SUBLINEAR TIME LOW-RANK APPROXIMATION OF POSITIVE SEMIDEFINITE MATRICES

Cameron Musco (MIT) and David P. Woodruff (CMU)

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 A near optimal low-rank approximation for any positive semidefinite (PSD) matrix can be computed in sublinear time (i.e. without reading the full matrix).

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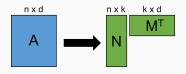
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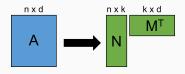
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- Concrete: Significantly improves on previous, roughly linear time approaches for general matrices, and bypasses a trivial linear time lower bound for general matrices.
- High Level: Demonstrates that PSD structure can be exploited in a much stronger way than previously known for low-rank approximation. Opens the possibility of further advances in algorithms for PSD matrices.

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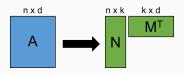


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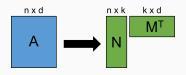
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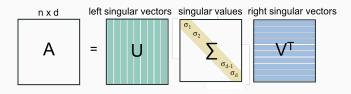


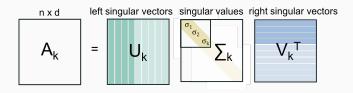
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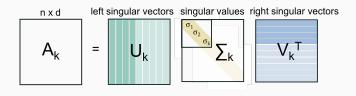
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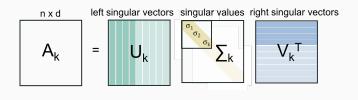
• Includes graph Laplacians, Gram matrices and kernel matrices, covariance matrices, Hessians for convex functions.





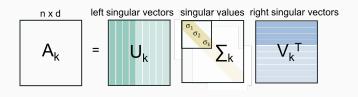


$$\mathbf{A}_k = \underset{\mathbf{B}: \mathsf{rank}(\mathbf{B}) = k}{\mathsf{arg} \, \mathsf{min}} \| \mathbf{A} - \mathbf{B} \|_F$$



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An optimal low-rank approximation can be computed via the singular value decomposition (SVD).



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• Unfortunately, computing the SVD takes $O(nd^2)$ time.

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Theorem (Clarkson, Woodruff '13)

There is an algorithm which in $O(\operatorname{nnz}(\mathbf{A}) + n \cdot \operatorname{poly}(k, 1/\epsilon))$ time outputs $\mathbf{N} \in \mathbb{R}^{n \times k}$, $\mathbf{M} \in \mathbb{R}^{d \times k}$ satisfying with prob. 99/100:

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- When $k, 1/\epsilon$ are not too large, runtime is linear in input size.
- Best known runtime for both general and PSD matrices.

Theorem (Main Result – Musco, Woodruff '17)

There is an algorithm running in $\tilde{O}\left(\frac{nk^2}{\epsilon^4}\right)$ time which, given PSD

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- Compare to CW'13 which takes $O(\text{nnz}(\mathbf{A})) + n \cdot \text{poly}(k, 1/\epsilon)$.
- If $k, 1/\epsilon$ are not too large compared to nnz(**A**), our runtime is significantly sublinear in the size of **A**.

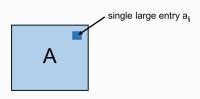
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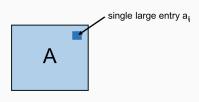
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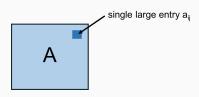
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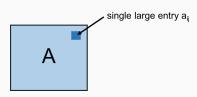
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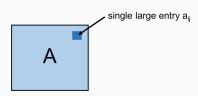


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$$\|\mathbf{A} - \mathbf{N}\mathbf{M}^T\|_F \le \|\mathbf{A} - \mathbf{A}_k\|_F + \epsilon \|\mathbf{A}\|_F.$$

WHAT ABOUT FOR PSD MATRICES?

Observation: For PSD **A**, we have for any entry a_{ij} :

$$\mathbf{a}_{ij} \leq \max(\mathbf{a}_{ii}, \mathbf{a}_{jj})$$

since otherwise $(\mathbf{e}_i - \mathbf{e}_j)^T \mathbf{A} (\mathbf{e}_i - \mathbf{e}_j) < 0$.



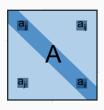
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 So we can find any 'hidden' heavy entry by looking at its corresponding diagonal entries.



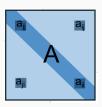
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Question: How can we exploit additional structure arising from positive semidefiniteness to achieve sublinear runtime?

EVERY PSD MATRIX IS A GRAM MATRIX

Very Simple Fact: Every PSD matrix $\mathbf{A} \in R^{n \times n}$ can be written as $\mathbf{B}^T \mathbf{B}$ for some $\mathbf{B} \in \mathbb{R}^{n \times n}$.

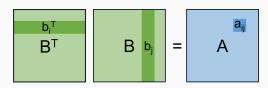
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• **B** can be any matrix square root of **A**, e.g. if we let $\mathbf{V}\mathbf{\Sigma}\mathbf{V}^T$ be the eigendecomposition of **A**, we can set $\mathbf{B} = \mathbf{\Sigma}^{1/2}\mathbf{V}^T$.

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- Letting $\mathbf{b}_1, ..., \mathbf{b}_n$ be the columns of \mathbf{B} , the entries of \mathbf{A} contain every pairwise dot product $\mathbf{a}_{ij} = \mathbf{b}_i^T \mathbf{b}_j$.



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 The heavy diagonal observation is just one example. By Cauchy-Schwarz:

$$\mathbf{a}_{ij} = \mathbf{b}_i^T \mathbf{b}_j \le \sqrt{(\mathbf{b}_i^T \mathbf{b}_i) \cdot (\mathbf{b}_j^T \mathbf{b}_j)} = \sqrt{\mathbf{a}_{ii} \cdot \mathbf{a}_{jj}} \le \max(\mathbf{a}_{ii}, \mathbf{a}_{jj}).$$

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Another View: A contains a lot of information about the column span of B in a very compressed form – with every pairwise dot product stored as a_{ij} .

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So the top k singular vectors are the same for the two matrices.
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- So the top k singular vectors are the same for the two matrices.
 An optimal low-rank approximation for B thus gives an optimal low-rank approximation for A.
- Things will be messier once we introduce approximation, but this simple idea will lead to a sublinear time algorithm for A.

Theorem (Deshpande, Vempala '06)

For any $\mathbf{B} \in \mathbb{R}^{n \times n}$, there exists a subset of $\tilde{O}(k^2/\epsilon)$ columns whose span contains $\mathbf{Z} \in \mathbb{R}^{n \times k}$ satisfying:

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Adaptive Sampling

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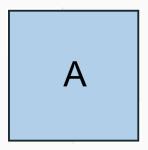
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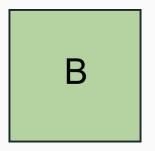
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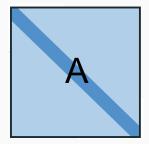
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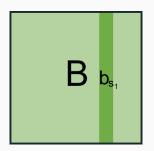
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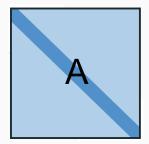
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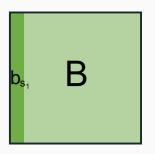
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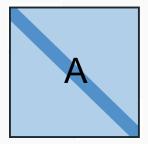
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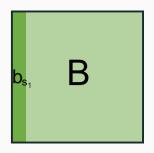


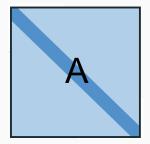
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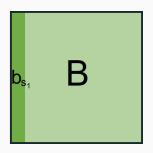


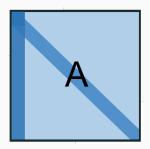
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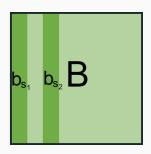


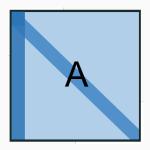
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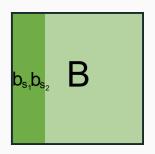


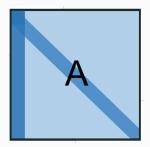
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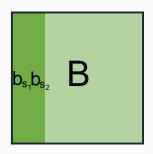


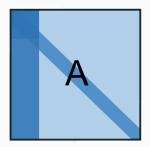
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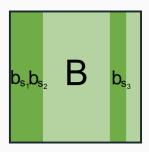


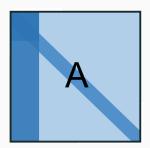
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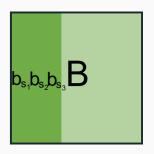


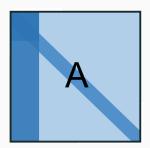
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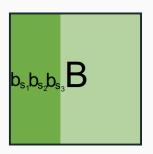


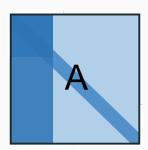
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SUBLINEAR DOT PRODUCT ALGORITHM

Theorem (Factor Matrix Low-Rank Approximation)

There is an algorithm using $\tilde{O}(nk^2/\epsilon)$ accesses to $\mathbf{A} = \mathbf{B}^T\mathbf{B}$ which computes $\mathbf{Z} \in \mathbb{R}^{n \times k}$ satisfying with probability 99/100:

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How does this translate to low-rank approximation of A itself?

Lemma

If
$$\|\mathbf{B} - \mathbf{Z}\mathbf{Z}^T\mathbf{B}\|_F^2 \le \left(1 + \frac{\epsilon^{3/2}}{\sqrt{n}}\right) \|\mathbf{B} - \mathbf{B}_k\|_F^2$$
, then for $\mathbf{A} = \mathbf{B}^T\mathbf{B}$:

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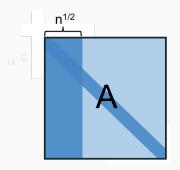
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- Our best algorithm accesses just $\tilde{O}\left(\frac{nk}{\epsilon^{2.5}}\right)$ entries of **A** and runs in $\tilde{O}\left(\frac{nk^2}{\epsilon^4}\right)$ time.

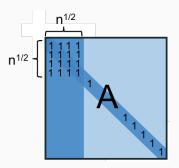
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• If we take fewer columns, we can miss a $\sqrt{n} \times \sqrt{n}$ block which contains a constant fraction of **A**'s Frobenius norm.

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- Sample AS is a projection-cost-preserving sketch for A [Cohen et al '15,'17]. For any rank-k projection P,

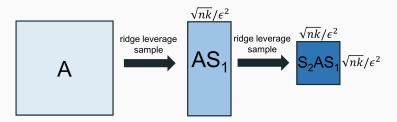
$$\|\mathbf{AS} - \mathbf{PAS}\|_F^2 = (1 \pm \epsilon) \|\mathbf{A} - \mathbf{PA}\|_F^2.$$

FINAL ALGORITHM

Recover low-rank approximation using two-sided sampling and projection-cost-preserving sketch property.

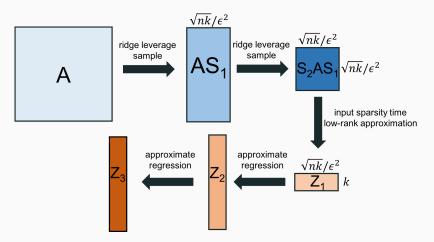
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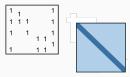
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- Obtain near-optimal complexity using ridge leverage scores to sample both rows and columns of A.

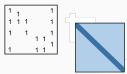
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 What can we do when we have PSD matrices with additional structure? E.g. kernel matrices. Thanks! Questions?