

# FIR Filters in Digital Signal Processing

ROLL NO.	PRN	Name
59	12310151	Prathamesh Murkute
70	12310901	Samruddhi Sangole
73	12310202	Vallabh Sangvikar

# Introduction to FIR Filters in DSP

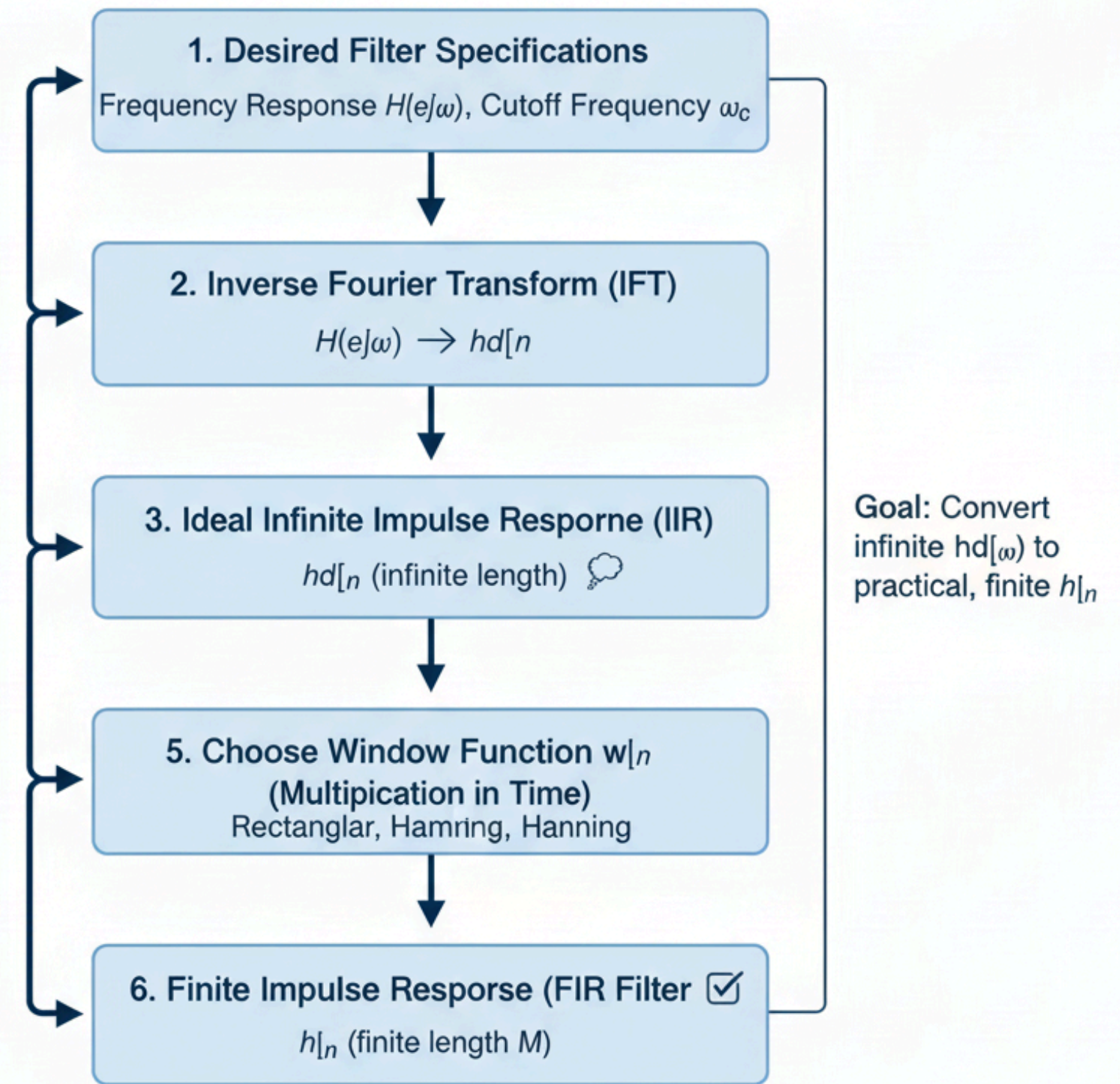
- What are Filters?
  - Filters are devices that are used to remove unwanted features from a signal.
- What is an FIR Filter?
  - It's a filter whose output depends only on the present and past values of the input signal.
  - Its key feature is that its impulse response, written as  $h(n)$ , is of finite duration. For example, the response might be  $\{1,2,3,4\}$  but not  $\{1,2,3,\dots\infty\}$ .
- Applications:
  - FIR filters are used in applications where a linear phase response is critical, such as in data transmission and speech processing.

The main goal is to find a practical, finite impulse response ( $h[n]$ ) that meets our filtering needs.

There are three common design approaches we will cover:

1. The Windowed Fourier Series Approach
2. The Frequency Sampling Approach
3. Computer-Based Optimization Methods

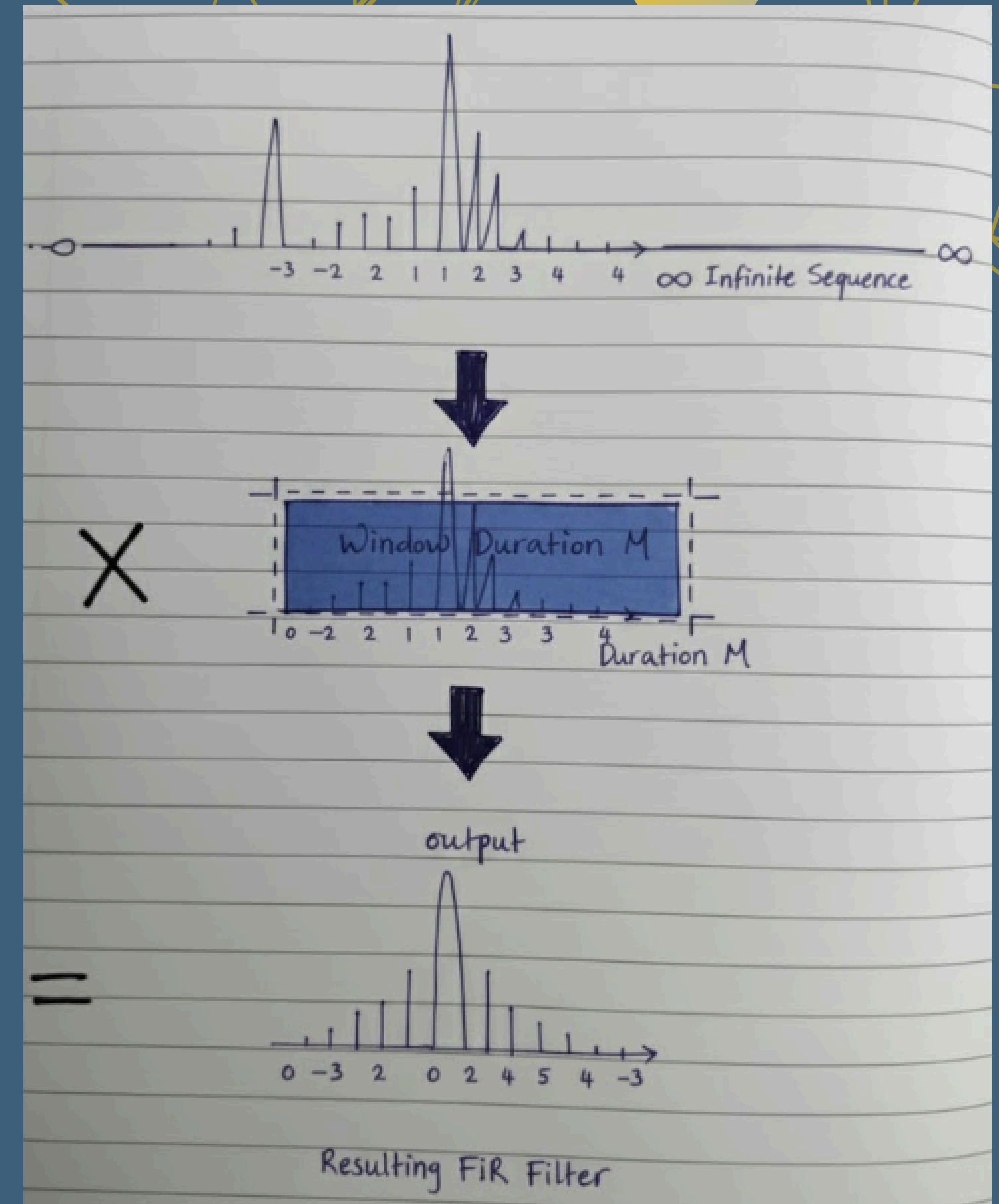
## FIR Filter Design: Window Method Flow





The window method is a technique used to convert an ideal, infinite impulse response into a usable, finite one.

- How it Works:
  - We take the infinite signal ( $h(n)$ ) and multiply it by a finite-length "window" function.
  - $h'(n) = h(n) \cdot WR(n)$
  - Think of the window as a gate. It lets a specific portion of the signal pass through and blocks the rest. The part of the signal outside the window is "clipped or remaining gets cut".
  - This process effectively cuts the infinite response down to a finite length, giving us our final FIR filter coefficients,  $h'(n)$ .



### Rectangular Window:

- This is the simplest window. It's like a switch that is "on" (value = 1) for the duration of the filter and "off" (value = 0) everywhere else

### Hamming Window:

- This is a more advanced window that tapers off smoothly at the ends, providing better performance than the rectangular window.

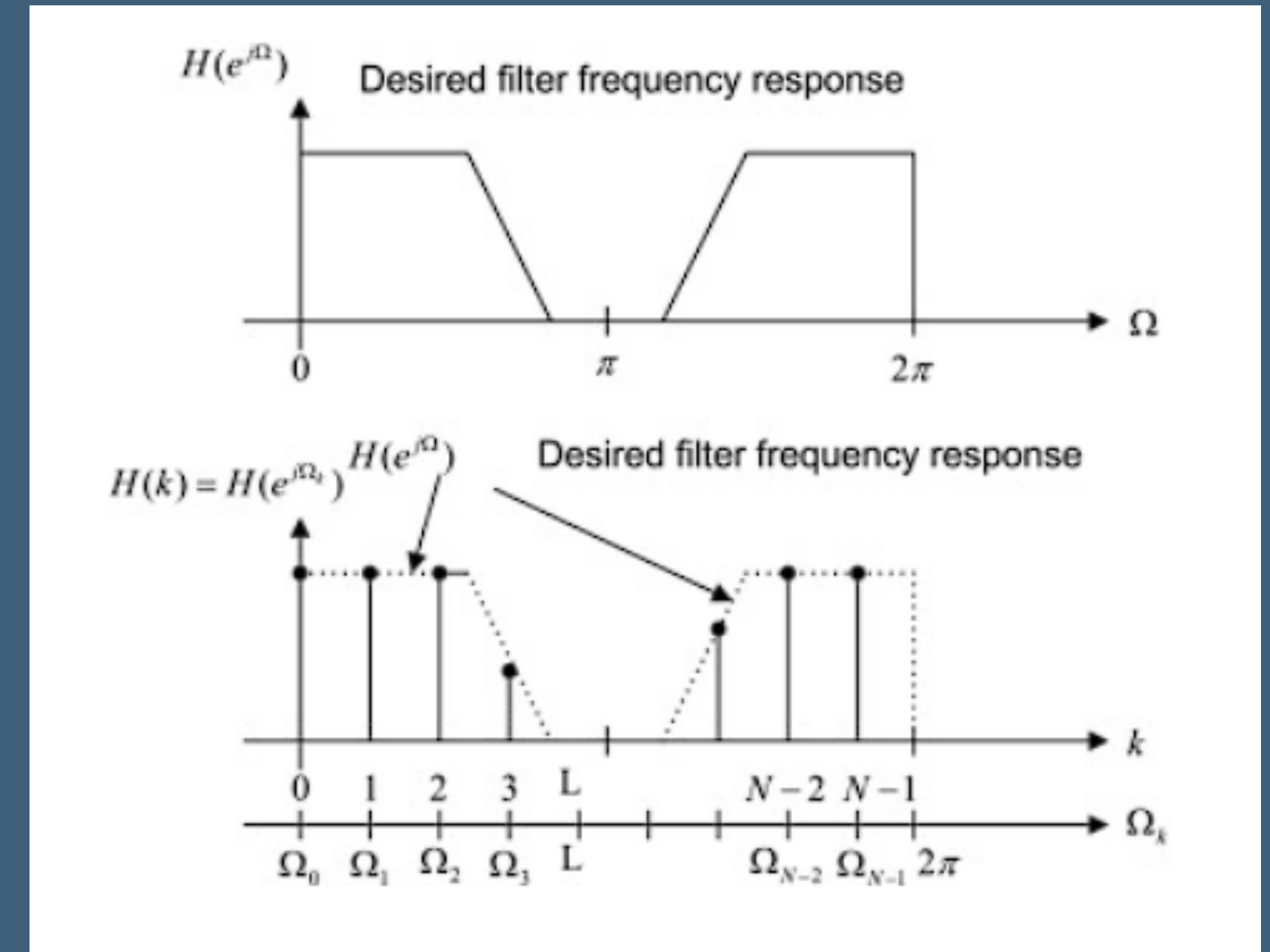
<i>Name of Window function</i>	<i>Window function <math>w(n), 0 \leq n \leq N</math></i>
Rectangular	1
Hanning	$0.5 - 0.5\cos\left(\frac{2\pi n}{N}\right)$
Hamming	$0.5 - 0.46\cos\left(\frac{2\pi n}{N}\right)$

### Hanning Window:

- Similar to the Hamming window, it also provides a smoother transition at the edges.

# The Frequency Sampling Approach

- Core Idea: Design filter by specifying key frequency points directly.
- Process:
  1. Sample: Pick  $N$  points from the desired frequency response.
  2. Synthesize: Compute impulse response  $h(n)$  via Inverse DFT of samples.
- Pros: Exact response at sampled frequencies.
- Cons: Ripple/errors may appear between sampled points.
- Primary Use: FIR filters with arbitrary or complex frequency responses.
- Key Point: Useful when conventional design methods are difficult to apply.



The Frequency Sampling method is fundamentally an application of the Discrete Fourier Transform (DFT).

- The Goal: We want to find a finite impulse response,  $h[n]$ , of length  $N$ . The DFT tells us that this  $h[n]$  corresponds to  $N$  discrete frequency samples,  $H[k]$ .
- The Process:
  - a. Sample the Ideal Response: We define our desired "ideal" frequency response,  $H_d(e^{j\omega})$ , and take  $N$  samples of it at equally spaced frequencies,  $\omega_k = N2\pi k$ . These samples become our target values,  $H[k]$ .
  - b. Calculate Coefficients using IDFT: The filter coefficients,  $h[n]$ , are then simply the Inverse Discrete Fourier Transform (IDFT) of these  $N$  frequency samples.
- Mathematical Representation:  $h[n] = \text{IDFT}\{H[k]\} = \frac{1}{N} \sum_{k=0}^{N-1} H[k] \cdot e^{jN2\pi kn}$
- Limitation: While this method gives perfect accuracy at the sampled frequencies, the response between these samples can deviate significantly, causing performance issues similar to those seen in the windowing method.

## Method 3 - Computer-Based Optimization

This is the most powerful and common method used today for designing high-quality FIR filters.  
The Goal: To find the absolute best filter for a given set of specifications.

### How it Works:

The designer provides the computer with the filter requirements: passband frequency, stopband frequency, and the maximum allowable ripple.

The algorithm then runs an iterative process to find the filter coefficients that minimize the maximum error across all the bands.

**Parks-McClellan Algorithm:** This is the most famous algorithm for this task. It produces an "equiripple" filter, which is optimal because it spreads the error evenly across the passband and stopband. This is considered the best possible FIR filter for a given order.



Computer-based optimization methods produce an optimal filter based on the "equi-ripple" criterion, which is derived from the Alternation Theorem.

**Weighted Error Function:** The algorithm's goal is to minimize a weighted error function,  $E(\omega)$ , which measures the difference between the actual filter response and the desired response in the passbands and stopbands.

An Equi-ripple filter is one where the weighted error function has ripples of equal magnitude across the passband and stopband.

**Why is it Optimal?**

The Alternation Theorem states that for a given filter length ( $N$ ), this equiripple solution is the unique, best possible approximation. No other FIR filter of the same length can achieve a lower maximum error (i.e., smaller ripples) for the same band-edge frequencies.

The Parks-McClellan algorithm is the computational procedure used to find these unique, equi-ripple filter coefficients.





FIR filters are popular for two main reasons:

- Advantages

- Perfect Linear Phase be designed to delay all frequency components of a signal by the same amount. This is extremely important in fields like audio and video, as it prevents signal distortion.
- Guaranteed Stability: FIR filters are always stable, meaning their output will not grow uncontrollably in response to a bounded input.

- Disadvantages

- High Computational Cost: Achieving sharp filter specifications often requires a high filter "order" (many coefficients), which means more calculations and processing power are needed compared to their IIR counterparts.
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# FIR Filters and Their Importance in DSP

- FIR filters are essential in **Digital Signal Processing** due to their stability and linear phase response.
- They provide precise control over frequency characteristics, making them ideal for applications such as audio processing and communications.