

System Design Documentation

1. System Overview

The "Third Eye for the Blind" device is a wearable technology designed to help visually impaired individuals detect obstacles in their path. It leverages ultrasonic sensors to gauge distances and provide real-time feedback through a buzzer. The device is intended to be integrated into a pair of glasses, ensuring that it is both practical and user-friendly.

2. Components List and Specifications

Key Components:

1. Arduino Nano:

- **Function:** Acts as the microcontroller, processing data from the ultrasonic sensor and controlling outputs like the buzzer.
- **Specifications:**
 - Microcontroller: ATmega328
 - Operating Voltage: 5V
 - Digital I/O Pins: 14 (6 PWM outputs)
 - Analog Input Pins: 8

2. Ultrasonic Sensor (HC-SR04):

- **Function:** Measures the distance to obstacles using sound waves.
- **Specifications:**
 - Operating Voltage: 5V
 - Measuring Range: 2cm to 400cm
 - Accuracy: ± 3 mm
 - Trigger and Echo pins for distance calculation

3. Buzzer:

- **Function:** Provides auditory feedback when an obstacle is detected within a critical distance.
- **Specifications:**
 - Operating Voltage: 3.3-5V
 - Sound Output: 85 dB

4. 9V Battery:

- **Function:** Powers the Arduino Nano and other components.
- **Specifications:**
 - Nominal Voltage: 9V
 - Capacity: 500mAh (varies by brand)

5. Battery Clip:

- **Function:** Connects the 9V battery to the Arduino and the circuit.

6. **Push Button:**

- **Function:** Acts as a power switch, allowing the user to start or stop the device.
- **Specifications:**
 - Normally open (NO) configuration
 - Rated Voltage: 12V

7. **Glasses:**

- **Function:** The platform where all the components are mounted, ensuring a wearable and user-friendly design.

8. **Jumper Wires:**

- **Function:** Connects the various components, including power, ground, and signal lines.

3. Detailed Schematic Diagram

The schematic diagram provides a clear view of how the components are interconnected:

1. **Ultrasonic Sensor:**

- **VCC:** Connected to the 5V output of the Arduino Nano.
- **GND:** Connected to the ground (GND) pin on the Arduino.
- **Trigger Pin:** Connected to digital pin D2 on the Arduino.
- **Echo Pin:** Connected to digital pin D3 on the Arduino.

2. **Buzzer:**

- **Positive Terminal:** Connected to digital pin D5 on the Arduino.
- **Negative Terminal:** Connected to the ground (GND) pin.

3. **Push Button:**

- **One Side:** Connected to a digital pin (D7) on the Arduino.
- **Other Side:** Connected to ground with an internal pull-up resistor configured in the code.

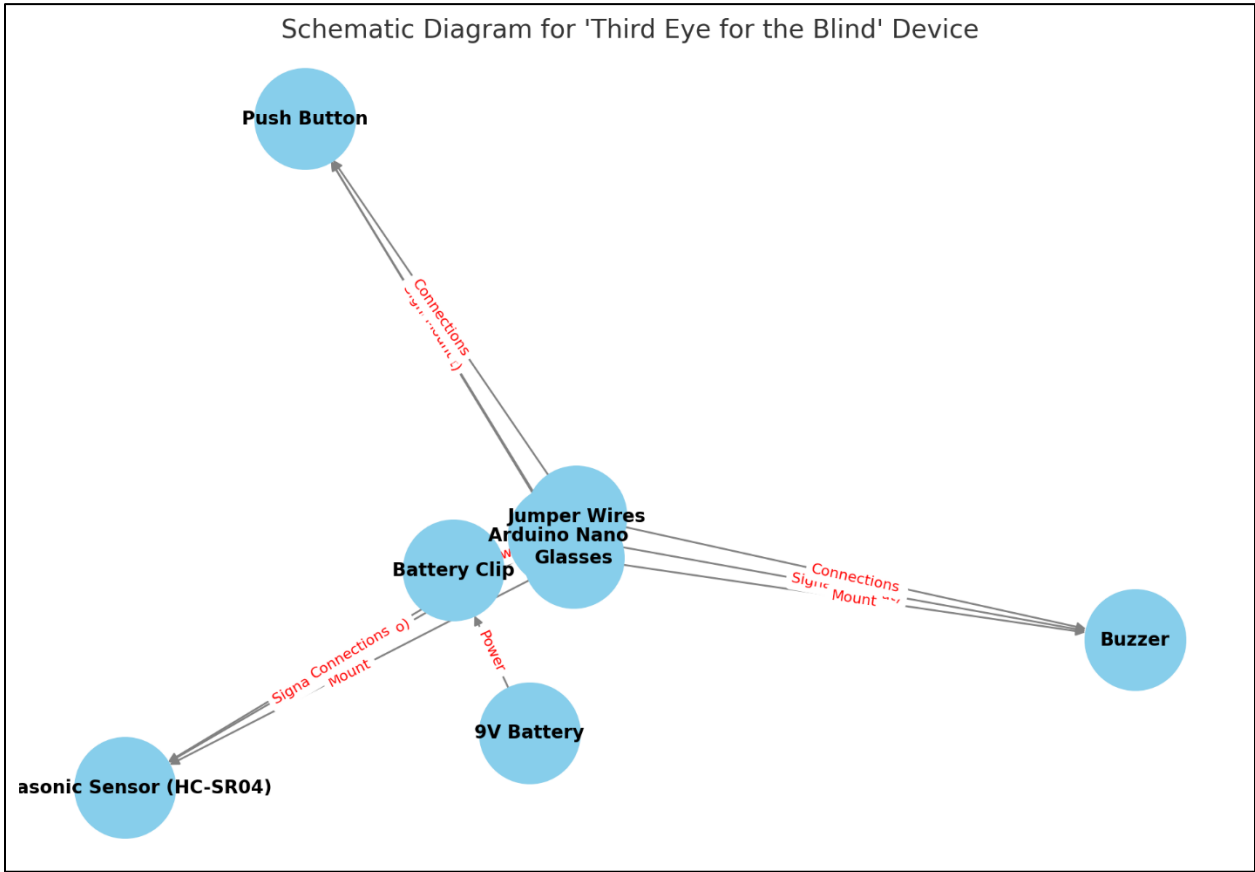
4. **Power Supply (9V Battery):**

- **Positive Terminal:** Connected to the VIN pin on the Arduino (which has an onboard voltage regulator).
- **Negative Terminal:** Connected to the GND pin on the Arduino.

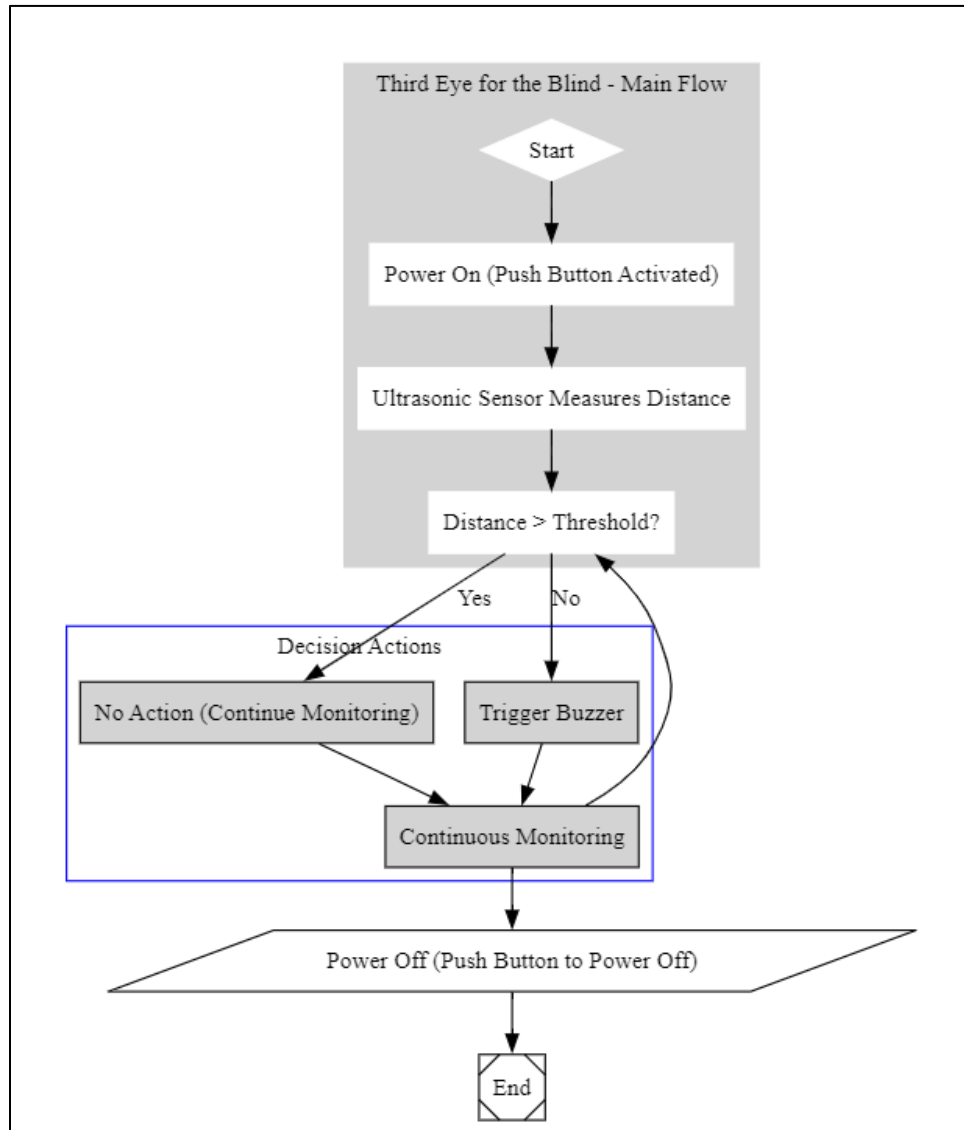
Circuit Design Explanation:

- The ultrasonic sensor continuously sends out sound waves and listens for the echo. When an object is within a set distance (e.g., 100 cm), the Arduino triggers the buzzer to alert the user.

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- Schematic Diagram for 'Third Eye for the Blind' Device
- The diagram illustrates the connections between the following components:
- Push Button** (top left)
 - Jumper Wires** (center top)
 - Arduino Nano Glasses** (center)
 - Battery Clip** (center left)
 - 9V Battery** (bottom center)
 - Ultrasonic Sensor (HC-SR04)** (bottom left)
 - Buzzer** (bottom right)
- The connections are labeled as follows:
- Connections (Signal Mount)** (red text) connects the Push Button to the Arduino Nano Glasses.
 - Connections (Signal Mount)** (red text) connects the Arduino Nano Glasses to the Buzzer.
 - Connections (Signal Mount)** (red text) connects the Arduino Nano Glasses to the Ultrasonic Sensor (HC-SR04).
 - Power** (red text) connects the 9V Battery to the Battery Clip.



4. Flowchart



- After powering on, the device continuously measures the distance in front of the user.
- If the measured distance falls below a predefined threshold (e.g., 100 cm), the buzzer is activated to warn the user.
- The device remains in this loop until the user deactivates it using the push button.

5. Design Considerations

Mounting the Components on Glasses:

- The ultrasonic sensor is mounted at the front of the glasses, pointing forward to detect obstacles.
- The Arduino Nano and battery are mounted on the sides or behind the user's head for balance and comfort.
- Jumper wires are neatly routed along the frame of the glasses, ensuring they do not obstruct the user's view or interfere with wearability.

Energy Management:

- The 9V battery should be selected based on its capacity to provide sufficient power for at least several hours of continuous use. A low-power design approach is critical to extend battery life.

Safety and Durability:

- All connections should be secure, with appropriate insulation to prevent short circuits.
- The glasses should be lightweight and ergonomically designed for long-term wear.