



AI2002 – ARTIFICIAL INTELLIGENCE

SPRING 2024 - LECTURE 37-39

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Kumar

Slides are taken from University
of Pennsylvania

What is Machine Learning?

“Learning is any process by which a system improves performance from experience.”

- Herbert Simon

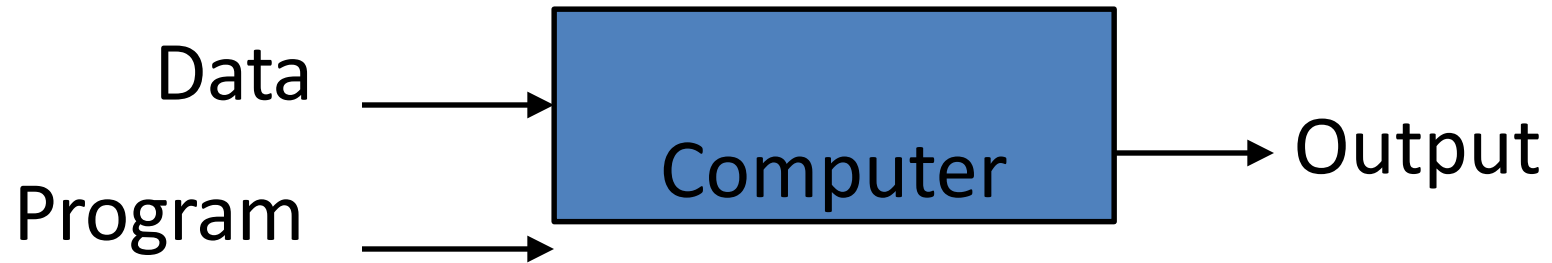
Definition by Tom Mitchell (1998):

Machine Learning is the study of algorithms that

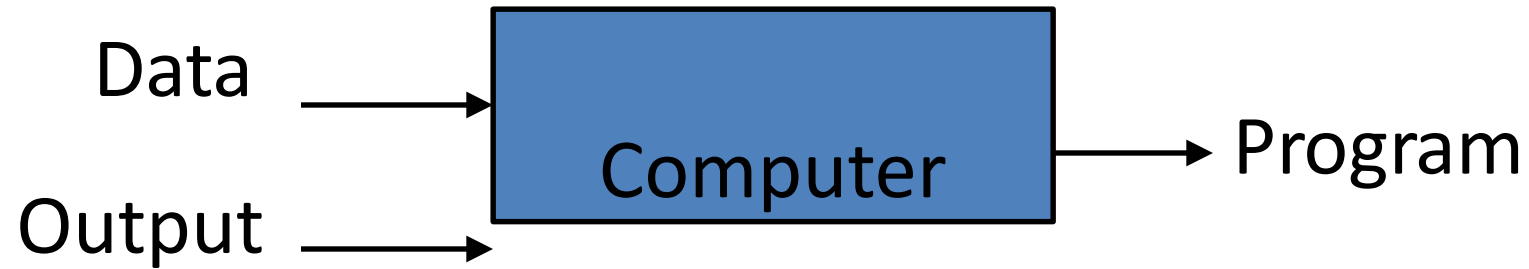
- improve their performance P
- at some task T
- with experience E .

A well-defined learning task is given by $\langle P, T, E \rangle$.

Traditional Programming



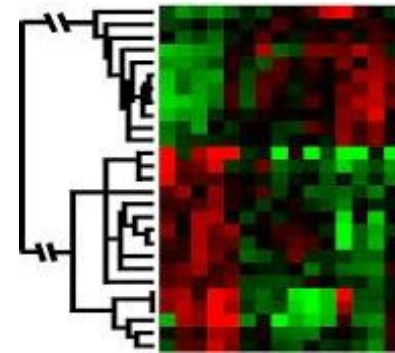
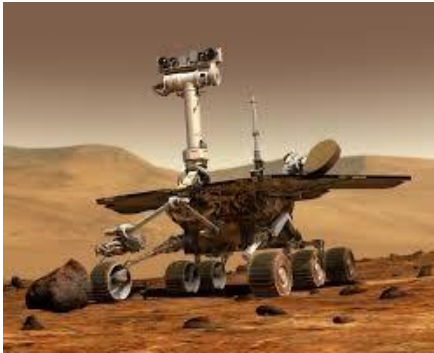
Machine Learning



When Do We Use Machine Learning?

ML is used when:

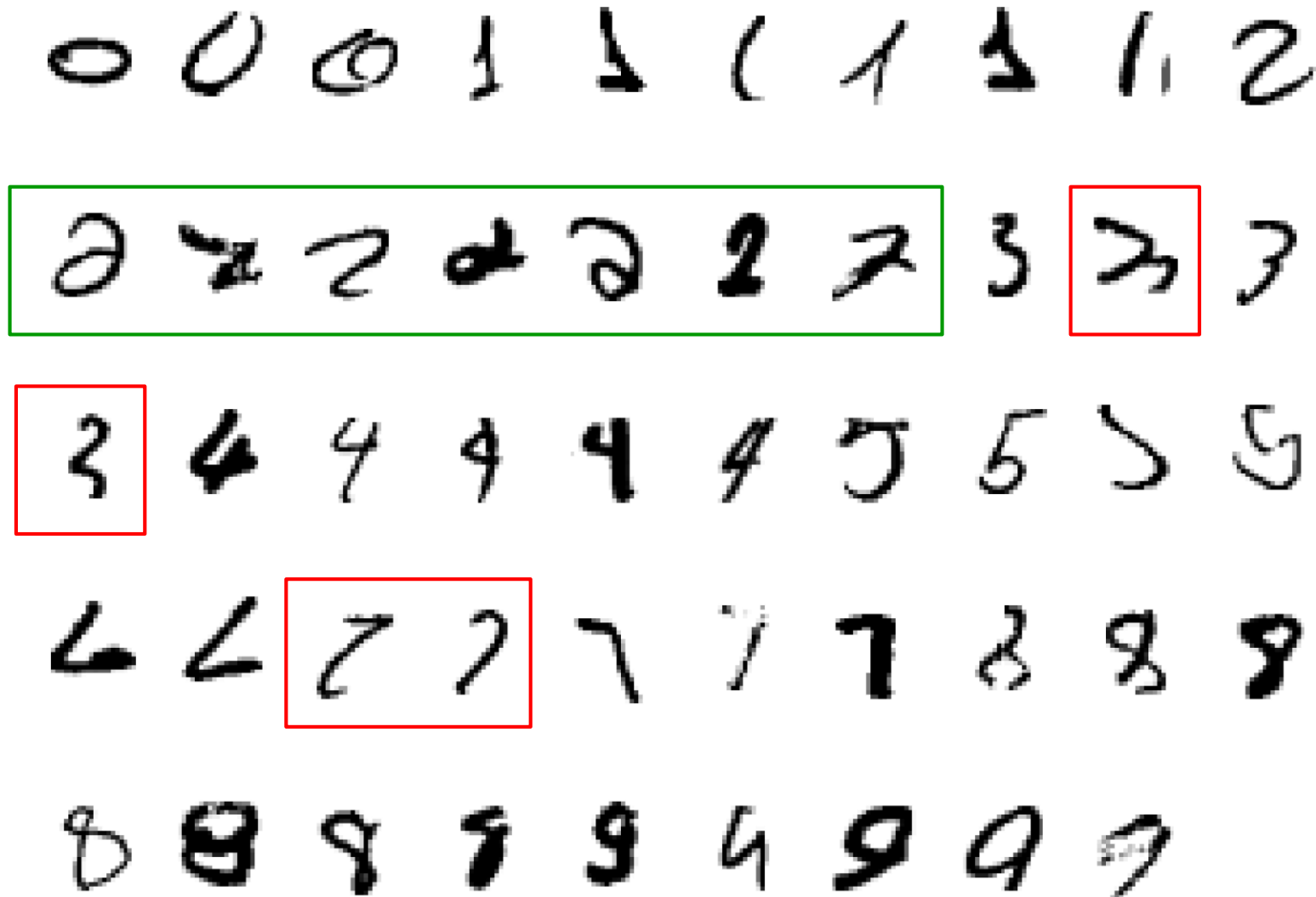
- Human expertise does not exist (navigating on Mars)
- Humans can't explain their expertise (speech recognition)
- Models must be customized (personalized medicine)
- Models are based on huge amounts of data (genomics)



Learning isn't always useful:

- There is no need to “learn” to calculate payroll

A classic example of a task that requires machine learning:
It is very hard to say what makes a 2



Some more examples of tasks that are best solved by using a learning algorithm

- Recognizing patterns:
 - Facial identities or facial expressions
 - Handwritten or spoken words
 - Medical images
- Generating patterns:
 - Generating images or motion sequences
- Recognizing anomalies:
 - Unusual credit card transactions
 - Unusual patterns of sensor readings in a nuclear power plant
- Prediction:
 - Future stock prices or currency exchange rates

Sample Applications

- Web search
- Computational biology
- Finance
- E-commerce
- Space exploration
- Robotics
- Information extraction
- Social networks
- Debugging software
- [Your favorite area]

Samuel's Checkers-Player

“Machine Learning: Field of study that gives computers the ability to learn without being explicitly programmed.” -Arthur Samuel (1959)



Defining the Learning Task

Improve on task T , with respect to
performance metric P , based on experience E

T : Playing checkers

P : Percentage of games won against an arbitrary opponent

E : Playing practice games against itself

T : Recognizing hand-written words

P : Percentage of words correctly classified

E : Database of human-labeled images of handwritten words

T : Driving on four-lane highways using vision sensors

P : Average distance traveled before a human-judged error

E : A sequence of images and steering commands recorded while observing a human driver.

T : Categorize email messages as spam or legitimate.

P : Percentage of email messages correctly classified.

E : Database of emails, some with human-given labels

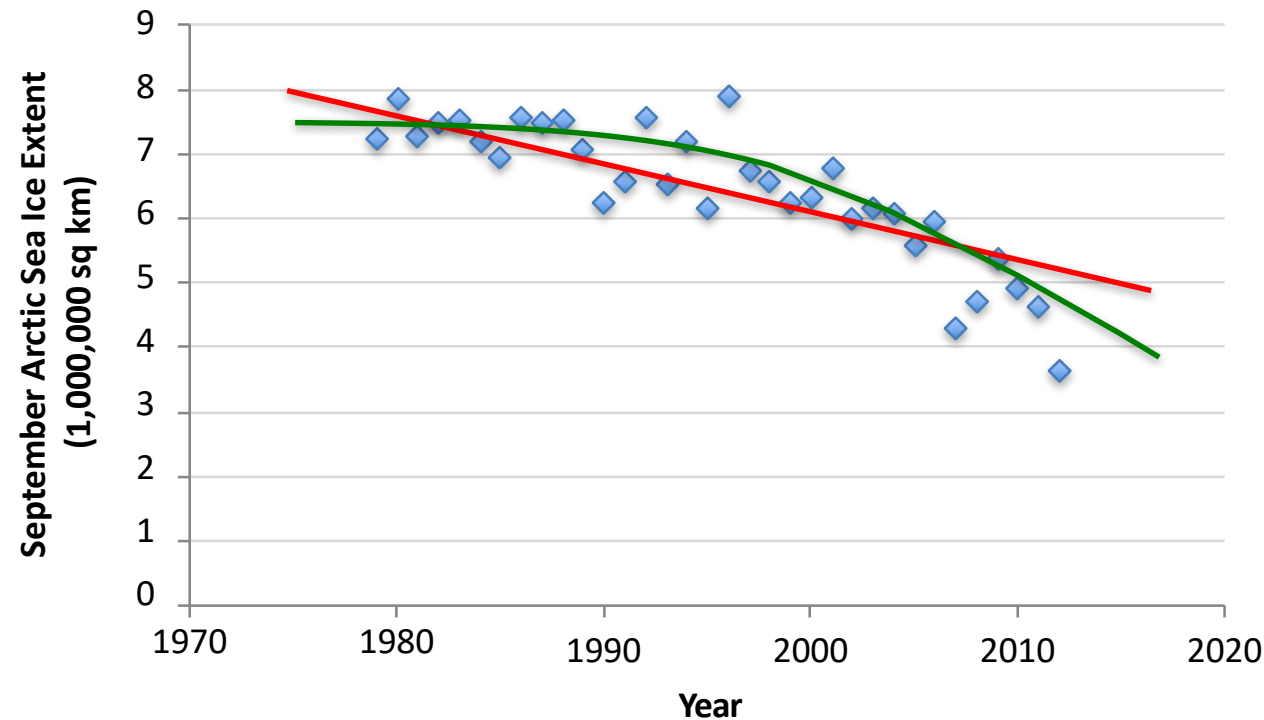
Types of Learning

Types of Learning

- **Supervised (inductive) learning**
 - Given: training data + desired outputs (labels)
- **Unsupervised learning**
 - Given: training data (without desired outputs)
- **Semi-supervised learning**
 - Given: training data + a few desired outputs
- **Reinforcement learning**
 - Rewards from sequence of actions

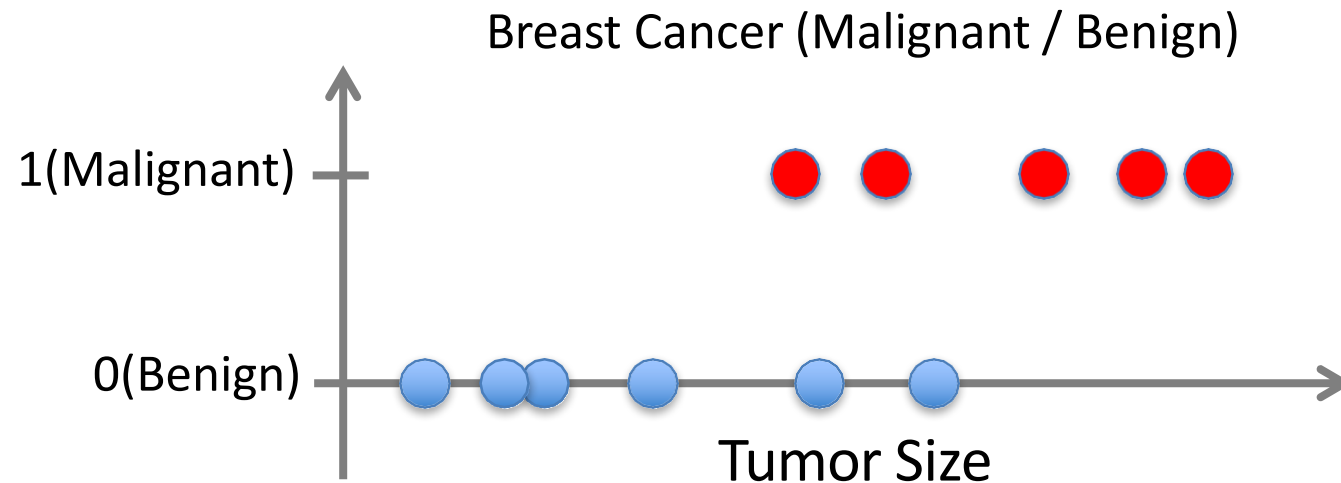
Supervised Learning: Regression

- Given $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$
- Learn a function $f(x)$ to predict y given x
 - y is real-valued == regression



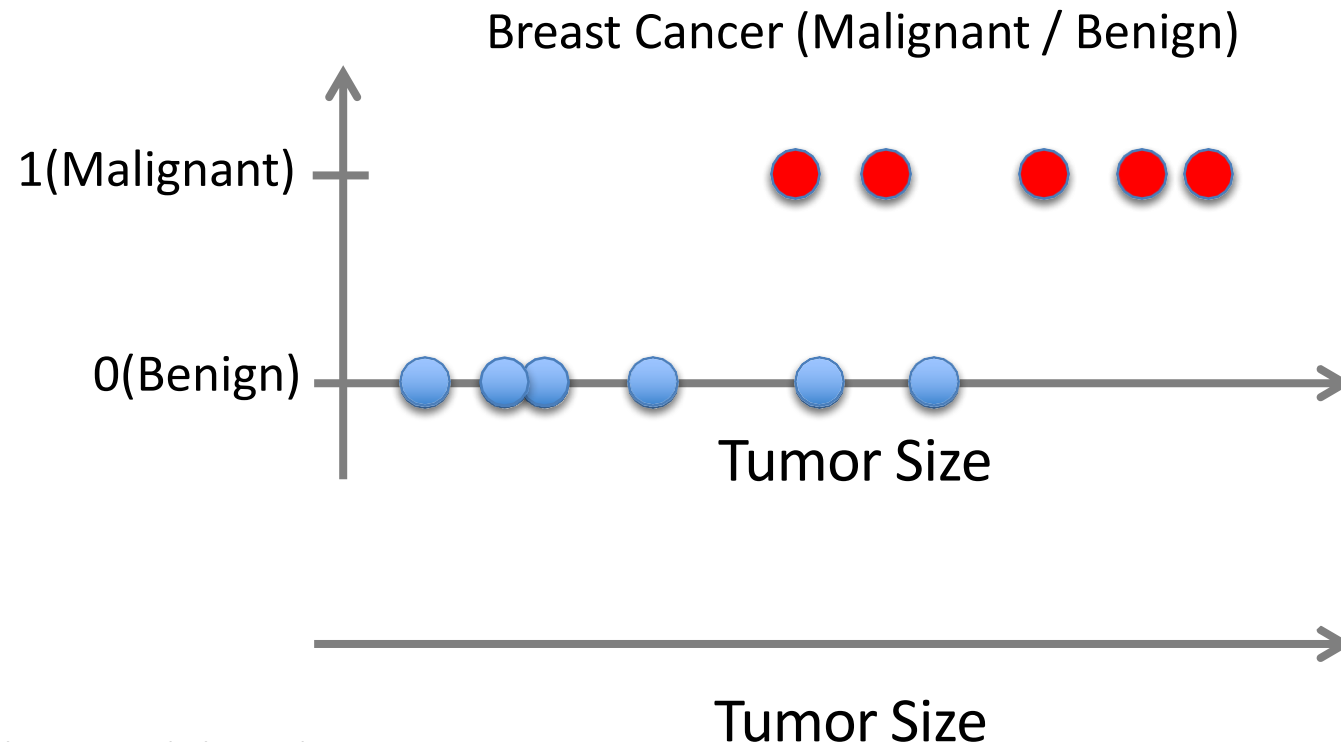
Supervised Learning: Classification

- Given $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$
- Learn a function $f(x)$ to predict y given x
 - y is categorical == classification



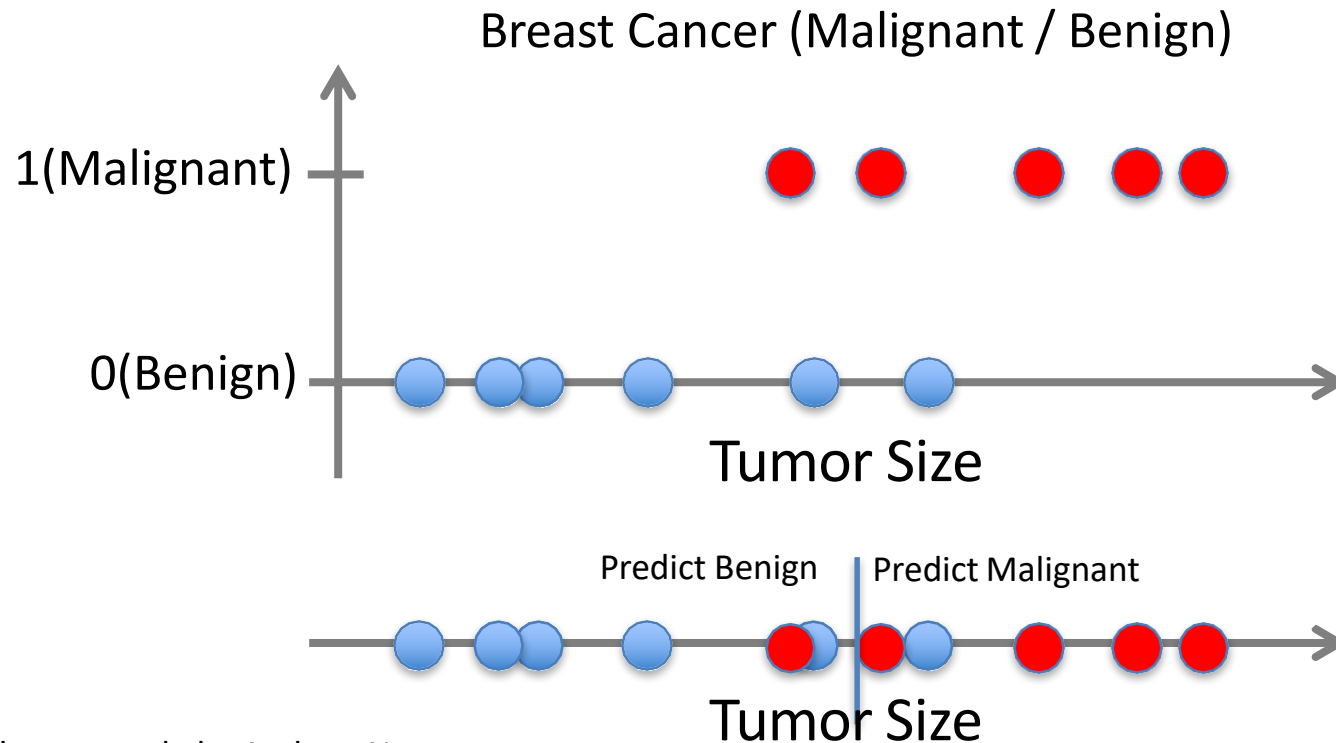
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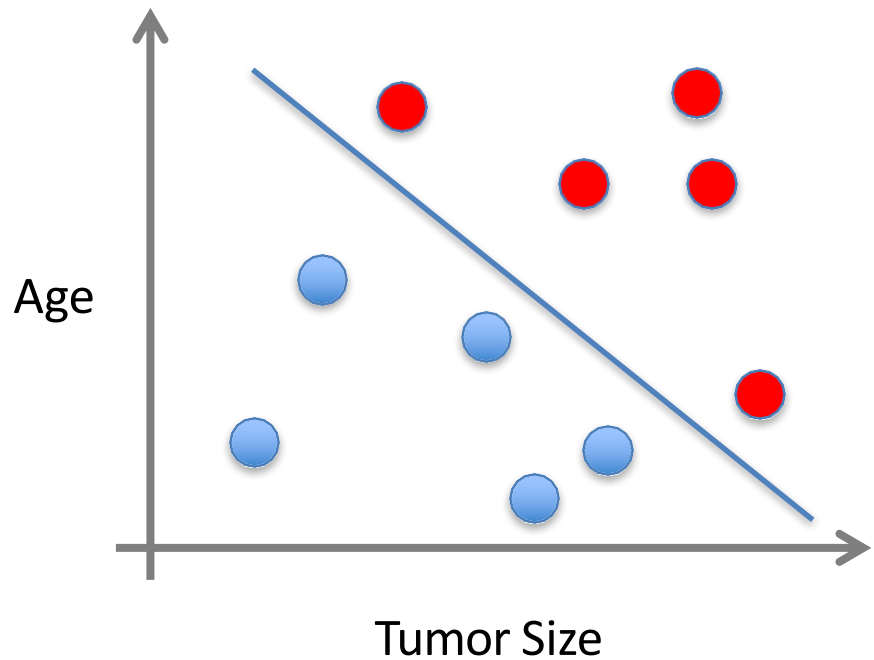
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Supervised Learning

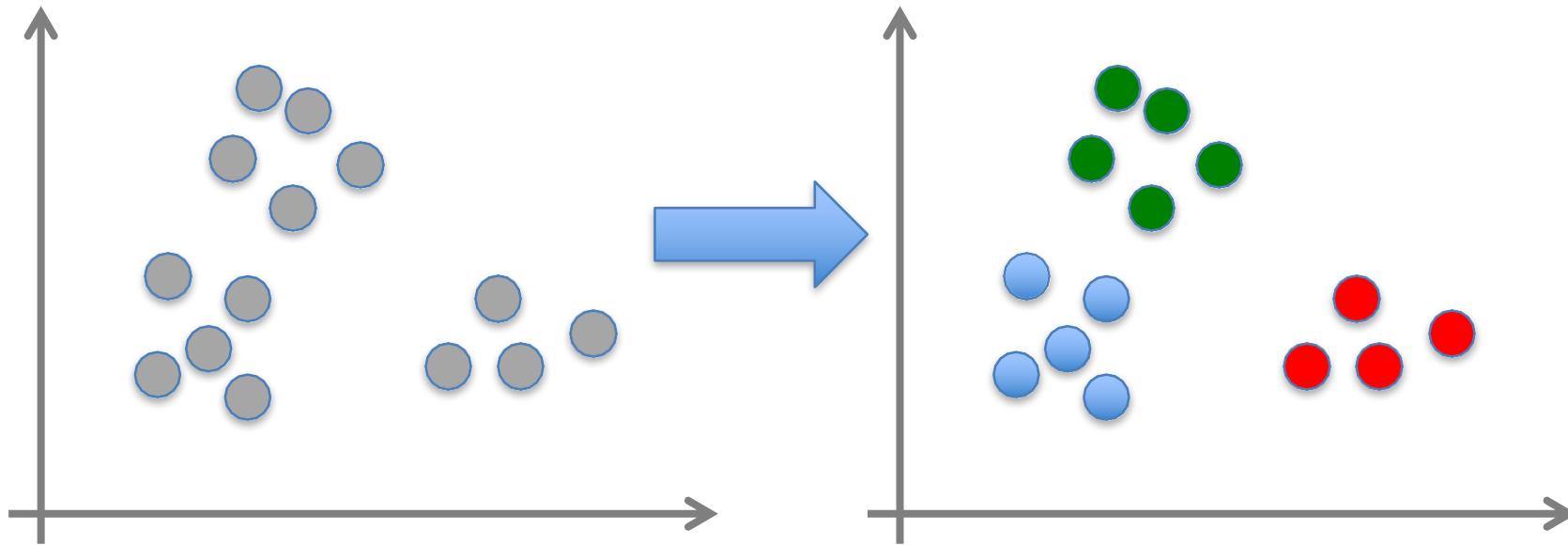
- x can be multi-dimensional
 - Each dimension corresponds to an attribute



- Clump Thickness
- Uniformity of Cell Size
- Uniformity of Cell Shape
- ...

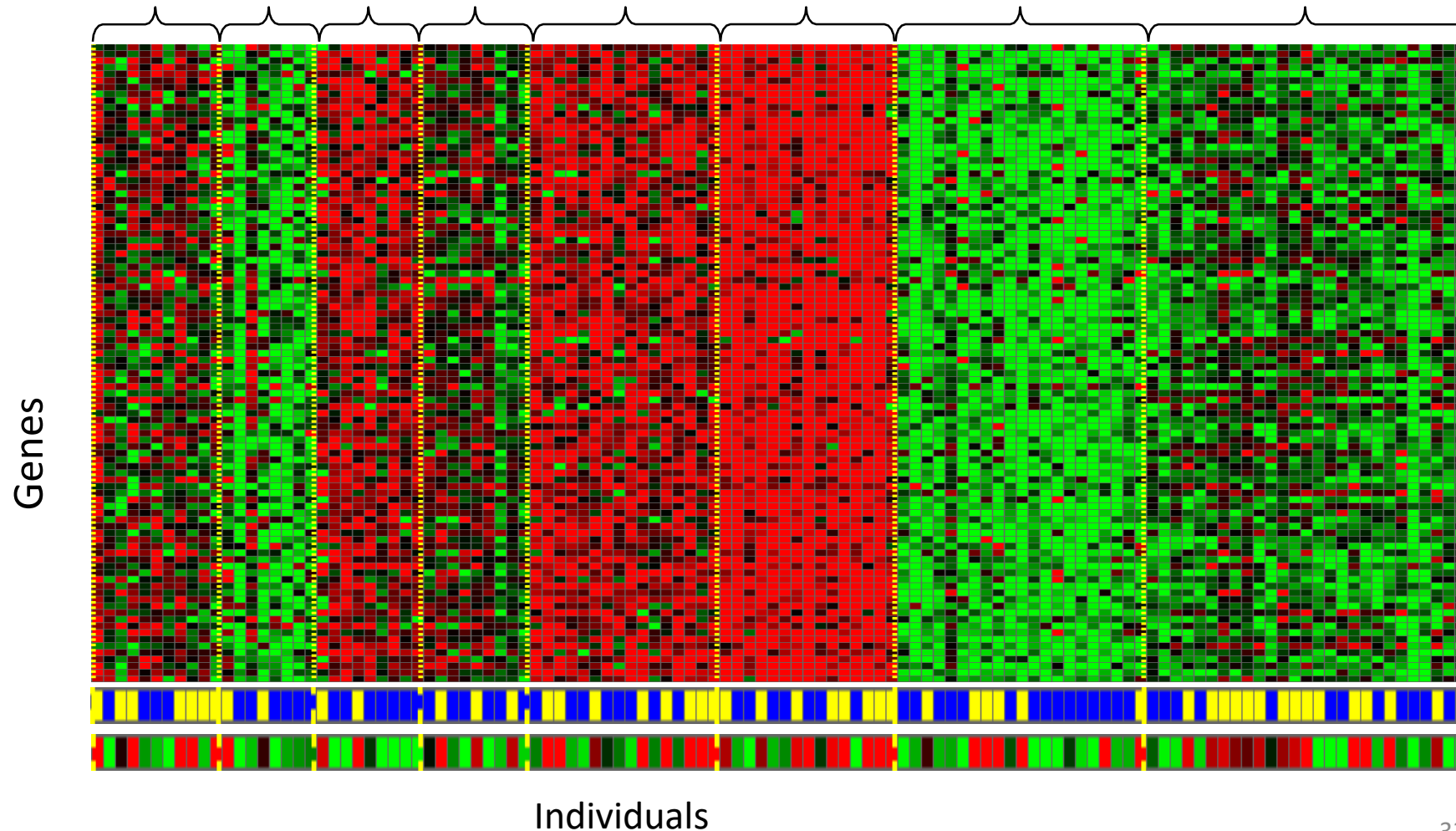
Unsupervised Learning

- Given x_1, x_2, \dots, x_n (without labels)
- Output hidden structure behind the x 's
 - E.g., clustering



Unsupervised Learning

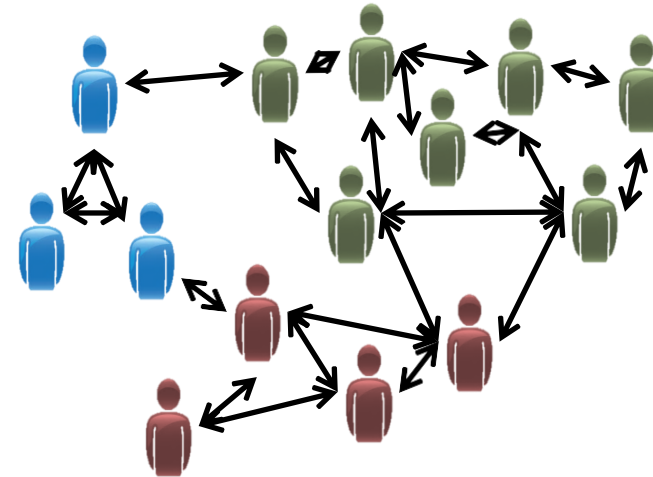
Genomics application: group individuals by genetic similarity



Unsupervised Learning



Organize computing clusters



Social network analysis



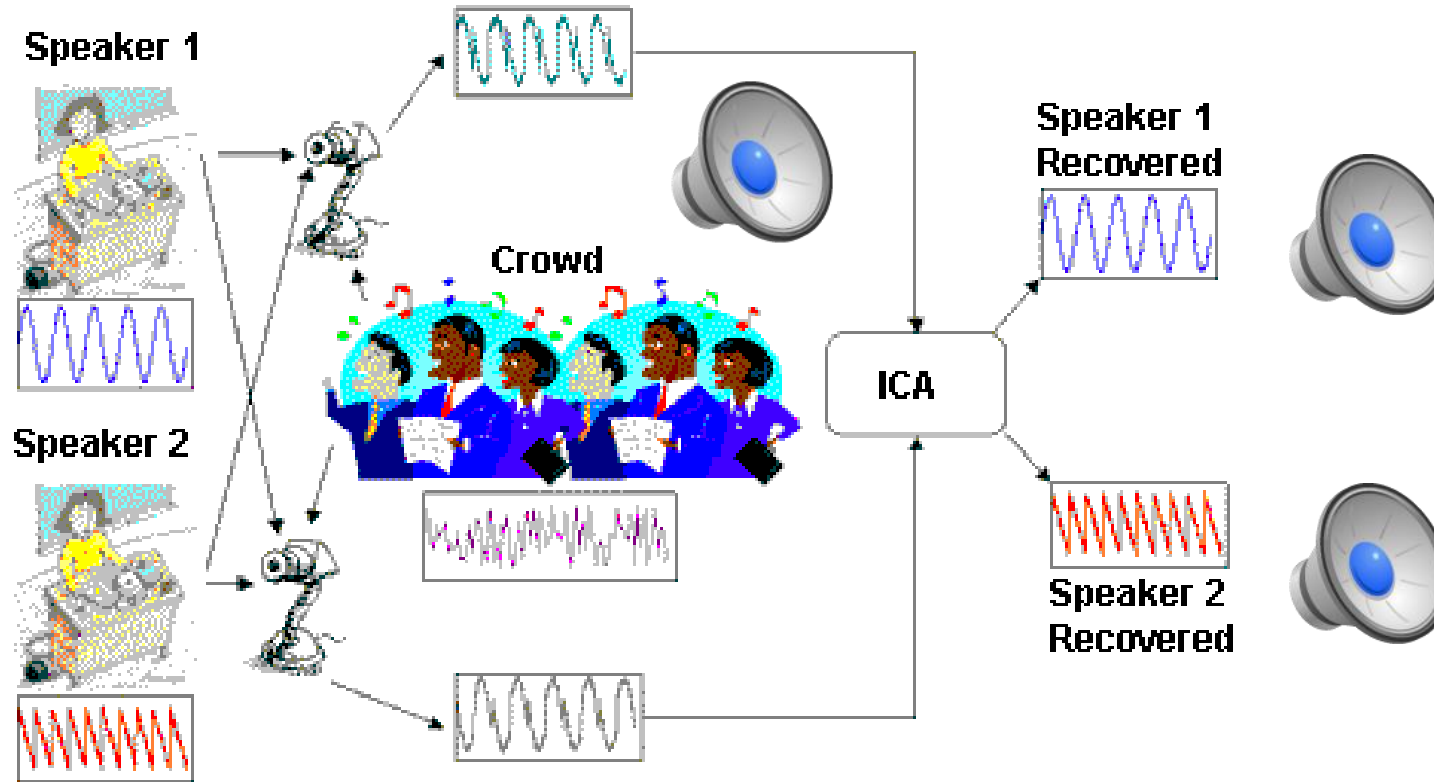
Market segmentation



Astronomical data analysis

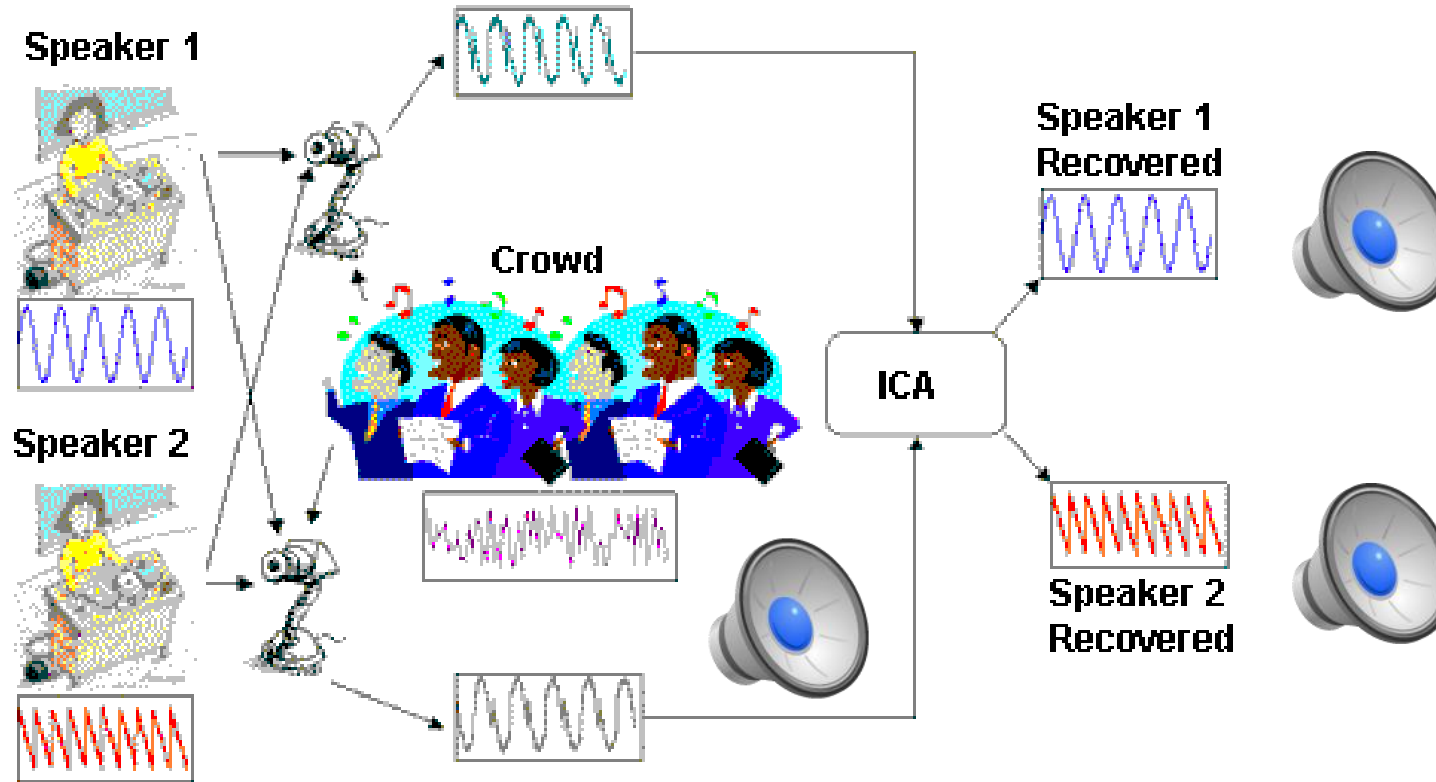
Unsupervised Learning

- Independent component analysis – separate a combined signal into its original sources



Unsupervised Learning

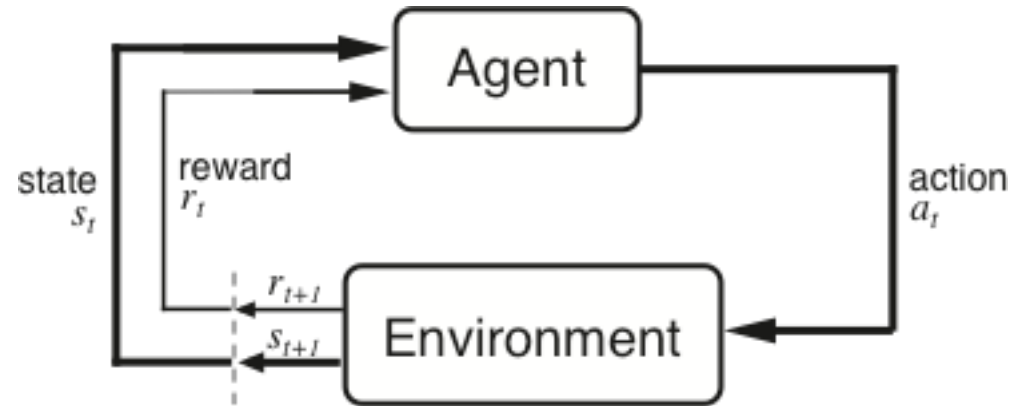
- Independent component analysis – separate a combined signal into its original sources



Reinforcement Learning

- Given a sequence of states and actions with (delayed) rewards, output a policy
 - Policy is a mapping from states \rightarrow actions that tells you what to do in a given state
- Examples:
 - Credit assignment problem
 - Game playing
 - Robot in a maze
 - Balance a pole on your hand

The Agent-Environment Interface



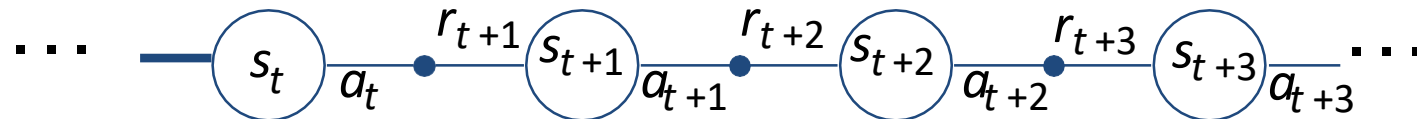
Agent and environment interact at discrete time steps : $t = 0, 1, 2, K$

Agent observes state at step t : $s_t \in \mathcal{S}$

produces action at step t : $a_t \in A(s_t)$

gets resulting reward : $r_{t+1} \in \mathcal{R}$

and resulting next state : s_{t+1}



Reinforcement Learning



<https://www.youtube.com/watch?v=4cgWya-wjgY>

Inverse Reinforcement Learning

- Learn policy from user demonstrations



Stanford Autonomous Helicopter

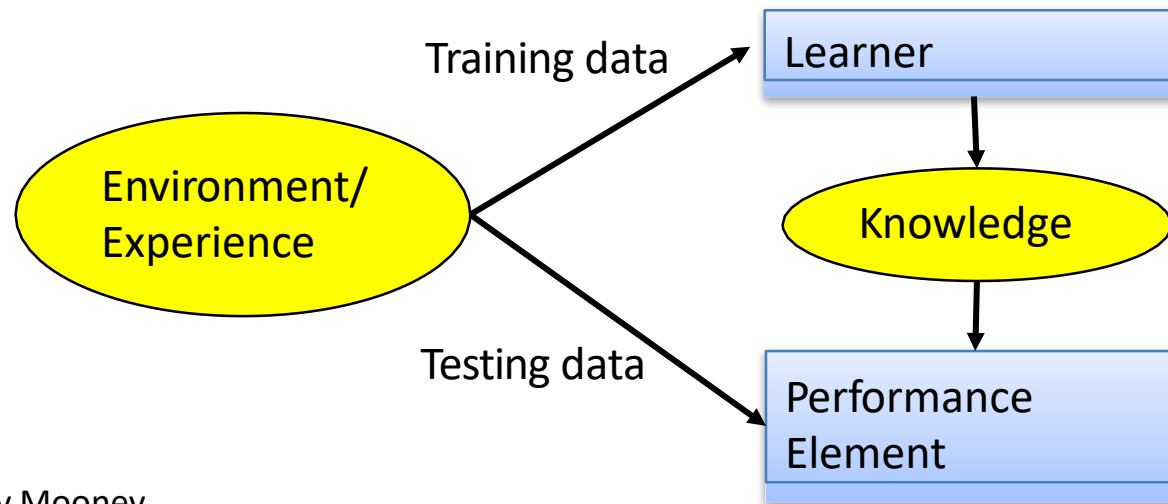
<http://heli.stanford.edu/>

<https://www.youtube.com/watch?v=VCdxqn0fcnE>

Framing a Learning Problem

Designing a Learning System

- Choose the training experience
- Choose exactly what is to be learned
 - i.e. the **target function**
- Choose how to represent the target function
- Choose a learning algorithm to infer the target function from the experience



Training vs. Test Distribution

- We generally assume that the training and test examples are independently drawn from the same overall distribution of data
 - We call this “i.i.d” which stands for “independent and identically distributed”
- If examples are not independent, requires *collective classification*
- If test distribution is different, requires *transfer learning*

ML in a Nutshell

- Tens of thousands of machine learning algorithms
 - Hundreds new every year
- Every ML algorithm has three components:
 - **Representation**
 - **Optimization**
 - **Evaluation**

Various Function Representations

- Numerical functions
 - Linear regression
 - Neural networks
 - Support vector machines
- Symbolic functions
 - Decision trees
 - Rules in propositional logic
 - Rules in first-order predicate logic
- Instance-based functions
 - Nearest-neighbor
 - Case-based
- Probabilistic Graphical Models
 - Naïve Bayes
 - Bayesian networks
 - Hidden-Markov Models (HMMs)
 - Probabilistic Context Free Grammars (PCFGs)
 - Markov networks

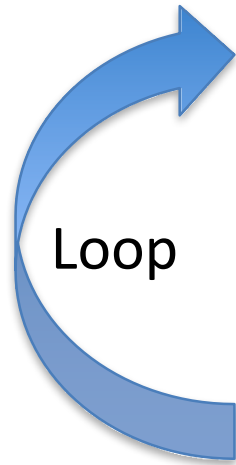
Various Search/Optimization Algorithms

- Gradient descent
 - Perceptron
 - Backpropagation
- Dynamic Programming
 - HMM Learning
 - PCFG Learning
- Divide and Conquer
 - Decision tree induction
 - Rule learning
- Evolutionary Computation
 - Genetic Algorithms (GAs)
 - Genetic Programming (GP)
 - Neuro-evolution

Evaluation

- Accuracy
- Precision and recall
- Squared error
- Likelihood
- Posterior probability
- Cost / Utility
- Margin
- Entropy
- K-L divergence
- etc.

ML in Practice



- Understand domain, prior knowledge, and goals
- Data integration, selection, cleaning, pre-processing, etc.
- Learn models
- Interpret results
- Consolidate and deploy discovered knowledge

Lessons Learned about Learning

- Learning can be viewed as using direct or indirect experience to approximate a chosen target function.
- Function approximation can be viewed as a search through a space of hypotheses (representations of functions) for one that best fits a set of training data.
- Different learning methods assume different hypothesis spaces (representation languages) and/or employ different search techniques.