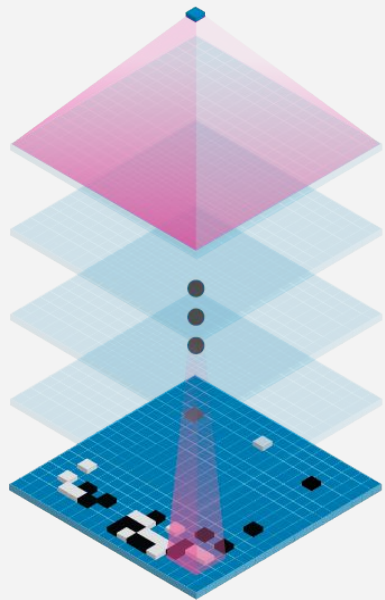


Evaluation



Position

$$v_{\theta}(s)$$



$\theta$

$s$