

- Aim

Object detection using Transfer learning of CNN architecture.

- a. Load in pre-trained CNN model trained on large data set
- b. Freeze parameters (weight) in the model's lower convolutional layers.
- c. Add a custom classifier with several layers of trainable parameter to model
- d. Train classifier layer on training data available for the task
- e. Fine-tune hyperparameters and unfreeze more layers as needed.

- Course objectives

1. To apply the algorithms to a real-world problem, optimise the models learned and report on the expected accuracy that can be achieved by applying the models.

- Course - outcomes

CO3: Apply Deep learning technique like CNN and RNN Auto encoders to solve real-world problems

CO4: Evaluate the performance of the model built using Deep learning.

- Softwares and hardware requirements.

sr.no	Hardwares and hardware	version / specification
1.	Jupyter notebook	v. 7.13.008
2.	computer /pc	IS version , 64 bits, 8 GB RAM

- Theory

Steps / Algorithm of object detection using Transfer learning of CNN architecture.

Step 1 :

Dataset link and libraries

Step 2 :

/ test

/ class1

/ class2

Libraries required :

PyTorch

torchvision important transform

pip install pytorch

(for installing pytorch)



### step 2 :

Prepare the dataset in splitting in three directory  
Train , validation and test with 50 25 56 25

### step 3 :

Do pre - processing on data with transform from  
pytorch training dataset transformation as follows:  
transform.Compose ([  
transform.RandomResizedCrop (size = 256, scale = (0.8, 1.0)),  
transform.RandomRotation (degrees = 15), transform.ColorJitter(),  
transform.RandomHorizontalFlip (), transforms.CenterCrop  
size = 224].

### step 4 :

Create Datasets and Loaders : data = {  
'train': (our name given to train data set dir created)  
datasets.ImageFolder (root = traindir, transform = image-  
transforms ['train']), 'valid':  
dataset.ImageFolder (root = validdir, transform =  
image-transform ['valid']),

DataLoaders = {

'train': DataLoader (data ['train'], batch\_size = batch\_size,  
shuffle = True), 'val':  
DataLoader (data ['valid'], batch\_size = batch\_size,  
shuffle = True)}

Step 5 :

Load Pretrain model : from torchvision import models

model = model.vgg16  
(pretrained = True)

Step 6 :

freeze all the model weights  
for param in model.parameters(): param.requires\_grad = False.

Step 7 :

Add our own custom classifier with following parameters: fully connected ReLU Activation function

Step 8 :

only train the sixth layer of classifier keep remaining layers off. sequential{  
(0) : Linear (in\_features = 25088, out\_features = 4096, bias = True)}

(1) : ReLU (inplace)

(2) : Dropout (p=0.5)

(3) : Linear (in\_feature = 4096, out\_feature = 4096, bias = True)

(4) (5) : ReLU (inplace)

(6) : Dropout (p=0.5)

(7) : sequential(

Step 9 :

Initialize the loss and optimizer criterion =  
`nn.NLLLoss()`  
`optimizer = optim.Adam(model.parameters())`

Step 10 :

Train the model using PyTorch for epoch in Range  
`(n_epochs)`: For data, targets in trainloader:

```
# Generate prediction out = model(data)
# calculate loss
loss = criterion(out, targets)
# Back propagation loss.backward()
# update model parameters optimizer.step()
```

Step 11 :

Perform Early stopping

Step 12 :

Draw performance curve

Step 13 :

Calculate Accuracy

`Pred = torch.max(ps, dim=1)` `equals = pred == targets`

`# calculate accuracy`

`accuracy = torch.mean(equals)`

- Conclusion

In this practical, I have learned about pre-trained CNN model is adapted for object detection by freezing lower layers, adding a custom classifier, and fine-tuning hyperparameters. unfreezing layers can enhance performance for the specific task.