Bayes Al

Introduction: Al Today and in the Past. Probability and Bayes Rule

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SLide 1

Observation:
$$y_{t+1} = H\theta_{t+1} + v$$
; $v \sim N(0, V)$ (1)
Evolution: $\theta_{t+1} = f_{\phi}(\theta_t) + w$; $w \sim N(0, W)$ (2)