Cartesian tree, also known as Treaps Theory and applications

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1 Some notations

- u, v, w some nodes of the binary search tree;
- parent(v) the parent of some node v in the binary search tree. If v is the root then parent(v) = NIL;
- left(v) left child of some node v in the binary search tree. If the left subtree is empty, then left(v) = NIL;
- right(v) right child of some node v in the binary search tree. If the right subtree is empty, then right(v) = NIL;
- key(v) the value of a node v that affects the tree structure;
- x(v) another way to denote keys in Cartesian trees. Usually, x(v) = key(v).
- y(v) some additional value associated with the node v and used to build the tree;
- subtree(v) the set of all nodes that lie inside the subtree of some node v (v is also included);
- size(v) the size of the subtree of some node v;
- $x_l(v)$ the minimum key in the subtree of the node v, that is:

$$x_l(v) = \min_{u \in subtree(v)} key(u)$$

• Same as $x_l(v)$ we define $x_r(v)$ as the maximum key in the subtree of the node v:

$$x_r(v) = \max_{u \in subtree(v)} key(u)$$

- depth(v) is the length of the path from root to v. depth(root) = 0.
- height(v) is the difference max(depth(u)) depth(v), where $u \in subtree(v)$.

2 Key points and definitions

- Greedy algorithm of finding an increasing subsequence: take first element that is greater than current, "left ladder". The expected length of the result on a random permutation is $O(\log n)$.
- BST stands for *binary search tree*, that is a binary rooted tree with some keys associated with every node, and the following two conditions hold:

$$key(u) < key(v), \forall u, v : u \in subtree(left(v))$$

and

$$key(u) > key(v), \forall u, v : u \in subtree(right(v))$$

- For any pair of nodes of any binary search tree v and u: $u \in subtree(v)$ if and only if $x_l(v) \leq key(u) \leq x_r(v)$
- For any tree and some keys stored in nodes of that tree we say that heap condition holds if for any v that is not the root:

$$key(parent(v)) \ge key(v)$$

- Binary search tree of size n is balanced if it's height is $O(\log n)$.
- Cartesian tree or treap is a balanced binary search tree, where each node is assigned some random values y(v), which satisfy to the heap condition. Hereafter we will treat y(v) as a random permutation.
- Cartesian tree is uniquely determined by a set of pairs (x_i, y_i) , such that all x_i are pairwise distinct and all y_i are pairwise distinct.
- Node v is an ancestor of a node u if and only if for every $w \neq v$ such that $min(key(v), key(u)) \leq key(w) \leq max(key(v), key(u))$ it's y is smaller than the y of v, i.e. y(v) > y(w).
- Linear algorithm to build Cartesian tree having a sorted pairs using stack.
- The expected depth of an *i*-th node (in the order of left-right traversal) is

$$\sum_{j=0}^{j < n} \frac{1}{|j-i|+1} \le 2 \cdot \sum_{j=1}^{j \le n} \frac{1}{j} = O(\log n)$$

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3 Some problems to think about

- Prove that if in merge operation one picks the root equiprobable (i.e. both l and r has probability 0.5 to become the root), the expected height is $\frac{n}{2}$.
- Prove that if in merge operation one picks the root proportional to the height (i.e. l has probability $\frac{height(l)}{height(l)+height(r)}$ to become the root), the expected height is \sqrt{n} .
- Prove that it's impossible to build Cartesian tree in linear time if the set of keys is not-sorted.
- Prove that it's impossible to merge two Cartesian trees of size n in o(n) time, if there are no guarantees on key ranges.
- What is the expected height of the tree if we pick y's as integers in range from 0 to p? Consider the case p = 1 first.
- Can you prove $O(\log n)$ expectation for height(root)?

4 Operations with treaps and some pseudocode snippets

```
Tree find(Tree a, Key v)
    if a == NIL then
        return NIL
    if x(a) == v then
        return a
    else if x(a) < v then
        return find(right(a), v)
    else
        return find(left(a), v)
Tree merge(Tree a, Tree b)
    if a == NIL then return b
    if b == NIL then return a
    if y(a) < y(b) then
        right(a) = merge(right(a), b)
        return a
    else
        left(b) = merge(a, left(b))
        return b
```

• Why is it incorrect to write left(b) = merge(left(b), a)?

• Note that x(v) is not used in merge

```
pair<Tree, Tree> split(Tree a, Key s) // first < s <= second
  if a == NIL then return (NIL, NIL)
  if x(a) < s then
     (u, v) = split(right(a), s)
     right(a) = u
     return (a, v)
  else
     (u, v) = split(left(a), s)
     left(a) = v
     return (u, a)</pre>
```

- What if we want first <= s < second?
- We can now insert a new value.

```
Tree insert(Tree a, Key nv) // assume nv not in a
   (u, v) = split(a, nv)
   Tree t = Tree(key = nv, y = random, left = right = NIL)
   u = merge(u, t)
   u = merge(u, v)
   return u
```

- Develop another version of insert that only uses one split and no merges. Hint: descend as searching for an element to insert, until you cannot go down because of heap property. Insert here.
- We can now remove a value.

```
Tree remove(Tree a, Key rv)
   (u, v) = split(a, rv)
   (NIL, v) = split(v, rv + 1)
   a = merge(u, v)
   return a
```

- Develop another version of remove that only uses one mege and no splits. Hint: find an element and remove it. What should we do with its children?
- How can we remove if we cannot consider rv + 1 (example: floating point numbers, strings)?
- Find the k-th element if we store subtree sizes (indexed from 0).

```
Tree find_kth(Tree a, int k)
  if size(left(a)) == k then
    return a
  else if size(left(a)) < k then
    return find(right(a), k - size(left(a)) - 1)
  else
    return find(left(a), k)</pre>
```

 \bullet We can also cut away the first k elements if we store subtree sizes.

```
pair<Tree, Tree> split_k(Tree a, int k) // size(first) = k
  if a == NIL then return (NIL, NIL) // assert k == 0
  if size(left(a)) >= k then
      (u, v) = split_k(left(a), k)
      left(a) = v
      return (u, a)
  else
      (u, v) = split(right(a), k - size(left(a)) - 1)
      right(a) = u
      return (a, v)
```

- Note that now both split_k and merge don't use x(v).
- We can make a similar functions that insert the element to the k-th position or remove the element from the k-th position.
- We can remove x(v) and store any z(v) instead. Now we get a data structure that supports the following operations:
 - maintain an array z[0..n-1]
 - set/get element z[i]
 - insert element after z[i]
 - remove element z[i]
 - concatenate two arrays
 - split array into two by cutting away the first k elements
- It is sometimes called a *rope*.