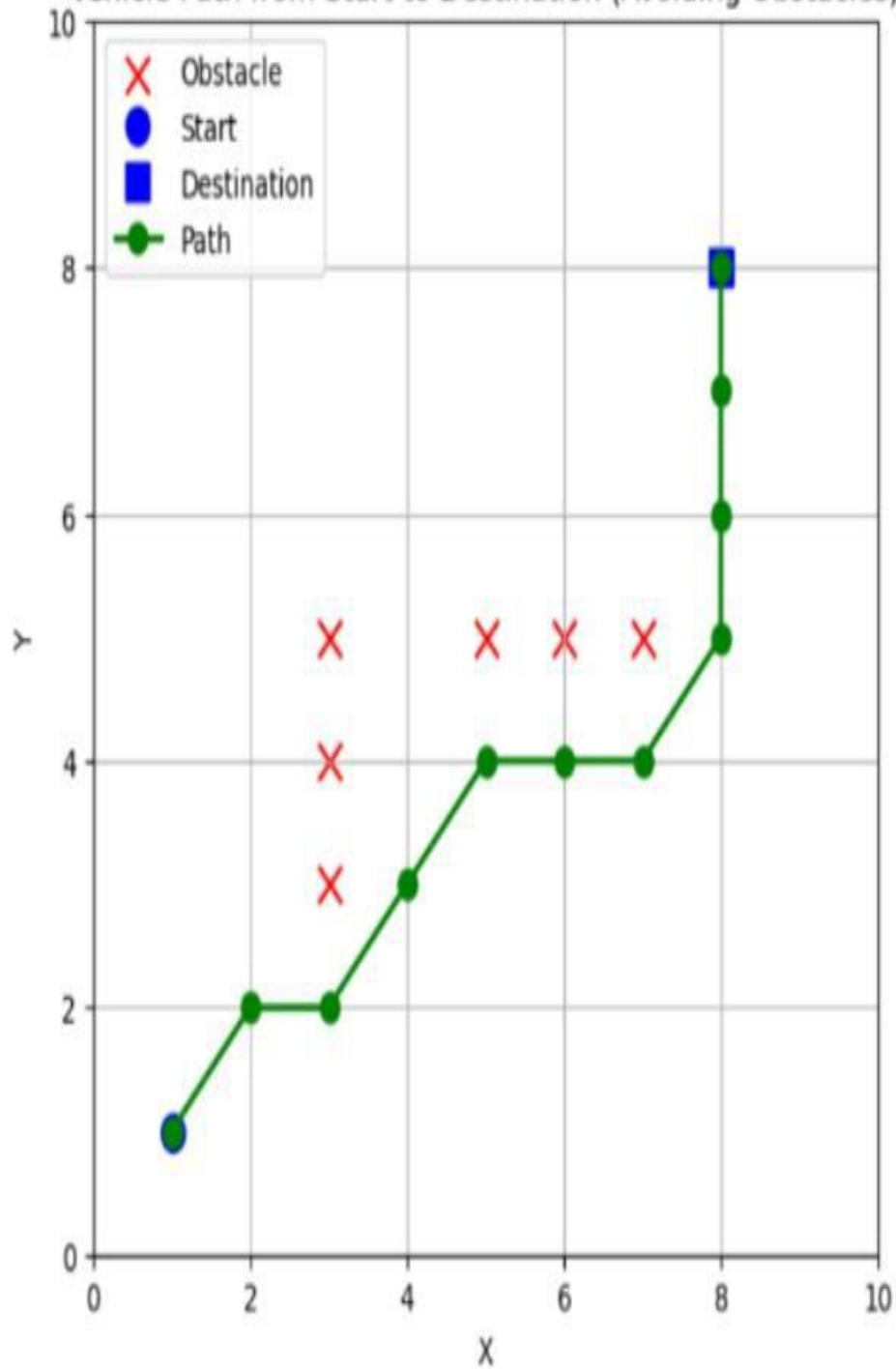


Vehicle Path from Start to Destination (Avoiding Obstacles)



--- Vehicle Path from Start to Destination ---

(1, 1)

(2, 2)

(3, 2)

(4, 3)

(5, 4)

(6, 4)

(7, 4)

(8, 5)

(8, 6)

(8, 7)

(8, 8)