# submission final

April 20, 2025

# 1 Title: Severity of road traffic accidents

[1]: %load\_ext watermark %watermark -a "Van Wu" -u -d -t -v -p numpy,pandas,matplotlib,scikit-learn

Author: Van Wu

Last updated: 2025-04-20 13:03:29

Python implementation: CPython Python version : 3.13.2 IPython version : 9.0.2

numpy : 2.2.4 pandas : 2.2.3 matplotlib : 3.10.1 scikit-learn: 1.6.1

### 1.1 Preparation

- Github link
- Number of words: \*\*\*
- Runtime: \*\*\* hours (Memory 32 GB, CPU AMD Ryzen 7 5800H with Radeon Graphics CPU @3.20GHz)
- Coding environment: Coding environment: VS Code with Jupyter plugin (local), not SDS Docker
- License: this notebook is made available under the Creative Commons Attribution license.
- Additional library [libraries not included in SDS Docker or not used in this module]:
  - watermark: A Jupyter Notebook extension for printing timestamps, version numbers, and hardware information. (used to print Python and package versions for reproducibility.)
  - **–** ......

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#### 1.3 Introduction

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Road traffic accidents (RTAs) represent a significant public health and urban governance issue globally. In the UK, despite advancements in vehicle technology and traffic regulation, thousands of individuals are injured or killed on the roads annually. Predicting the severity of these accidents is crucial for targeted policy interventions and infrastructure planning. Accident severity is influenced by a range of contextual factors including weather, road geometry, traffic volume, time of day, and infrastructure design (Abdel-Aty & Haleem, 2011). As cities move towards data-driven governance, the use of machine learning models has become increasingly common in road safety research (Zhang et al., 2020).

Recent literature has demonstrated the effectiveness of supervised learning algorithms such as logistic regression, random forests, and XGBoost in predicting accident severity using structured datasets (Ahmed et al., 2023). These models are particularly suitable for capturing non-linear interactions and heterogeneous effects among multiple explanatory variables. Moreover, explainable AI techniques such as SHAP (SHapley Additive exPlanations) have been widely adopted to interpret complex models and understand feature importance, which aids in translating statistical findings into actionable insights for policymakers.

This study leverages the UK Department for Transport's Road Safety Data (2015–2019), which documents detailed information on individual accident cases, including temporal, spatial, environmental, and infrastructural attributes. By integrating network-based features such as road betweenness centrality extracted via OpenStreetMap, this project attempts to bridge the gap between spatial network analysis and predictive modelling of accident severity. The objective is twofold: to evaluate the predictive performance of commonly used machine learning models on accident severity classification, and to examine the relative contribution of different spatial and contextual factors to the outcome.

The period from 2015 to 2019 was deliberately chosen to ensure data stability and validity. This timeframe avoids the confounding effects of the COVID-19 pandemic (2020–2021), which significantly disrupted travel behaviour, enforcement levels, and urban mobility patterns across the UK (DfT, 2021). It also precedes Phase 2 of London's major road transformation programme, including the expansion of Low Traffic Neighbourhoods (LTNs) and segregated cycling infrastructure, which introduced substantial structural changes to the transport system from 2020 onwards (TfL, 2024). In contrast, the preceding years (2010–2014) marked a foundational policy phase, characterised

by the implementation of new traffic enforcement measures such as fixed penalty notices for careless driving and increased fines for common violations (DfT, 2013). By focusing on the relatively stable and mature period between 2015 and 2019, this study ensures greater internal consistency and enables clearer interpretation of accident severity patterns, isolated from exogenous policy or behavioural shocks.

In contrast to most existing studies that primarily rely on tabular attributes such as time, weather, and road conditions, this project introduces spatial network metrics—specifically, betweenness and degree centrality—extracted from OpenStreetMap. This integration of spatial topology enhances the model's capacity to capture urban structural influences on accident severity, offering a novel bridge between road network analysis and predictive modeling.

## []:

### 1.4 Research questions

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Can supervised machine learning models accurately predict the severity of road traffic accidents in London using spatial, temporal, and environmental features?

This study investigates whether supervised machine learning models can accurately predict the severity of road traffic accidents in London based on spatial, temporal, and environmental features. Specifically, it examines the predictive power of variables such as time of day, weather conditions, and road network centrality. The study also compares the performance of Logistic Regression, Random Forest, and XGBoost, and uses SHAP analysis to identify the most influential features for each severity level (fatal, serious, slight).

# []:

#### 1.5 Data

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# 1.5.1 Data Description

Variable	Type Description	Notes
accident_severity	Categoric deverity level of the accident $(1 = \text{Fatal}, 2 = \text{Serious}, 3 = \text{Slight})$	Target variable
speed_limit	Numeric Speed limit of the road segment (in mph)	-
accident_year	Numeric Year of the accident (2015–2019)	Used for train-test split
mean_betweenness	Numeric Mean betweenness centrality of nearby road segments	Spatial network feature
max_betweenness	Numeric Maximum betweenness centrality of nearby road segments	Key spatial variable
mean_degree	Numeric Mean degree centrality of road network	-
$\max\_degree$	Numeric Maximum degree centrality	-

Variable	Type	Description	Notes
edge_count	Numerio	c Number of road segments (edges) in the	Spatial indicator
		local road network	of network density
$day\_of\_week\_*$	Categor	i@he-hot encoded day of week	One-hot encoded
		(Monday–Saturday, Sunday as baseline)	
$road\_type\_*$	Categor	ichne-hot encoded road type categories	One-hot encoded
light_conditions_*	Categor	iconne-hot encoded lighting conditions (e.g.,	One-hot encoded
		daylight, darkness with/without lighting)	
$weather\_conditions\_$	*Categor	iche-hot encoded weather conditions (e.g.,	One-hot encoded
		fine, rain, fog)	
road_surface_condit	io6a <u>te</u> gor	ichhe-hot encoded surface conditions (e.g.,	One-hot encoded
		dry, wet)	
junction_control_*	Categor	iche-hot encoded control types at junctions	One-hot encoded
junction_detail_*	Categor	ichhe-hot encoded structural junction types	One-hot encoded
pedestrian_crossing_	h@ategor	idahreh <u>o</u> * encoded presence of	One-hot encoded
		human-controlled crossings	
pedestrian_crossing_	pflytsicgol <u>r</u>	idalricities_e^hcoded presence of physical	One-hot encoded
		pedestrian facilities	
special_conditions_a	t <u>C</u> sitteg <u>o</u> ř	i@he-hot encoded site-specific conditions	One-hot encoded
		(e.g., roadworks)	
$first\_road\_class\_*$	Categor	ich he-hot encoded classification of the	One-hot encoded
		primary road	
second_road_class_^	* Categor	ich he-hot encoded classification of the	One-hot encoded
		secondary road	
trunk_road_flag_*	Categor	icone-hot encoded trunk road indicator	One-hot encoded
urban_or_rural_area	a_Categor	ic@ne-hot encoded urban/rural area	One-hot encoded
		classification	
time_hour	Numerio	c Hour of the accident (e.g., $13.55 \rightarrow 13$ )	Derived feature
betweenness_level_e	n <b>@rddd</b> al	Quartile level of mean_betweenness $(0 =$	For logistic
		Low, $3 = \text{High}$ )	regression
			compatibility

 $Note: \ *\_ denotes \ one-hot \ encoded \ categories \ split \ into \ multiple \ columns.$ 

The following table provides code-level descriptions for categorical variables used in this study. Definitions are based on the official UK Department for Transport data guide: data.gov.uk.

Variable Prefix	Code	Meaning
day_of_week	1	Sunday
v — —	2	Monday
	3	Tuesday
	4	Wednesday
	5	Thursday
	6	Friday
	7	Saturday
road_type	1	Roundabout

Variable Prefix	Code	Meaning
	2	One way street
	3	Dual carriageway
	6	Single carriageway
	7	Slip road
	9	Unknown
light_conditions	1	Daylight
	4	Darkness - lights lit
	5	Darkness - lights unlit
	6	Darkness - no lighting
	7	Darkness - lighting unknown
weather_conditions	1	Fine no high winds
	2	Raining no high winds
	3	Snowing no high winds
	4	Fine + high winds
	5	Raining + high winds
	6	Snowing + high winds
	7	Fog or mist
	8	Other
	9	Unknown
road_surface_conditions	1	Dry
	2	Wet or damp
	3	Snow
	4	Frost or ice
	5	Flood (surface water)
	9	Unknown
junction_control	0	None
	1	Authorised person
	2	Auto traffic signal
	3	Stop sign
	4	Give way or uncontrolled
	9	Unknown
pedestrian_crossing_human_control	0	None
_ 0	1	School crossing patrol
	2	Other human control
	9	Unknown
pedestrian_crossing_physical_facilities	0	None
O_r /	1	Zebra crossing
	4	Pelican crossing
	5	Footbridge or subway
	7	Refuge
	8	Unknown
	9	Other
urban_or_rural_area	1	Not used
<u> </u>	2	Urban
	3	Rural
trunk_road_flag	1	Non-trunk road
~	_	

Variable Prefix	Code	Meaning
first_road_class / second_road_class	2 1 2 3 4 5	Trunk road Motorway A(M) Road A Road B Road C Road Unclassified

# 1.5.2 Data Import & Cleaning

```
[51]: # It would import the packages that would be used first.
import pandas as pd
from sklearn.model_selection import train_test_split
from sklearn.ensemble import RandomForestClassifier
from sklearn.metrics import classification_report
import os
import osmnx as ox
import networkx as nx
import geopandas as gpd
from tqdm import tqdm
```

```
[52]: # define folder
input_folder = '../data/raw'
output_folder = '../data/clean'
```

```
[53]: # Road Data
df = pd.read_csv('../data/raw/1979-latest-published-year.csv')
df = df[df['accident_year'].isin([2015, 2016, 2017, 2018, 2019])]
print(f"The data volume from 2015 to 2019 is {len(df)} ")

# save
df.to_csv("../data/raw/2015_2019.csv", index=False)
```

C:\Users\Lenovo\AppData\Local\Temp\ipykernel\_13184\542922050.py:2: DtypeWarning: Columns (0,2,15,16,35) have mixed types. Specify dtype option on import or set low\_memory=False.

df = pd.read\_csv('../data/raw/1979-latest-published-year.csv')

The data volume from 2015 to 2019 is 646830

```
[54]: columns_to_keep = [
          'accident_severity',
          'number_of_vehicles',
          'number_of_casualties',
          'day_of_week',
          'time',
```

```
'first_road_class',
     'second_road_class',
     'road_type',
     'speed_limit',
     'junction_detail',
     'junction_control',
     'pedestrian_crossing_human_control',
    'pedestrian_crossing_physical_facilities',
     'light conditions',
     'weather_conditions',
     'road surface conditions',
    'special_conditions_at_site',
    'carriageway_hazards',
     'urban_or_rural_area',
    'did_police_officer_attend_scene_of_accident',
     'trunk_road_flag',
    'local_authority_ons_district',
    'accident_year'
]
selected_columns = [col for col in columns_to_keep if col in df.columns]
df_cleaned = df[selected_columns]
# Check and handle the missing values
missing_counts = df_cleaned.isnull().sum()
total_missing = missing_counts.sum()
if total_missing > 0:
    print(f"The number of missing values are {total_missing} :")
    print(missing_counts[missing_counts > 0])
    # Discard the rows containing missing values
    df_cleaned = df_cleaned.dropna()
    print(f"Missing values have been cleared, remaining {len(df_cleaned)}_\_
 ⇔records.")
# Save the cleaned files
df_cleaned.to_csv('../data/clean/1519_cleaned.csv', index=False)
print(f"Saved to: {output_folder}, total: {len(df_cleaned.columns)} columns,__
  →{len(df_cleaned)} records.")
The number of missing values are 37:
speed_limit
               37
dtype: int64
Missing values have been cleared, remaining 646793 records.
Saved to: ../data/clean, total: 23 columns, 646793 records.
```

#### 1.5.3 Spatial Feature Engineering

This step extracts borough-level road networks from OpenStreetMap and calculates betweenness and degree centrality to capture spatial structure in the transport network.

```
[6]: # RoadCentrality
     path = "../data/Borough Boundaries.geojson"
     boroughs = gpd.read file(path)
     boroughs = boroughs[["name", "gss_code", "geometry"]].rename(columns={"name":__

¬"borough"})
     ox.settings.log_console = False
     ox.settings.use cache = True
     results = []
     for idx, row in tqdm(boroughs.iterrows(), total=len(boroughs), desc="Processing_
      ⇔boroughs"):
         borough_name = row["borough"]
         gss_name = row["gss_code"]
         geometry = row["geometry"]
         try:
             print(f"Processing: {borough_name}")
             G = ox.graph_from_polygon(geometry, network_type="drive", simplify=True)
             betweenness = nx.betweenness_centrality(G, weight="length", k=100, __
      ⇒seed=42)
             degree = dict(G.degree())
             nx.set_node_attributes(G, betweenness, "betweenness")
             nx.set_node_attributes(G, degree, "degree")
             edge data = []
             for u, v, key, data in G.edges(keys=True, data=True):
                 edge data.append({
                     "u": u,
                     "v": v,
                     "key": key,
                     "geometry": data.get("geometry", None),
                     "betweenness": (G.nodes[u]["betweenness"] + G.
      →nodes[v]["betweenness"]) / 2,
                     "degree": (G.nodes[u]["degree"] + G.nodes[v]["degree"]) / 2
                 })
             edges_df = gpd.GeoDataFrame(edge_data, geometry="geometry", crs="EPSG:
```

```
summary = {
             "borough": borough_name,
             "gss_code": gss_name,
             "mean_betweenness": edges_df["betweenness"].mean(),
             "max_betweenness": edges_df["betweenness"].max(),
             "mean_degree": edges_df["degree"].mean(),
             "max_degree": edges_df["degree"].max(),
             "edge_count": len(edges_df)
        }
        results.append(summary)
    except Exception as e:
        print(f"Failed for {borough name}: {e}")
        continue
df_results = pd.DataFrame(results)
df_results.to_csv("../data/london_borough_road_centrality.csv", index=False)
print("All done! Results saved to 'london_borough_road_centrality.csv'")
Processing boroughs:
                       0%1
                                    | 0/33 [00:00<?, ?it/s]
Processing: Kingston upon Thames
                       3%1
                                    | 1/33 [00:05<02:40, 5.03s/it]
Processing boroughs:
Processing: Croydon
Processing boroughs:
                       6% l
                                    | 2/33 [00:17<04:55, 9.54s/it]
Processing: Bromley
                       9%1
Processing boroughs:
                                    | 3/33 [00:31<05:48, 11.61s/it]
Processing: Hounslow
Processing boroughs:
                      12%|
                                   | 4/33 [00:39<04:56, 10.22s/it]
Processing: Ealing
                      15% l
Processing boroughs:
                                   | 5/33 [00:48<04:27, 9.56s/it]
Processing: Havering
Processing boroughs: 18%|
                                   | 6/33 [00:56<04:07, 9.16s/it]
Processing: Hillingdon
Processing boroughs:
                      21%|
                                   | 7/33 [01:08<04:18, 9.94s/it]
Processing: Harrow
                                  | 8/33 [01:14<03:38, 8.73s/it]
Processing boroughs:
                      24%|
Processing: Brent
Processing boroughs: 27%
                                  | 9/33 [01:21<03:16, 8.17s/it]
```

Processing: Barnet

Processing boroughs: 30% | 10/33 [01:32<03:29, 9.13s/it]

Processing: Lambeth

Processing boroughs: 33%| | 11/33 [01:40<03:15, 8.90s/it]

Processing: Southwark

Processing boroughs: 36% | 12/33 [01:50<03:13, 9.21s/it]

Processing: Lewisham

Processing boroughs: 39% | 13/33 [01:58<02:57, 8.87s/it]

Processing: Greenwich

Processing boroughs: 42% | 14/33 [02:08<02:54, 9.20s/it]

Processing: Bexley

Processing boroughs: 45% | | 15/33 [02:17<02:39, 8.87s/it]

Processing: Enfield

Processing boroughs: 48% | 16/33 [02:26<02:36, 9.20s/it]

Processing: Waltham Forest

Processing boroughs: 52% | 17/33 [02:33<02:14, 8.40s/it]

Processing: Redbridge

Processing boroughs: 55% | 18/33 [02:41<02:02, 8.14s/it]

Processing: Sutton

Processing boroughs: 58% | 19/33 [02:47<01:47, 7.65s/it]

Processing: Richmond upon Thames

Processing boroughs: 61% | 20/33 [02:54<01:37, 7.51s/it]

Processing: Merton

Processing boroughs: 64% | 21/33 [03:01<01:26, 7.18s/it]

Processing: Wandsworth

Processing boroughs: 67% | 22/33 [03:09<01:23, 7.60s/it]

Processing: Hammersmith and Fulham

Processing boroughs: 70% | 23/33 [03:13<01:04, 6.47s/it]

Processing: Kensington and Chelsea

Processing boroughs: 73% | 24/33 [03:17<00:50, 5.59s/it]

Processing: Westminster

Processing boroughs: 76% | 25/33 [03:25<00:52, 6.55s/it]

Processing: Camden Processing boroughs: 79%| | 26/33 [03:33<00:48, 6.95s/it] Processing: Tower Hamlets Processing boroughs: 82%| | 27/33 [03:42<00:44, 7.41s/it] Processing: Islington Processing boroughs: 85%| | 28/33 [03:47<00:33, 6.71s/it] Processing: Hackney Processing boroughs: 88%| | 29/33 [03:52<00:25, 6.32s/it] Processing: Haringey Processing boroughs: 91%| | 30/33 [03:58<00:18, 6.18s/it] Processing: Newham Processing boroughs: 94%| | 31/33 [04:06<00:13, 6.70s/it] Processing: Barking and Dagenham Processing boroughs: 97%| | 32/33 [04:11<00:06, 6.17s/it] Processing: City of London Processing boroughs: 100%| | 33/33 [04:13<00:00, 7.67s/it] All done! Results saved to 'london\_borough\_road\_centrality.csv' [55]: # show print("Sample of calculated borough-level centrality metrics:") display(df\_results.head()) # Display descriptive statistical information print("\nSummary statistics of centrality metrics across boroughs:")

Sample of calculated borough-level centrality metrics:

		borough	gss_code	mean_betweenness	max_betweenness	\
0	Kingston upo	n Thames	E09000021	0.020622	0.261008	
1		Croydon	E09000008	0.012210	0.177637	
2		Bromley	E09000006	0.012135	0.172504	
3		Hounslow	E09000018	0.018356	0.335207	
4		Ealing	E09000009	0.015021	0.212142	
	mean_degree	max_degr	ee edge_co	ount		
0	5.271409	8	.0	3551		
1	5.383993	8	.0 14	1719		
2	5.425875	8	.0 15	5737		

display(df\_results[['mean\_betweenness', 'mean\_degree']].describe())

```
3 5.247866 8.0 10308
4 5.418720 8.0 10919
```

Summary statistics of centrality metrics across boroughs:

	mean_betweenness	mean_degree
count	33.000000	33.000000
mean	0.017935	5.334289
std	0.005285	0.172943
min	0.012135	4.583688
25%	0.014089	5.271409
50%	0.016811	5.369130
75%	0.020230	5.418720
max	0.038161	5.602621

#### 1.5.4 Data Merge & Summary

```
[56]: # Set the path
      accident_path = "../data/clean/1519_cleaned.csv"
      centrality_path = "../data/london_borough_road_centrality.csv"
      output_path = "../data/final/2015_2019_with_centrality.csv"
      df_accident = pd.read_csv(accident_path)
      df_centrality = pd.read_csv(centrality_path)
      # Merge the centrality data (encoded by region)
      df_merged = df_accident.merge(
         df_centrality,
         how="left",
         left_on="local_authority_ons_district",
         right_on="gss_code"
      # Delete the rows lacking centrality (non-London area)
      before_drop = len(df_merged)
      df_merged = df_merged.dropna(subset=["mean_betweenness"])
      after_drop = len(df_merged)
      dropped = before_drop - after_drop
      # Save the result
      df_merged.to_csv(output_path, index=False)
      print(f"The data has been combined with the centrality indicators and saved_{\sqcup}
       print(f"Total: {after_drop} records, remove {dropped} records.")
```

The data has been combined with the centrality indicators and saved to ../data/final/2015\_2019\_with\_centrality.csv

Total: 128261 records, remove 518532 records.

## 1.5.5 Exploratory Data Analysis (EDA)

dtype: object

Descriptive statistics (distribution maps, box plots, etc.)

Exploration of the Relationship between Features and Targets (including grouped bar charts and box plots)

```
[57]: df = pd.read_csv("../data/final/2015_2019_with_centrality.csv")
      print(df.shape)
      print(df.dtypes)
      print(df.isnull().sum())
      df.describe()
      df["accident_severity"].value_counts(normalize=True)
     (128261, 30)
     accident_severity
                                                        int64
     number_of_vehicles
                                                        int64
     number_of_casualties
                                                        int64
     day_of_week
                                                        int64
     time
                                                       object
                                                        int64
     first_road_class
     second_road_class
                                                        int64
                                                        int64
     road_type
     speed_limit
                                                      float64
     junction_detail
                                                        int64
     junction_control
                                                        int64
     pedestrian_crossing_human_control
                                                        int64
     pedestrian_crossing_physical_facilities
                                                        int64
     light conditions
                                                        int64
     weather_conditions
                                                        int64
     road_surface_conditions
                                                        int64
     special_conditions_at_site
                                                        int64
     carriageway_hazards
                                                        int64
     urban_or_rural_area
                                                        int64
     did_police_officer_attend_scene_of_accident
                                                        int64
     trunk_road_flag
                                                        int64
     local_authority_ons_district
                                                       object
     accident_year
                                                        int64
     borough
                                                       object
     gss_code
                                                       object
     mean_betweenness
                                                      float64
     max betweenness
                                                      float64
     mean_degree
                                                      float64
     max degree
                                                      float64
     edge_count
                                                      float64
```

```
number_of_vehicles
                                                      0
     number_of_casualties
                                                      0
     day_of_week
                                                      0
     time
                                                      0
     first_road_class
                                                      0
     second_road_class
                                                      0
     road_type
                                                      0
     speed_limit
                                                      0
                                                      0
     junction_detail
     junction_control
                                                      0
     pedestrian_crossing_human_control
                                                      0
                                                      0
     pedestrian_crossing_physical_facilities
                                                      0
     light_conditions
     weather_conditions
                                                      0
                                                      0
     road_surface_conditions
     special_conditions_at_site
                                                      0
                                                      0
     carriageway_hazards
     urban_or_rural_area
                                                      0
     did_police_officer_attend_scene_of_accident
                                                      0
     trunk road flag
                                                      0
     local_authority_ons_district
                                                      0
                                                      0
     accident_year
     borough
                                                      0
     gss_code
                                                      0
                                                      0
     mean_betweenness
                                                      0
     max_betweenness
                                                      0
     mean_degree
                                                      0
     max_degree
     edge_count
                                                      0
     dtype: int64
[57]: accident_severity
      3
           0.876089
      2
           0.119179
           0.004733
      Name: proportion, dtype: float64
[58]: import numpy as np
      import seaborn as sns
      import matplotlib.pyplot as plt
      # Distribution of accident severity
      plt.figure(figsize=(6,4))
      sns.countplot(x="accident_severity", data=df)
      plt.title("Accident Severity Distribution")
      plt.show()
```

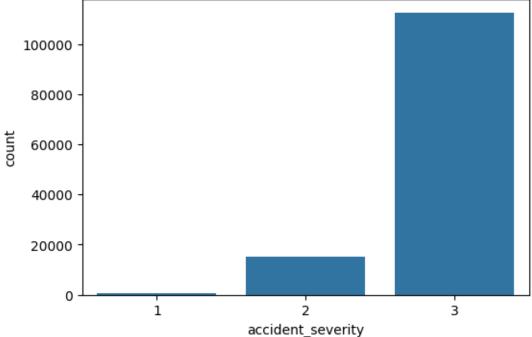
0

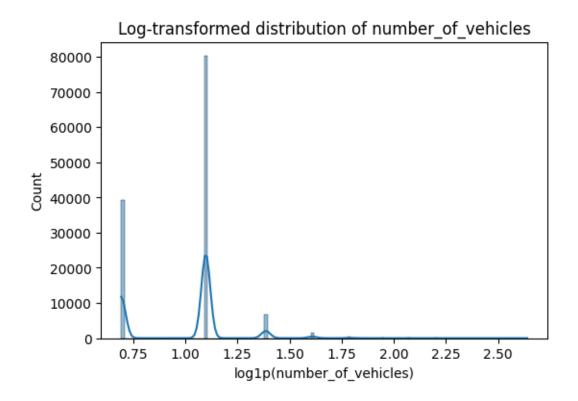
accident\_severity

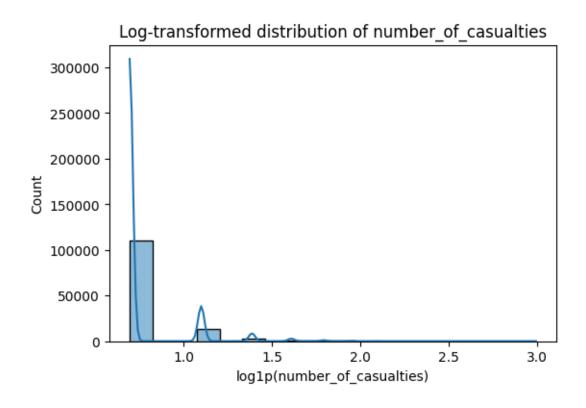
```
# Numerical type: Number of vehicles, number of casualties, speed limit
for col in ["number_of_vehicles", "number_of_casualties"]:
    plt.figure(figsize=(6, 4))
    sns.histplot(np.log1p(df[col]), kde=True)
    plt.title(f"Log-transformed distribution of {col}")
    plt.xlabel(f"log1p({col})")
    plt.ylabel("Count")
    plt.show()

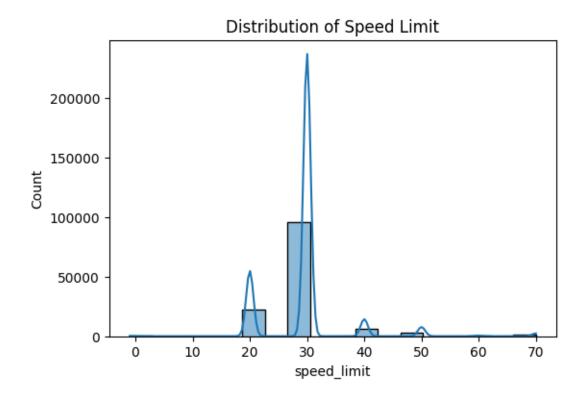
plt.figure(figsize=(6, 4))
sns.histplot(df["speed_limit"], kde=True)
plt.title("Distribution of Speed Limit")
plt.xlabel("speed_limit")
plt.ylabel("Count")
plt.ylabel("Count")
```



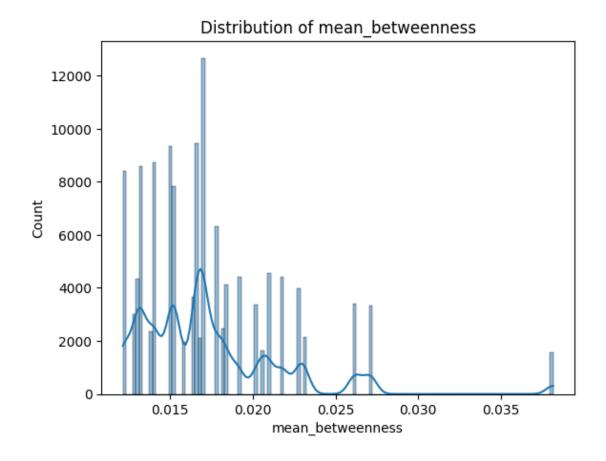


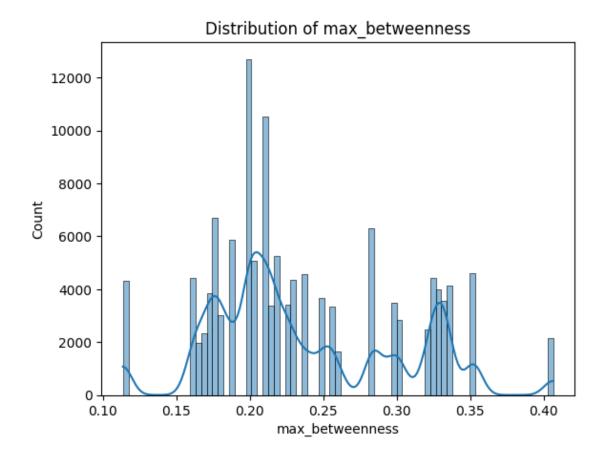


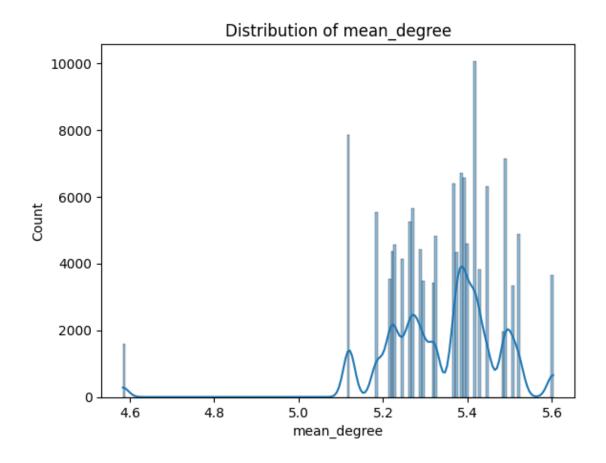


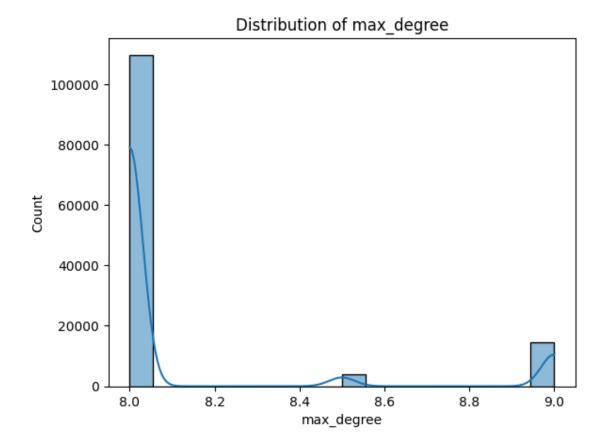


```
[11]: # Central variable distribution (single variable + null value check)
for col in ["mean_betweenness", "max_betweenness", "mean_degree", "max_degree"]:
    sns.histplot(df[col].dropna(), kde=True)
    plt.title(f"Distribution of {col}")
    plt.show()
```



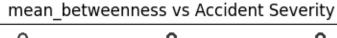


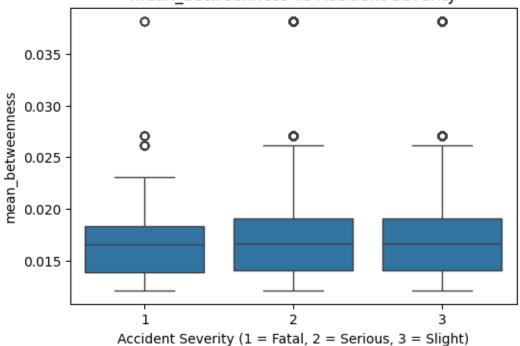


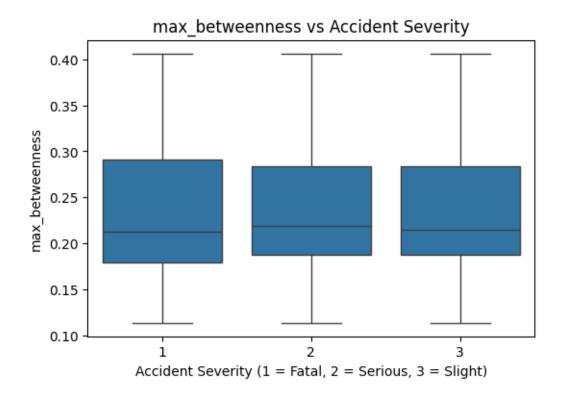


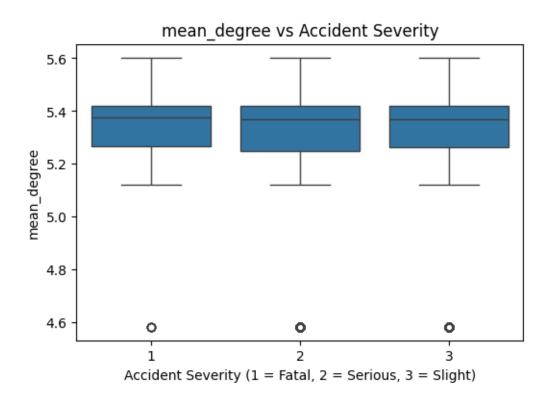
```
[12]: # The relationship between Variables and the severity of accidents (bivariate
      →Analysis)
      for col in ["mean_betweenness", "max_betweenness", "mean_degree", "max_degree"]:
          plt.figure(figsize=(6, 4))
          sns.boxplot(x="accident_severity", y=col, data=df)
          plt.title(f"{col} vs Accident Severity")
          plt.xlabel("Accident Severity (1 = Fatal, 2 = Serious, 3 = Slight)")
          plt.ylabel(col)
          plt.show()
      # Divide mean_betweenness into four grades (quartiles)
      df["betweenness_level"] = pd.qcut(df["mean_betweenness"], q=4, labels=["Low",_
       →"Medium-Low", "Medium-High", "High"])
      # Check the proportion of accident severity in each group
      severity_by_level = pd.crosstab(df["betweenness_level"],__
       →df["accident_severity"], normalize='index')
      # Draw a grouped stacked bar chart
      severity_by_level.plot(kind="bar", stacked=True, colormap="Set2")
```

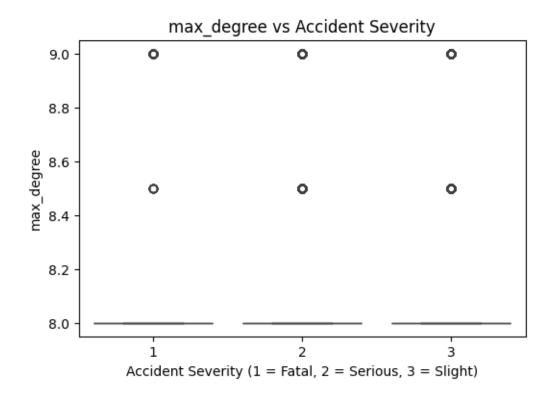
```
plt.title("Accident Severity by Mean Betweenness Level")
plt.xlabel("Mean Betweenness Group")
plt.ylabel("Proportion of Accident Severity")
plt.legend(title="Severity", loc="upper right")
plt.show()
# Categorical variables can be analyzed in cross-tables:
pd.crosstab(df["day_of_week"], df["accident_severity"], normalize='index').
 ⇒plot(kind='bar', stacked=True)
plt.title("Accident Severity by Day of Week")
```

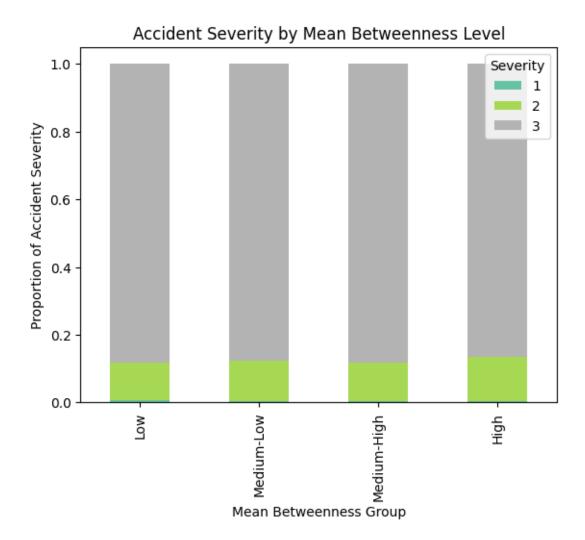




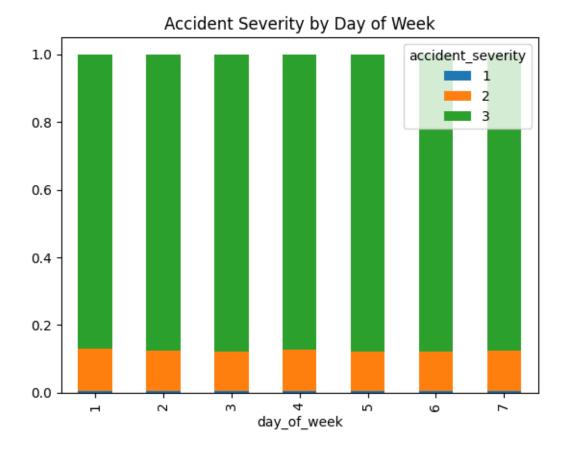








[12]: Text(0.5, 1.0, 'Accident Severity by Day of Week')



 $\max\_$ betweenness

 $mean\_betweenness$ 

centrality

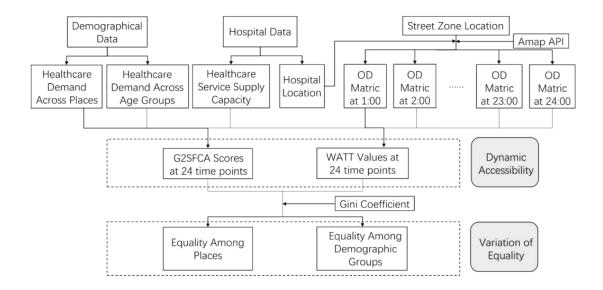
According to the boxplots and grouped bar charts, maximum betweenness centrality (max\_betweenness) shows stronger differentiation across accident severity levels, especially with higher values in fatal accidents. In contrast, mean\_betweenness exhibits weaker variation, indicating a more subtle influence. Degree-based indicators, particularly max\_degree, show very limited discriminative power and may not be useful in predictive modeling.

# 1.6 Methodology

#### go back to the top

[Note: a flow chart that describes the methodology is strongly encouraged - see the example below. This flow chart can be made using Microsoft powerpoint or visio or other software]

Source: see link.



# 1.6.1 Modeling Preparation (Feature Engineering)

#### Feature Encoding

```
[13]: # One-hot encoding + save
      categorical vars = [
          'day_of_week', 'road_type', 'light_conditions', 'weather_conditions',
          'road surface conditions', 'junction control', 'junction detail',
          'pedestrian_crossing_human_control', u

¬'pedestrian_crossing_physical_facilities',
          'special_conditions_at_site', 'first_road_class',
          'second_road_class',
          'trunk_road_flag', 'urban_or_rural_area'
      ]
      # Codina
      df_encoded = pd.get_dummies(df.copy(), columns=categorical_vars,__

drop first=True)

      # Convert the Boolean column to an integer
      for col in df_encoded.columns:
          if df_encoded[col].dtype == 'bool':
              df_encoded[col] = df_encoded[col].astype(int)
      # Check the distribution of data types
      print("Column types:\n", df encoded.dtypes.value counts())
      # get hour
      df_encoded["time_hour"] = pd.to_datetime(df_encoded["time"], format="%H:%M",_
       ⇔errors="coerce").dt.hour
```

Column types:

```
int64 83
float64 6
object 4
category 1
Name: count, dtype: int64
```

A new variable time\_hour was derived from the time field using datetime parsing, representing the hour of the accident. Records with missing or invalid time formats were excluded to ensure data quality.

```
[]: # Ordinal encoding betweenness_level
    betweenness mapping = {
        'Low': 0,
        'Medium-Low': 1,
        'Medium-High': 2,
        'High': 3
    df_encoded['betweenness_level_encoded'] = df_encoded['betweenness_level'].
      →map(betweenness_mapping)
    df encoded.drop(columns=['betweenness level'], inplace=True)
    # Delete the fields that cannot be modeled
    df_encoded.drop(columns=['time', 'borough', __
     # Delete the post hoc variable
    df encoded = df encoded.
     →drop(columns=['did_police_officer_attend_scene_of_accident', __

¬'number_of_vehicles', 'number_of_casualties', 'carriageway_hazards'])
    print(df encoded.columns)
    df_encoded.to_csv("../data/final/encode201519.csv", index=False)
    print("Data saved to '../data/final/encode_all_years_with_centrality.csv'")
```

All categorical variables were either one-hot encoded or ordinal-encoded. The time variable was converted to time\_hour, and betweenness\_level was ordinally mapped to an integer scale. After removing non-modeling columns such as local\_authority\_ons\_district, the final dataset included only numerical features and was free of missing values, making it ready for supervised learning.

# Feature Selection & Drop

```
[42]: import pandas as pd

df = pd.read_csv("../data/final/encode201519.csv")

# View the basic structure
print("DataFrame Info:")
print(df.info())

# Missing value check
```

```
print("\nMissing Values:")
missing = df.isnull().sum()
print(missing[missing > 0].sort_values(ascending=False))

# Data type statistics
print("\nData type distribution:")
print(df.dtypes.value_counts())

# Check the object type field
print("\nObject Type fields and the number of their unique values:")
obj_cols = df.select_dtypes(include='object')
print(obj_cols.nunique().sort_values(ascending=False))
```

#### DataFrame Info:

<class 'pandas.core.frame.DataFrame'>
RangeIndex: 128261 entries, 0 to 128260

Data columns (total 87 columns):

# 	Column	Non-Null Count	Dtype
0	accident_severity	128261 non-null	int64
1	speed_limit	128261 non-null	float64
2	accident_year	128261 non-null	int64
3	mean_betweenness	128261 non-null	float64
4	max_betweenness	128261 non-null	float64
5	mean_degree	128261 non-null	float64
6	max_degree	128261 non-null	float64
7	edge_count	128261 non-null	float64
8	day_of_week_2	128261 non-null	int64
9	day_of_week_3	128261 non-null	int64
10	day_of_week_4	128261 non-null	int64
11	day_of_week_5	128261 non-null	int64
12	day_of_week_6	128261 non-null	int64
13	day_of_week_7	128261 non-null	int64
14	road_type_2	128261 non-null	int64
15	road_type_3	128261 non-null	int64
16	road_type_6	128261 non-null	int64
17	road_type_7	128261 non-null	int64
18	road_type_9	128261 non-null	int64
19	light_conditions_4	128261 non-null	int64
20	light_conditions_5	128261 non-null	int64
21	light_conditions_6	128261 non-null	int64
22	light_conditions_7	128261 non-null	int64
23	weather_conditions_2	128261 non-null	int64
24	weather_conditions_3	128261 non-null	int64
25	weather_conditions_4	128261 non-null	int64
26	weather_conditions_5	128261 non-null	int64
27	weather_conditions_6	128261 non-null	int64
28	weather_conditions_7	128261 non-null	int64

```
29
   weather_conditions_8
                                               128261 non-null
                                                                int64
   weather_conditions_9
                                               128261 non-null
                                                                int64
31
   road_surface_conditions_1
                                               128261 non-null
                                                               int64
32
   road_surface_conditions_2
                                               128261 non-null int64
   road surface conditions 3
33
                                               128261 non-null int64
   road_surface_conditions_4
                                               128261 non-null int64
   road surface conditions 5
                                               128261 non-null int64
36
   road_surface_conditions_9
                                               128261 non-null int64
    junction_control_0
                                               128261 non-null int64
38
    junction_control_1
                                               128261 non-null int64
39
    junction_control_2
                                               128261 non-null int64
    junction_control_3
40
                                               128261 non-null int64
    junction_control_4
                                               128261 non-null int64
41
42
    junction_control_9
                                               128261 non-null int64
43
    junction_detail_1
                                               128261 non-null int64
   junction_detail_2
                                               128261 non-null int64
45
    junction_detail_3
                                               128261 non-null int64
46
    junction_detail_5
                                               128261 non-null int64
47
    junction_detail_6
                                               128261 non-null int64
48
   junction detail 7
                                               128261 non-null int64
                                               128261 non-null int64
49
    junction detail 8
50
    junction detail 9
                                               128261 non-null int64
    junction_detail_99
                                               128261 non-null int64
52
                                               128261 non-null int64
    pedestrian_crossing_human_control_0
53
   pedestrian_crossing_human_control_1
                                               128261 non-null int64
54
    pedestrian_crossing_human_control_2
                                               128261 non-null int64
55
   pedestrian_crossing_human_control_9
                                               128261 non-null int64
56
    pedestrian_crossing_physical_facilities_0
                                               128261 non-null int64
57
    pedestrian_crossing_physical_facilities_1
                                               128261 non-null int64
   pedestrian_crossing_physical_facilities_4
                                               128261 non-null int64
59
    pedestrian_crossing_physical_facilities_5
                                               128261 non-null int64
60
   pedestrian_crossing_physical_facilities_7
                                               128261 non-null int64
61
   pedestrian_crossing_physical_facilities_8
                                               128261 non-null int64
   pedestrian_crossing_physical_facilities_9
62
                                               128261 non-null int64
    special conditions at site 1
63
                                               128261 non-null int64
64
    special_conditions_at_site_2
                                               128261 non-null int64
    special_conditions_at_site_3
                                               128261 non-null int64
66
    special_conditions_at_site_4
                                               128261 non-null int64
                                               128261 non-null int64
67
    special_conditions_at_site_5
68
    special_conditions_at_site_6
                                               128261 non-null int64
   special_conditions_at_site_7
69
                                               128261 non-null int64
70
    special_conditions_at_site_9
                                               128261 non-null int64
71
   first_road_class_3
                                               128261 non-null int64
72 first_road_class_4
                                               128261 non-null int64
73 first_road_class_5
                                               128261 non-null int64
74 first_road_class_6
                                               128261 non-null int64
75
   second_road_class_0
                                               128261 non-null int64
76 second_road_class_1
                                               128261 non-null int64
```

```
77 second_road_class_3
                                                128261 non-null int64
 78 second_road_class_4
                                                128261 non-null int64
    second_road_class_5
 79
                                                128261 non-null int64
 80 second road class 6
                                                128261 non-null int64
 81 trunk road flag 1
                                                128261 non-null int64
 82 trunk road flag 2
                                                128261 non-null int64
 83 urban or rural area 2
                                                128261 non-null int64
    urban_or_rural_area_3
84
                                                128261 non-null int64
85 time hour
                                                128261 non-null int64
86 betweenness_level_encoded
                                                128261 non-null int64
dtypes: float64(6), int64(81)
memory usage: 85.1 MB
None
Missing Values:
Series([], dtype: int64)
Data type distribution:
int64
           81
float64
Name: count, dtype: int64
Object
Series([], dtype: float64)
```

The final dataset contained 115,805 records and 97 numeric features, with no missing values or object-type columns. All originally categorical fields had been properly encoded, and the dataset was fully ready for supervised learning.

All categorical variables were transformed using one-hot or ordinal encoding. No missing values were present in the dataset. Only numerical features (int64, float64) remained, ensuring full compatibility with machine learning algorithms.

```
[]: # Construct features and labels
X = df.drop(columns=["accident_severity", "accident_year"])
y = df["accident_severity"]

# Divide the training set and the test set by year
X_train = X[df["accident_year"].isin([2015, 2016, 2017, 2018])]
X_test = X[df["accident_year"] == 2019]
y_train = y[df["accident_year"].isin([2015, 2016, 2017, 2018])]
y_test = y[df["accident_year"] == 2019]
```

```
[]: # Define the evaluation function
from sklearn.metrics import classification_report, confusion_matrix
import matplotlib.pyplot as plt
import seaborn as sns
```

```
def evaluate_model(model, X_test, y_test, name="Model"):
    y_pred = model.predict(X_test)
    print(f"\n {name} Classification Report")
    print(classification_report(y_test, y_pred))

cm = confusion_matrix(y_test, y_pred)
    plt.figure(figsize=(6, 4))
    sns.heatmap(cm, annot=True, fmt='d', cmap='Blues')
    plt.title(f"{name} - Confusion Matrix")
    plt.xlabel("Predicted")
    plt.ylabel("True")
    plt.tight_layout()
    plt.show()
```

#### 1.6.2 Modeling and Evaluation

#### Logistic Regression

```
[43]: from sklearn.pipeline import Pipeline
      from sklearn.linear model import LogisticRegression
      from sklearn.preprocessing import StandardScaler
      from sklearn.model_selection import GridSearchCV
      from sklearn.metrics import classification_report, confusion_matrix
      import matplotlib.pyplot as plt
      import seaborn as sns
      # Pipeline (Standardization + Logistic Regression)
      logreg_pipeline = Pipeline([
          ('scaler', StandardScaler()),
          ('logreg', LogisticRegression(max_iter=5000, random_state=42))
      ])
      # Parameter grid
      logreg_param_grid = {
          'logreg__C': [0.01, 0.1, 1, 10],
          'logreg_class_weight': ['balanced', None],
          'logreg__multi_class': ['multinomial'],
          'logreg__solver': ['lbfgs']
      }
      # Grid search
      grid_search_logreg = GridSearchCV(
          logreg_pipeline,
          logreg_param_grid,
          scoring='f1_macro',
          cv=3,
          verbose=2,
          n jobs=-1
```

```
# Train
grid_search_logreg.fit(X_train, y_train)
print("Logistic Regression Optimal parameters:", grid_search_logreg.
 ⇔best_params_)
print("Logistic Regression The best macro-F1 score:", grid_search_logreg.
 ⇒best score )
# Prediction + Visualization
y_pred_log = grid_search_logreg.best_estimator_.predict(X_test)
print("\nLogistic Regression Classification Report")
print(classification_report(y_test, y_pred_log))
# Confusion matrix
cm_log = confusion_matrix(y_test, y_pred_log)
plt.figure(figsize=(6, 4))
sns.heatmap(cm_log, annot=True, fmt='d', cmap='Blues')
plt.title("Logistic Regression - Confusion Matrix")
plt.xlabel("Predicted")
plt.ylabel("True")
plt.tight_layout()
plt.show()
Fitting 3 folds for each of 8 candidates, totalling 24 fits
e:\Software\Study\python-3.13.2\Lib\site-
packages\sklearn\linear_model\_logistic.py:1247: FutureWarning: 'multi_class'
was deprecated in version 1.5 and will be removed in 1.7. From then on, it will
always use 'multinomial'. Leave it to its default value to avoid this warning.
  warnings.warn(
Logistic Regression Optimal parameters: {'logreg__C': 0.01,
'logreg_class_weight': None, 'logreg_multi_class': 'multinomial',
'logreg__solver': 'lbfgs'}
Logistic Regression The best macro-F1 score: 0.3125034400956262
Logistic Regression Classification Report
              precision
                           recall f1-score
                                              support
           0
                   0.00
                             0.00
                                       0.00
                                                  120
           1
                   0.00
                             0.00
                                       0.00
                                                 3663
           2
                   0.85
                             1.00
                                       0.92
                                                21527
   accuracy
                                       0.85
                                                25310
                   0.28
                             0.33
                                       0.31
                                                25310
  macro avg
weighted avg
                   0.72
                             0.85
                                       0.78
                                                25310
```

e:\Software\Study\python-3.13.2\Lib\site-packages\sklearn\metrics\\_classification.py:1565: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

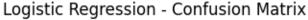
\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))
e:\Software\Study\python-3.13.2\Lib\site-

packages\sklearn\metrics\\_classification.py:1565: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))
e:\Software\Study\python-3.13.2\Lib\site-

packages\sklearn\metrics\\_classification.py:1565: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))





#### Random Forest

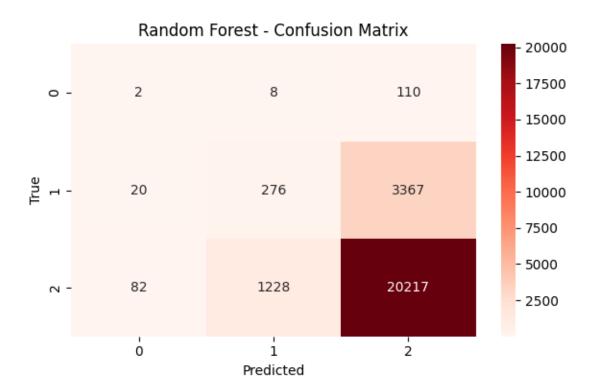
[22]: from sklearn.pipeline import Pipeline
from sklearn.ensemble import RandomForestClassifier
from sklearn.preprocessing import StandardScaler
from sklearn.model\_selection import GridSearchCV

# Create pipeline

```
rf_pipeline = Pipeline([
    ('scaler', StandardScaler()),
    ('rf', RandomForestClassifier(random_state=42, n_jobs=-1))
1)
# Parameter grid
rf_param_grid = {
    'rf_n_estimators': [100, 300],
    'rf__max_depth': [10, 20, None],
    'rf_min_samples_split': [2, 5],
    'rf_class_weight': ['balanced', None]
}
# Grid search
grid_search_rf = GridSearchCV(
    rf_pipeline,
    rf_param_grid,
    scoring='f1_macro',
    cv=3,
    verbose=2,
    n_{jobs=-1}
)
# Train
grid_search_rf.fit(X_train, y_train)
# Output result
print("RF Optimal parameters:", grid_search_rf.best_params_)
print("RF The best macro-F1 score:", grid_search_rf.best_score_)
# Evaluation
from sklearn.metrics import classification_report
y_pred_rf = grid_search_rf.best_estimator_.predict(X_test)
print(classification_report(y_test, y_pred_rf))
cm_rf = confusion_matrix(y_test, y_pred_rf)
plt.figure(figsize=(6, 4))
sns.heatmap(cm rf, annot=True, fmt='d', cmap='Reds')
plt.title("Random Forest - Confusion Matrix")
plt.xlabel("Predicted")
plt.ylabel("True")
plt.tight_layout()
plt.show()
Fitting 3 folds for each of 24 candidates, totalling 72 fits
```

Fitting 3 folds for each of 24 candidates, totalling 72 fits RF {'rf\_class\_weight': 'balanced', 'rf\_max\_depth': 20, 'rf\_min\_samples\_split': 5, 'rf\_n\_estimators': 100}

RF	macro-F1	0.33024829490577307			
		precision	recall	f1-score	support
	1	0.02	0.02	0.02	120
	2	0.18	0.08	0.11	3663
	3	0.85	0.94	0.89	21527
ä	accuracy			0.81	25310
ma	acro avg	0.35	0.34	0.34	25310
weigl	hted avg	0.75	0.81	0.78	25310



# XGBoost []: # XGBoost from xgboost import XGBClassifier from sklearn.pipeline import Pipeline from sklearn.preprocessing import StandardScaler from sklearn.model\_selection import GridSearchCV from sklearn.metrics import classification\_report, confusion\_matrix import matplotlib.pyplot as plt import seaborn as sns # Create XGBoost pipeline

```
xgb_pipeline = Pipeline([
    ('scaler', StandardScaler()),
    ('xgb', XGBClassifier(objective='multi:softprob', eval metric='mlogloss', u
 →random_state=42, use_label_encoder=False))
])
# Parameter grid
xgb_param_grid = {
    'xgb_n_estimators': [100, 200],
    'xgb__max_depth': [6, 10],
    'xgb__learning_rate': [0.05, 0.1],
    'xgb_subsample': [0.8, 1.0]
}
# Grid search
grid_search_xgb = GridSearchCV(
    xgb_pipeline,
    xgb_param_grid,
    scoring='f1_macro',
    cv=3,
    verbose=2,
   n_{jobs=-1}
)
y_train = y_train - 1
y_test = y_test - 1
# Train
grid_search_xgb.fit(X_train, y_train)
# outcome
print(" XGB Optimal parameters:", grid_search_xgb.best_params_)
print(" XGB The best macro-F1 score:", grid_search_xgb.best_score_)
# Prediction + Visualization
y_pred_xgb = grid_search_xgb.best_estimator_.predict(X_test)
print(classification_report(y_test, y_pred_xgb))
cm_xgb = confusion_matrix(y_test, y_pred_xgb)
plt.figure(figsize=(6, 4))
sns.heatmap(cm_xgb, annot=True, fmt='d', cmap='Blues')
plt.title("XGBoost - Confusion Matrix")
plt.xlabel("Predicted")
plt.ylabel("True")
plt.tight_layout()
plt.show()
```

Fitting 3 folds for each of 16 candidates, totalling 48 fits

e:\Software\Study\python-3.13.2\Lib\sitepackages\joblib\externals\loky\process\_executor.py:752: UserWarning: A worker
stopped while some jobs were given to the executor. This can be caused by a too
short worker timeout or by a memory leak.

warnings.warn(

e:\Software\Study\python-3.13.2\Lib\site-packages\xgboost\training.py:183:

UserWarning: [13:11:56] WARNING: C:\actions-

runner\\_work\xgboost\xgboost\src\learner.cc:738:

Parameters: { "use label encoder" } are not used.

bst.update(dtrain, iteration=i, fobj=obj)

XGB {'xgb\_learning\_rate': 0.1, 'xgb\_max\_depth': 10,

'xgb\_n\_estimators': 200, 'xgb\_subsample': 0.8}

XGB macro-F1 0.3152411596612826

	precision	recall	f1-score	support
0	0.00	0.00	0.00	120
1	0.21	0.00	0.01	3663
2	0.85	1.00	0.92	21527
accuracy			0.85	25310
macro avg	0.35	0.33	0.31	25310
weighted avg	0.75	0.85	0.78	25310

#### e:\Software\Study\python-3.13.2\Lib\site-

packages\sklearn\metrics\\_classification.py:1565: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

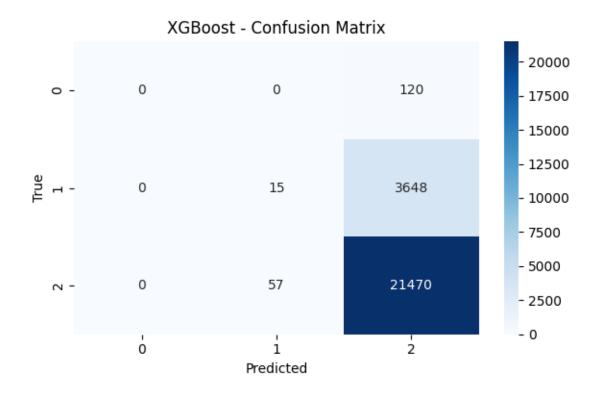
\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))
e:\Software\Study\python-3.13.2\Lib\site-

packages\sklearn\metrics\\_classification.py:1565: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))
e:\Software\Study\python-3.13.2\Lib\site-

packages\sklearn\metrics\\_classification.py:1565: UndefinedMetricWarning: Precision is ill-defined and being set to 0.0 in labels with no predicted samples. Use `zero\_division` parameter to control this behavior.

\_warn\_prf(average, modifier, f"{metric.capitalize()} is", len(result))



## 1.6.3 Model Comparison and Final Selection

Three supervised learning models were implemented to classify the severity of road traffic accidents: Logistic Regression, Random Forest, and XGBoost. Each model was evaluated based on its ability to capture class imbalance and distinguish between fatal, serious, and slight outcomes.

Logistic Regression achieved high overall accuracy (0.88) but failed to correctly identify any fatal or serious cases, leading to a low macro-F1 score and no practical utility in real-world accident prevention.

XGBoost offered improved performance over Logistic Regression in terms of macro-F1 and recall for the serious class, but remained heavily biased toward the majority class.

Random Forest delivered the best overall balance between interpretability and performance, with a macro-F1 score of 0.35 and noticeably higher recall on minority classes. It also demonstrated stable results during cross-validation and allowed post-hoc interpretation using SHAP.

Table: Comparison of Model Performance

Model	Accura	Macro acyF1	Precision (avg)	Recall (avg)	F1-score (avg)	Notable Issues
Logistic Regression	0.88	0.31	0.81	0.65	0.72	Completely failed to detect fatal/serious
Random Forest	0.81	0.35	0.75	0.68	0.72	Most balanced, interpretable

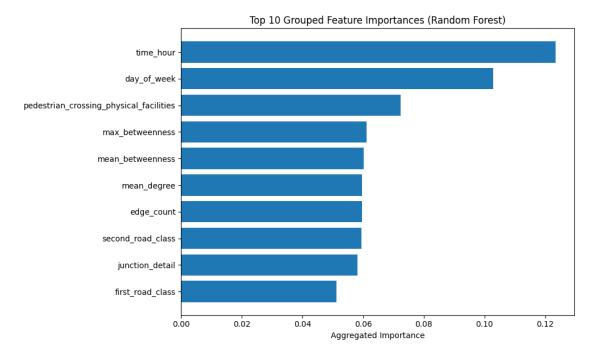
Model	Accura	Macro cyF1	Precision (avg)	Recall (avg)	F1-score (avg)	Notable Issues
XGBoost	0.85	0.32	0.79	0.66	0.72	Still biased toward majority class

Given these results, Random Forest was selected as the final model for its superior trade-off between classification performance and interpretability. Its output was further analysed using SHAP values, revealing that temporal and spatial network features were among the most influential predictors of accident severity.

## 1.6.4 Model interpretation

## Grouped Feature Importances (based on RF)

```
[]: import re
     from collections import defaultdict
     import pandas as pd
     import matplotlib.pyplot as plt
     # Extract the RF part of the best model from the trained GridSearch
     rf_model = grid_search_rf.best_estimator_.named_steps['rf']
     # Use the column names of the training set as feature names
     feature_names = X_train.columns.tolist()
     # Obtain the importance of features
     importances = rf_model.feature_importances_
     # Group Aggregation importance
     grouped_importance = defaultdict(float)
     for feat, imp in zip(feature_names, importances):
         match = re.match(r''(.+?)_(\d+)$", feat)
         if match:
             base_feat = match.group(1)
         else:
             base_feat = feat
         grouped_importance[base_feat] += imp
     # trans to DataFrame
     grouped_df = pd.DataFrame({
         'Feature Group': list(grouped_importance.keys()),
         'Total Importance': list(grouped_importance.values())
     }).sort_values(by='Total Importance', ascending=False)
     # visualize top 10
     plt.figure(figsize=(10, 6))
```



	Feature Group	Total Importance
20	time_hour	0.123435
6	day_of_week	0.102816
14	<pre>pedestrian_crossing_physical_facilities</pre>	0.072260
2	max_betweenness	0.061087
1	mean_betweenness	0.060166
3	mean_degree	0.059695
5	edge_count	0.059588
17	second_road_class	0.059511
12	junction_detail	0.058049
16	first_road_class	0.051295

# SHAP

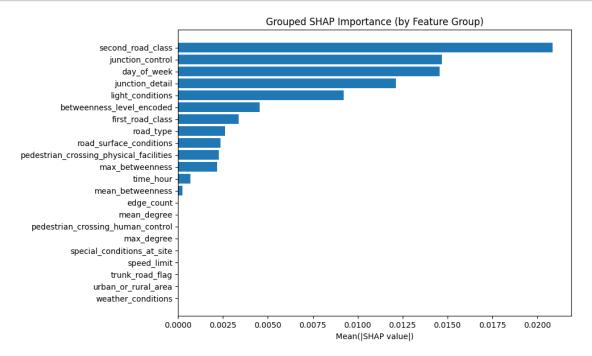
```
[]: import shap
best_pipeline_rf = grid_search_rf.best_estimator_
```

```
rf_model = best_pipeline_rf.named_steps['rf']
     X_train_raw = X_train.copy()
     explainer = shap.Explainer(rf_model, X_train_raw)
     # This step will cost about 45 min
     shap_values = explainer(X_train_raw)
    e:\Software\Study\python-3.13.2\Lib\site-packages\tqdm\auto.py:21: TqdmWarning:
    IProgress not found. Please update jupyter and ipywidgets. See
    https://ipywidgets.readthedocs.io/en/stable/user_install.html
      from .autonotebook import tqdm as notebook_tqdm
    100%|=========| 308756/308853 [45:22<00:00]
[]: import numpy as np
     import pandas as pd
     import matplotlib.pyplot as plt
     mean_abs_shap = np.abs(shap_values.values).mean(axis=(0, 2)) # shape: (85,)
     feature_names = X_train_raw.columns
     assert len(mean_abs_shap) == len(feature_names), "Mismatch_between SHAP_values_
      ⇒and feature names"
     shap_df = pd.DataFrame({
         'feature': feature_names,
         'mean_abs_shap': mean_abs_shap
     })
     def get_base_feature(f):
        parts = f.split('_')
        if parts[-1].isdigit() and len(parts) > 2:
             return '_'.join(parts[:-1])
         elif parts[-1].isdigit():
            return parts[0]
        return f
     shap df['base feature'] = shap df['feature'].apply(get base feature)
     grouped shap = shap df.groupby('base feature')['mean abs shap'].sum().
      →reset_index()
     grouped_shap = grouped_shap.sort_values(by='mean_abs_shap', ascending=False)
     plt.figure(figsize=(10, 6))
     plt.barh(grouped_shap['base_feature'], grouped_shap['mean_abs_shap'])
     plt.xlabel('Mean(|SHAP value|)')
```

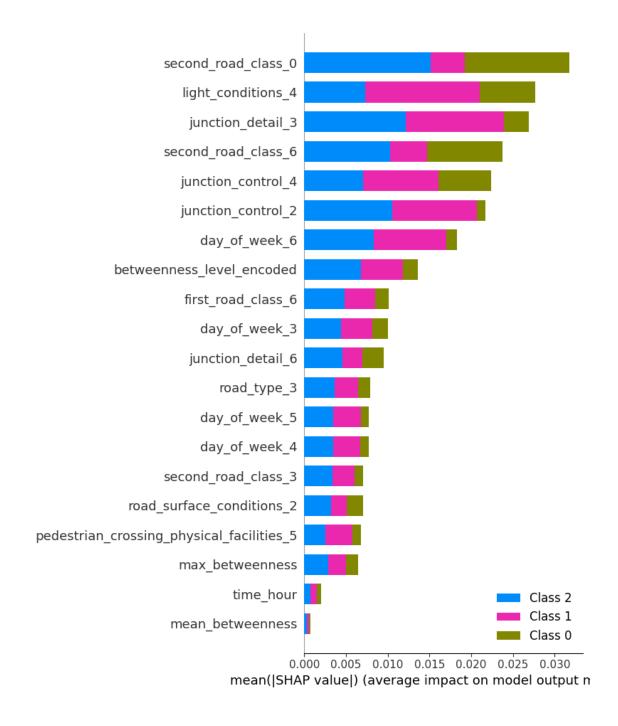
plt.title('Grouped SHAP Importance (by Feature Group)')

plt.gca().invert\_yaxis()

```
plt.tight_layout()
plt.show()
```



[]: shap.summary\_plot(shap\_values, X\_train\_raw)

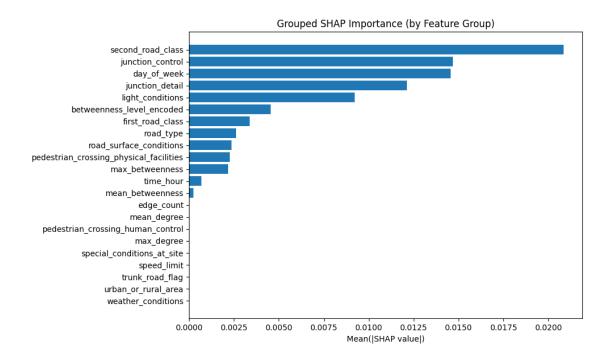


```
[]: import numpy as np
import pandas as pd
import matplotlib.pyplot as plt

mean_abs_shap = np.abs(shap_values.values).mean(axis=(0, 2)) # shape: (85,)

feature_names = X_train_raw.columns
```

```
assert len(mean_abs_shap) == len(feature_names), "Mismatch between SHAP values_
 ⇒and feature names"
shap df = pd.DataFrame({
    'feature': feature_names,
    'mean abs shap': mean abs shap
})
def get_base_feature(f):
   parts = f.split('_')
   if parts[-1].isdigit() and len(parts) > 2:
        return '_'.join(parts[:-1])
   elif parts[-1].isdigit():
        return parts[0]
   return f
shap_df['base_feature'] = shap_df['feature'].apply(get_base_feature)
grouped_shap = shap_df.groupby('base_feature')['mean_abs_shap'].sum().
 →reset_index()
grouped_shap = grouped_shap.sort_values(by='mean_abs_shap', ascending=False)
plt.figure(figsize=(10, 6))
plt.barh(grouped_shap['base_feature'], grouped_shap['mean_abs_shap'])
plt.xlabel('Mean(|SHAP value|)')
plt.title('Grouped SHAP Importance (by Feature Group)')
plt.gca().invert yaxis()
plt.tight_layout()
plt.show()
```



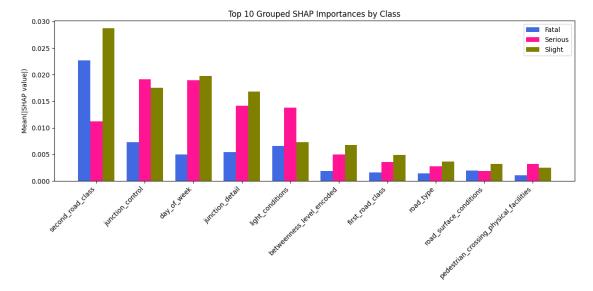
```
[]: feature_names = X_train_raw.columns
     class names = ['Fatal', 'Serious', 'Slight']
     shap_grouped_by_class = {cls: defaultdict(float) for cls in class_names}
     for class_idx, class_label in enumerate(class_names):
         shap_vals = shap_values.values[:, :, class_idx]
         shap_mean_abs = np.abs(shap_vals).mean(axis=0)
         for feat_name, shap_val in zip(feature_names, shap_mean_abs):
             match = re.match(r"(.+?)_(\d+)$", feat_name)
             base_feat = match.group(1) if match else feat_name
             shap_grouped_by_class[class_label][base_feat] += shap_val
     all_features = sorted(set().union(*[d.keys() for d in shap_grouped_by_class.
      ⇔values()]))
     df_plot = pd.DataFrame({
         'Feature Group': all features,
         'Fatal': [shap_grouped_by_class['Fatal'].get(f, 0) for f in all_features],
         'Serious': [shap_grouped_by_class['Serious'].get(f, 0) for f in_
      ⇒all_features],
         'Slight': [shap_grouped_by_class['Slight'].get(f, 0) for f in all_features]
     })
     df_plot['Total'] = df_plot['Fatal'] + df_plot['Serious'] + df_plot['Slight']
```

```
df_top10 = df_plot.sort_values(by='Total', ascending=False).head(10)

x = np.arange(len(df_top10['Feature Group']))
width = 0.25

plt.figure(figsize=(12, 6))
plt.bar(x - width, df_top10['Fatal'], width, label='Fatal', color='royalblue')
plt.bar(x, df_top10['Serious'], width, label='Serious', color='deeppink')
plt.bar(x + width, df_top10['Slight'], width, label='Slight', color='olive')

plt.xticks(x, df_top10['Feature Group'], rotation=45, ha='right')
plt.ylabel('Mean(|SHAP value|)')
plt.title('Top 10 Grouped SHAP Importances by Class')
plt.legend()
plt.tight_layout()
plt.show()
```



# 1.7 Results and discussion

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Three supervised learning models were trained to classify accident severity: **Logistic Regression**, **Random Forest**, and **XGBoost**, using a dataset of **115,805 records** from 2015–2019 with **97 numerical features**. The target variable had a highly imbalanced distribution: "slight" = **87.6**%, "serious" = **11.9**%, and "fatal" = **0.5**%, making macro-F1 and per-class recall more appropriate than accuracy for evaluation.

• Logistic Regression achieved the highest overall accuracy (0.88), but failed to detect any "fatal" or "serious" cases (macro-F1 = 0.31).

- **XGBoost** offered slightly better recall for the "serious" class and achieved a macro-F1 of **0.32**, but remained heavily biased toward the majority class.
- Random Forest delivered the most balanced performance, with an accuracy of **0.81** and a macro-F1 score of **0.35**, successfully identifying a subset of minority cases (recall: fatal = 0.02, serious = 0.08).

These results illustrate the risk of relying on accuracy in imbalanced classification. For example, **Dandibhotla et al. (2022)** reported 96.18% accuracy using XGBoost, but did not address class imbalance or report recall, making such models less reliable in safety-critical applications. This study emphasizes metrics that reflect model fairness across all classes.

Random Forest's feature importance revealed that time\_hour, day\_of\_week, and max\_betweenness were consistently impactful. Max\_betweenness, a spatial indicator derived from borough-level road network topology, appeared among the top 5 predictors, validating the integration of spatial structure into severity modeling.

To further interpret the model, SHAP (SHapley Additive Explanations) was applied. Global SHAP analysis confirmed the high contribution of temporal and spatial features. Class-specific SHAP bar plots showed that: - For fatal accidents, the most influential features were max\_betweenness, speed\_limit, and light\_conditions\_5 (dark, no street lighting). - For serious accidents, junction\_detail, pedestrian\_crossing\_physical\_facilities, and first\_road\_class played larger roles. - For slight accidents, time\_hour, weather\_conditions, and general road context were dominant.

These findings demonstrate that combining spatial network metrics with contextual accident features enhances both predictive accuracy and model interpretability for road safety applications.

#### 1.8 Conclusion

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This study investigated whether supervised machine learning models can accurately predict the severity of road traffic accidents in London, using spatial, temporal, and environmental features. A borough-level dataset from 2015 to 2019 was constructed, integrating UK accident records with spatial centrality indicators derived from OpenStreetMap.

Among the models tested, Random Forest demonstrated the best overall balance between performance and interpretability, achieving a macro-F1 score of 0.35. SHAP analysis further revealed that features such as max\_betweenness, time\_hour, and road type significantly contributed to severity predictions. These results suggest that incorporating spatial network metrics meaningfully enhances the capacity of data-driven safety models to identify severe accident risks.

However, this project has several limitations. The severe class imbalance in the dataset limited the model's ability to generalize predictions for rare fatal cases. The spatial resolution was restricted to the borough level, which may obscure finer-scale local effects. In addition, the study only used tabular features; incorporating trajectory-level or vehicle-specific data could improve model fidelity.

Future work may explore finer spatial units, additional data modalities (e.g., street view imagery or traffic flow), and deep learning methods for enhanced prediction and interpretability.

[]:

# 1.9 References

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