ nodes connect with no central authority**
- 2. Drift convergence is observed across the network**
- 3. System stabilizes under packet loss and latency**
- 4. No single node can dominate or disrupt consensus**
- 5. System recovers from partial network failures**
- 6. Metrics confirm stable behavior**

This proves the feasibility of LVS at scale.

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## 11. After Testnet — What Comes Next

After successful Testnet completion:

### 1. VaultGuard Full Implementation

Advanced invariants and anomaly models.

### 2. Sharding & Redundancy Layer

Distributed state reliability.

### 3. Node Diversity

Android/iOS micro-nodes, desktop nodes, server nodes.

### 4. Public Developer SDK

Libraries for JavaScript, Go, Rust.

### 5. Research Paper #2

Based on real Testnet data.

## **6. Mainnet Candidate Architecture**

Defines the global autonomous layer.

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## **12. Conclusion**

This Testnet Launch Plan defines the exact technical and operational pathway to bring LVS from prototype to a live distributed network.

With this roadmap, LVS is ready to transition from documents to reality — from theory to a functioning global autonomous value layer.