## commit01

## April 7, 2022

```
[]: from lib.functions0 import *
    import numpy as np
    import datetime
    from qiskit.ignis.mitigation.measurement import CompleteMeasFitter
    from qiskit import Aer, assemble, QuantumCircuit, QuantumRegister, U
     →ClassicalRegister, IBMQ, transpile, execute
    from qiskit.providers.aer import AerSimulator, QasmSimulator
    from qiskit.opflow import Zero, One, I, X, Y, Z
    from qiskit.ignis.verification.tomography import state_tomography_circuits,u
     →StateTomographyFitter
    from qiskit.quantum_info import state_fidelity
    import matplotlib.pyplot as plt
    %load ext autoreload
    %autoreload 2
    import warnings
    warnings.filterwarnings('ignore')
    IBMQ.load_account()
    provider = IBMQ.get_provider(hub='ibm-q-community',
                                group='ibmquantumawards',
                                project='open-science-22')
    backend_sim_jakarta = QasmSimulator.from_backend(provider.
     backend_real_jakarta = provider.get_backend('ibmq_jakarta')
    backend sim = Aer.get backend('qasm simulator')
```

## 0.1 IBM open-science-prize-2021/22 solution. By Quantum Polo Gang: Ruben, Fabio & Valerio

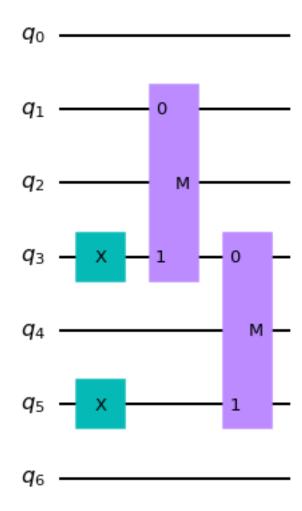
## 0.2 Decomposition:

- We computed numerically the operator of N trotter steps, for a certain evolution time:  $U^n$
- Observing that this operator preserves the magnetization of the system, if the initial state belongs to an eigenspace of the magnetization is possible to decompose the operator with 4 c-not. If the initial state is a superposition of states with different magnetization the best decomposition we found has 11 c-not (14 for the Jakarta geometry).
- Our initial state is  $|110\rangle$  (qubits 5,3 and 1 respectively) so we can use the best decomposition (4 c-not).

To see the decomposition procedure open decomposition.ipynb file.

Let's start from the defining of the evolution circuit parameters:

- *steps*: number of trotter steps (integer).
- *time*: time of evolution (double).
- *initial\_state*: the 3-qubit initial state (string): from right to left, associated with qubits 1, 3 and 5 respectively
- reps: number of times each circuit is runned, in order to compute a standard deviation of the fidelity.
- *shots*: number of shots for every run.
- backend: here you can choose on which backend run the simulation: backend\_sim\_jakarta (noisy simulator), backend real jakarta (real device), backend sim (simulator)



Then we add the copy check for the mitigation (see Ancillas\_Error\_mitigation\_Git\_Hub.pynb)

Then, we build the tomography circuits

```
[]: from qiskit.ignis.verification.tomography import state_tomography_circuits,__

StateTomographyFitter

qcs = state_tomography_circuits(qc, [qr[1],qr[3],qr[5]])
qcs_na = state_tomography_circuits(qc, [qr[1],qr[3],qr[5]])
```

```
## add the measure on the ancillas

for qc in qcs:
    cr_anc = ClassicalRegister(4)
    qc.add_register(cr_anc)
    #qc.barrier()
    qc.measure([0,2,4,6],cr_anc)

## qcs_tot is a list holding the tomography cirquits reps times.

qcs_tot = []
for _ in range(reps):
    qcs_tot=qcs_tot + qcs

qcs[10].draw(output="mpl")
```

Building the calibration circuits

```
[]: state_lables[0]
```

```
[]: meas_calibs[2].draw(output="mpl")
```

```
[]: qcs_calibs[2].draw(output="mpl")
```

Than we run all the circuits

```
[]: jobs_evo=execute(qcs_tot, backend=backend, shots=shots)
job_cal_our=execute(qcs_calibs, backend=backend, shots=shots)
job_cal=execute(meas_calibs, backend=backend, shots=shots)
```

```
[]: jobs_evo_result = jobs_result(job_evolution = jobs_evo, reps = reps, u 

→ancillas=[0,2,4,6])
```

or we can retrieve the jobs

```
[]: #evo_ID = "6233ae39d97bff04d66929e9"
    #cal_ID = "6233ae3ba2f72dff43da994f"

#evo_job=backend.retrieve_job(evo_ID)
    #job_cal_our=backend.retrieve_job(cal_ID)
    '''
    reps=8
    steps=42
    backend=backend_real_jakarta
```

```
job\_cal\_our = backend.retrieve\_job("6237aee18293e9eb4e1e4c4a")
job\_cal = backend.retrieve\_job("6237aedf0af65dc88cd92302")
job=backend.jobs(limit=30, start\_datetime= "2022-03-19", \_
\rightarrow end\_datetime="2022-03-26")[2]
jobs\_evo\_result = jobs\_result(job\_evolution = job, reps = reps, \_
\rightarrow ancillas=[0,2,4,6])
```

```
[]: #### DA CANCELLAREEEEEEEEEEEEEEE
#state_lables = bin_list(7)
#qcs_na = circuits_without_ancillas_measuraments(job)
```

Next we apply the mitigation in the following way:

- measure mitigation: we apply the inverse of the calibration matrix to each circuit (see *measure mitigation.ipynb*)
- ancillas mitigation: we throw away all the measures which contain a value for the ancillas physically forbidden.

this is done by the *mitigate* function.

Then we compute the fidelity for both the mitigated results and not-mitigated ones, in order check the gain given by the mitigation.

```
[]: meas_fitter_our = CompleteMeasFitter(job_cal_our.result(),__
     ⇒state_labels=state_lables)
     meas_fitter = CompleteMeasFitter(job_cal.result(), state_labels=state_lables)
     target_state = (One^One^Zero).to_matrix()
     fids=np.zeros([reps,4])
     fids_mean=np.zeros(4)
     fids_dev=np.zeros(4)
     for j in range(reps):
         res = jobs_evo_result[j]
         print(j)
         new_res, new_res_nm = mitigate(res, Measure_Mitig="yes",_
     →ancillas_conditions=['0011','1110','1101'], meas_fitter=meas_fitter)
         new_res_our, new_res_nm = mitigate(res, Measure_Mitig="yes",_
      →ancillas_conditions=['0011','1110','1101'], meas_fitter=meas_fitter_our)
         new_res_not_mitigated = mitigate(res, Measure_Mitig="no",_
      →ancillas conditions=bin list(4))
```

```
fids[j,0] = fidelity_count(new_res_not_mitigated, qcs_na, target_state)
         fids[j,1] = fidelity_count(new_res_nm, qcs_na, target_state)
         fids[j,2] = fidelity_count(new_res, qcs_na, target_state)
         fids[j,3] = fidelity_count(new_res_our, qcs_na, target_state)
     for i in range(4):
         fids_mean[i]=np.mean(fids[:,i])
         fids_dev[i]=np.std(fids[:,i])
[]: new_res_our.get_counts(-1)
    Printing the fidelity
[]: labels = ["raw:
               "ancillas mitigation:
               "ancillas and qiskit measurement mitigation:",
               "ancillas and our measurement mitigation:
     ]
     for i in range(4):
         print(labels[i], fids_mean[i], " +- ", fids_dev[i])
```

[]: