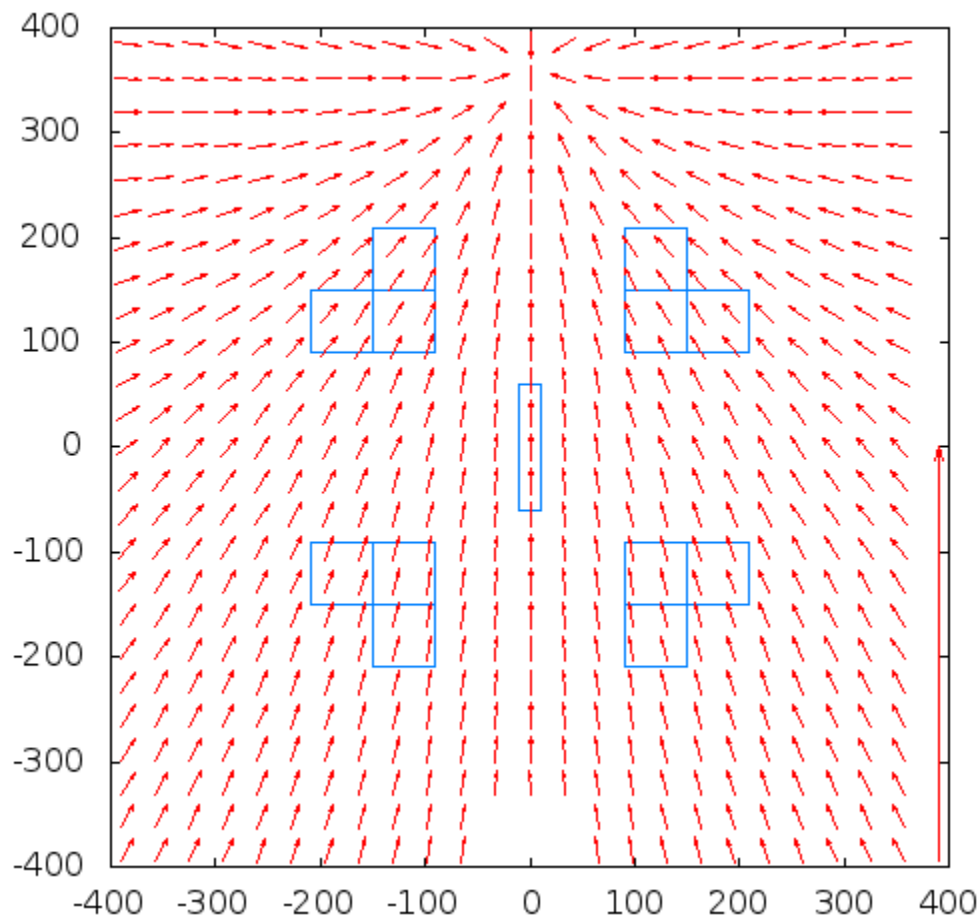


## **Potential Fields**

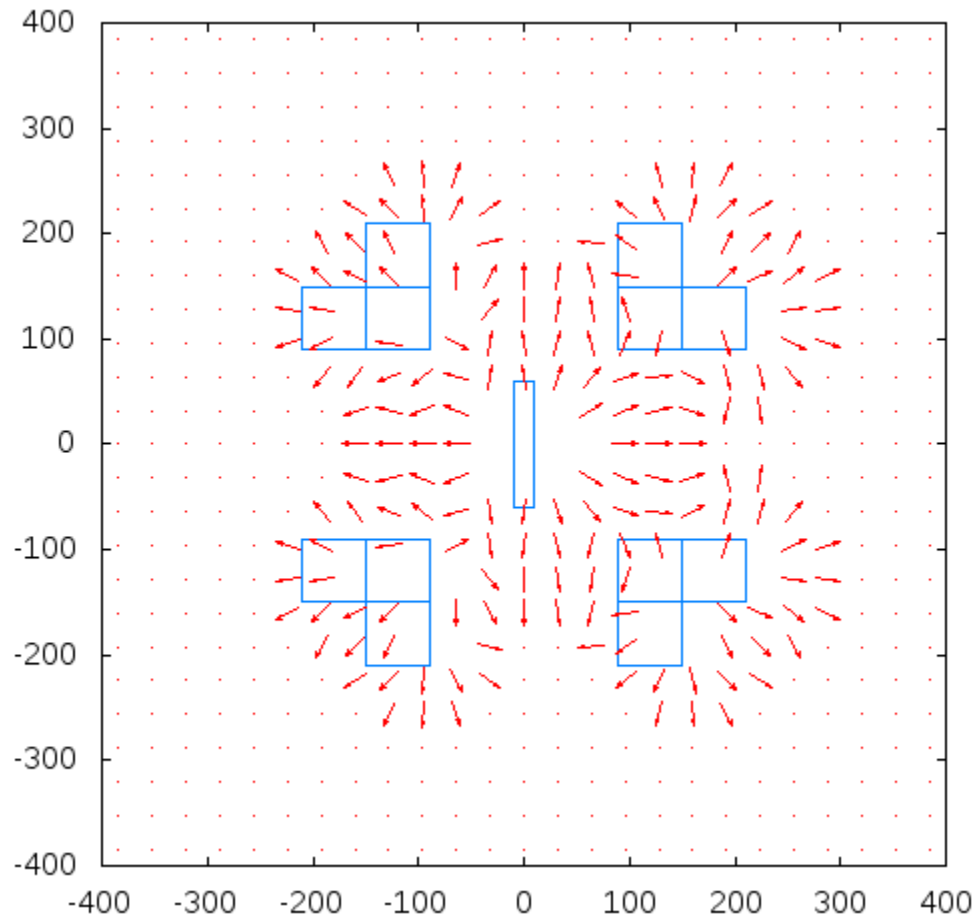
### **Attractive Fields**

The attractive fields were generated by using the information from the potential fields specification. Each flag has an attractive field but in our implementation a randomly designated teams flag was given a exceeding weight so as to help pull our tanks to the flag. This is why the field generated is directed completely towards the flags position. At first the weight of the goal flag was set too low and the tanks would not be pulled strongly enough, then it was set it too high to the point where it seemed to negated all other fields.



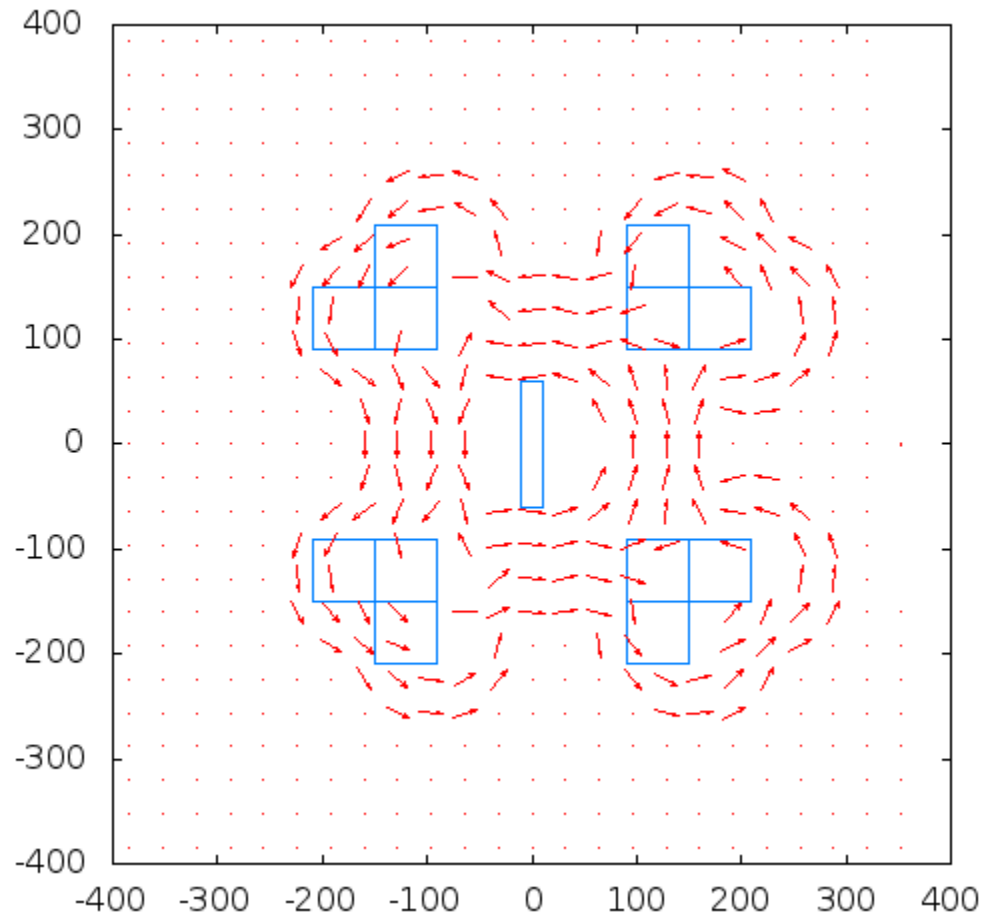
## Repulsive Fields

The repulsive fields were generated from the specification and calculated for objects by finding the center and creating a radius. The drawbacks we found with this type of field is that in close spaces, cycles can interrupt even a strong pull from a goal. It was found that the tanks would go in circles if they went in between the obstacles so the weight was cut down.



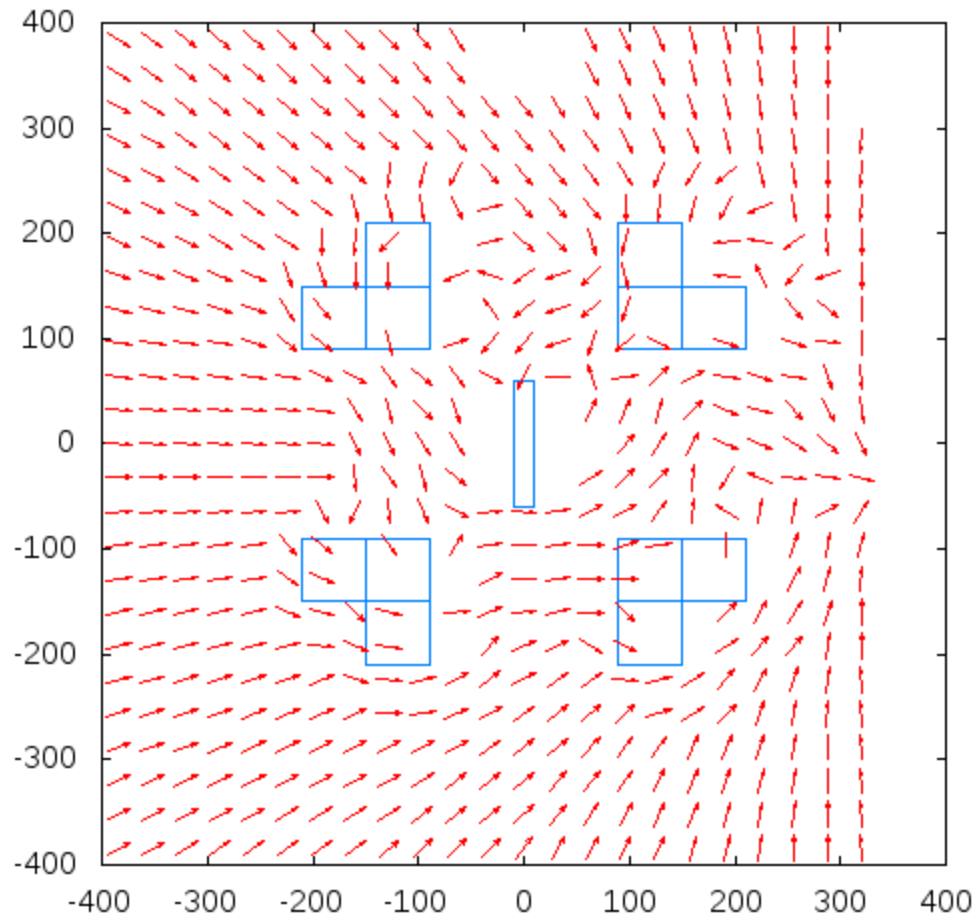
## Tangential Fields

Tangential fields were created in a similar fashion to the repulsive fields except 90 degrees were added to the calculated angle before calculating the deltaX and deltaY of a given position. This field allowed for some ability to escape from cycles with a strong enough attractive field. It was found that angle was too high in some places however and caused the tanks to jut out unnecessarily far when it approached the sides of the obstacles.



### All Fields

This shows what the potential field values were when all the different types were added together. It shows that the tanks are attracted to the target flag while trying to avoid the obstacles.



## **Tests**

### **Other Team**

The opposing team consisted of: Cameron McCord and Trevor Fenn.

### **PF vs Really Dumb Agent**

The first time this test was run, the PF agent got stuck and the test needed to be restarted. The second time, the PF agent had no problem getting to the flag, destroying enemy tanks on the way, and getting back to its base. It did this multiple times. The PF agent dodged the obstacles with a much greater curve than was needed. The dumb agent made no progress over the course of ten minutes

### **PF vs Two Really Dumb Agents**

The result of this test was almost exactly the same as the previous test. The PF agent did remarkably well while the two dumb agents didn't do too much. Sometimes the PF agent would get stuck on friendly or enemy tanks, but it would always escape after a few seconds. Twice the dumb agents almost accidentally shot the PF agent, and one dumb agent actually managed to grab a flag of a separate team.

### **PF vs PF**

This test was by far the most interesting thus far. The blue team had no problem getting ream team's flag and getting it back to its base. However, on the second run to get the flag, on its way back it got stuck on friendly tanks. The red team had a harder time getting through the obstacles, but it was also able to get a flag and return it. However, on its second run it got stuck on the obstacles and was unable to escape.

### **PF vs Other Team's Really Dumb Agent**

Our agent was able to beat the other teams really dumb agent though due to the position in both the four l's map and the tilted map some problems came up when trying to carry the flag back. The weight of the home base wasn't high enough to draw the agent through some cycles that existed and so while we were able to beat the other it was more on shots that scores.

### **PF vs Other Team's Two Really Dumb Agents**

This test was similar to the previous with our agent only having occasional problems with the potential field rather than the other teams really dumb agents.

### **PF vs Other Team's PF**

This test went in our favor as well due to the timing of the test. The other team hadn't completely finished their PF agent and thus ours had navigation advantages.

### **Time Spent on the Project**

Taft Sandbakken: 8 hours

Kevin Hinton: 10 - 12 hours