

Vaidehi Som

☎ +1(215)397-5735 | 🌐 [vaidehisom.github.io](https://github.com/vaidehisom) | ✉ somv@seas.upenn.edu | 🔗 [vaidehi-som](#) | 🐙 VaidehiSom

EDUCATION

University of Pennsylvania, U.S.A

Aug'22 – May'24

Master of Science in Robotics Engineering (Specializing in Artificial Intelligence and Computer Vision)

Indian Institute of Technology (IIT) Jammu, India

Aug'17 – Jun'21

Bachelors in Mechanical Engineering

TECHNICAL SKILLS AND COURSEWORK

Languages: C++, Python

Frameworks: PyTorch, Keras, ROS, Gazebo, CARLA

Developer Tools: Linux, CMake, Git, VS Code

Libraries: NumPy, Matplotlib, OpenCV, Open3D, Sklearn, Eigen

Graduate Coursework: Deep Learning, Machine Perception, Machine Learning, Control and Optimization

Online: *C++ Nanodegree from Udacity, Robotics Software Engineer Nanodegree from Udacity , Controls for Mobile Robotics, Pursuing Photogrammetry I II and Mobile Sensing and Robotics-* Cyrill Stachniss

WORK EXPERIENCE

Research Assistant- Generalizing over unseen tasks | *Reinforcement Learning, Perception*

Oct'22 – Present

Dr. Dinesh Jayaraman, PAL Group (GRASP Lab), University of Pennsylvania [Code](#)

- **Robot learning** based on minimal **3D visual data** for unseen robot tasks for homes
- Collecting data- joint positions, camera feed- for policy training using ROS communication with Kinova 7dof robotic arm
- Implementing, training and deploying **goal based offline RL** for sub-tasks segmented by [VIP](#)

Mobile Robotics Software Engineer | *C++, ROS, Startup, Automated Guided Vehicle*

Aug'21 – Jun'22

Addverb Technologies, Noida, India

- Deployed automated mobile robot which uses **LIDAR**, **IMU**, and QR codes for navigation
- Implemented **motion (Pure pursuit, Lyapunov) controller** packages for **navigation** stack
- Improved odometry with calibration, controllers, and **IMU** infused data using **Kalman filter**
- Reduced testing time by 50% by automating odometry calibration and sensor testing

Research Intern- Cycle GANs for biometric conversion | *Deep Learning, Computer Vision*

May'20 – Dec'20

IIT Jammu, National Institute of Informatics, Japan and the Government of India [Code/Report](#)

- Conceptualized from start to end- AI-driven biometric privacy using modified **cycle GANs**
- Implemented **encoders-decoders**, compared different matching algorithms, implemented **image augmentation** techniques, heatmap, used **latent vectors**, and prepared datasets

Research Intern- Behavioral cloning for SDCs | *Deep End-to-End learning, Computer Vision*

May'19 – July'19

Dr. Virendra Singh, IIT Bombay Certificate/Report

- Developed deep learning model for self driving car based on **behavioral cloning** and for object detection using CNN
- Compared usage of end to end learning for **object detection** vs **path following**. Performed data augmentation

DEEP LEARNING AND COMPUTER VISION PROJECTS

Trajectory prediction and Dynamic Obstacle avoidance for SDC | *PINN, LSTM, Deep Learning*

Nov'22 – Present

- Implemented **social LSTM**, **OLSTM** and **GRU** for pedestrians trajectory prediction [Report/Code](#)
- Implemented **Physics informed Neural Nets** and **MPC** for **motion planning** [Report/Code](#)
- Used **Lifelong A*** and pedestrian's trajectory as dynamic obstacles for planning obstacles

Gesture Recognition controlled Robotic Arm | *Deep Learning, Computer Vision, Python, ROS, Gazebo*

Jun'20 – Dec'20

- Implemented **CNN, non-max suppression, cross-entropy** loss, and detected hand landmarks [Video/Report](#)
- Detected key-points from **video input** using Intel-RealSense Camera, were used to define various gestures
- **Simulated** robotic arm using ROS and Gazebo to perform pick up tasks. Enhanced arm movements using gesture inputs

Mobile Robot: Simulation and SLAM | ROS Navigation stack, C++, AMCL, EKF, Gazebo

May'21 - Jun'21

- **Simulated** ball chasing robot, detection via colors. Designed URDF model and arena [Code/Video](#)
- Implemented localization using **AMCL**, **gmapping** for 2D and RTABMap for **3D mapping**
- Deployed SLAM and Navigation using **Dijkstra** algorithm and simulated pick and place operation

SLAM projects

- Implemented **2-view** and **multiple view stereo** algorithms to convert multiple 2D viewpoints into 3D reconstruction [Code](#)
- Recovering 3D transformation between two views using **RANSAC**, Pose recovery and 3D reconstruction [Code](#)
- Augmented Reality with AprilTags using both **PnP** and **P3P algorithm** [Code](#)
- Implement **ES-EKF** to localize self driving car in simulation

HONORS

Prof. Sudhir K. Leadership Award | *Leadership award*

Apr'21

- Awarded for exceptional initiatives taken, leadership shown and contributions made towards student activity [Link](#)