Advanced Data Structures and Algorithms

BRANCH-and-BOUND

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Topics

General Method

Travelling Sales Person Problem

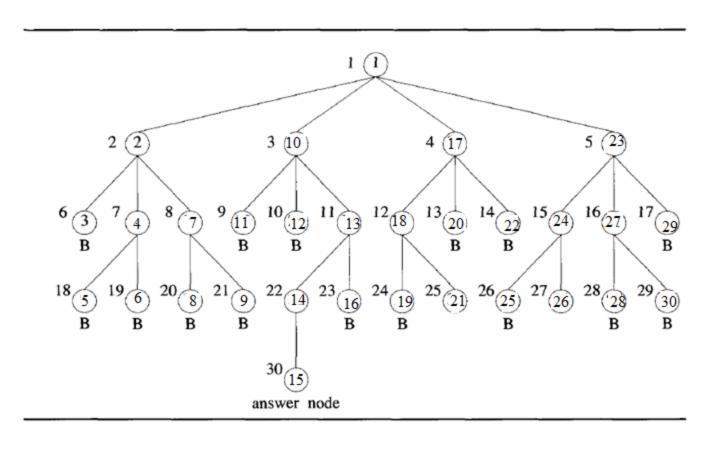
0/1 Knapsack Problem

Branch-and-Bound

- The term branch-and-bound refers to all state space search methods in which all children of the E-node are generated before any other live node can become the E-node.
- In branch-and-bound terminology, a BFS-like state space search will be called FIFO(First In First Out) branch-and-bound as the list of live nodes is a first-in-first-out list (or queue).
- A D-search-like state space search will be called LIFO(Last In First Out) branch-and bound as the list of live nodes is a last-in-first-out list (or stack).

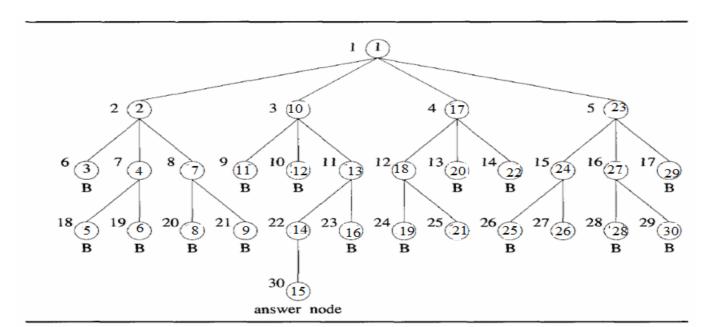
Branch-and-Bound

 In both FIFO and LIFO selection for next E-node is rigid and not useful to get answer node quickly.



LC Search

- The search for an answer node can often be speeded by using an "intelligent" ranking function $\hat{c}(\cdot)$ for live nodes.
- The next E-node is selected on the basis of this ranking function.
- If in the previous example we use a ranking function that assigns node 10 a better rank than all other live nodes, then node 10 will become the Ende following node 1.
- The remaining live nodes will never become E-nodes as the expansion of node 10 results in the generation of an answer node (node31).



LC Search

Let $\hat{g}(x)$ be an estimate of the additional effort needed to reach an answer node from x. Node x is assigned a rank using a function $\hat{c}(\cdot)$ such that $\hat{c}(x) = f(h(x)) + \hat{g}(x)$, where h(x) is the cost of reaching x from the root and $f(\cdot)$ is any nondecreasing function.

A search strategy that uses a cost function $c^{(x)} = f(h(x)) + g^{(x)}$ select the next E-node with least $c^{(.)}$. Hence, such a search strategy is called an LC-search (Least Cost search).

An LC-search coupled with bounding functions is called an LC branch-and-bound search.

Control Abstraction of LC Search

```
listnode = \mathbf{record} {
         listnode * next, * parent; float cost;
    Algorithm LCSearch(t)
\frac{2}{3}
        Search t for an answer node.
4
         if *t is an answer node then output *t and return;
5
         E := t; // E-node.
         Initialize the list of live nodes to be empty;
         repeat
             for each child x of E do
10
                  if x is an answer node then output the path
11
12
                      from x to t and return;
                  Add(x); // x is a new live node.
13
                  (x \to parent) := E; // Pointer for path to root.
14
15
             if there are no more live nodes then
16
17
                  write ("No answer node"); return;
18
19
20
             E := \mathsf{Least}();
21
         } until (false);
22
```

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Travelling Sales Person Problem

- Let G = (V, E) be a directed graph defining an instance of the traveling sales person problem.
- Let Cij equal the cost of edge(i,j), Cij = ∞ if (i,j) not in E, and let |V|= n.
- Without loss of generality, we can assume that every tour starts and ends at vertex1.
- Identify the tour path for TSP in such a way that every location should be visited only once.

An Example State Space Tree for TSP

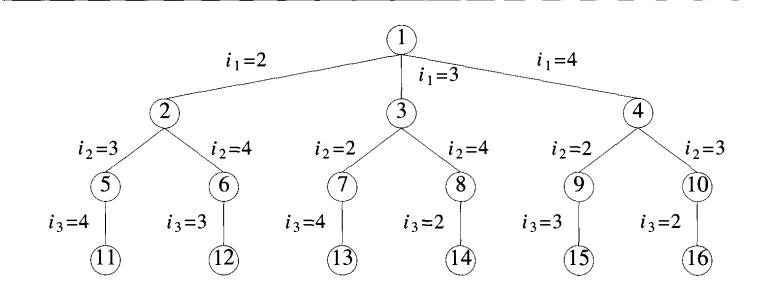


Figure 8.10 State space tree for the traveling salesperson problem with n = 4 and $i_0 = i_4 = 1$

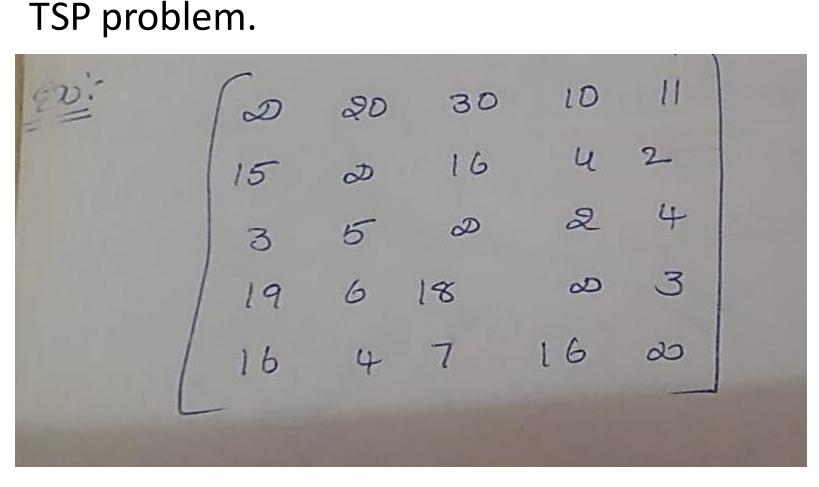
TSP with LCBB

To use LCBB to search the traveling salesperson state space tree, we need to define a cost function $c(\cdot)$ and two other functions $\hat{c}(\cdot)$ and $u(\cdot)$ such that $\hat{c}(r) \leq c(r) \leq u(r)$ for all nodes r. The cost $c(\cdot)$ is such that the solution node with least $c(\cdot)$ corresponds to a shortest tour in G. One choice for $c(\cdot)$ is

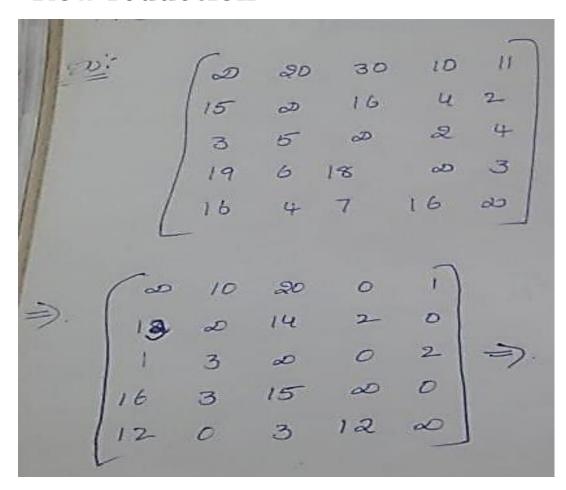
$$c(A) = \begin{cases} \text{length of tour defined by the path from the root to } A, \text{ if } A \text{ is a leaf cost of a minimum-cost leaf in the subtree } A, \text{ if } A \text{ is not a leaf} \end{cases}$$

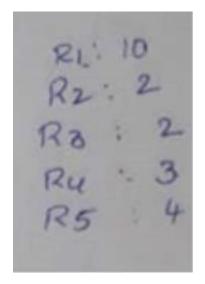
- A better c[^](.) can be obtained by using the reduced cost matrix corresponding to G.
- A matrix is reduced iff every row and column is reduced.
- A row (column)is said to be reduced iff it contains at least one zero and all remaining entries are non-negative.
- The total amount subtracted from the columns and rows is a lower bound on the length of a minimum-cost tour and can be used as the c^(.) value for the root of the state space tree.

 Find the shortest path tour for the following TSP problem.

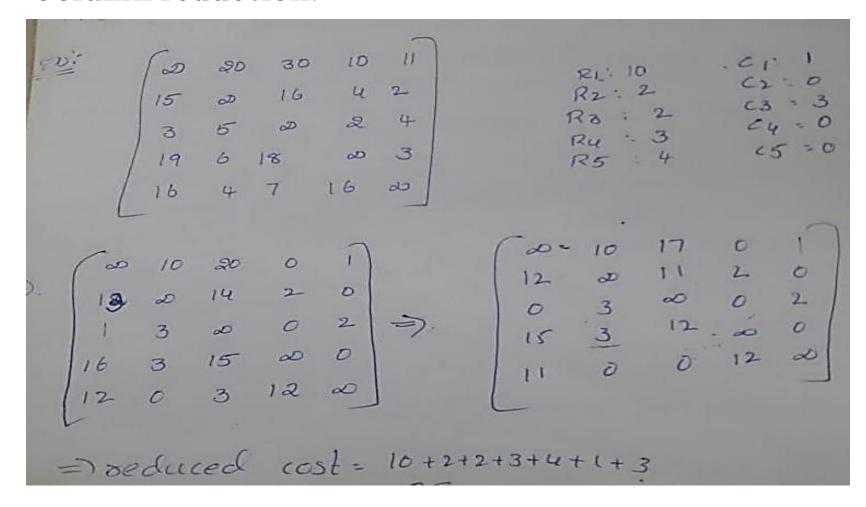


- Reduce the matrix to get c^(.)
- Row reduction

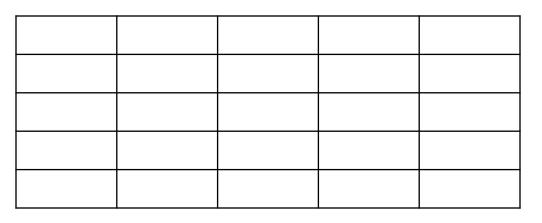


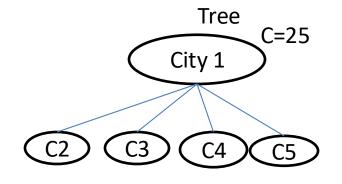


- Reduce the matrix to get c^(.)
- Column reduction:



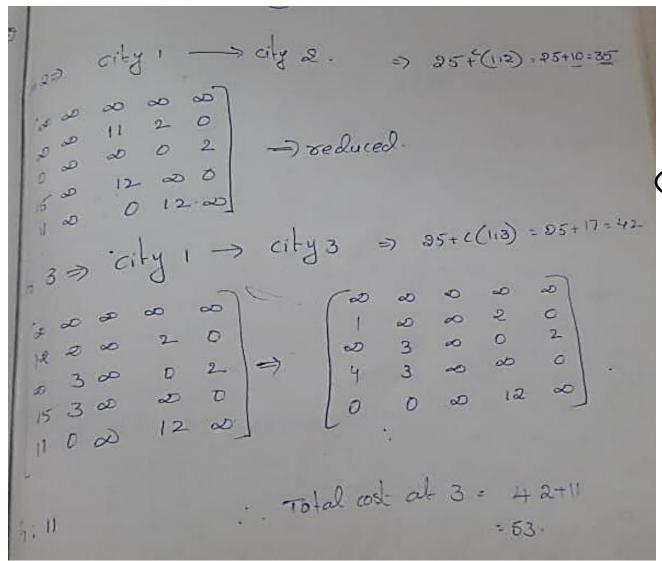
City 1 to City 2: $1 \rightarrow 2$

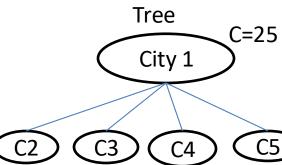


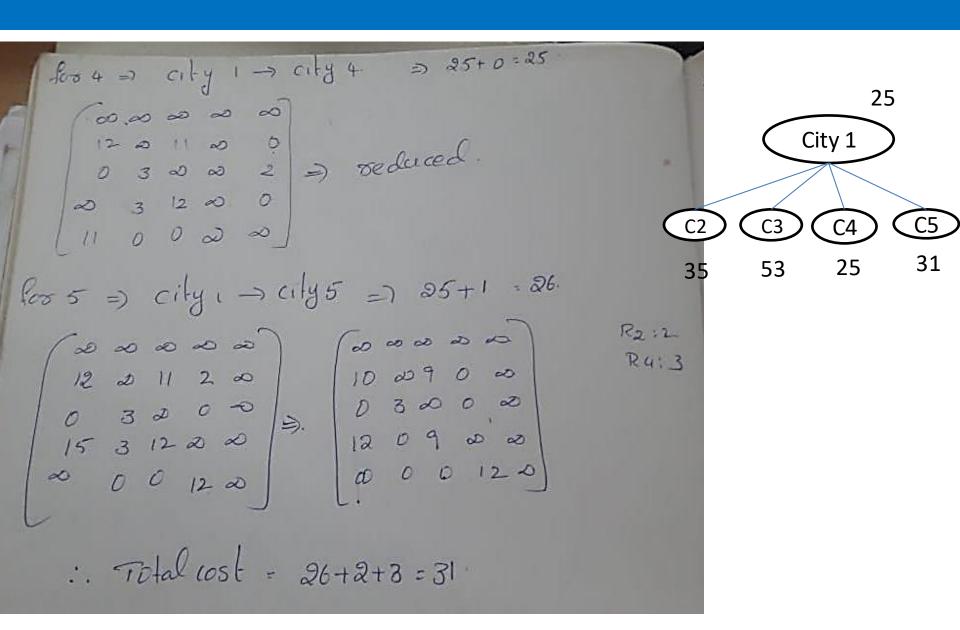


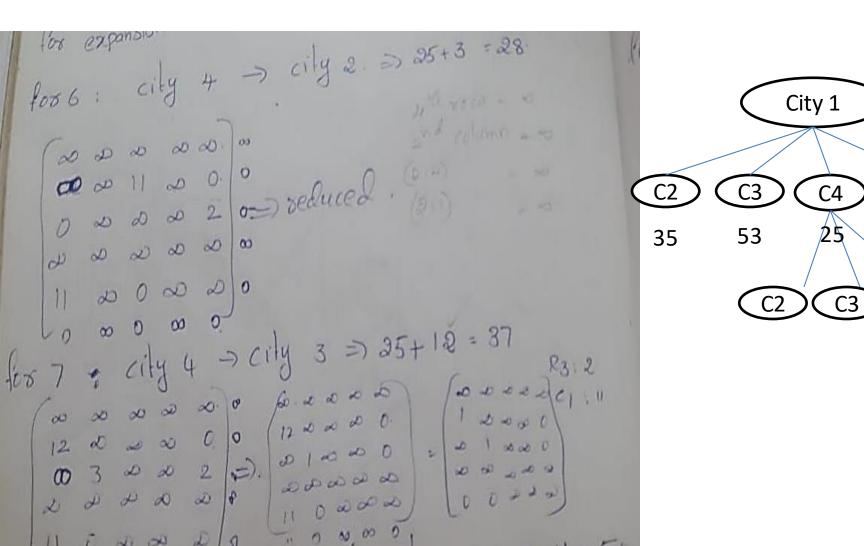
Reduced matrix at root node

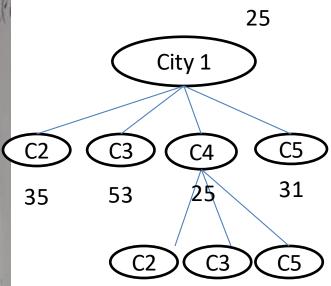
∞	10	17	0	1
12	8	11	2	0
0	3	8	0	2
15	3	12	8	0
11	0	0	12	∞

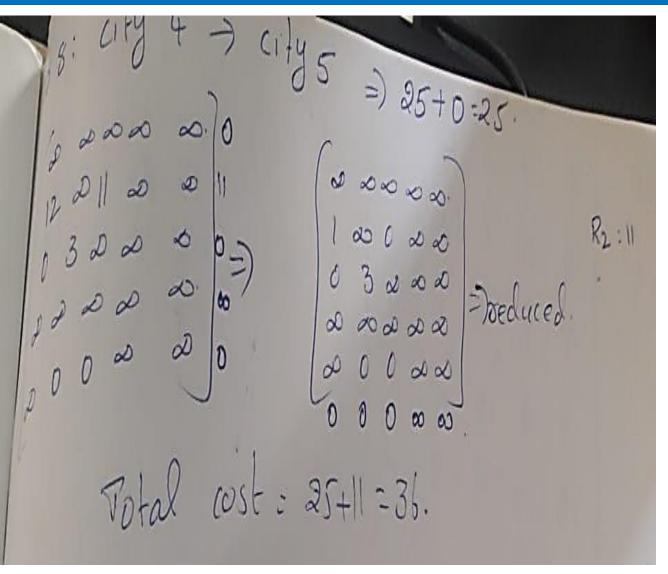


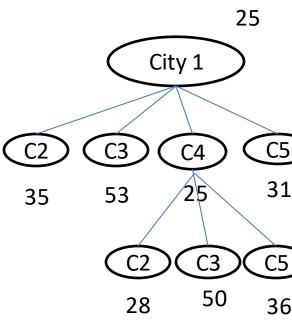


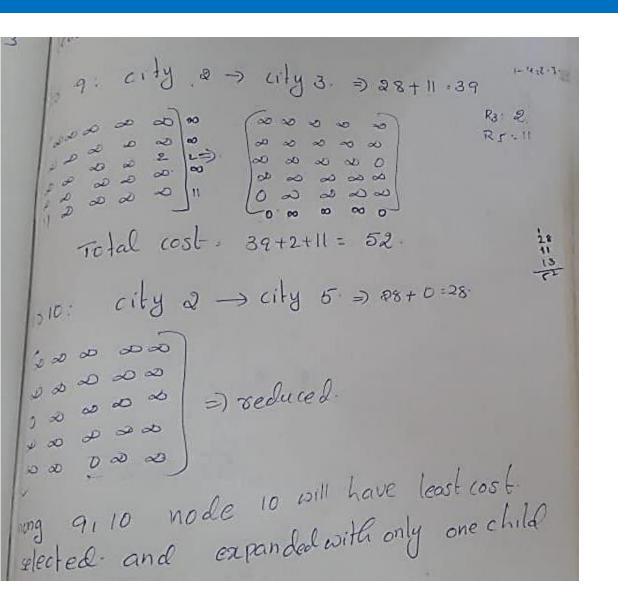


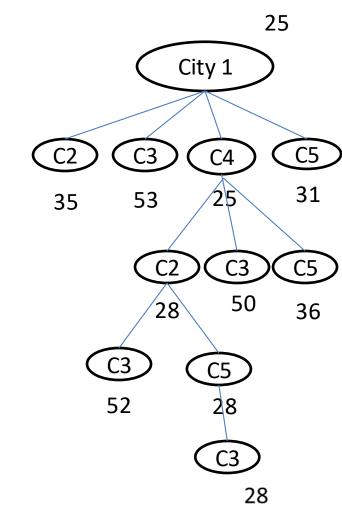












Problems for Practice

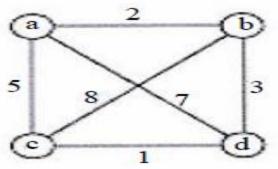
Find optimal tour of travelling salesperson for the following cost matrix using LCBB.

15M

∞	7	3	12	8
3	8	6	14	9
5	8	8	6	18
9	3	5	8	11
18	1	9	8	8

Solve the following Travelling Sales Person Problem using branch and bound technique and draw the solution state space tree.

15M



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we cannot directly apply the techniques of LCBB since these were discussed with respect to minimization problems whereas the knapsack problem is a maximization problem. This difficulty is easily overcome by replacing the objective function $\sum p_i x_i$ by the function $-\sum p_i x_i$. Clearly, $\sum p_i x_i$ is maximized iff $-\sum p_i x_i$ is minimized. This modified knapsack problem is stated as:

minimize
$$-\sum_{i=1}^{n} p_i x_i$$

subject to
$$\sum_{i=1}^{n} w_i x_i \le m$$

$$x_i = 0 \text{ or } 1, \quad 1 \le i \le n$$

Upper bound function

```
Algorithm UBound(cp, cw, k, m)
    // cp, cw, k, and m have the same meanings as in
   // Algorithm 7.11. w[i] and p[i] are respectively
\frac{4}{5}
    // the weight and profit of the ith object.
         b := cp; c := cw;
         for i := k + 1 to n do
             if (c+w[i] \leq m) then
10
                 c := c + w[i]; b := b - p[i];
11
12
13
14
         return b;
15
```

Consider the knapsack instance n = 4, (P1,P2, P3,P4) = (10,10,12,18),(W1,W2,W3,W4) = (2, 4, 6,9), and m = 15.

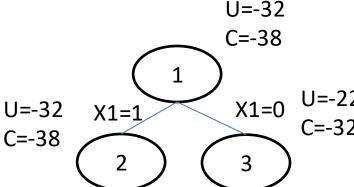
 The computation of U(1) and C(1) is done as follows: The bound U(1) has a value Ubound (0,0,0,15).

1 U=-32 C=-38

• Ubound(0,0,0,15) returns -32.

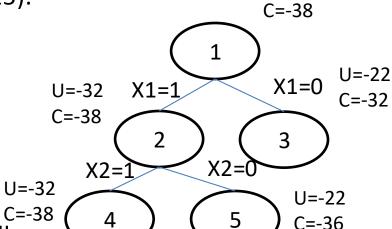
Function Bound is similar to UBound, except that it also considers a fraction of the first object that doesn't fit the knapsack. For example, in computing $\hat{c}(1)$, the first object that doesn't fit is 4 whose weight is 9. The total weight of the objects 1, 2, and 3 is 12. So, Bound considers a fraction $\frac{3}{9}$ of the object 4 and hence returns $-32 - \frac{3}{9} * 18 = -38$.

- The computation of U(2) and C(2) is done as follows: The bound U(2) has a value Ubound (-10,2,1,15).
- Ubound(-10,2,1,15) returns -32.
- $C(2) = -32 18 * \frac{3}{9} = -38$



- The computation of U(3) and c(3) is done as follows: The bound U(3) has a value Ubound (0,0,1,15).
- Ubound(0,0,1,15) returns -22.
- C(3) = -22-18* $\frac{5}{9}$ = -32
- Because of node 2 is having lease cost expand it to the next level.

- The computation of U(4) and C(4) is done as follows: The bound U(4) has a value Ubound (-20,6,2,15).
- Ubound(-20,6,2,15) returns -32.
- $C(4) = -32 18 * \frac{3}{9} = -38$

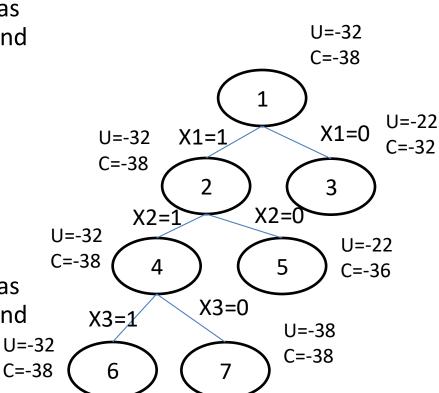


U = -32

- The computation of U(5) and c(5) is done as follows: The bound U(5) has a value Ubound (-10,2,2,15).
- Ubound(-10,2,2,15) returns -22.
- $C(5) = -22 18 * \frac{7}{9} = -36$
- Because of node 4 is having lease cost expand it to the next level.

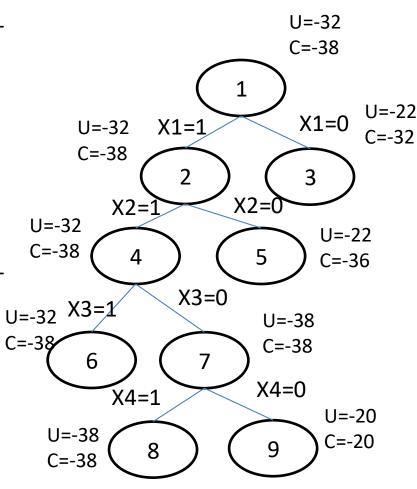
- The computation of U(6) and C(6) is done as follows: The bound U(6) has a value Ubound (-32,12,3,15).
- Ubound (-32,12,3,15) returns -32.
- C(6) = $-32 18 * \frac{3}{9} = -38$

- The computation of U(7) and C(7) is done as follows: The bound U(7) has a value Ubound (-20,6,3,15).
- Ubound(-20,6,3,15) returns -38.
- C(3) = -38 0 = -38
- Because of node 7 is having lease cost expand it to the next level.



- The computation of U(8) and C(8) is done as follows: The bound U(8) has a value Ubound (-38,15,4,15).
- Ubound (-38,15,4,15) returns -38.
- C(6) = -38-0=-38

- The computation of U(9) and C(9) is done as follows: The bound U(9) has a value Ubound (-20,6,4,15).
- Ubound(-20,6,4,15) returns -20.
- C(3) = -20-0 = -20
- Because of node 8 is having lease cost and all the object are over. Hence node 8 is the Answer Node.
- The solution is (1,1,0,1) with total profit of 38.



Problem for practice

- Consider the knapsack instance n = 5, (P1,P2, P3,P4,P5) = (10,15,6,8,4),(W1,W2,W3,W4,W5) = (4,6,3,4,2), and m = 12.
- Consider the knapsack instance n = 5, (P1,P2, P3,P4,P5) = (12,10,5,9,3),(W1,W2,W3,W4,W5) = (3,5,2,5,3), and m = 12.

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