

Model Checking Real-Time Systems

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1. Timed Automata

1.1 Preliminaries

1.2 Timed Automata

1.3 Regions and zones

1.4 Extensions

2. Model Checking Real-Time Systems

2.1 TLTL

2.2 Timed Games

3. Language-Theoretic Properties

4. References

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Set of *time values*: $\mathbb{R}_{\geq 0}$

Timed words over $\Sigma \times \mathbb{R}_{\geq 0}$

Set of *valuations* over a set of clocks C : $\mathbb{R}_{\geq 0}^C$

Constraints over C : $\varphi ::= x \odot k \mid \varphi \wedge \varphi$ where $x \in C$, $k \in \mathbb{Z}$ and $\odot \in \{<, \leq, =, \geq, >\}$

Set of valuations *satisfying* φ : $\llbracket \varphi \rrbracket_C = \{v \in \mathbb{R}_{\geq 0}^C \mid v \models \varphi\}$

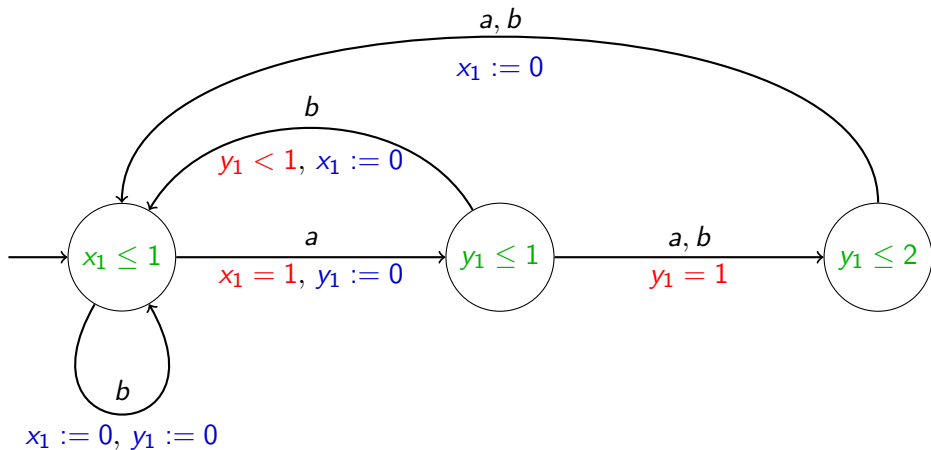
Definition 1

A *Timed Automaton* (TA) \mathcal{A} is the tuple $(L, \ell_0, C, \Sigma, I, E)$ where:

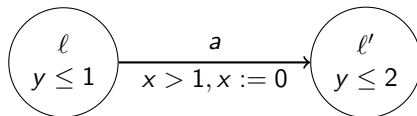
- L is a finite set of *locations* with initial location $\ell_0 \in L$
- C is a finite set of *clocks*
- Σ is a finite set of *actions*
- $I: L \rightarrow \Phi(C)$ is an *invariant mapping*
- $E \subseteq L \times \Phi(C) \times \Sigma \times 2^C \times L$ is a set of edges.

Edges are denoted by $\ell \xrightarrow{\varphi, a, r} \ell'$.

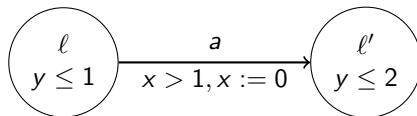
Example of a TA with 3 locations, 2 clocks and 2 actions (letters):



Operational Semantics

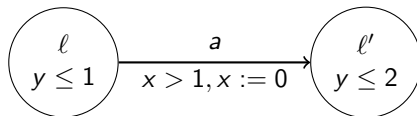


Operational Semantics



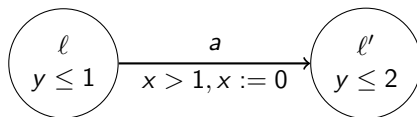
$$\begin{cases} v(x) = 1.2 \\ v(y) = 0.8 \end{cases}$$

Operational Semantics



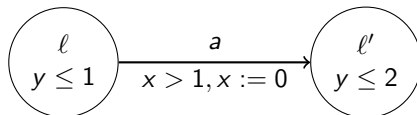
$$\begin{cases} v(x) = 1.2 \\ v(y) = 0.8 \end{cases} \quad (\ell, v) \xrightarrow{0.5, a} (\ell', v')$$

Operational Semantics

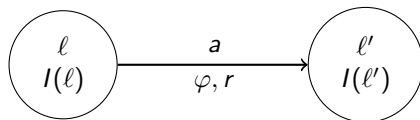


$$\left\{ \begin{array}{l} v(x) = 1.2 \\ v(y) = 0.8 \end{array} \right. \quad (\ell, v) \xrightarrow{0.5, a} (\ell', v') \quad \left\{ \begin{array}{l} v'(x) = 0 \\ v'(y) = 1.3 \end{array} \right.$$

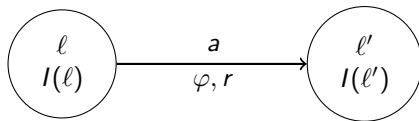
Operational Semantics



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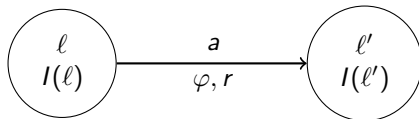


Operational Semantics



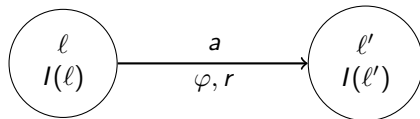
$$(\ell, v) \xrightarrow{d, a} (\ell', v')$$

Operational Semantics



$$(\ell, v) \xrightarrow{d, a} (\ell', (v + d)[r])$$

Operational Semantics



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provided that:

$\ell \xrightarrow{\varphi, a, r} \ell'$ is a transition in the TA

$$\forall t \in [0, d], v + t \models I(\ell)$$

$$v + d \models I(\ell')$$

Operational Semantics

Definition 2

The *operational semantics* of a TA $A = (L, \ell_0, C, \Sigma, I, E)$ is the infinite-state timed transition system $\llbracket A \rrbracket = (S, s_0, \Sigma \times \mathbb{R}_{\geq 0}, T)$, where

$$S := \{(\ell, v) \in L \times \mathbb{R}_{\geq 0}^C \mid v \models I(\ell)\}, \quad s_0 := (\ell_0, \mathbf{0}_C),$$

$$T := \{(\ell, v) \xrightarrow{d, a} (\ell', (v + d)[r]) \mid d \in \mathbb{R}_{\geq 0},$$

$$\forall d' \in [0, d], v + d' \models I(\ell) \wedge \exists \ell' \xrightarrow{\varphi, a, r} \ell' \in E, v + d \models \varphi\}$$

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Region Equivalence

Definition 3

Two valuations $v, v' \in \mathbb{R}_{\geq 0}^C$ are region equivalent, i.e. $v \cong_M v'$ iff:

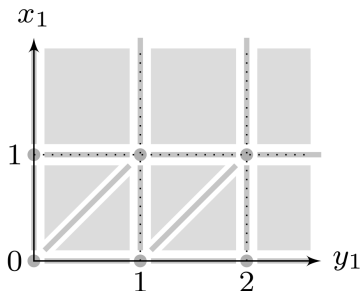
- $\forall x \in C, \lfloor v(x) \rfloor = \lfloor v'(x) \rfloor \vee v(x), v'(x) > M_x$
- $\forall x \in C, \langle v(x) \rangle = 0 \Leftrightarrow \langle v'(x) \rangle = 0 \vee v(x) \geq M_x$
- $\forall x, y \in C, \langle v(x) \rangle \leq \langle v(y) \rangle \Leftrightarrow \langle v'(x) \rangle \leq \langle v'(y) \rangle \vee v(x) > M_x \vee v(y) > M_y$

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- $\forall x, y \in C, \langle v(x) \rangle \leq \langle v(y) \rangle \Leftrightarrow \langle v'(x) \rangle \leq \langle v'(y) \rangle \vee v(x) > M_x \vee v(y) > M_y$



Definition 4 (Region Automaton)

$\mathcal{R}_{\cong_M}(A) = (S, s_0, \Sigma, T)$ is the *region automaton* of A , where:

- $S := (L \times \mathbb{R}_{\geq 0}^C) / \cong_M$, $s_0 := \mathbf{0}_C$
- $T := \{[\ell, v]_{\cong_M} \xrightarrow{a} [\ell', v']_{\cong_M} \mid \exists d \in \mathbb{R}_{\geq 0}, (\ell, v) \xrightarrow{d, a} (\ell', v')\}$

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- $T := \{[\ell, v]_{\cong_M} \xrightarrow{a} [\ell', v']_{\cong_M} \mid \exists d \in \mathbb{R}_{\geq 0}, (\ell, v) \xrightarrow{d, a} (\ell', v')\}$
- $|S|$ is exponential in the number of clocks and in the maximal constants of the timed automaton
- Is there a way to reduce the number of states?

Definition 5 (Zone)

A set of valuations $Z \subseteq \mathbb{R}_{\geq 0}^C$ is a zone iff: $\exists \varphi \in \Phi_d(C), Z = \llbracket \varphi \rrbracket_C$

In this case, we define:

- the *delay* of Z : $Z^\uparrow \triangleq \{v + d \mid v \in Z \wedge d \in \mathbb{R}_{\geq 0}\}$
- the *reset* of Z : $Z[r] \triangleq \{v[r] \mid v \in Z\}$ for $r \subseteq C$

Definition 6 (Zone automaton)

The *zone automaton* $\llbracket A \rrbracket_Z$ of A is the tuple $(S, s_0, \Sigma \cup \{\delta\}, T)$, where:

$$S := \{(\ell, Z) \mid \ell \in L, Z \in \mathbb{R}_{\geq 0}^C \text{ is a zone}\}, \quad s_0 := (\ell_0, \llbracket \mathbf{0}_C \rrbracket)$$

$$T := \{(\ell, Z) \xrightarrow{\delta} (\ell', Z^\uparrow \cap \llbracket I(\ell') \rrbracket_C)\} \cup \\ \{(\ell, Z) \xrightarrow{a} (\ell', (Z \cap \llbracket I(\ell) \rrbracket_C)[r] \cap \llbracket I(\ell') \rrbracket_C) \mid \ell \xrightarrow{\varphi, a, r} \ell' \in E\}$$

References