

ECE 210 Final Exam Review: Chapters 1-11

Major Topics: Node and Loop Analysis, Op-amps, Superposition, Thevenin and Norton Equivalency, RLC circuit analysis, Phasors, Frequency Response, Fourier Series, Fourier Transform, Modulation, Sampling, Bandwidth, Energy, Convolution, Linearity, Time-Invariance, Stability, Causality, Laplace Transform, Laplace-domain circuit analysis

Stability and Causality

a) $h(t) = e^{-3t} u(t)$

Causal because it is zero for all $t < 0$.

Stable because $\int_{-\infty}^{\infty} |h(t)| dt = \int_0^{\infty} e^{-3t} dt = \frac{e^{-3t}}{-3} \Big|_0^{\infty} = \frac{1}{3} < \infty$

b) $y(t) = x(t+1)$

Non causal because $y(0)$ depends upon $x(1)$.

Laplace Transform

$$h(t) = e^{-3t} u(t)$$

$$\begin{aligned} H(s) &= \int_0^{\infty} e^{-3t} e^{-st} dt \\ &= \int_0^{\infty} e^{-(s+3)t} dt \\ &= \frac{e^{-(s+3)t}}{-(s+3)} \Big|_0^{\infty} \\ &= \frac{1}{s+3} \end{aligned}$$

Region of convergence: $\operatorname{Re}\{s\} > -3$

Pole: $s = -3$

Stable because all poles are in the left half plane.

Causal because $h(t)$ is zero for all $t < 0$.

Characteristic Mode: $c_i = e^{-3t}$

Formula	$c_i(t) = t^{k_i} e^{p_i t}$	$0 \leq k_i < r_i$
p_i	= poles	
r_i	= multiplicities	

Significance: the zero input response is a linear sum of the characteristic modes.

Inverse Laplace Transform: Partial Fraction Expansion

$$H(s) = \frac{s+3}{(s+2)(s+4)^2} = \frac{A}{s+2} + \frac{B}{s+4} + \frac{C}{(s+4)^2}$$

$$\frac{s+3}{(s+2)(s+4)^2} = A + \frac{B(s+2)}{s+4} + \frac{C(s+2)}{(s+4)^2}$$

$$s = -2$$

$$\frac{1}{4} = A + 0 + 0$$

$$\frac{s+3}{(s+2)} = A(s+4)^2 + B(s+4) + C$$

$$s = -4$$

$$\frac{-1}{-2} = 0 + 0 + C$$

$$\therefore \frac{s+3}{(s+2)(s+4)^2} = \frac{\frac{1}{4}}{s+2} + \frac{\frac{B}{4}}{s+4} + \frac{\frac{1}{2}}{(s+4)^2}$$

This must hold for all s. Therefore s=0

$$\frac{3}{2 \cdot 16} = \frac{\frac{1}{4}}{2} + \frac{\frac{B}{4}}{4} + \frac{\frac{1}{2}}{16}$$

$$3 = 4 + 8B + 1$$

$$-2 = 8B$$

$$B = -\frac{1}{4}$$

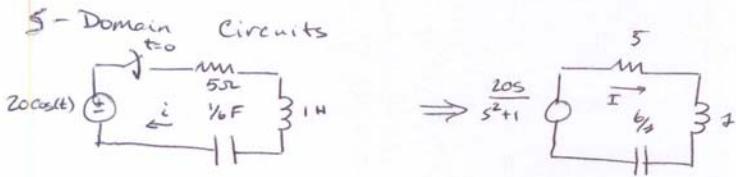
$$H(s) = \frac{\frac{1}{4}}{s+2} - \frac{\frac{1}{4}}{s+4} + \frac{\frac{1}{2}}{(s+4)^2}$$

Formulas: Table II.1
$e^{pt} u(t) \leftrightarrow \frac{1}{s-p}$
$te^{pt} u(t) \leftrightarrow \frac{1}{(s-p)^2}$

$$h(t) = \left[\frac{1}{4} e^{-2t} - \frac{1}{4} e^{-4t} + \frac{1}{2} t e^{-4t} \right] u(t)$$

Stable because all poles are in the left half plane.

Causal because h(t) is zero for all t < 0.



Find transfer function, impulse response, output current

$$V = I \left(5 + s + \frac{1}{s} \right)$$

$$= I \left(\frac{s^2 + 5s + 6}{s} \right)$$

$$H = \frac{I}{V} = \frac{1}{s^2 + 5s + 6}$$

$$H = \frac{1}{(s+2)(s+3)} = \frac{A}{s+2} + \frac{B}{s+3}$$

$$A = \frac{1}{s+3} \Big|_{s=-2} = \frac{-2}{1} = -2$$

$$B = \frac{1}{s+2} \Big|_{s=-3} = \frac{-3}{-1} = 3$$

$$H = \frac{-2}{s+2} + \frac{3}{s+3}$$

$$h = [-2e^{-2t} + 3e^{-3t}]u(t)$$

$$I = HV$$

$$= \frac{1}{(s+2)(s+3)} \cdot \frac{20s}{s^2 + 1}$$

$$= \frac{20s^2}{(s^2 + 1)(s+2)(s+3)} = \frac{A}{s+2} + \frac{B}{s+3} + \frac{Cs + D}{s^2 + 1}$$

$$A = \frac{20s^2}{(s^2 + 1)(s+3)} \Big|_{s=-2} = \frac{80}{5 \cdot 1} = 16$$

$$B = \frac{20s^2}{(s^2 + 1)(s+2)} \Big|_{s=-3} = \frac{180}{10 \cdot -1} = -18$$

True for all $s \Rightarrow$ true for $s=0$

$$0 = \frac{16}{2} - \frac{18}{3} + \frac{0+D}{1}$$

$$0 = 8 - 6 + D$$

$$D = -2$$

True for all $s \Rightarrow$ true for $s=-1$

$$\frac{20}{2+1+2} = \frac{A}{1} + \frac{B}{2} + \frac{-C+D}{2}$$

$$5 = 16 - 9 - \frac{C}{2} - 1$$

$$5 = 6 - \frac{C}{2}$$

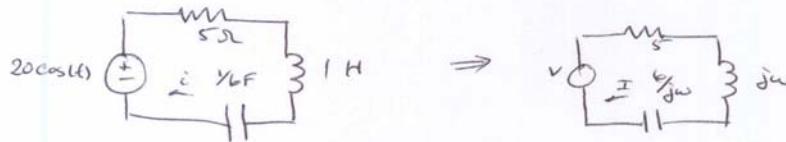
$$-1 = -\frac{C}{2}$$

$$C = 2$$

$$I = \frac{16}{s+2} + \frac{-18}{s+3} + \frac{2s-2}{s^2+1}$$

$$i = [16e^{-2t} - 18e^{-3t} + 2\cos(t) - 2\sin(t)] u(t)$$

Formula: $\cos(\omega_0 t) u(t) \Leftrightarrow \frac{1}{s^2 + \omega_0^2}$
 $\sin(\omega_0 t) u(t) \Leftrightarrow \frac{\omega_0}{s^2 + \omega_0^2}$



Find Frequency response and output current

$$V = I (j\omega + 5 + \frac{1}{j\omega})$$

$$= I \left(-\frac{\omega^2 + j\omega + 5}{j\omega} \right)$$

$$H = \frac{j\omega}{-\omega^2 + j\omega + 5}$$

Note $H(j\omega) = H(s) \Big|_{s=j\omega}$
↑ transfer function
frequency response

$$H(j) = \frac{j}{-1 + j5 + 5} = \frac{j}{5 + j5}$$

$$|H(j)| = \frac{1}{5\sqrt{2}}$$

$$\angle H(j) = \frac{\pi}{2} - \arctan(\frac{5}{5}) = \frac{\pi}{2} - \frac{\pi}{4} = \frac{\pi}{4}$$

$$i(t) = \frac{1}{5\sqrt{2}} \cdot 20 \cdot \cos(t + \frac{\pi}{4})$$

= ~~2√2 cos(t + π/4)~~ perfectly correct answer, continued to show comparison with above.

~~= 2√2 [cos(t) cos(π/4) - sin(t) sin(π/4)]~~

~~= 2√2 [cos(t) \frac{\sqrt{2}}{2} - sin(t) \frac{\sqrt{2}}{2}]~~

~~= 2cos(t) - 2sin(t)~~

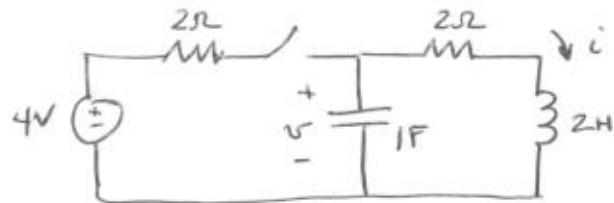
Formula:

$$x(t) = A \cos(\omega_0 t) \Leftrightarrow$$

$$y(t) = A \cdot |H(j\omega)| \cos(\omega_0 t + \angle H(j\omega))$$

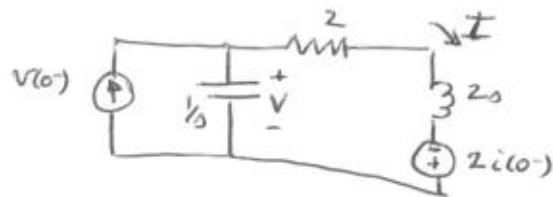
In this picture, the switch is closed until time $t=0$. Then it is opened.

S -domain circuits



$$v(0^-) = 2V$$

$$i(0^-) = 1A$$



Loop equations:

$$-\frac{1}{s}(I - v(0^-)) - 2I - 2sI + 2i(0^-) = 0$$

$$I\left(-\frac{1}{s} - 2 - 2s\right) + \frac{v(0^-)}{s} + 2i(0^-) = 0$$

$$I\left(\frac{1 + 2s + 2s^2}{s}\right) = \frac{2}{s} + 2$$

$$I\left(\frac{1 + 2s + 2s^2}{s}\right) = \frac{2 + 2s}{s}$$

$$I = \frac{1 + s}{s^2 + s + 1/2}$$

Convolution

$$x(t) = e^{-|t|}, \quad h(t) = 2 \operatorname{rect}\left(\frac{t-1}{3}\right)$$



Case 1: $t + \frac{1}{2} < 0 \Rightarrow t < -\frac{1}{2}$

$$\begin{aligned} y(t) &= \int_{t-\frac{1}{2}}^{t+\frac{1}{2}} 2e^{\tau} d\tau \\ &= 2(e^{t+\frac{1}{2}} - e^{t-\frac{1}{2}}) \end{aligned}$$

Case 2: $t + \frac{1}{2} > 0 \Rightarrow t > -\frac{1}{2}$
 $t - \frac{1}{2} < 0 \Rightarrow t < \frac{1}{2}$

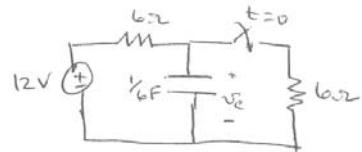
$$\begin{aligned} y(t) &= \int_{t-\frac{1}{2}}^0 2e^{\tau} d\tau + \int_0^{t+\frac{1}{2}} 2e^{-\tau} d\tau \\ &= 2(2 - e^{t-\frac{1}{2}} - e^{-t-\frac{1}{2}}) \end{aligned}$$

Case 3: $t - \frac{1}{2} > 0 \Rightarrow t > \frac{1}{2}$

$$\begin{aligned} y(t) &= \int_{t-\frac{1}{2}}^{t+\frac{1}{2}} 2e^{-\tau} d\tau \\ &= 2(e^{-t+\frac{1}{2}} - e^{-t-\frac{1}{2}}) \end{aligned}$$

$$y(t) = \begin{cases} 2(e^{t+\frac{1}{2}} - e^{t-\frac{1}{2}}) & t < -\frac{1}{2} \\ 2(2 - e^{t-\frac{1}{2}} - e^{-t-\frac{1}{2}}) & -\frac{1}{2} < t < \frac{1}{2} \\ 2(e^{-t+\frac{1}{2}} - e^{-t-\frac{1}{2}}) & \frac{1}{2} < t \end{cases}$$

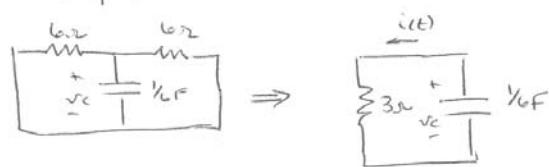
(6) Find $v_c(t)$ for $t \geq 0$. Assume DC Steady State at $t=0$.



$$\text{At } t=0^-, v_c = 12V$$

$$\therefore \text{at } t=0^+, v_c = 12V$$

Zero Input



$$i(t) = -\frac{1}{6} \frac{dv_c(t)}{dt}$$

$$i(t) = \frac{v_c(t)}{3}$$

$$\frac{v_c(t)}{3} = -\frac{1}{6} \frac{dv_c(t)}{dt}$$

$$\frac{dv_c(t)}{dt} + 2v_c(t) = 0$$

$$\text{Assume } v_c(t) = Ae^{mt}$$

$$Am e^{mt} + 2Ae^{mt} = 0$$

$$Ae^{mt}(m+2) = 0$$

$$\frac{A}{t} \neq 0 \quad \therefore m+2=0$$

$$m = -2$$

$$v_c(t) = Ae^{-2t}$$

Zero State



$$v_c(t) = \frac{12V}{2} = 6V$$

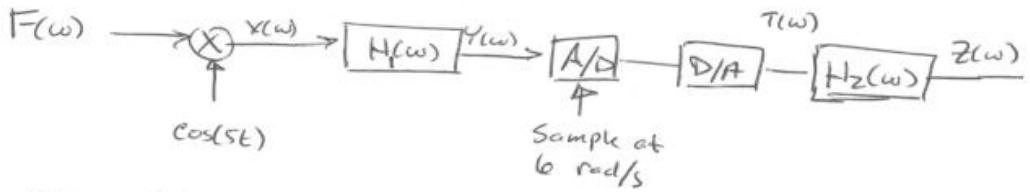
$$v_c(t) = 6 + Ae^{-2t}$$

$$v_c(0) = 6 + A = 12$$

$$A = 6$$

$$v_c(t) = (6 + 6e^{-2t}) \quad t \geq 0$$

Modulation and Sampling



$$F(\omega) = \delta(\omega - 10) + \delta(\omega + 10)$$

$$H_1(\omega) = \text{rect} \left(\frac{\omega}{10} \right)$$

$H_2(\omega)$ = ideal anti-imaging filter

$$X(\omega) = \frac{1}{2} \delta(\omega - 15) + \frac{1}{2} \delta(\omega - 5) + \frac{1}{2} \delta(\omega + 5) + \frac{1}{2} \delta(\omega + 15)$$

$$Y(\omega) = \underbrace{\frac{1}{2} \delta(\omega - 5) + \frac{1}{2} \delta(\omega + 5)}$$

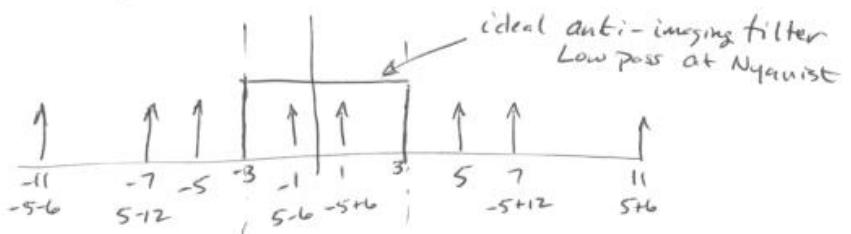
Signal at 5 rad/s > $\frac{6}{2} = 3$

- i. aliasing

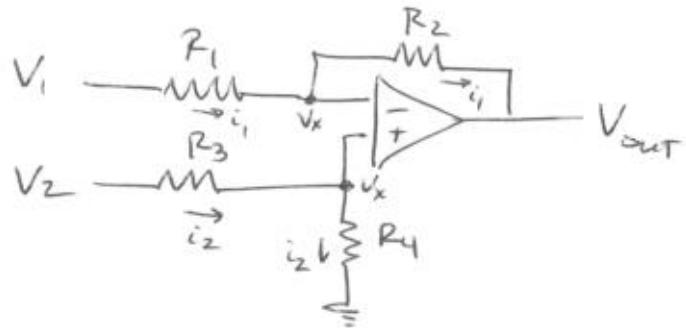
↑ Nyquist

$$Z(\omega) = \frac{1}{2} \delta(\omega - 1) + \frac{1}{2} \delta(\omega + 1)$$

T(ω) :



Op-amps and Superposition



$$\text{Set } V_2 = 0$$

$$\frac{V_1 - V_x^0}{R_1} = i_1 = \frac{V_x^0 - V_{\text{out}}}{R_2}$$

$$V_{\text{out}} = -\frac{R_2}{R_1} V_1$$

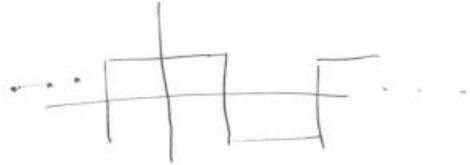
$$\text{Set } V_1 = 0$$

$$V_x = V_2 \left(\frac{R_4}{R_3 + R_4} \right) \quad V_x = V_{\text{out}} \left(\frac{R_2}{R_1 + R_2} \right)$$

$$V_{\text{out}} = V_2 \left(\frac{R_1 + R_2}{R_2} \right) \left(\frac{R_4}{R_3 + R_4} \right)$$

$$V_{\text{out}} = -\frac{R_2}{R_1} V_1 + \left(1 + \frac{R_1}{R_2} \right) \left(\frac{R_4}{R_3 + R_4} \right) V_2$$

Fourier Series



$$\begin{aligned}
 F_n &= \frac{1}{T} \int_{-T/4}^{T/4} A e^{-j \frac{2\pi n t}{T}} dt + \frac{1}{T} \int_{T/4}^{3T/4} -A e^{-j \frac{2\pi n t}{T}} dt \\
 &= \frac{A}{T} \left[\frac{e^{-j \frac{2\pi n t}{T}}}{-j \frac{2\pi n}{T}} \right]_{-T/4}^{T/4} + \frac{A}{T} \left[\frac{e^{-j \frac{2\pi n t}{T}}}{-j \frac{2\pi n}{T}} \right]_{T/4}^{3T/4} \quad \underline{\underline{n \neq 0}} \\
 &= \frac{A}{-j 2\pi n} \left(e^{-j \frac{\pi n}{2}} - e^{j \frac{\pi n}{2}} - e^{-j \frac{3\pi n}{2}} + e^{-j \frac{\pi n}{2}} \right) \\
 &\quad \uparrow \\
 &\text{Complex exponentials are periodic} \\
 &\therefore e^{j \frac{\pi n}{2}}
 \end{aligned}$$

$$\begin{aligned}
 &= \frac{2A}{\pi n} \left(\frac{e^{j \frac{\pi n}{2}} - e^{-j \frac{\pi n}{2}}}{j 2} \right) \\
 &= \frac{2A}{\pi n} \sin \left(\frac{\pi n}{2} \right)
 \end{aligned}$$

$$\begin{aligned}
 F_0 &= \frac{1}{T} \int_{-T/4}^{T/4} A dt + \frac{1}{T} \int_{T/4}^{3T/4} -A dt \\
 &= \frac{A}{T} \left[\frac{T}{4} + \frac{T}{4} - \left(\frac{3T}{4} - \frac{T}{4} \right) \right] \\
 &= 0
 \end{aligned}$$

$$F_n = \begin{cases} \frac{2A}{\pi n} \sin \left(\frac{\pi n}{2} \right) & n \neq 0 \\ 0 & n = 0 \end{cases}$$