Vaibhav Raheja

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Education

University of Illinois Urbana-Champaign, *Masters Degree* 08/2023 - 12/2024
Major: Autonomy and Robotics CGPA: 3.77/4

NMIMS' MPSTME, *Bachelors Degree* 07/2017 - 06/2023
Major: Computer Engineering CGPA: 3.18/4

NMIMS' MPSTME, *Diploma Certificate* 07/2017 - 06/2023
Major: Computer Engineering

Work Experience

Intelligent Motion Laboratory, *Research Developer* 08/2023 - 12/2023

- Implemented FaceMesh, OpenFace 1.0, and DeepFace for face detection for a robotic eye exam.
- Developed head pose estimation techniques using ZED camera's depth tracking of facial features.
- Analyzed FaceMesh and OpenFace 1.0 face detection models for accuracy and adaptability in various scenarios.
- Designed and simulated a robotic arm, optimizing camera placement for effective 3D mapping.
- **Technologies Used:** Python, Robot Operating System (ROS), CAD.

All India Institute of Medical Sciences (AIIMS) Hospital, *Research Intern* 02/2021 - 05/2023

- Collaborated with a multidisciplinary team on the development and execution of a pioneering research project funded by the Indian Council of Medical Research (ICMR), resulting in a 15% reduction in surgery duration and a 20% increase in surgical precision.
- Played a pivotal role in the design and assembly of a custom 2-directional catheter and mouthpiece integrated with a camera system, contributing to successful intubation.
- **Technologies Used:** Python, 'xArm 5' robotic arm, Machine Learning, Robot Operating System (ROS), CAD.

Granuler: CIO Consulting, *Intern* 01/2020 – 05/2020

- Successfully implemented a CRM (Customer Relation Management) system using HubSpot CRM, streamlining workflow and increasing efficiency by 40% and Automated CEO's tasks using UiPath for Robotic Process Automation (RPA), resulting in at least 20% saving in resources.

Projects

Intelligent Ground Vehicle Competition (IGVC), | (*ROS, OpenCV, PID Control, Path Planning, CAD*)

- Managed a multidisciplinary team as Co-Captain for this international robotics competition held in Detroit, USA. As Co-Captain of Team D.A.R.V.I.N, we achieved impressive 2nd and 3rd place rankings in the highly competitive Cyber and Auto-Nav Challenge categories, demonstrating our excellence in autonomous vehicle navigation in challenging environments.

Autonomous Driving Car | (*Python, Path Planning, Vehicle Control, CARLA Simulator*)

- Engineered path planning and control algorithms for an autonomous racing car in the CARLA simulator. Implemented Hybrid A* search for waypoint navigation for racetracks.
- Implemented a Proportional-Derivative (PD) controller for real-time autonomy with obstacle avoidance and steering angle adjustments, speed, and braking, enhancing the car's efficient navigation through racetracks.

Soft Robotics Hand | (*Arduino, 3D Modelling and Printing*)

- Created a Soft Robotic Hand controlled by five individual stepper motors, enhancing dexterity and flexibility, with Arduino for control and 3D modeling and printing for construction.

Custom Surveillance Drone | (*Arduino, 3D Modelling and Printing, ESC Controller, Pix hawk*)

- Engineered a custom surveillance drone featuring a modular 3D-printed body and high-performance 1200KV BLDC motors, controlled via a Pix hawk Flight Controller and an ESC for motor control.

Skills

Programming: Python, C++, Robot Operating System(ROS), OpenCV, PyTorch, PID Controllers, Motion Planning algorithms, Machine Learning(ML), CNN

Tools: Autodesk Fusion 360, Computer Aided Design (CAD), Linux, Git, Arduino, Raspberry Pi

Publications

Raheja, Vaibhav et al. (Nov. 2022). "Multi-Disease Prediction System using Machine Learning". In: *International Conference on Futuristic Technologies (INCOFT)*. URL: https://ieeexplore.ieee.org/document/10094382.