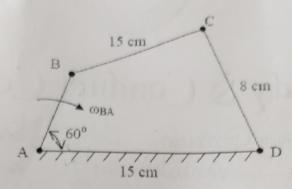
Four - Bar Mechanism: In a four bar chain ABCD link AD is fixed and in 15 cm long. The crank AB is 4 cm long rotates at 180 rpm (cw) while link CD rotates about D is 8 cm long BC = AD and | BAD = 60°. Find angular velocity of link CD.



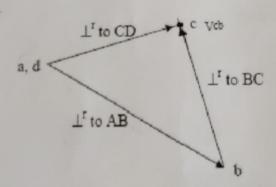
Configuration Diagram

Velocity vector diagram

$$V_b = \omega r = \omega_{ba} \times AB = \frac{2\pi x \cdot 120}{60} \times 4 = 50.24 \text{ cm/sec}$$

Choose a suitable scale

$$1 \text{ cm} = 20 \text{ m/s} = \overline{ab}$$



$$V_{cb} = \overrightarrow{bc}$$

 $V_c = \overrightarrow{dc} = 38 \text{ cm/sec} = V_{cd}$

We know that $V = \omega R$

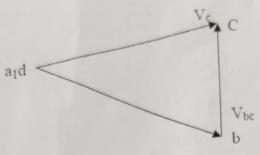
$$V_{cd} = \omega_{CD} \times CD$$

 $\omega_{cD} = \frac{V_{cd}}{CD} = \frac{38}{8} = 4.75 \text{ rad/sec (cw)}$

Step 2: Draw velocity vector diagram to a scale.

$$V_b = \omega_2 x AB$$

 $V_b = 10.5 \times 0.05$
 $V_b = 0.525 \text{ m/s}$



Step 3: Prepare a table as shown below:

Sl.	3: Prepare a table Link	Magnitude	Direction	Sense
No. 1.	AB	$f^c = \omega^2_{AB}r$	Parallel to AB	→ A
		$f^{c} = (10.5)^{2}/0.525$	Control of the last	
		$f^c = 5.51 \text{ m/s}^2$	-	→B
2.	BC	$f^c = \omega^2_{BC}r$	Parallel to BC	7.0
		$f^{c} = 1.75$		
		$f^t = \alpha r$	⊥ ^r to BC	-
3.	CD	$f^c = \omega^2 cDr$	Parallel to DC	→ D
		f ^c = 2.75		
		$f^t = ?$	⊥r to DC	-

Step 4: Draw the acceleration diagram.

