VS Wheel

Main.cpp

Thread 2 (HeartBeat)

Thread 1 (Joy. thread)

Thread 3 (PWM)

MSG: Ary.

Array is the data receive by report IN and contains FFB data

Ary.

Led on LPC

Motors.cpp

Call fct.

Call fct. Return Ary.

Multiplexor

Inputs.cpp

USBJoystick.cpp (Descriptor, send & read report)

Inputs Val

Inputs Val

To motor controller

Pots Value & Buttons Value

Pots Value & Buttons Value

USB

Computer

HID Protocol