Week_3

11.c

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
int stoi(char *str)
                     // converts string input to integer value
{
       int x;
       sscanf(str, "%d", &x);
       return x;
}
int find_index(int *A, int n)
       // finds the index of first element which is greater than the A[n-1] element
{
  int i=0:
  for(i=n-2; i>=0; i--)
              // i starts from the end i.e. i-2 as input array is in decreasing order
  {
       //printf("%d", i);
               if(A[i]>A[n-1])
              // when it finds that element is greater than A[n-1], it returns
                      return i:
       }
        return i;
                             // i returns the index at which our A[n-1] should be
placed
}
int main (int argc, char **argv)
       char line[128];
       char v1[15];
       char v2[15];
       char v3[15];
       int *A, n, temp, ind=0;
       fgets(line, sizeof line, stdin);
                                           // scans from standard input
       sscanf(line, "%s", v1);
                                           // v1 from the input line
```

```
n=stoi(v1);
                                           //converts v1 to integer
       //scanf("%d", &n);
       A = (int*)malloc(n*sizeof(int));
                                           // allocating size to array A
       for(int i=0;i< n;i++)
       {
                            // scanning the array values and putting into the array
  fgets(line, sizeof line, stdin);
  sscanf(line, "%s", v1);
  A[i] = stoi(v1);
       }
 // for(int i=0; i<n; i++)
       // scanf("%d", A+i);
                                   // finding index to insert at
       ind = find_index(A, n);
       //printf("index is:%d", ind);
       for(int i=n-1; i>ind+1; i--)
                            // switching the values uptill index+1 starting from n-1
       {
       temp = A[i];
       A[i]=A[i-1];
       A[i-1]=temp;
       }
       for(int i=0; i<n; i++)
                                   // printing the sorted array
       printf("%d\n", *(A+i));
                            // free up the memory allocated to A
       free(A);
       return 0;
}
Time complexity: O(n)
              Finds time to find index, same time for swapping the whole array.
Space complexity: O(n)
              For initializing array size increases with the size of n.
12.c
```

#include<stdio.h>

```
#include<stdlib.h>
#include <string.h>
                            // converts string input to integer value
int stoi(char *str)
{
       int x:
       sscanf(str, "%d", &x);
       return x;
}
void merge(int* ar1, int* ar2, int len1, int len2)
// takes two sorted arrays (pointer) as input and merge them and outputs one
sorted array.
{
  int i=0, j=0, k=0;
                            // making of array of size len1+len2
  int a[len1+len2];`
  while(i<len1 && j<len2)
                                   // loop until any one of the array is not empty
  {
               if(ar1[i]<=ar2[j])
                            // checking if array 2 has bigger element than array 1
              {
                             a[k] = ar1[i];
                     // if yes it stores the value of array 2 in the initialized array a
                             i++; k++;
               }
               else
                                   // else stores the value of array 1 in the array a
               {
                             a[k] = ar2[i];
                             j++;
                                    k++;
              }
  }
  while(i<len1)
                     // if array 2 got empty first , it will go untill array 1 is also empty
  {
                                   // stores the value of array 1 in the array a
               a[k] = ar1[i];
               i++; k++;
  }
  while(j<len2)
                     // if array 1 got empty first , it will go untill array 2 is also empty
  {
               a[k]= ar2[j]; // stores the value of array 2 in the array a
```

```
j++; k++;
  }
  // only one of the two while loops will run, as at least one of the arrays has to be
empty after the first while
  for(i=0; i<len1; i++)
                      // storing the sorted value of array a into array 1 and array 2
        ar1[i]=a[i];
  for(i=0; i<len2; i++)
        ar2[i]=a[i+len1];
}
int main (int argc, char **argv)
  char line[128];
  char v1[15];
  char v2[15];
  char v3[15];
  int *arr1, *arr2, n1, n2;
  fgets(line, sizeof line, stdin);
                                            // scans from standard input
  sscanf(line, "%s", v1);
                                            // v1 from the input line
                                            //converts v1 to integer
  n1=stoi(v1);
                                            // allocating memory to the array 1
  arr1 = (int *)malloc(n1*sizeof(int));
                                                     // takes the value into the array 1
          for(int i=0;i<n1;i++)
        fgets(line, sizeof line, stdin);
     sscanf(line, "%s", v1);
        arr1[i]= stoi(v1);
        }
        fgets(line, sizeof line, stdin);
        sscanf(line, "%s", v1);
        n2=stoi(v1);
                                             //scanf("%d", &n2);
  arr2 = (int*)malloc(n2*sizeof(int));
                                                    // allocating memory to the array 2
  for(int i=0;i<n2;i++)
                                                     // takes the value into the array 2
  {
        fgets(line, sizeof line, stdin);
     sscanf(line, "%s", v1);
```

Time Complexity: O(n)

Function merge takes O(n) time to execute. Rest the two loops in the main function also takes O(n) time to run.

Space Complexity: O(n)

Function merge takes O(n) space . It initializes array (a) of length n (len1+len2). As lengths of individual arrays increases it also increases linearly.

21.c

```
int heapSize=0;
void swap(int *x, int *y)
                     // takes two integer pointers and swap the value at their
location
  int temp;
  temp = *x;
  *x = *y;
  *y = temp;
      /* Fill in */
}
void minHeapify(int A[],int i)
// takes an index i of an array and form it a node of a min heap. It goes from index
i to the point where both of its children are greater than the parent or upto a leaf
i.e. no children.
{
  int smt = i;
  if(A[i]>A[2*i+1] && 2*i+1<heapSize)
                     // checking the smaller value and storing the index int smt
       smt = 2*i+1;
  if(A[2*i+2]<A[smt] && 2*i+2<heapSize)
                     // if child A[2*i+2] is the smallest one swap A[i] and A[2*i+2]
  {
       smt = 2*i+2;
       swap(&A[i], &A[smt]);
       minHeapify(A, smt);
  }
  else if(smt!=i)
              // else if child A[2*i+1] is the smallest one swap A[i] and A[2*i+1]
  {
       swap(&A[i], &A[2*i+1]);
       minHeapify(A, 2*i+1);
  }
  else
                     // else A[i] is minimum and nothing to be done, therefore return
       return;
       /* Ensure that the subtree rooted at A[i] is a min heap. */
}
```

```
int insertKey(int A[], int key)
              // insert a key in the heap
  int flag=0;
  A[heapSize]=key;
                            // insert a key at the last index
  int i = heapSize;
                            // increasing the heap size
  heapSize++;
  while(i>0)
  {
                     // now checking that if the inserted key is smaller its parent
                                   // if yes then swap
       if(A[i] < A[(i-1)/2])
       {
               swap(&A[i], &A[(i-1)/2]);
               i = (i-1)/2;
       }
       else
                     // if no then min heap is formed as key is greater than its
              parent
               return 1;
       flag=1;
  }
  if(flag==1 || i==0)
       return 1;
  return -1:
       /* Insert the element key into the heap represented by A.
       Return 1 if the operation is successful and -1 otherwise. */
}
int increaseKey(int A[], int i, int newVal)
                     // increase the key at index i
{
  if(i>=heapSize)
              // if the index is greater than heapSize than operation is wrong
       return -1:
  A[i]=newVal;
                     // else increase the value at index i
  minHeapify(A, i);
              // if the new value is greater than it's child then we need to swap , as
now heap property may be lost. Therefore min heapify is called. (As the nodes at
the children are already a min heap)
  return;
}
```

```
int decreaseKey(int A[], int i, int newVal)
              // decrease the value at index i
  if(i>=heapSize)
              // if the given index i is greater than heapSize , invalid operation
       return -1;
                            // else decrementing the value
  A[i]=newVal;
  while(i>0)
                     // now decremented value may be smaller than it's parent
  {
                     // so we need to swap the untill heap property is satisfied
       if(A[i] < A[(i-1)/2])
               swap(&A[i], &A[(i-1)/2]);
               i = (i-1)/2;
       }
       else
               return 1;
       flag=1;
  }
  return 1:
       /* Decrease the value of A[i] to newVal. Return 1 if the
       operation is successful and -1 otherwise. */
}
int deleteKey(int A[], int i) // delete the value at index i
  if(heapSize==0 || i>heapSize)
// if heapSize if 0 , nothing to delete or if index i is greater than heapSize , index is
out of bounds
       return -1:
                            // deleting the value at index i
  A[i]=A[heapSize-1];
                            // decrementing the heapSize
  heapSize--;
  minHeapify(A, i);
// now A[i] can be greater than it's children , so min heap property is lost , so
minHeapify to restore the heap property at index i
  return 1:
       /* Delete the element A[i] from the heap represented by A.
       Return 1 if the operation is successful and -1 otherwise. */
}
int extractMin(int A[])
{
              // same as delete key , here key is at last index
```

```
int val;
  if(heapSize==0)
        return -1;
  val=A[0];
  A[0]=A[heapSize-1];
  heapSize--;
  minHeapify(A,0);
  return val;
                      // returning the value of min
       /* Delete the root of the min heap represented by A. Return
       the deleted element if the operation is successful and -1
       otherwise. */
}
int getMin(int A[])
              // return the min of the min heap
  if(heapSize==0)
                             // check if heap is empty
        return -1;
  return A[0];
       /* Get the root of the min heap represented by A. Return
       the element if the operation is successful and -1 otherwise. */
}
void print(int A[])
              // printing the values of min heap
{
  int i=0;
  while(i<heapSize)
                             // until heap size is greater than the index i
  {
        printf("%d\n",A[i]);
        j++;
  }
       /* Display the heap represented by A in the increasing order
       of their indices, one element per line.*/
}
int main (int argc, char **argv)
{
       char line[128];
       char v1[15];
       char v2[15];
       char v3[15];
       int *A = NULL;
```

```
int ret;
     int lineNo = 0;
    while (fgets(line, sizeof line, stdin) != NULL ) // standard input in a line
     sscanf(line, "%s %s %s", v1, v2, v3); // taking out v1, v2, v3 from line
     lineNo++;
     if(lineNo == 1)
     A = (int*) malloc(sizeof(int)* stoi(v1));
                                          // allocating maximum memory to the array
     continue;
    }
     if(strcmp(v1,"INS") == 0)
     {
     ret = insertKey(A, stoi(v2));
     if(ret < 0)
            printf("%d\n", -1);
     else if(strcmp(v1,"DEL") == 0)
     ret = deleteKey(A, stoi(v2));
     if(ret < 0)
            printf("%d\n", -1);
    }
     else if(strcmp(v1,"EXT") == 0)
     ret = extractMin(A);
     printf("%d\n", ret);
     else if(strcmp(v1,"PRT") == 0)
     print(A);
     else if(strcmp(v1,"INC")==0)
{
     ret = increaseKey(A, stoi(v2), stoi(v3));
     if(ret<0)
             printf("%d\n", -1);
```

}

```
else if(strcmp(v1,"DEC") == 0)
        ret = decreaseKey(A, stoi(v2), stoi(v3));
        if(ret < 0)
               printf("%d\n", -1);
       }
       else if(strcmp(v1,"MIN") == 0)
       ret = getMin(A);
        if(ret < 0)
               printf("%d\n", -1);
       }
       else
       printf("INVALID\n");
       }
       }
       if(A)
                      // if allocated free up the memory of A
       free(A);
        return 0:
}
```

Time Complexity:

- 1. minHeapify O(logn) : If we want to heapify top node, it will max go up to a leaf and travel to it's height, which is logn .
- 2. Insert O(logn): If the inserted value is the smallest (smaller than the first element), then it will travel up to its height which is logn.
- 3. increaseKey O(logn): if first node value is increased such that it is the biggest among all the nodes, then it will travel up to its base which is logn farther away.
- 4. decreaseKey O(logn): Same asd insert . If we decrease a leaf to min of the heap so it will travel to its height.
- 5. deleteKey O(logn): Delete the first node and travel to its base.
- 6. extractMln O(logn): same as deleting the first node.
- 7. getMin- O(1): first node contains the minimum value, we can access it in constant time.
- 8. Print- O(n): accessing all the elements one at a time takes linear time.

Space Complexity:

- 1. minHeapify O(logn): uses recursion logn times, each time constant memory allocation.
- 2. Insert O(1): uses constant amount of memory.
- 3. increaseKey O(logn): uses minheapify.
- 4. decreaseKey- O(1): uses constant amount of memory.
- 5. deleteKey- O(logn): uses minheapify.
- 6. extractMin- O(long): uses minheapify.
- 7. getMin- O(1): first index, nothing to initialize
- 8. Print- O(1): no extra allocation based on input n.