Defining NLME Models in Pumas

```
1 nlme_model = @model begin
    @param begin
        \theta \in \text{VectorDomain}(3, \text{init}=[3.24467E+01, 8.72879E-02, 1.49072E+00])
 3
        1.20854E-02 2.02375E-02 -6.47803E-03
 5
                                              5.69131E-02 -6.47803E-03 4.34671E-01]))
        Σ ∈ PDiagDomain(init=[1.70385E-02, 8.28498E-02])
    end
    @random begin
10
11
        \eta \sim MvNormal(\Omega)
12
    end
13
14
    @pre begin
15
       V = \theta[1] * \exp(\eta[1])
        Ke = \theta[2] * exp(\eta[2])
16
        Ka = \theta[3] * exp(\eta[3])
17
18
        CL = Ke * V
19
    end
20
21
    @vars begin
22
        conc = Central / V
23
    end
24
25
    @dynamics begin
26
        Gut' = -Ka*Gut
27
        Central' = Ka*Gut - Ke*Central
28
    end
29
30
    @derived begin
        dv \sim @. Normal(conc, sqrt(conc^2 *\Sigma.diag[1] + \Sigma.diag[end]) + eps())
31
32
    end
33 end
```

@param: Model parameters (Population averages)

This specifies the parameters of the model, and their domains:

- RealDomain: real values (possibly subject to upper/lower bounds)
- VectorDomain: vector of real values
- PSDDomain: symmetric positive-definite matrices (e.g. for covariance matrices)
- PDiagDomain: postive-valued diagonal matrices

@random: Random effects (Individual differences)

```
1 @random begin
2 η ~ MvNormal(Ω)
3 end
```

Specifies the random effects, dependent on parameters. The random effects are defined by a distribution from Distributions.jl.