Analyze of Schwarz algorithms for idealized ocean-atmosphere coupling

Tutor : Éric Blayo et Florian Lemarié

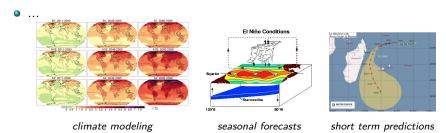
Sophie THERY

21/11/2017

General framework: ocean-atmosphere coupling

Physical phenomena governed by the ocean atmosphere interactions:

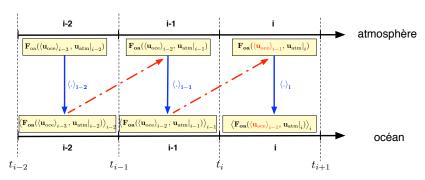
- climate
- El Niño
- tropical cyclones



Motivations

The current methods of oceans-atmospheres coupling are unsatisfactory :

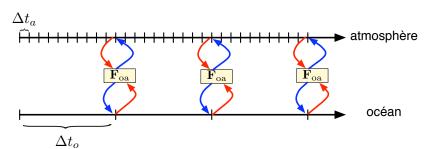
- Asynchrone coupling
 - Balance of the flows average on every window of time
 - problem of synchronisation



Motivations

The current methods of oceans-atmospheres coupling are unsatisfactory :

- Asynchrone coupling
- Synchrone coupling
 - ▶ lot of communication ⇒ inefficient implementation
 - problems of physical validity



Proposed solutions: Schwarz algorithms

Proof of concept: Simulation of the tropical cyclone Erica (2003):

ROMS : Oceanic model

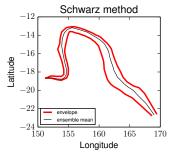
(Shchepetkin-McWilliams, 2005)

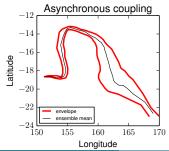
WRF : Atmospheric model

(Skamarock-Klemp, 2007)



Impact





 \Rightarrow Reduction of the uncertainty on the trajectory and the intensity of the cyclone.

Lemarié et al. 2014

Aim of the internship: Study of the convergence of the Schwarz algorithms on simplified ocean-atmosphere coupling

- Présentation du sujet
 - Modelling of the ocean atmosphere interaction
 - Schwarz algorithms
 - Description of the method: example without Coriolis effect
 - With Coriolis effect
- The instationary case
 - Convergence factor in the instationary case
 - Constant diffusion coefficients
 - Linear diffusion coefficients
 - Numerical results and optimisation
- What remains to be done
 - Phd



Navier-Stokes equations

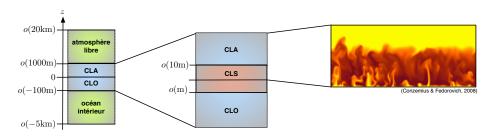
- Navier-Stokes equations
- Dominant physics : vertical axis (1d)

- Navier-Stokes equations
- Dominant physics : vertical axis (1d)
- Dominant terms

$$\begin{cases} \partial_t u - f v + \partial_z (w u) = \nu \partial_{zz}^2 u \\ \partial_t v + f u + \partial_z (w v) = \nu \partial_{zz}^2 v \end{cases}$$

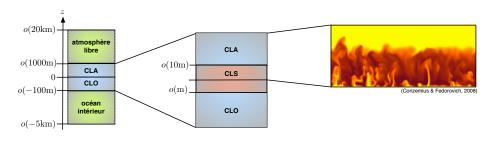
- \blacktriangleright (u, v, w) : speed
- ▶ z : altitude
- $\triangleright \nu$: mollecular diffusion
- f : Coriolis frequency

Simplified ocean atmosphere coupling model Small-scale turbulence parametrisation



Simplified ocean atmosphere coupling model

Small-scale turbulence parametrisation



⇒ Reynolds average

$$\begin{cases} \partial_t u - f v - \partial_z (D(z) \partial_z u) = F^u \\ \partial_t v + f u - \partial_z (D(z) \partial_z v) = F^v \end{cases}$$

with D(z) = az + b > 0,

Our model of study

Atmosphère

$$\begin{aligned} \mathcal{F}2(u_2) &= 0 \text{ in } \Omega_2 \\ \mathcal{G}_2(u_1) &= 0 \text{ on } \partial\Omega_2 \backslash \partial\Omega_1 \\ \mathcal{B}_2(\ u_2|_{\Gamma},\ u_1|_{\Gamma}) &= 0 \\ \hline \mathcal{B}_1(\ u_1|_{\Gamma},\ u_2|_{\Gamma}) &= 0 \end{aligned}$$

$$\mathcal{B}_1(\ u_1|_{\Gamma},\ u_2|_{\Gamma}) &= 0$$

$$\mathcal{G}_1(u_1) &= 0 \text{ on } \partial\Omega_1 \backslash \partial\Omega_2 \\ \mathcal{F}_1(u_1) &= 0 \text{ in } \Omega_1 \end{aligned}$$

Océan

Sur $\Omega_2 \times [0, T]$:

$$\begin{cases} \partial_t u_2 - fv_2 - \partial_z (D_2(z)\partial_z u_2) = F_2^u \\ \partial_t v_2 + fu_2 - \partial_z (D_2(z)\partial_z v_2) = F_2^v \end{cases}$$

Sur $\Omega_1 \times [0, T]$:

$$\begin{cases} \partial_t u_1 - fv_1 - \partial_z (D_1(z)\partial_z u_1) = F_1^u \\ \partial_t v_1 + fu_1 - \partial_z (D_1(z)\partial_z v_1) = F_1^v \end{cases}$$

- + initial conditions
- + outside conditions
- + interfaces conditions

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$$\mathcal{B}_2(u_2|_{\Gamma}, u_1|_{\Gamma}) &= 0$$

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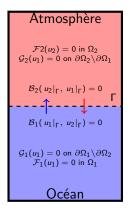
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Sur $\Omega_1 \times [0,\, \mathcal{T}]$:

$$\begin{cases} \partial_t u_1 - fv_1 - \partial_z (D_1(z)\partial_z u_1) = F_1^u \\ \partial_t v_1 + fu_1 - \partial_z (D_1(z)\partial_z v_1) = F_1^v \end{cases}$$

- + initial conditions
- + outside conditions
- + interfaces conditions
- \Rightarrow complexe values U = u + iv





$$\begin{cases} & \operatorname{Sur} \ \Omega_1 \times [0,T]: \\ & \partial_t U_1 + i f U_1 - \partial_z (D_1(z) \partial_z U_1) = \tilde{F}_1 \\ & \operatorname{Sur} \ \Omega_2 \times [0,T]: \\ & \partial_t U_2 + i f U_2 - \partial_z (D_2(z) \partial_z U_2) = \tilde{F}_2 \\ & + \operatorname{Conditions initiales} \\ & + \operatorname{Conditions au limites extérieurs} \\ & + \operatorname{Conditions d'interfaces} \end{cases}$$

Théorie de couche limite :

$$D_j(z) = a_j z + b_j > 0$$

Schwarz algorithms

Algorithm 1 Schwarz algorithms

Require:
$$u_2^0$$
 sur Γ

$$n = 0$$

while non convergence ou $n < n_{max}$ **do**

solve

$$\begin{cases} \mathcal{L}_1 u_1^n = f_1 & \text{sur } \Omega_1, \\ \mathcal{G}_1 u_1^n = g_1 & \text{sur } \partial \Omega_1^{ext}, \\ \mathcal{B}_1 u_1^n = \mathcal{B}_1 u_2^{n-1} & \text{sur } \Gamma. \end{cases}$$

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end while

State of the art

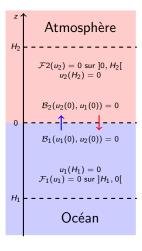
		Coefficients de diffusion constants	Coefficients de diffusion affines
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Aim of the internship: Study of the convergence of the Schwarz algorithms on simplified ocean-atmosphere coupling

We focus on two questions

- How the coriolis effect impact the convergence of the algorithm ?
- How "freeze" the diffusion coefficient by a constant impact the convergence ?

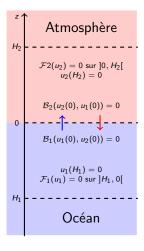
System verified by the errors



• On each area:

$$\begin{cases}
-\partial_z(D_j(z)\partial_z u_j^n(z)) = F_j^u & \text{on } \Omega_j \\
u_j^n(H_j) = G_j \\
\mathcal{B}_j u_j^n(0) = \mathcal{B}_j u_k^{n-1}(0)
\end{cases}$$

System verified by the errors



On each area:

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\end{cases}$$

System verified by the errors :

$$e_j^n(z) = u_j^n(z) - u_j^*(z)$$

$$\begin{cases}
-\partial_z(D_j(z)\partial_z e_j^n(z)) = 0 & \text{sur } \Omega_j \\
e_j^n 1(H_j) = 0 \\
\mathcal{B}_j e_i^n(0) = \mathcal{B}_j e_k^{n-1}(0)
\end{cases}$$

Definition of the convergence factor:

$$\rho = \frac{||e_j^n||}{||e_j^{n-1}||}$$

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Study of the convergence :

- \bullet If $\rho < 1$ then the algorithm converge.
- If $\rho \geq 1$ then the algorithm do not converge.

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Method for the stationary case :

ullet Solve probleme without interface conditions \Rightarrow $e_j^n(z) = C_j^n \; ilde{e}_j(z)$

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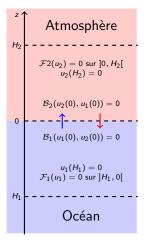
Method for the stationary case :

- Solve probleme without interface conditions $\Rightarrow e_j^n(z) = C_j^n \ \tilde{e}_j(z)$
- Convergence factor: $\rho = \left| \frac{C_j^n}{C_i^{n-1}} \right|$

Where C_i^n is determined by the interface conditions.



Dirichlet-Neumann conditions



Dirichlet-Neumann interface conditions : exemple without Coriolis effect

$$\begin{cases}
-\partial_{z}(D_{j}(z)\partial_{z}e_{1}^{n}(z)) &= 0 \\
& \text{sur }]H_{1}, 0[\\
e_{1}^{n}(H_{1}) &= 0 \\
e_{1}^{n}(0) &= e_{2}^{n-1}(0) \end{cases}$$

$$\begin{cases}
-\partial_{z}(D_{j}(z)\partial_{z}e_{2}^{n}(z)) &= 0 \\
& \text{sur }]0, H_{2}[\\
e_{2}^{n}(H_{2}) &= 0 \\
D_{2}(0)\partial_{z}e_{2}^{n}(0) &= D_{1}(0)\partial_{z}e_{1}^{n}(0)
\end{cases}$$

$$ho_{0,DN} = rac{\int_{\Omega_2} (D_2(z))^{-1} dz}{\int_{\Omega_1} (D_1(z))^{-1} dz}$$



$$\rho_{0,DN} = \frac{\int_{\Omega_2} (D_2(z))^{-1} dz}{\int_{\Omega_1} (D_1(z))^{-1} dz}$$

- depends on D_i on all the area.
- $D_j(z)$ is not necessary constant.

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- depends on D_i on all the area.
- $D_i(z)$ is not necessary constant.
- particular case :

$$D_j(z) = constant$$

$$\rho_{0,DN}^{cst} = \frac{H_2 D_1}{H_1 D_2}$$

$$D_j(z) = a_j z + b_j$$
:

$$\rho_{0,DN}^{var} = \frac{a_1}{a_2} \frac{\ln(1 + H_2 \frac{a_2}{b_2})}{\ln(1 + H_1 \frac{a_1}{b_1})}$$

Study of the convergence with Coriolis effect

		Coefficients de diffusion constants	Coefficients de diffusion affines
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With Coriolis effect

System to solve :

$$\begin{cases} ife_1^n(z) - \partial_z(D_1(z)\partial_z e_1^n(z)) &= 0 & \text{sur }]H_1, 0[\\ e_1^n(H_1) &= 0 \\ e_1^n(0) &= e_2^{n-1}(0) \end{cases}$$

$$\begin{cases} ife_2^n(z) - \partial_z(D_2(z)\partial_z e_2^n(z)) &= 0 & \text{sur }]0, H_2[\\ e_2^n(H_2) &= 0 \\ D_2(0)\partial_z e_2^n(0) &= D_1(0)\partial_z e_1^n(0) \end{cases}$$

- with $D_j = \text{constant} \Rightarrow \text{well known solutions}$
- with $D_j = a_j z + b_j > 0$

With Coriolis effect

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- with $D_i = \text{constant} \Rightarrow \text{well known solutions}$
- with $D_i = a_i z + b_i > 0$

Bessel's equation

$$z\partial_{zz}^2 u + (2\alpha - 2\beta\nu + 1)z\partial_z u + (\beta^2\gamma^2z^{2\beta} + \alpha(\alpha - 2\beta\nu))u = 0$$

• $D_j = \text{constant}$:

$$ho_{DN}^{cst} = \sqrt{rac{D_1}{D_2}} \left| rac{ anh(H_2 \lambda_2)}{ anh(H_1 \lambda_1)}
ight|$$

with
$$\lambda_j = \sqrt{i \frac{f}{D_j}}$$
 and $f \neq 0$.

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with
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 and $f \neq 0$.

• $D_j = a_j z + b_j$:

$$\rho_{DN}^{var} = \sqrt{\frac{D_1(0)}{D_2(0)}} \left| \frac{I_0(\mu_2(H_2))K_0(\mu_2(0)) - K_0(\mu_2(H_2))I_0(\mu_2(0))}{I_0(\mu_1(H_1))K_0(\mu_1(0)) - K_0(\mu_1(H_1))I_0(\mu_1(0))} \right| \\
\times \left| \frac{I_0(\mu_1(H_1))K_1(\mu_1(0)) + K_0(\mu_1(H_1))I_1(\mu_1(0))}{I_0(\mu_2(H_2))K_1(\mu_2(0)) + K_0(\mu_2(H_2))I_1(\mu_2(0))} \right|$$

with
$$\mu_j(z) = 2\sqrt{\frac{if}{a_j}\left(z + \frac{b_j}{a_j}\right)}$$

Summary of the stationary case

		Coefficients de diffusion constants	Coefficients de diffusion affines
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Plan

- Présentation du sujet
- The instationary case
 - Convergence factor in the instationary case
 - Constant diffusion coefficients
 - Linear diffusion coefficients
 - Numerical results and optimisation
- What remains to be done

Study of the convergence in the instationary case

$$\begin{cases} \partial_t e_j^n(t,z) + \textit{if} e_j^n(t,z) - \partial_z (D(z) \partial_z e_j^n(t,z)) &= 0 & \text{sur }]0, T[\times \Omega_j \\ e_j^n(t,H_j) &= 0 & \text{sur }]0, T[\\ \mathcal{B} e_j^n(t,0) &= \mathcal{B} e_k^n(0) & \text{sur }]0, T[\\ e_j^n(0,z) &= 0 & \text{sur } \Omega_j \end{cases}$$

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Fourier transform on the time

$$\hat{u}(\omega,z) = \int_{-\infty}^{\infty} u(t,z)e^{-i\omega t}dt$$
, with $\omega \in \mathbb{R}$



Study of the convergence in the instationary case

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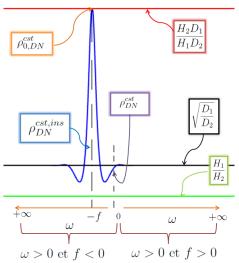
Fourier transform on the time

$$\hat{u}(\omega,z)=\int_{-\infty}^{\infty}u(t,z)\mathrm{e}^{-i\omega t}dt$$
, with $\omega\in\mathbb{R}$

$$\begin{cases} i(f+\omega)\hat{\mathbf{e}}_{j}^{n}(\omega,z) - \partial_{z}(D(z)\partial_{z}\hat{\mathbf{e}}_{j}^{n}(\omega,z)) &= 0 \\ \hat{\mathbf{e}}_{j}^{n}(\omega,H_{j}) &= 0 \\ \mathcal{B}\hat{\mathbf{e}}_{j}^{n}(\omega,0) &= \mathcal{B}_{j}\hat{\mathbf{e}}_{k}^{n}(\omega,0) \end{cases}$$

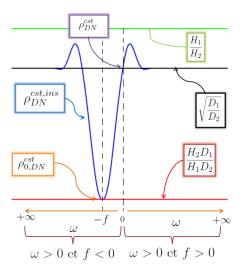
 \Rightarrow Stationary case equations with $f \rightarrow f + \omega$

Convergence factor in instationary case with Coriolis effect, with Dirichlet-Neumann conditions:



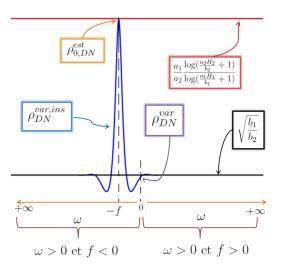
If
$$ho_{0,DN}^{\mathit{var}} \geq \sqrt{rac{b_1}{b_2}}$$

Facteur de convergence pour le cas instationnaire, des coefficients affines et conditions de Dirichlet-Neumann



If
$$\rho_{0,DN}^{var} \le \sqrt{\frac{b_1}{b_2}}$$

Convergence factor in instationary case with Coriolis effect, with Dirichlet-Neumann conditions:

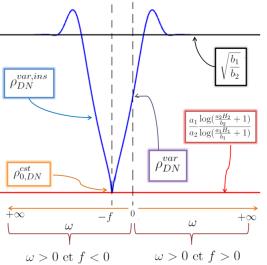


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Convergence factor in instationary case with Coriolis effect, with Dirichlet-Neumann conditions:



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ullet approximations linear diffusion coefficient o constant diffusion coefficients ?

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Elements of answer in the report :

- ▶ convergence ↔ no convergence
- typical values for ocean-atmosphere coupling : results are close.

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- ightharpoonup convergence \leftrightarrow no convergence
- typical values for ocean-atmosphere coupling: results are close.
- Interpretation of the disymmetry of the convergence factor following the sign of f ?

Elements of answer in the report:

Comparison between theoretical et numerical results.

Questions:

 approximations linear diffusion coefficient → constant diffusion coefficients ?

Elements of answer in the report :

- ightharpoonup convergence \leftrightarrow no convergence
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- Interpretation of the disymmetry of the convergence factor following the sign of f?

Elements of answer in the report:

Comparison between theoretical et numerical results.

• How can we optimize the convergence ?



Numerical results

- No disymetries between f < 0 et f > 0.
- When $\omega << |f|$ or $\omega >> |f|$ theoretical results and numerical results are consistant.
- When $\omega \approx |f|$: dispersion of the numerical results.

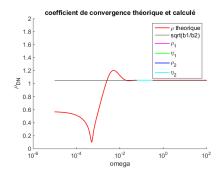


Figure: Theoretical and numerical convergence factor, f < 0

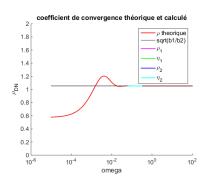


Figure: Theoretical and numerical convergence factor, f > 0

31 / 34

Numerical results

- No disymetries between f < 0 et f > 0.
- When $\omega << |f|$ or $\omega >> |f|$ theoretical results and numerical results are consistant.
- When $\omega \approx |f|$: dispersion of the numerical results.

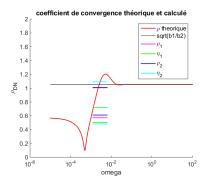


Figure: Theoretical and numerical convergence factor, f < 0

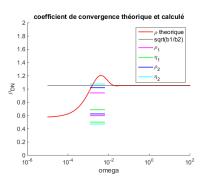


Figure: Theoretical and numerical convergence factor, f > 0

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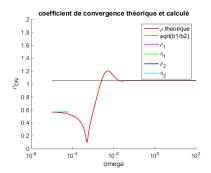


Figure: Theoretical and numerical convergence factor, f < 0

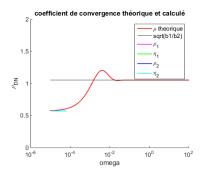


Figure: Theoretical and numerical convergence factor, f > 0

Optimisation

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- Easy to determinate in the stationary case.
- In the instationary case, a numerical method can calculate "good" Robin coefficients.
- Could we be help by the optimal coefficients from the stationary case to find better coefficient in the instationary case ?

During the Phd

- More realistic models.
 - ⇒ more complicated interface conditions.
- Link with Charles's thesis.
- Realistic applications in collaboration with climatologists



Thanks