

ECE 210 (AL2)

Chapter 9

Convolution, Impulse, Sampling, and
Reconstruction

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Chapter objectives

- Understand what convolution represents
- Understand how to convolve two signals
- Understand and be able to apply properties of convolution
- Understand what an impulse represents
- Understand and be able to apply properties of the impulse
- Understand what the impulse response of an LTI system represents
- Understand Fourier Transforms of power signals
- Understand sampling and reconstruction
- Understand Nyquist sampling frequency and aliasing
- Understand the difference between sampling bandwidth and energy bandwidth

• Convolution

- Recall that

$$f(t) = \underbrace{\frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega}_{\text{Fourier Transform}} \rightarrow \boxed{H(\omega)} \xrightarrow{\text{LTI}} y(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(\omega) F(\omega) e^{j\omega t} d\omega$$

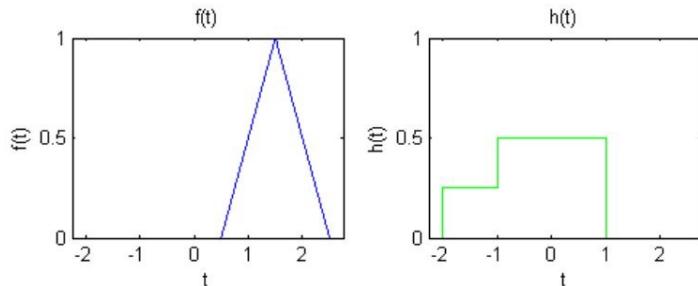
- Can we do this strictly in the time domain?

$$\begin{aligned}
 y(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} H(\omega) F(\omega) e^{j\omega t} d\omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(\omega) \left(\int_{-\infty}^{\infty} f(\tau) e^{-j\omega \tau} d\tau \right) e^{j\omega t} d\omega = \\
 &= \int_{-\infty}^{\infty} f(\tau) \left(\frac{1}{2\pi} \int_{-\infty}^{\infty} H(\omega) e^{j\omega(t-\tau)} d\omega \right) d\tau = \\
 &= \boxed{\int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau = y(t) = f(t) * h(t)}
 \end{aligned}$$

convolution

- Convolution-Example #1

- Consider $f(t)$ and $h(t)$ given below.

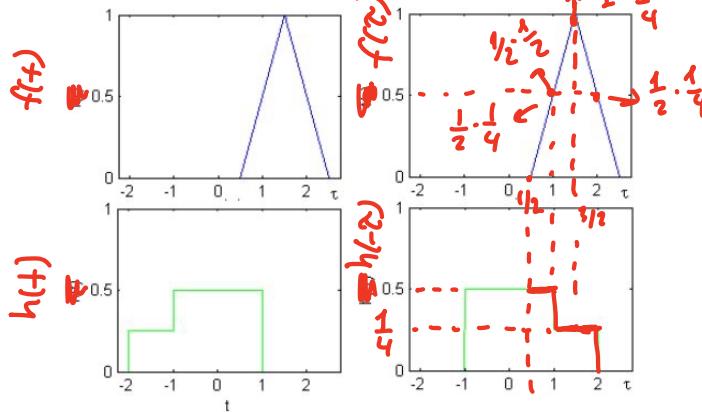


- Let $y(t) = f(t) * h(t)$, and obtain $y(0)$.

$$y(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau \quad \text{look at } t=0 \Rightarrow y(0) = \int_{-\infty}^{\infty} f(\tau) h(-\tau) d\tau$$

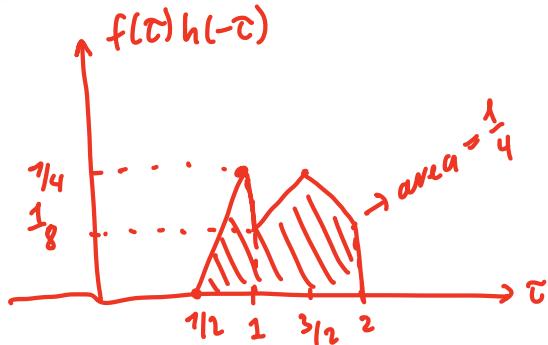
• Convolution-Example #1-cont

$$y(t) = \int_{-\infty}^{\infty} f(\tau)h(t-\tau)d\tau \Rightarrow y(0) = \int_{-\infty}^{\infty} f(\tau)h(-\tau)d\tau$$



$$\begin{aligned} &= \int_{-1}^1 f(\tau) \cdot 0 d\tau + \\ &+ \int_{-1}^1 f(\tau) \cdot \frac{1}{2} d\tau + \\ &+ \int_{-1}^1 f(\tau) \cdot \frac{1}{4} d\tau + \\ &+ \int_{-1}^1 f(\tau) \cdot 0 d\tau \end{aligned}$$

$h(-\tau)$ is assigning weights to all of $f(\tau)$

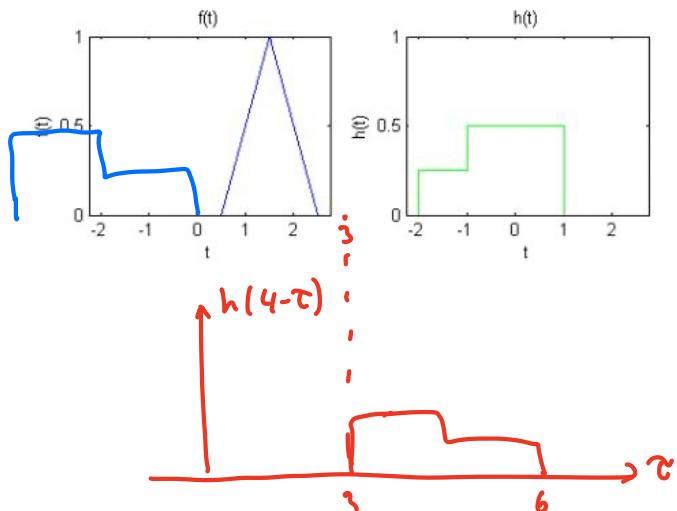


$y(0)$ is a linear superposition of all of the values of f with different weights.

• Convolution-Example #1-cont

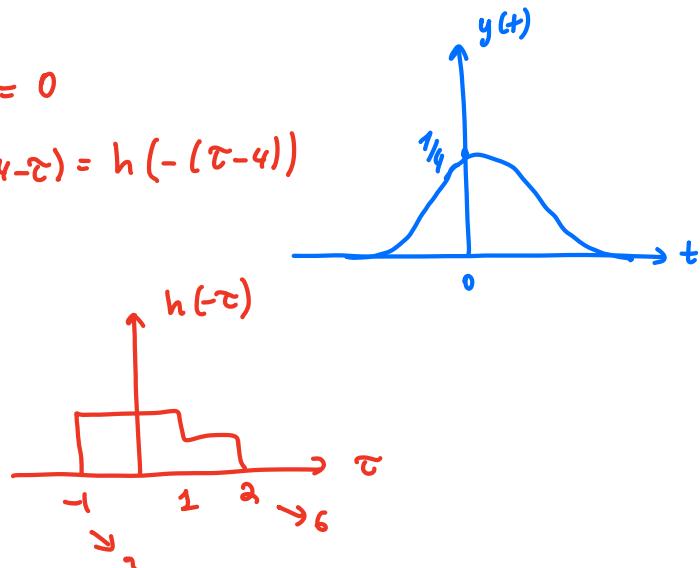
- What about other values of t ?

- E.g., $t = 4$



$$y(4) = \int_{-\infty}^{\infty} f(\tau)h(4-\tau)d\tau = 0$$

$$h(4-\tau) = h(-(\tau - 4))$$



$h(4-\tau)$ is giving $f(\tau)$ different weights than $h(-\tau) =$
the value of t in $y(t)$ changes the location of the weights
given by $h(t)$

- Convolution - Properties

Table 9.1 Commutative:

$$Y(\omega) = F(\omega) H(\omega) = \downarrow H(\omega) F(\omega)$$

$$\begin{aligned} y(t) &= f(t) * h(t) = \underbrace{h(t)}_{-\infty} * \overbrace{f(t)}^{\infty} \\ &= \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau = \int_{-\infty}^{\infty} h(\tau) f(t-\tau) d\tau \end{aligned}$$

table 7.1

#13 : time
convolution

multip. in freq.
domains corresponds
to a convolution
in time domain

• Convolution-Example #2

- Let $f(t) = u(t)$ and $h(t) = e^{-t}u(t)$

- Obtain $y(t) = f(t) * h(t) = \int_{-\infty}^{\infty} f(\tau) h(t-\tau) d\tau$
 $= \int_{-\infty}^{\infty} u(\tau) e^{-(t-\tau)} u(t-\tau) d\tau$
 $= \int_{-\infty}^{\infty} u(\tau) e^{-(t-\tau)} u(-(\tau-t)) d\tau$

