

# Bayesian Estimation

- \* It uses the Bayes theory.

- \* Recall: Bayes Theorem.

For two events A and B  
(A and B are not independent events),

$$P(B|A) = \frac{P(A|B) P(B)}{P(A)}$$

- \* Data:  $\{x_n\}_{n=1}^N$

- \* The objective: Find an estimate of a parameter value  $\theta$  using Bayes' Rule for the given data  $\{x_n\}_{n=1}^N$

- \* Using Bayes' Rule for data (denoted as  $D = \{x_n\}_{n=1}^N$ )

$$\pi_{\theta|x}(\theta|D) = \frac{f_{x|\theta}(D|\theta) \pi(\theta)}{\int_x(D)}$$

$\pi(\theta)$ : Prior Distribution

$\pi_{\theta|x}(\theta|D)$ : Posterior distribution

$f_{x|\theta}(D|\theta)$ : Likelihood

$f_x(D)$ : Normalizing factor

\* Prior: Our belief about possible values of  $\theta$  (or distribution)

\* Posterior:  $\rightarrow \{x_n\}_{n=1}^N$  are observed, the new information on  $\theta$  has obtained. Then, updating prior in the light of  $\{x_n\}_{n=1}^N$  is the posterior distribution

$$\pi_{\theta|x}(\theta|D)$$

\*  $f_x(D)$ : Normalizing constant

$$f_x(x_1, \dots, x_N) = \int P(\theta|x) p(\theta) d\theta$$

$$* \boxed{\pi_{\theta|x}(\theta|D) \propto f_x(D|\theta) \pi_{\theta}(\theta)}$$

How can we estimate  $\pi_{\theta|x}(\theta|D)$ ?

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Example:

Data:  $x_1 \dots x_n$

Distribution:  $N(\mu, \sigma^2)$

$\mu$ : unknown and  $\sigma^2$  is known.

Prior:  $\mu \sim N(\mu_0, \sigma_0^2)$  is available.

$$\begin{aligned} * f_X(x_1 \dots x_n / \mu) &= \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2} \end{aligned}$$

$$* \pi(\mu) = \frac{1}{(2\pi\sigma_0^2)^{1/2}} e^{-\frac{1}{2\sigma_0^2} (\mu - \mu_0)^2}$$

\* Joint Probability distribution

$$\begin{aligned} f(x_1 \dots x_n, \mu) &= \frac{1}{(2\pi\sigma^2)^{n/2}} \frac{1}{(2\pi\sigma_0^2)^{1/2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 - \frac{1}{2\sigma_0^2} (\mu - \mu_0)^2} \end{aligned}$$

$$= \frac{1}{(2\pi\sigma^2)^{n/2} \sqrt{2\pi\sigma_0^2}} e^{-\frac{1}{2} \left[ \left( \frac{1}{\sigma_0^2} + \frac{N}{\sigma^2} \right) \mu^2 - \left( \frac{\sigma^2 \mu_0 + \sigma_0^2 \bar{x}}{N} \right) \mu \right]}$$

$h(\cdot)$  is a function of  $x_1 \dots x_n, \sigma^2, \mu_0$

$$= e^{-\frac{1}{2} \left( \frac{1}{\sigma_0^2} + \frac{N}{\sigma^2} \right) \left[ \mu^2 - 2 \frac{\left( \frac{\sigma^2 \mu_0 + \sigma_0^2 \bar{x}}{N} \right) \mu}{\left( \frac{1}{\sigma_0^2} + \frac{N}{\sigma^2} \right)} \right]}$$

Def.  $e^{-\frac{1}{2\sigma_N^2} \left[ \mu^2 - 2\mu\mu_N \right]} \tilde{h}(\cdot)$

Then, the posterior distribution for  $\mu$  is also a normal distribution with

$$\frac{1}{\sigma_N^2} = \frac{1}{\sigma_0^2} + \frac{N}{\sigma^2}$$

$$\Leftrightarrow \sigma_N^2 = \frac{\sigma_0^2 \sigma^2}{\sigma^2 + N\sigma_0^2}$$

$$\& \mu_N = \frac{\frac{\sigma^2 \mu_0 + \sigma_0^2 \bar{x}}{N}}{\frac{1}{\sigma_0^2} + \frac{N}{\sigma^2}}$$

Now, Bayes Estimator of  $\theta$   
 $\hat{\theta} = E[\theta | \text{sample}]$  or  
mean of posterior  
distribution

Note that the mean can be  
directly determined if  $f(\theta | D)$   
is a known probability  
distribution.