

# Model Checking Real-Time Systems

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# 1. Timed Automata

## 1.1 Preliminaries

## 1.2 Timed Automata

## 1.3 Regions and zones

## 1.4 Extensions

# 2. Model Checking Real-Time Systems

## 2.1 Timed Temporal Logic

## 2.2 Some results

## 2.3 Timed Games

# 3. Language-Theoretic Properties

# 4. References

Set of *time values*:  $\mathbb{R}_{\geq 0}$

*Timed words* over  $\Sigma \times \mathbb{R}_{\geq 0}$

Set of *valuations* over a set of clocks  $C$ :  $\mathbb{R}_{\geq 0}^C$

*Constraints* over  $C$ :  $\varphi ::= x \odot k \mid \varphi \wedge \varphi$  where  $x \in C$ ,  $k \in \mathbb{Z}$  and  $\odot \in \{<, \leq, =, \geq, >\}$

Set of valuations *satisfying*  $\varphi$ :  $\llbracket \varphi \rrbracket_C = \{v \in \mathbb{R}_{\geq 0}^C \mid v \models \varphi\}$

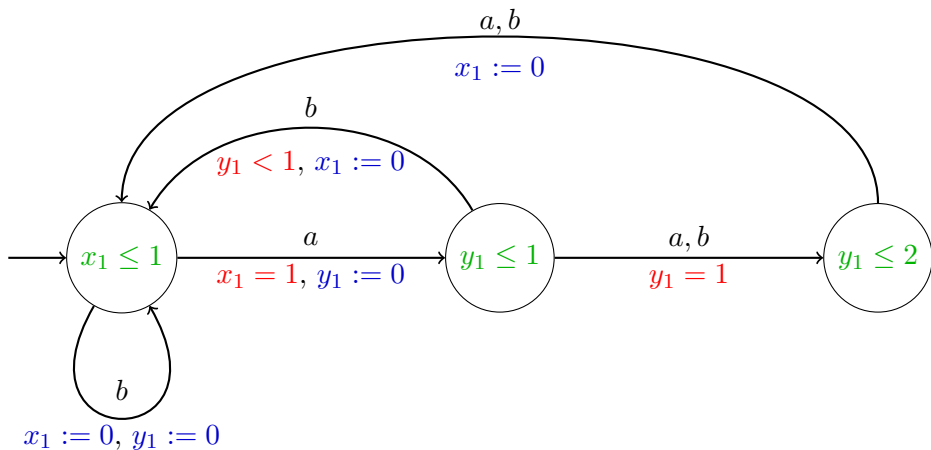
## Definition 1

A *Timed Automaton* (TA)  $\mathcal{A}$  is the tuple  $(L, \ell_0, C, \Sigma, I, E)$  where:

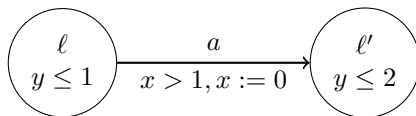
- $L$  is a finite set of *locations* with initial location  $\ell_0 \in L$
- $C$  is a finite set of *clocks*
- $\Sigma$  is a finite set of *actions*
- $I: L \rightarrow \Phi(C)$  is an *invariant mapping*
- $E \subseteq L \times \Phi(C) \times \Sigma \times 2^C \times L$  is a set of edges.

Edges are denoted by  $\ell \xrightarrow{\varphi, a, r} \ell'$ .

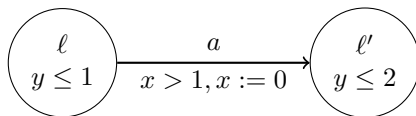
Example of a TA with 3 locations, 2 clocks and 2 actions (letters):



# Operational Semantics

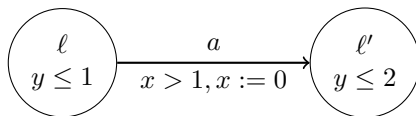


# Operational Semantics



$$\begin{cases} v(x) = 1.2 \\ v(y) = 0.8 \end{cases}$$

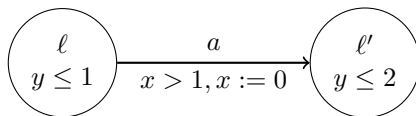
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$$\begin{cases} v(x) = 1.2 \\ v(y) = 0.8 \end{cases} \quad (\ell, v) \xrightarrow{0.5, a} (\ell', v')$$

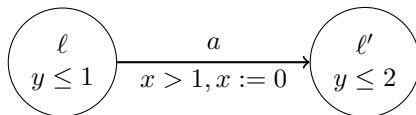


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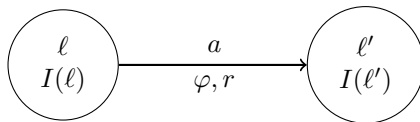


$$\left\{ \begin{array}{l} v(x) = 1.2 \\ v(y) = 0.8 \end{array} \right. \quad (\ell, v) \xrightarrow{0.5, a} (\ell', v') \quad \left\{ \begin{array}{l} v'(x) = 0 \\ v'(y) = 1.3 \end{array} \right.$$

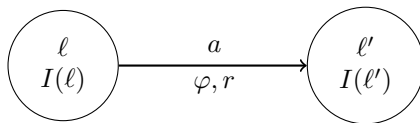
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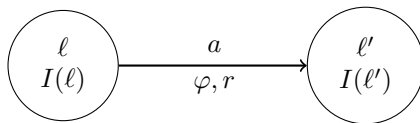


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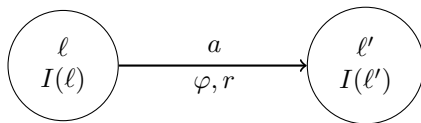
$$(\ell, v) \xrightarrow{d, a} (\ell', v')$$

# Operational Semantics



$$(\ell, v) \xrightarrow{d, a} (\ell', (v + d)[r])$$

# Operational Semantics



$$(\ell, v) \xrightarrow{d, a} (\ell', (v + d)[r])$$

provided that:

$\ell \xrightarrow{\varphi, a, r} \ell'$  is a transition in the TA

$$\forall t \in [0, d], \quad v + t \models I(\ell)$$

$$v + d \models I(\ell')$$

# Operational Semantics

## Definition 2

The *operational semantics* of a TA  $A = (L, \ell_0, C, \Sigma, I, E)$  is the infinite-state timed transition system  $\llbracket A \rrbracket = (S, s_0, \Sigma \times \mathbb{R}_{\geq 0}, T)$ , where

$$S := \{(\ell, v) \in L \times \mathbb{R}_{\geq 0}^C \mid v \models I(\ell)\}, \quad s_0 := (\ell_0, \mathbf{0}_C),$$

$$T := \{(\ell, v) \xrightarrow{d, a} (\ell', (v + d)[r]) \mid d \in \mathbb{R}_{\geq 0},$$

$$\forall d' \in [0, d], v + d' \models I(\ell) \wedge \exists \ell' \xrightarrow{\varphi, a, r} \ell' \in E, v + d \models \varphi\}$$

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# Region Equivalence

## Definition 3

Two valuations  $v, v' \in \mathbb{R}_{\geq 0}^C$  are region equivalent, i.e.  $v \cong_M v'$  iff:

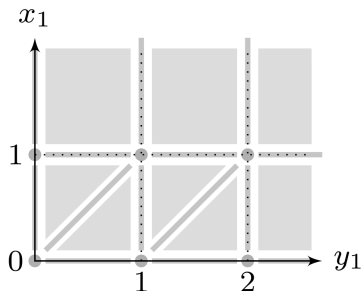
- $\forall x \in C, \lfloor v(x) \rfloor = \lfloor v'(x) \rfloor \vee v(x), v'(x) > M_x$
- $\forall x \in C, \langle v(x) \rangle = 0 \Leftrightarrow \langle v'(x) \rangle = 0 \vee v(x) \geq M_x$
- $\forall x, y \in C, \langle v(x) \rangle \leq \langle v(y) \rangle \Leftrightarrow \langle v'(x) \rangle \leq \langle v'(y) \rangle \vee v(x) > M_x \vee v(y) > M_y$

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- $\forall x, y \in C, \langle v(x) \rangle \leq \langle v(y) \rangle \Leftrightarrow \langle v'(x) \rangle \leq \langle v'(y) \rangle \vee v(x) > M_x \vee v(y) > M_y$



## Definition 4 (Region Automaton)

$\mathcal{R}_{\cong_M}(A) = (S, s_0, \Sigma, T)$  is the *region automaton* of  $A$ , where:

- $S := (L \times \mathbb{R}_{\geq 0}^C) / \cong_M$ ,  $s_0 := \mathbf{0}_C$
- $T := \{[\ell, v]_{\cong_M} \xrightarrow{a} [\ell', v']_{\cong_M} \mid \exists d \in \mathbb{R}_{\geq 0}, (\ell, v) \xrightarrow{d, a} (\ell', v')\}$

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- $T := \{[\ell, v]_{\cong_M} \xrightarrow{a} [\ell', v']_{\cong_M} \mid \exists d \in \mathbb{R}_{\geq 0}, (\ell, v) \xrightarrow{d, a} (\ell', v')\}$
- $|S|$  is exponential in the number of clocks and in the maximal constants of the timed automaton
- Is there a way to reduce the number of states?

## Definition 5 (Zone)

A set of valuations  $Z \subseteq \mathbb{R}_{\geq 0}^C$  is a zone iff:  $\exists \varphi \in \Phi_d(C), Z = \llbracket \varphi \rrbracket_C$

In this case, we define:

- the *delay* of  $Z$ :  $Z^\uparrow \triangleq \{v + d \mid v \in Z \wedge d \in \mathbb{R}_{\geq 0}\}$
- the *reset* of  $Z$ :  $Z[r] \triangleq \{v[r] \mid v \in Z\}$  for  $r \subseteq C$

## Definition 6 (Zone automaton)

The *zone automaton*  $\llbracket A \rrbracket_Z$  of  $A$  is the tuple  $(S, s_0, \Sigma \cup \{\delta\}, T)$ , where:

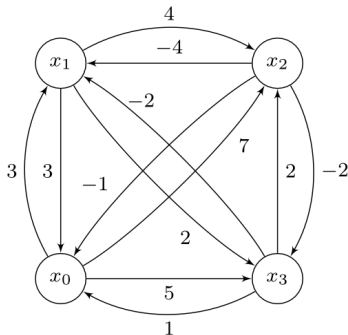
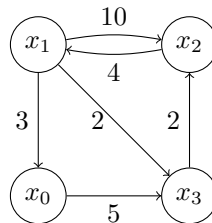
$$S := \{(\ell, Z) \mid \ell \in L, Z \in \mathbb{R}_{\geq 0}^C \text{ is a zone}\}, \quad s_0 := (\ell_0, \llbracket \mathbf{0}_C \rrbracket_C)$$

$$T := \{(\ell, Z) \xrightarrow{\delta} (\ell, Z^\uparrow \cap \llbracket I(\ell) \rrbracket_C)\} \cup$$

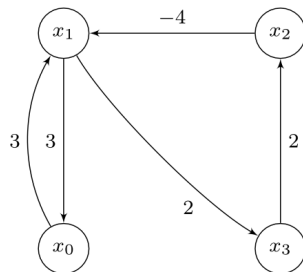
$$\{(\ell, Z) \xrightarrow{a} (\ell', (Z \cap \llbracket \varphi \rrbracket_C)[r] \cap \llbracket I(\ell') \rrbracket_C) \mid \ell \xrightarrow{\varphi, a, r} \ell' \in E\}$$

→ Normalisation ( $\simeq$  quotienting), shortest-path-closed DBM extrapolation

$$Z = \begin{cases} x_1 & \leq 3 \\ x_1 - x_2 & \leq 10 \\ x_1 - x_2 & \geq 4 \\ x_1 - x_3 & \leq 2 \\ x_3 - x_2 & \leq 2 \\ x_3 & \geq -5 \end{cases}$$



Shortest-path closure



Shortest-path reduction

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## Decidable extensions:

- *diagonal constraints*:  $x - y \odot k$
- *updatable TA*: clocks can be reset to any natural number ( $x := k \in \mathbb{Z}$ ) or can be synchronized with another clock ( $x := y$ )
- *urgency constraints*: some locations must be left immediately

## Undecidable extensions:

- *linear constraints*:  $\lambda x + \mu y \leq k$
- updates such as  $x := x + k$  or  $x :> k$  (non-determinism)
- *stopwatch automata*
- *hybrid automata*
- ...



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- updates such as  $x := x + k$  or  $x :=> k$  (non-determinism)
- *stopwatch automata*
- *hybrid automata*
- pretty much everything else you can think of

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## Definition 7 (Metric Temporal Logic)

Given a set of atomic propositions  $P$ , the formulas of MTL are defined for any time interval  $I$  with the *time-constrained until* operator  $\mathbf{U}_I$  as follows:

$$\varphi ::= p \in P \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \mathbf{U}_I \varphi$$

The *constrained always*  $\Box_I$  and *constrained eventually*  $\Diamond_I$  operators can be defined with  $\mathbf{U}_I$  in a similar way as in LTL, namely:

$$\Diamond_I \varphi \triangleq \top \mathbf{U}_I \varphi$$

$$\Box_I \varphi \triangleq \neg \Diamond_I \neg \varphi$$

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What is  $\mathbf{U}_I$ ?!

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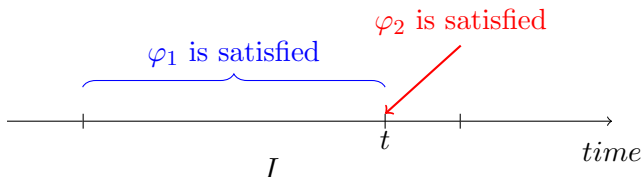
**What is  $\mathbf{U}_I$ ?! → give its semantics**

## Continuous semantics:

$$f \models \varphi_1 \mathbf{U}_I \varphi_2 \quad \text{iff} \quad \exists t \in I, f^t \models \varphi_2 \wedge \forall u \in (0, t), f^u \models \varphi_1$$

## Continuous semantics:

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**Pointwise semantics:** Let  $w = ((a_i, t_i))_{i \in \mathbb{N}}$  be a timed word over  $2^P$ .

$$w, i \models \varphi_1 \mathbf{U}_I \varphi_2 \quad \text{iff} \quad \exists i < j < |w|, \begin{cases} w, j \models \varphi_2 & \wedge \\ t_j - t_i \in I & \wedge \\ \forall i < k < j, w, k \models \varphi_1 \end{cases}$$

<Insert figure>



# References