

ALU Verification Document

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Introduction

This document outlines the verification process for an Arithmetic Logic Unit (ALU) design, ensuring that the implemented functionality adheres to the specified requirements. The ALU is a critical component in digital systems, responsible for performing arithmetic and logical operations, and its correct operation is essential for overall system reliability.

The verification process involves a thorough review of the design specification, development of a comprehensive testbench, and execution of test cases to validate the ALU's functionality under various scenarios. The testbench will include randomized tests to cover all conditions.

Key Objectives

Key objectives of the project are :-

- Understanding the ALU design specification, including supported operations (e.g., addition, subtraction, AND, OR, XOR, shifts) and control signals.
- Developing a structured testbench using a hardware verification language (e.g., SystemVerilog) with assertions and coverage metrics.
- Executing functional verification to confirm that all operations produce expected results.
- Analyzing coverage (code, functional, and assertion coverage) to ensure all design aspects are thoroughly tested.

DUT INTERFACES

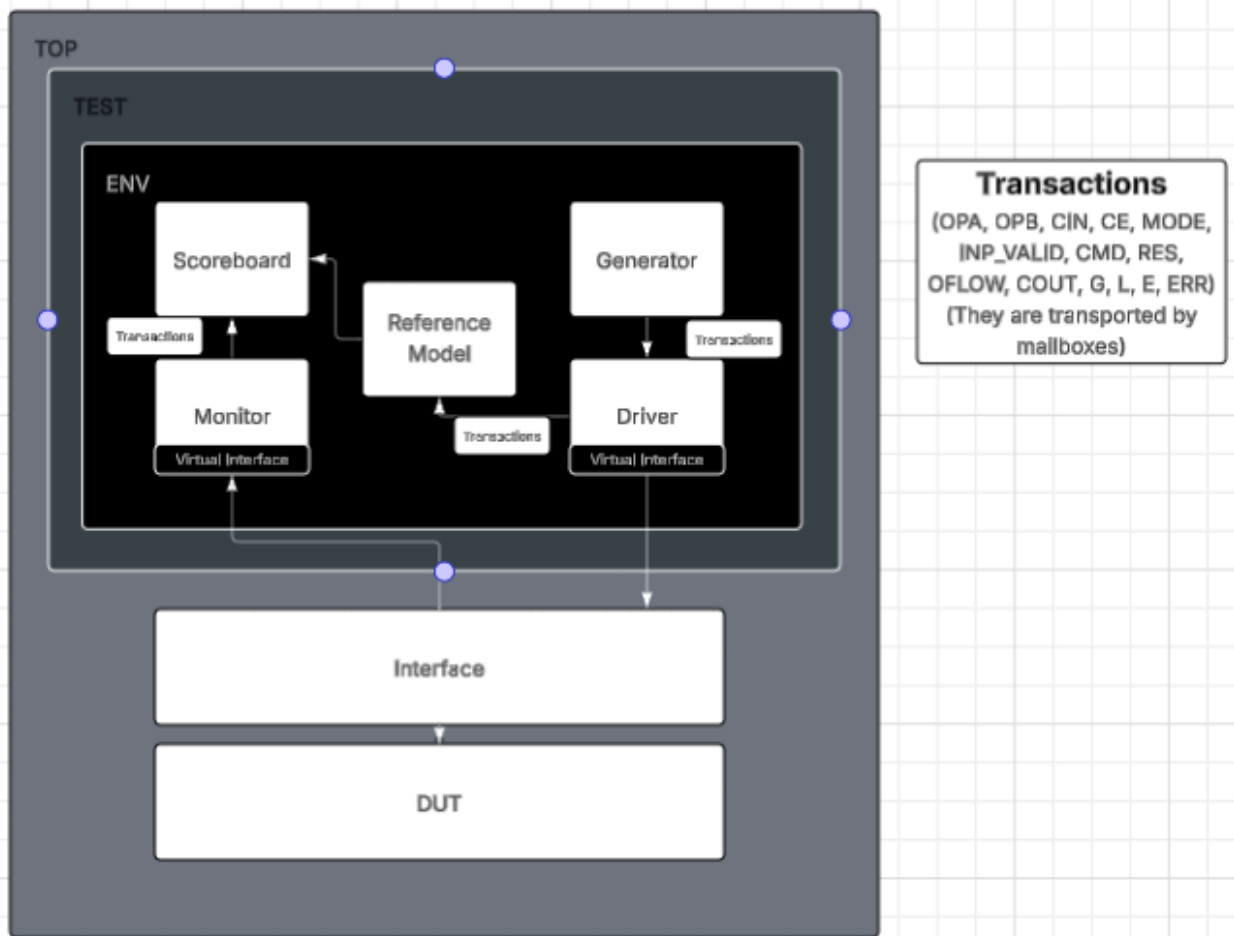
The DUT consists of the following input and output pins.

PIN name	Direction	Width	Description
OPA	INPUT	Parameterized	Parameterized operand 1
OPB	INPUT	Parameterized	Parameterized operand 2
CIN	INPUT	1	This is the active high carry in input signal of 1-bit.
CLK	INPUT	1	This is the clock signal to the design and it is edge

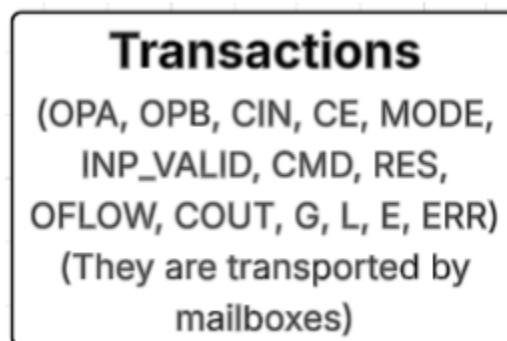
			sensitive.
RST	INPUT	1	This is the active high asynchronous reset to the design.
CE	INPUT	1	This is the active high clock enable signal 1 bit.
MODE	INPUT	1	MODE signal 1 bit is high, then this is an Arithmetic Operation otherwise it is logical operation
INP_VALID INPUT	INPUT	2	Operands are valid as per below table :- 00 : No operand is valid. 01: Operand A is valid. 10: Operand B is valid. 11: Both Operands are valid.
CMD	INPUT	4	Selects the command to be executed.
RES	OUTPUT	Parameterized + 1	This is the total parameterized plus 1 bits result of the instruction performed by the ALU.
OFLOW	OUTPUT	1	This 1-bit signal indicates an output overflow, during Addition/Subtraction
COUT	OUTPUT	1	This is the carry out signal of 1-bit, during Addition/Subtraction
G	OUTPUT	1	This is the comparator output of 1-bit, which indicates that the value of OPA is greater than the value of OPB.

L	OUTPUT	1	This is the comparator output of 1-bit, which indicates that the value of OPA is lesser than the value of OPB/
E	OUTPUT	1	This is the comparator output of 1-bit, which indicates that the value of OPA is equal to the value of OPB.
ERR	OUTPUT	1	When Cmd is selected as 12 or 13 and mode is logical operation, if 4th, 5th, 6th and 7th bit of OPB are 1, then ERR bit will be 1 else it is high impedance.

Testbench Architecture



Transactions



Transactions are class objects that encapsulate all input and output signals of the ALU. They serve as the primary data structure passed between testbench components (via mailboxes). They consist of the following signals.

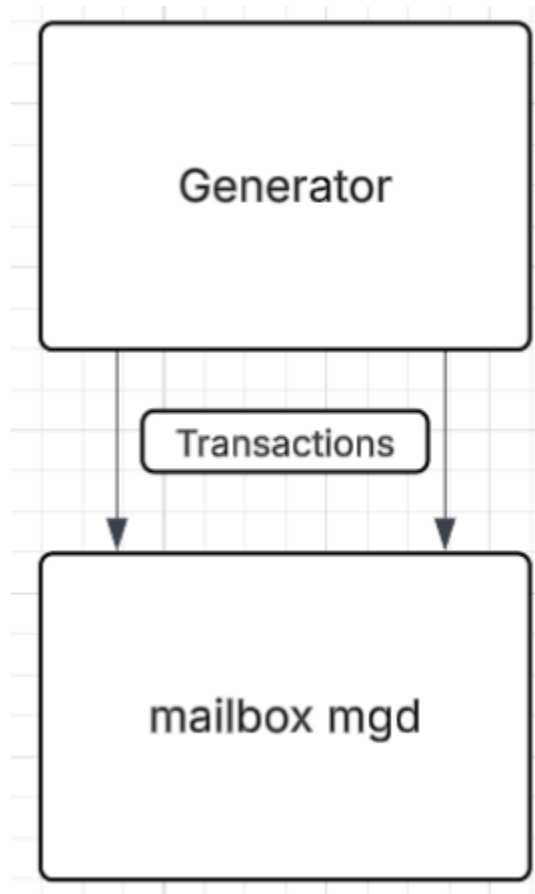
1. Inputs

- OPA, OPB (Operands)
- CIN (Carry-in)
- CE (Clock Enable)
- MODE (Operation Mode)
- CMD (Command/Opcode)

2. Outputs

- RES (Result)
- OFLOW (Overflow)
- COUT (Carry-out)
- G, L, E (Greater, Less, Equal flags)
- ERR (Error flag)

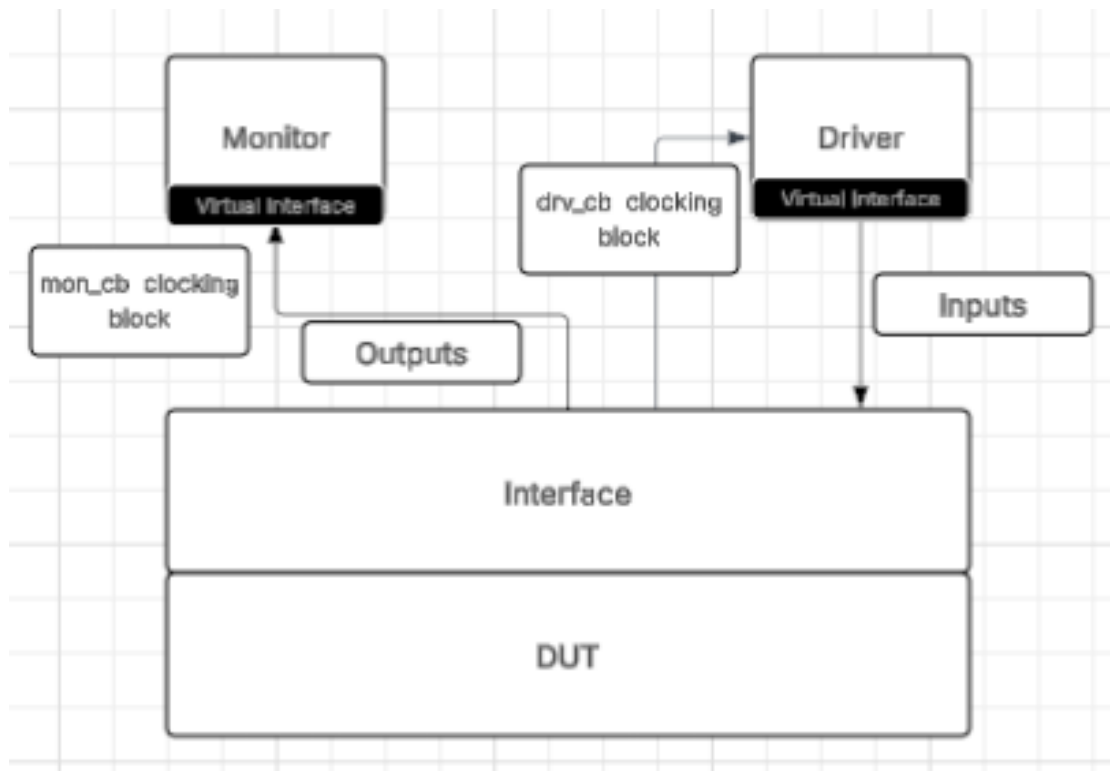
Generator



- Generates transactions containing randomized ALU inputs (OPA, OPB, CMD, CIN, MODE, CMD).

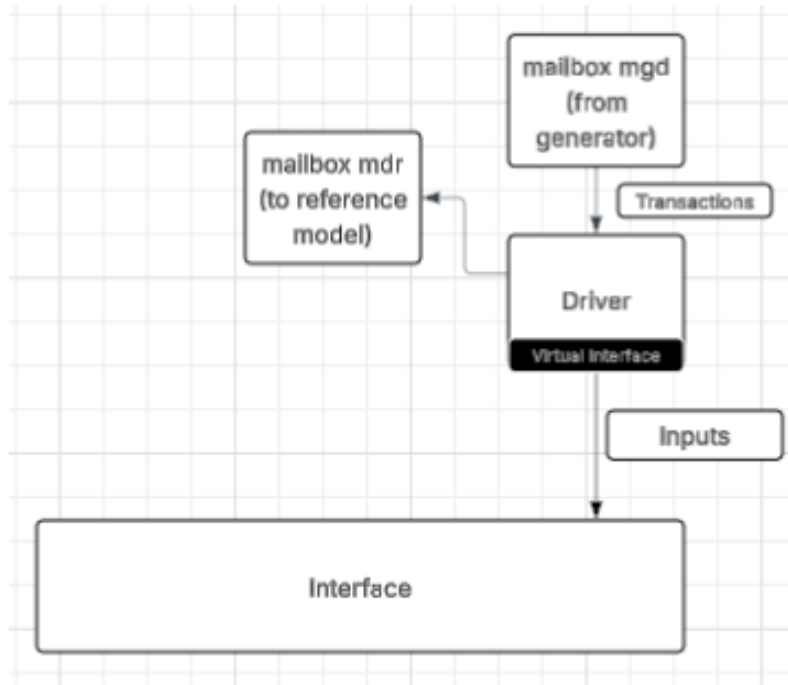
- Controls test variability by applying constraints to randomization (e.g., valid opcodes, corner-case operands).
- Sends transactions to the Driver via a mailbox for execution on the DUT.

Interface



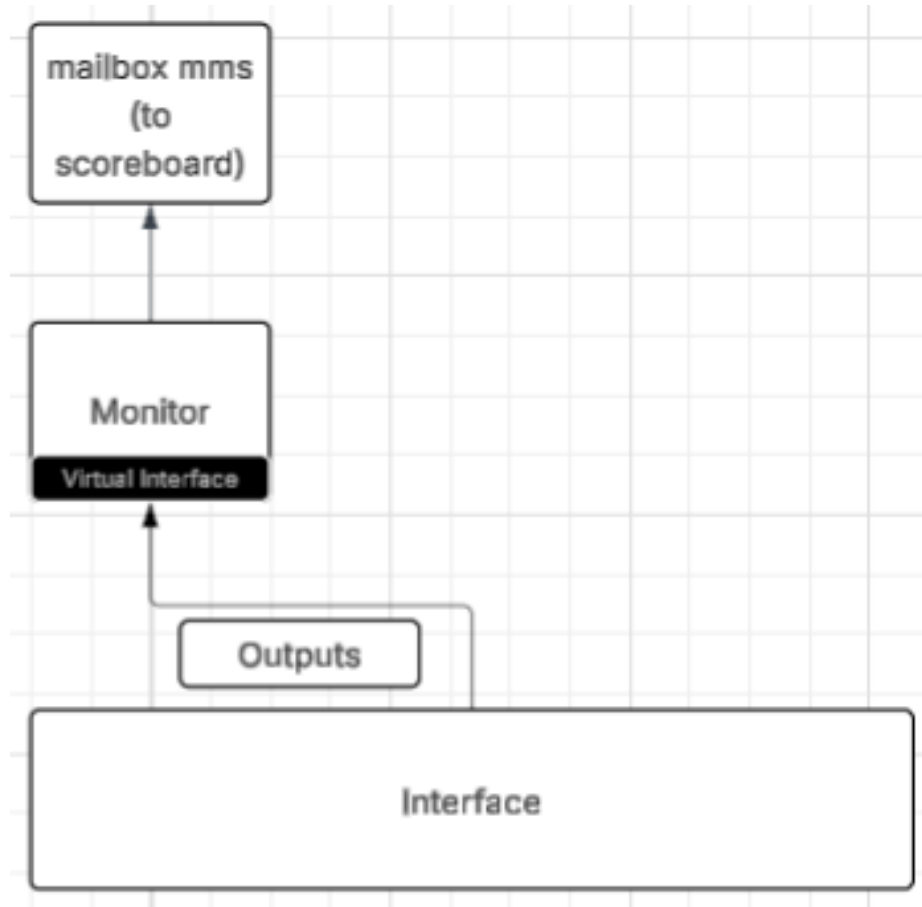
- It is used to bundle all inputs and outputs of DUT, so we don't have to instantiate DUT every time and can directly use an interface.
- It is used to synchronize different components of the testbench to work together via clocking blocks namely **drv_cb** (for driver), **mon_cb**(for monitor), **ref_cb**(for reference model).
- It is used to drive the inputs from the driver to the DUT, and used to access output values from DUT to the monitor.

Driver



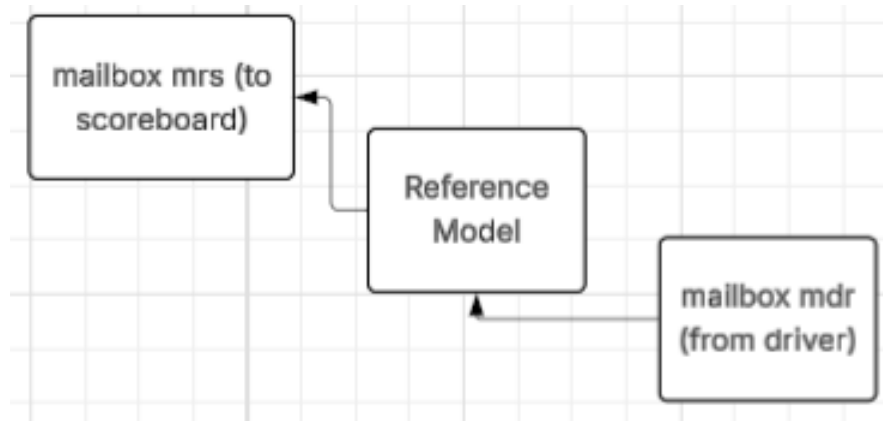
- Driver receives transactions from Generator via mailbox mgd.
- Drives inputs to the DUT through a virtual interface.
- Handles special cases (single operand commands, multi operand commands with wrong inp_valid, multiplication operations).
- Send transactions to the reference model via mailbox mdr.
- Tracks functional coverage of inputs being driven to DUT.

Monitor



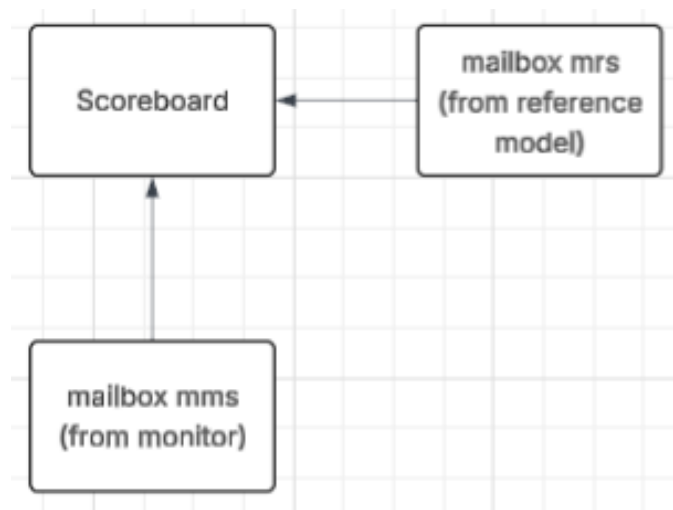
- Monitor as the name states is used to monitor the outputs from the DUT via the interface.
- The Monitor then takes these outputs and puts them in a mailbox which is sent to the scoreboard.

Reference Model



- It allows us to replicate the ALU operations.
- We take inputs from transaction objects received from the driver via a mailbox.
- We take these inputs, feed it to our ALU, perform the operations and generate the outputs.
- These outputs are sent to the scoreboard via a mailbox, where they get compared with the outputs from the DUT.

Scoreboard



- It compares the DUT outputs with the outputs generated by our reference model.
- It calculates how many test cases have passed and how many have failed.
- It lets us know whether the DUT works as intended.

Errors in DUT Functionality

Sno	Operation	Errors
1	Add Unsigned	-
2	Subtraction Unsigned	-
3	Addition (Cin)	Cin arriving at the next clock cycle.
4	Subtraction (Cin)	Cin arriving at the next clock cycle.
5	Increment A	Wrong operation logic, Not working for inp_valid = 2'b01.
6	Decrement A	Not working for inp_valid = 2'b01
7	Increment B	Wrong operation logic, Not working for inp_valid = 2'b10.
8	Decrement B	Wrong operation logic. Not working for inp_valid = 2'b10
9	Comparision	-
10	Increment Multiplication	-
11	Shift Multiplication	Wrong operation logic
12	AND	-
13	NAND	-
14	OR	Wrong operation logic
15	NOR	-
16	XOR	-
17	XNOR	-
18	NOT of A	Not working for inp_valid = 2'b01
19	NOT of B	Not working for inp_valid = 2'b10

20	Shift Right A by 1 bit	Wrong Operation Logic, Not working for inp_valid = 2'b01.
21	Shift Left A by 1 bit	Not working for inp_valid = 2'b01.
22	Shift Right B by 1 bit	Wrong Operation Logic, Not working for inp_valid = 2'b10.
23	Shift Left B by 1 bit	Not working for inp_valid = 2'b10.
24	Rotate A left by B bits	-
25	Rotate A right by B bits	Error not being asserted if OPA[7:4] > 0.
26	Invalid Inputs	Error not being asserted when inp_valid = 2'b00.
27	16 Clock Cycle Timeout	Error not being asserted if inp_valid = 2'b11 is not received even after waiting 16 clock cycles.

Coverage

Coverage is a metric used in verification to measure how thoroughly a design has been tested. It provides quantitative data on:

- Which parts of the design have been exercised.
- Which test scenarios have been executed.
- Whether all functional requirements have been verified.

In digital design verification, coverage ensures that:

- All features of the ALU are tested.
- Corner cases (edge conditions) are exercised.

We are using two major covergroups to measure our coverage :- cg(covergroup for inputs) and mon_cg(covergroup for outputs).

Input Coverage (cg)

The covergroup cg is used to measure the range of inputs we have provided to the DUT.

cg

Summary	Total Bins	Hits	Hit %
Coverpoints	26	26	100.00%
Crosses	104	104	100.00%

Search:

CoverPoints	Total Bins	Hits	Misses	Hit %	Goal %	Coverage %
c1	1	1	0	100.00%	100.00%	100.00%
c2	1	1	0	100.00%	100.00%	100.00%
c3	2	2	0	100.00%	100.00%	100.00%
c4	2	2	0	100.00%	100.00%	100.00%
c5	4	4	0	100.00%	100.00%	100.00%
c6	16	16	0	100.00%	100.00%	100.00%

Search:

Crosses	Total Bins	Hits	Misses	Hit %	Goal %	Coverage %
#cross_0#	32	32	0	100.00%	100.00%	100.00%
#cross_1#	8	8	0	100.00%	100.00%	100.00%
#cross_2#	64	64	0	100.00%	100.00%	100.00%

Output Coverage (mon_cg)

This covergroup is used to measure the range of inputs we have received from the DUT.

mon_cg

Summary	Total Bins	Hits	Hit %
Coverpoints	14	11	78.57%
Crosses	0	0	0.00%

Search:

CoverPoints	Total Bins	Hits	Misses	Hit %	Goal %	Coverage %
c1	2	2	0	100.00%	100.00%	100.00%
c2	2	1	1	50.00%	50.00%	50.00%
c3	2	1	1	50.00%	50.00%	50.00%
c4	2	1	1	50.00%	50.00%	50.00%
c5	2	2	0	100.00%	100.00%	100.00%
c6	2	2	0	100.00%	100.00%	100.00%
c7	2	2	0	100.00%	100.00%	100.00%

Assertion Coverage

They are used to check whether the DUT is functioning as specified.

No.	Feature	Signal	Description	Status
1	Valid Inputs Check			PASS
1.1		opa	opa should not have x or z in any of its bits.	
1.2		opb	opb should not have x or z in any of its bits.	
1.3		cin	cin should not be x or z.	
1.4		mode	mode should not have x or z in any of its bits.	
1.5		cmd	cmd should not have x or z in any of its bits.	
1.6		inp_valid	inp_valid should not have x or z in any of its bits.	
2	Error Check			FAIL
2.1		inp_valid	Check if inp_valid = 2'b01/10, then if within 16 clock cycles inp_valid != 2'b11, error flag is high.	
2.2		mode, cmd, opb, err	Check if inp_valid = 2'b11, mode = 0, cmd = 4'b1100 / 4'b1101 (rotate operation), then if any of bits with position > log2(width), then it will set the err flag as high.	
3	Clock Enable Check			PASS
		ce	Clock enable should be stable once made high.	
4	Reset Check			PASS
		rst	Reset signal should set output bins to z.	

Assertions	Failure Count	Pass Count	Attempt Count	Vacuous Count	Disable Count	Active Count	Peak Active Count	Status
assert_rst_check	0	1	2446	2445	0	0	1	Covered
assert_stable_cen	0	2443	2446	2	0	1	2	Covered
assert_rotate_err	1770	55	2446	619	1	1	2	Failed
assert_loop_err	0	0	2446	2445	1	0	1	ZERO
assert_valid_ip	0	2443	2446	1	1	1	2	Covered

1) Valid Inputs Check

```

property valid_ip;
    @(posedge clk)
        disable iff(rst) cen ==> not($isunknown({opa, opb, cin, mode, cmd, inp_valid}));
endproperty
assert property(valid_ip)begin
    $info("Valid Inputs Pass");
end
else begin
    $error("Valid Inputs Fail");
end

```

2) Error Check

```

//Check 16 cycle error condition
property loop_err;
    @(posedge clk)
        disable iff(rst) (cen && (inp_valid == 1 || inp_valid == 2)) |-> (inp_valid == 3)[*16] |> err;
endproperty
assert property(loop_err)begin
    $info("Loop error condition Pass");
end
else begin
    $info("Loop error condition Fail");
end

//Rotate error
property rotate_err;
    @(posedge clk)
        disable iff(rst) (cen && inp_valid == 3 && mode == 0 && (cmd == 12 || cmd == 13) && opb[7:4] > 0) |> err;
endproperty
assert property(rotate_err)begin
    $info("Rotate Error Condition Pass");
end
else begin
    $info("Rotate Error Condition Fail");
end
end

```

3) Clock Enable Check

```

//Cen stable
property stable_cen;
    @(posedge clk) cen |>=> $stable(cen);
endproperty
assert property(stable_cen)begin
    $info("Stable Cen Pass");
end
else begin
    $info("Stable Cen Fail");
end
end

```

4) Reset Check

```

//Check if asserting reset is making outputs z
property rst_check;
    @(posedge clk)
        rst |-> (res == 9'bzzzzzzz && cout == 1'bz && oflow == 1'bz && e == 1'bz && g == 1'bz && l == 1'bz && err == 1'bz);
endproperty
assert property(rst_check)begin
    $info("Reset Check Pass");
end
else begin
    $info("Reset Check Fail");
end
end

```

Overall Coverage

Coverage Summary by Type:

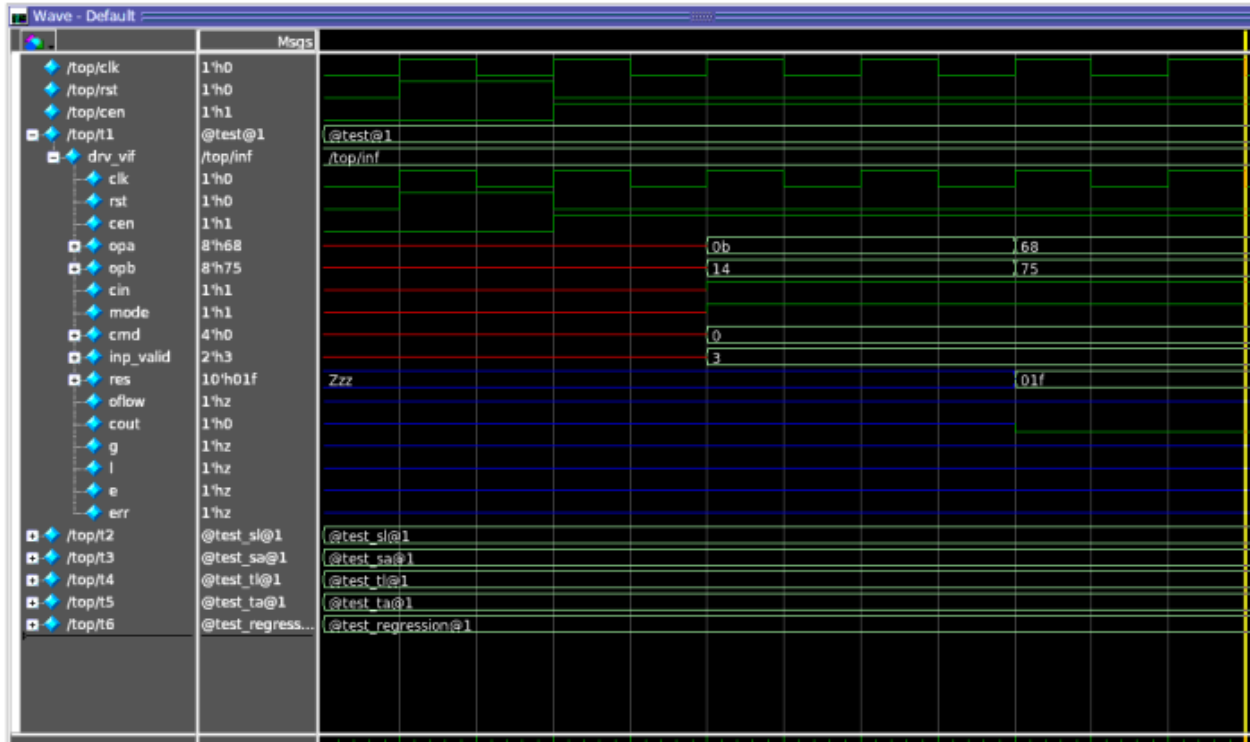
Total Coverage:					92.44%	84.08%
Coverage Type ◀	Bins ◀	Hits ◀	Misses ◀	Weight ◀	% Hit ◀	Coverage ◀
Covergroups	144	141	3	1	97.91%	89.28%
Statements	550	507	43	1	92.18%	92.18%
Branches	208	195	13	1	93.75%	93.75%
FEC Conditions	55	42	13	1	76.36%	76.36%
Toggles	296	275	21	1	92.90%	92.90%
Assertions	5	3	2	1	60.00%	60.00%

Covergroup	Metric	Goal	Status

TYPE /pkg/driver/cg	100.0%	100	Covered
covered/total bins:	130	130	
missing/total bins:	0	130	
% Hit:	100.0%	100	

Output Waveform

2 Cycle Operation (Unsigned Addition here) Waveform



3 Cycle Operation (Increment and Multiply) Waveform

