My name is Fu Chunjiang, I was born in Northern East of China. I studied in ECUST Shanghai for 6 years and Osaka Univeristy for 7 years. Recently I start to work in Honda Research Institute near Tokyo.



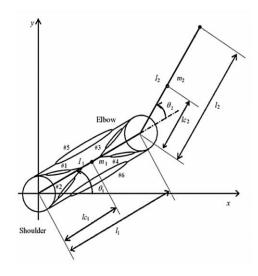




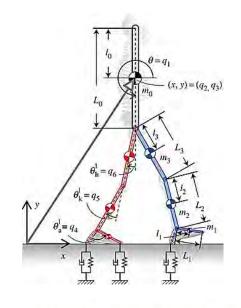
I did some research on human motor control, such as reaching movement impedance and optimal control, walking limit cycle stability and sitting perturbation.

Now I want to learn robotics.

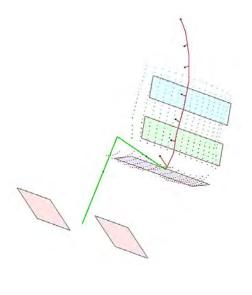
Reaching



Walking



Sitting





rsif.royalsocietypublishing.org

An intermittent control model of flexible human gait using a stable manifold of saddle-type unstable limit cycle dynamics

Chunjiang Fu¹, Yasuyuki Suzuki¹, Ken Kiyono¹, Pietro Morasso² and Taishin Nomura¹



