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Batch: C4 Sub:MD

Practical 6

Aim: LCD interfacing

Code:

ORG 0000H ; Set the origin of the program

MOV A,#38H ; Load the command to initialize LCD ACALL COMMAND ; Call the command subroutine

MOV A,#0EH ; Load the command for display ON, cursor ON

ACALL COMMAND ; Call the command subroutine MOV A,#01H ; Load the command to clear display ACALL COMMAND ; Call the command subroutine

MOV A,#06H ; Load the command to increment cursor

ACALL COMMAND ; Call the command subroutine MOV A,#86H ; Set the cursor to a specific position ACALL COMMAND ; Call the command subroutine

; Display "VANSH" on the LCD

MOV A,#'V' ; Load 'V' into the accumulator

ACALL DATA_DISPLAY; Display 'V'

MOV A,#'A' ; Load 'A' into the accumulator

ACALL DATA_DISPLAY; Display 'A'

MOV A,#'N'; Load 'N' into the accumulator

ACALL DATA_DISPLAY; Display 'N'

MOV A,#'S'; Load 'S' into the accumulator

ACALL DATA_DISPLAY; Display 'S'

MOV A,#'H'; Load 'H' into the accumulator

ACALL DATA_DISPLAY; Display 'H'

HERE: SJMP HERE ; Infinite loop to stop the program from exiting

; Subroutine for sending commands to the LCD COMMAND:

ACALL READY ; Call the ready subroutine to ensure LCD is ready MOV P1,A ; Move the contents of the accumulator to Port 1 (data)

CLR P2.0 ; RS = 0, for command CLR P2.1 ; R/W = 0, for write SETB P2.2 ; Enable high CLR P2.2 ; Enable low, to send command

RET ; Return from subroutine

; Subroutine for displaying data on the LCD

DATA_DISPLAY:

ACALL READY ; Call the ready subroutine to ensure LCD is ready

MOV P1,A ; Move the contents of the accumulator to Port 1 (data)

SETB P2.0 ; RS = 1, for data CLR P2.1 ; R/W = 0, for write

SETB P2.2 ; Enable high

CLR P2.2 ; Enable low, to send data RET ; Return from subroutine

; Subroutine to ensure the LCD is ready before sending the next command/data READY:

SETB P1.7 ; Set the busy flag (assumes P1.7 is used for busy flag)

CLR P2.0 ; RS = 0, for command SETB P2.1 ; R/W = 1, for read

BACK:

SETB P2.2 ; Enable high

CLR P2.2 ; Enable low, to latch the data

JB P1.7,BACK ; If P1.7 (busy flag) is set, loop back and wait

RET ; Return when LCD is ready

END ; End of **program**

OUTPUT:

