

ECE 210/211 HWs HW 7

Student NAX6 SKC7

TOTAL POINTS

50.5 / 54

QUESTION 1

1 0 / 0

✓ - 0 pts Correct

QUESTION 2

2 8.5 / 10

✓ - 1.5 pts $H(2)$ term has minor error

QUESTION 3

14 pts

3.1 2 / 2

✓ - 0 pts Correct

3.2 2 / 2

✓ - 0 pts Correct

3.3 2 / 2

✓ - 0 pts Correct

3.4 2 / 2

✓ - 0 pts Correct

3.5 4 / 4

✓ - 0 pts Correct

3.6 2 / 2

✓ - 0 pts Correct: Lower resistance leads to narrower passbands. Higher resistance corresponds to wider passband

QUESTION 4

4 10 / 10

✓ - 0 pts Correct

QUESTION 5

5 10 / 10

✓ - 0 pts Correct

QUESTION 6

6 8 / 10

✓ - 1 pts Incorrect Magnitude

✓ - 1 pts Extra terms

655479542

Varadachari

03/05/2022 ECE 210 HW 7

Varadachari Jain

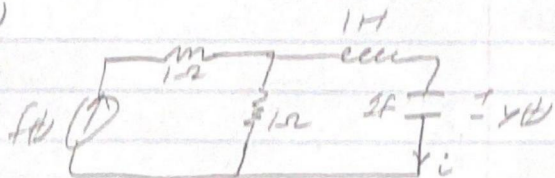
1

1. Varadachari Jain

2. $f(t) = 1 + 2\cos(t) + \cos(2t)$

$$Z_L = j\omega L = j\omega$$

$$Z_C = \frac{1}{j\omega C} = \frac{-j}{\omega} = \frac{-j}{\omega}$$



$$H(\omega) = Y/F$$

$$F = 1 + 2 + 1 = 4 \text{ Amper}$$

$$\hookrightarrow Z_L = j\omega - \frac{1}{\omega} = \frac{j\omega^2 - 1}{\omega}, \quad Z_C = \frac{Y}{j\omega} = \frac{-\omega Y}{j}$$

$$\text{Current Divider: } I_C = F \cdot \frac{2\Omega}{1\Omega + (j\omega^2 - 1)/\omega} \quad \left\{ \begin{array}{l} F \cdot 1 \\ \frac{\omega + j(\omega^2 - 1)}{\omega} \end{array} \right\} = \frac{-\omega Y}{j}$$

$$\hookrightarrow \frac{F\omega}{\omega + j(\omega^2 - 1)} = \frac{-\omega Y}{j} \rightarrow \frac{Y}{F} = H(\omega) = \frac{j}{\omega + j(\omega^2 - 1)}$$

$$\hookrightarrow y(t) = |H(\omega)| \cdot f(t + \phi H(\omega))$$

$$2\cos(t) \rightarrow H(\omega) = \frac{j}{1 + j} = 0 - j \rightarrow |H(1)| = 1 \rightarrow \phi H(1) = \tan^{-1}\left(\frac{-1}{1}\right) = -\pi/2$$

$$\cos(2t) \rightarrow H(\omega) = \frac{j}{2 + j} \cdot j = \frac{-1}{2 + j} \rightarrow +\pi \rightarrow \frac{-1}{2 + j} \cdot \left(\frac{2 - j}{2 - j}\right)$$

$$\hookrightarrow H(\omega) = \frac{-2j - 1}{13} = \frac{-1}{13} - \frac{2j}{13} \rightarrow |H(2)| = \sqrt{\frac{1 + 4}{13^2}} = \frac{\sqrt{5}}{13}$$

$$\phi H(2) = -\pi \tan^{-1}\left(\frac{-2}{-1}\right) = -\pi \tan^{-1}(2)$$

$$\hookrightarrow y(t) = 2 + 2\cos\left(t - \frac{\pi}{2}\right) + \frac{\sqrt{5}}{13} \cos\left(2t + \pi - \pi \tan^{-1}(2)\right)$$

1 0 / 0

✓ - 0 pts Correct

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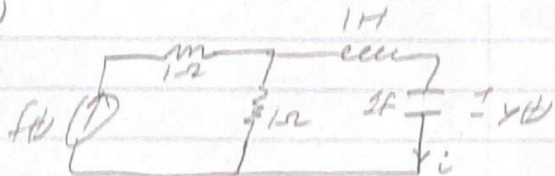
1

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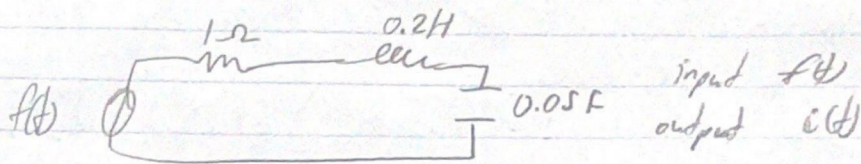
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2 8.5 / 10

✓ - 1.5 pts $H(2)$ term has minor error

2

3.



$$a) \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{\frac{1}{5} \cdot \frac{1}{20}}} = \frac{1}{\sqrt{\frac{1}{100}}} = \frac{1}{\frac{1}{10}} = 10 \text{ rad/s}$$

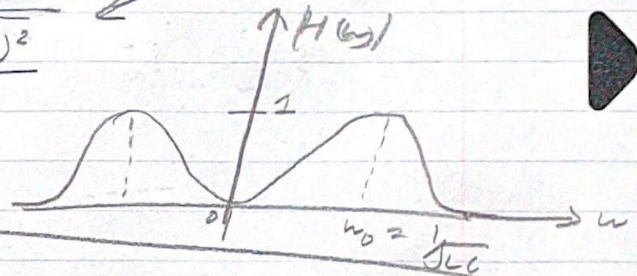
$$b) H(\omega) = \frac{V}{I} = \frac{I}{V_s} \rightarrow I = \frac{V_s}{R + j\omega L + \frac{1}{j\omega C}}$$

$$\rightarrow I = \frac{j\omega C}{j\omega RC - \omega^2 LC + 1} \cdot V_s \rightarrow H(\omega)$$

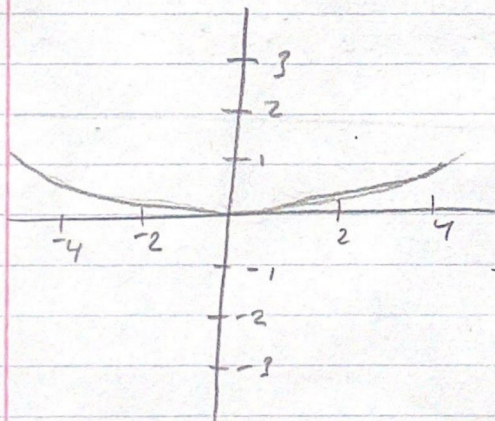
Band-Pass filter

$$\rightarrow H(\omega) = \frac{j\omega C}{\sqrt{(1 - \omega^2 LC)^2 + (\omega RC)^2}}$$

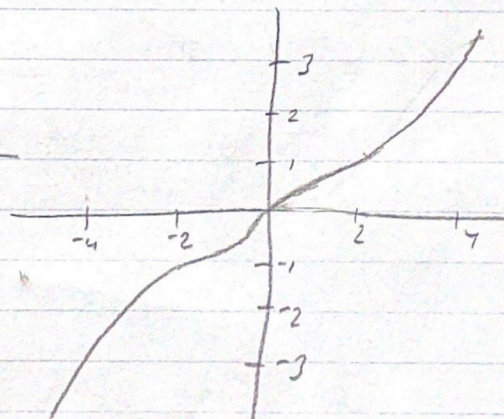
$$\downarrow |H(0)| = 1 \rightarrow$$



$$c) \text{Re} \{ H(\omega) \}$$



$$\text{Im} \{ H(\omega) \}$$



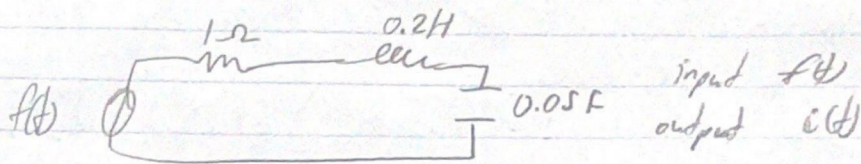
* Approximate drawings, not precise representations

3.1 2 / 2

✓ - 0 pts Correct

2

3.



$$a) \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{\frac{1}{5} \cdot \frac{1}{20}}} = \frac{1}{\sqrt{\frac{1}{100}}} = \frac{1}{\frac{1}{10}} = 10 \text{ rad/s}$$

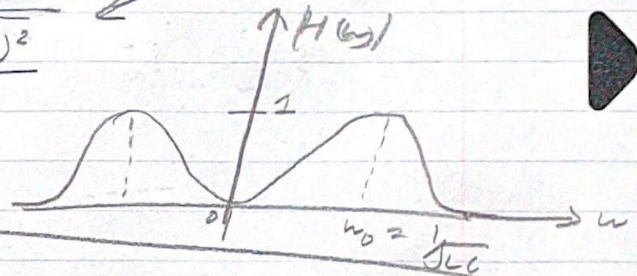
$$b) H(\omega) = \frac{V}{I} = \frac{I}{V_s} \rightarrow I = \frac{V_s}{R + j\omega L + \frac{1}{j\omega C}}$$

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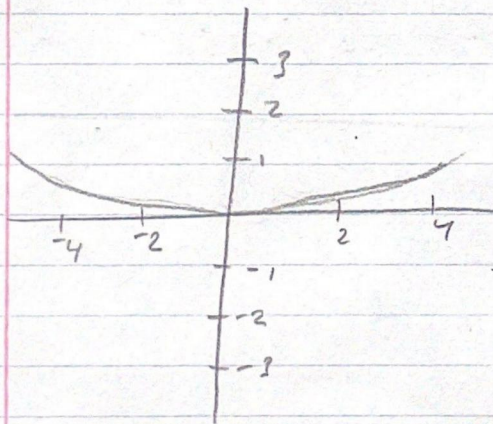
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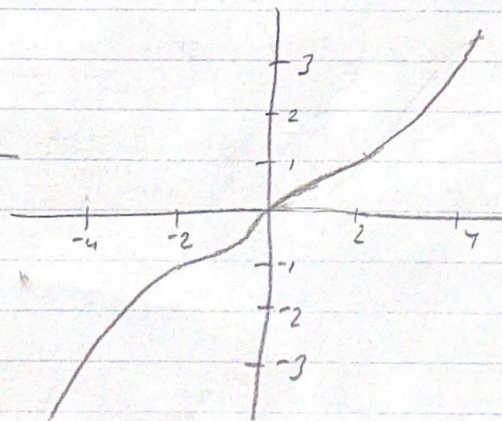
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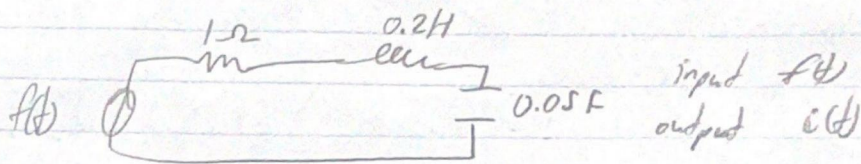
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3.2 2 / 2

✓ - 0 pts Correct

2

3.



$$a) \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{\frac{1}{5} \cdot \frac{1}{20}}} = \frac{1}{\sqrt{\frac{1}{100}}} = \frac{1}{\frac{1}{10}} = 10 \text{ rad/s}$$

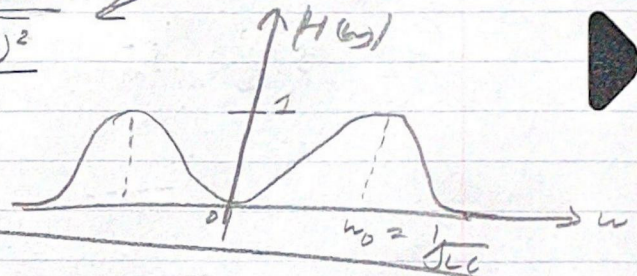
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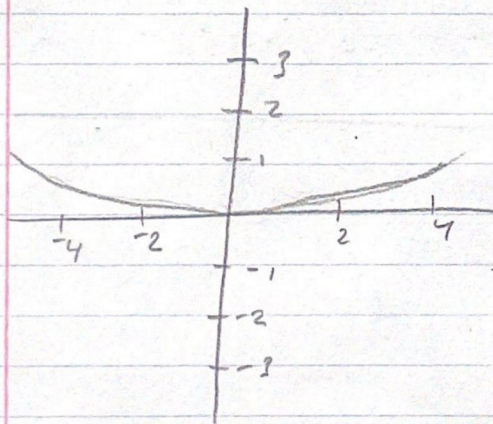
Band-Pass filter

$$\rightarrow H(\omega) = \frac{j\omega C}{\sqrt{(1 - \omega^2 LC)^2 + (\omega RC)^2}}$$

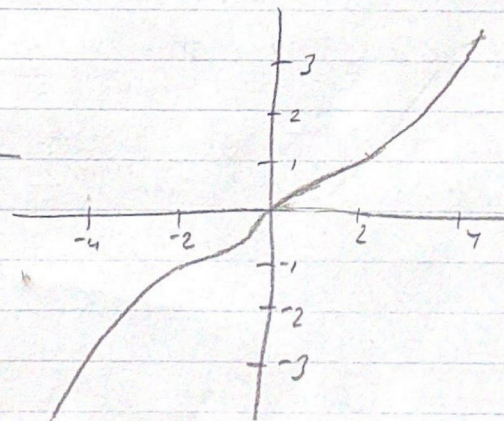
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* Approximate drawings, not precise representations

3.3 2 / 2

✓ - 0 pts Correct

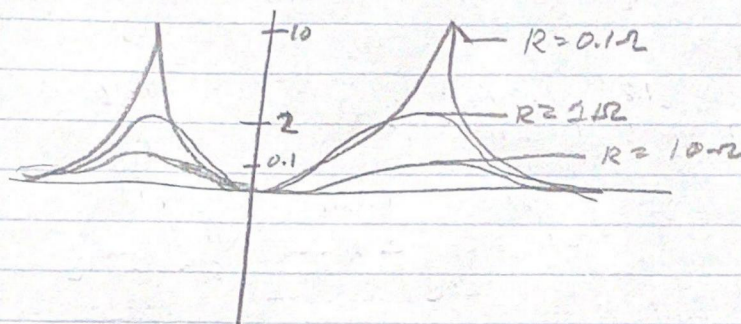
3) d) This circuit might be called a "bandpass" filter because it only allows certain frequencies to pass through and attenuates/rejects all other signals

e) $\omega_0 = \frac{1}{\sqrt{LC}} = 10 \text{ rad/s}$

$$H(\omega) = \frac{j\omega L}{j\omega RC - \omega^2 LC + 1}$$

$$|H(\omega)| = \frac{|\omega| L}{\sqrt{(1 - \omega^2 LC)^2 + (\omega RC)^2}}$$

$\rightarrow R = 10 \Omega \rightarrow |H(10)| = 0.1$
 $R = 0.1 \Omega \rightarrow |H(10)| = 10$



f) Decreasing R results in narrower peaks with higher amplitudes, so as R decreases so does the width of the filter's passband.

3.4 2 / 2

✓ - 0 pts Correct

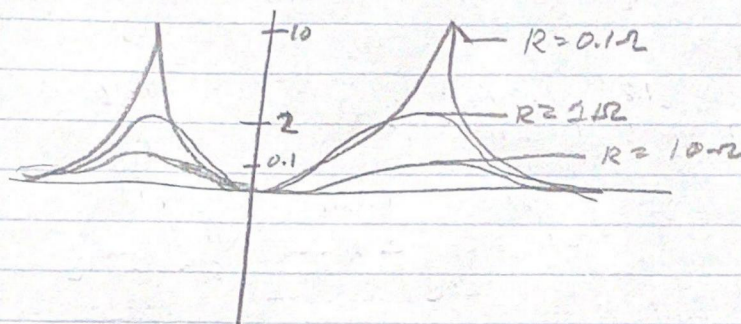
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3.5 4 / 4

✓ - 0 pts Correct

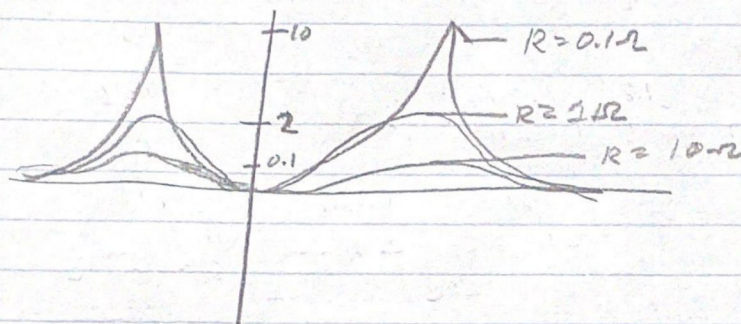
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$\rightarrow R = 10 \Omega \rightarrow |H(10)| = 0.1$
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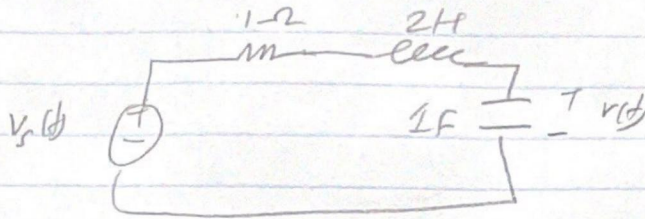


f) Decreasing R results in narrower peaks with higher amplitudes, so as R decreases so does the width of the filter's passband.

3.6 2 / 2

✓ - 0 pts Correct: Lower resistance leads to narrower passbands. Higher resistance corresponds to wider passband

4



$$H(\omega) = \frac{Y}{F} = \frac{V_c}{V_s}$$

$$\hookrightarrow H = \frac{V_c}{V_s} = \frac{I}{I} \cdot \frac{Z_c}{Z_T} = \frac{Z_c}{R + j\omega L + \frac{1}{j\omega C}}$$

$$\hookrightarrow H = \frac{j\omega C}{j\omega RC - \omega^2 RC + 1} \cdot \frac{1}{j\omega C} = \boxed{\frac{1}{j\omega - 2\omega^2 + 1} = H(\omega)}$$

5. $\begin{matrix} \text{input } f(t) \\ \text{output } y(t) \end{matrix} \Rightarrow \frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 2y(t) = \frac{df}{dt} + \frac{d^2 f}{dt^2}$

$$H(\omega) = \frac{Y}{F} \hookrightarrow (j\omega)^2 Y + 4j\omega Y + 2Y = j\omega F + (j\omega)^2 F$$

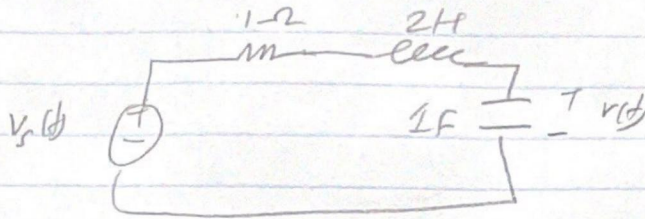
$$\hookrightarrow Y(-\omega^2 + 4j\omega + 2) = F(j\omega - \omega^2)$$

$$\hookrightarrow \boxed{\frac{Y}{F} = \frac{j\omega - \omega^2}{2 + 4j\omega - \omega^2} = H(\omega)}$$

4 10 / 10

✓ - 0 pts Correct

4



$$H(\omega) = \frac{Y}{F} = \frac{V_c}{V_s}$$

$$\hookrightarrow H = \frac{V_c}{V_s} = \frac{I}{I} \cdot \frac{Z_c}{Z_T} = \frac{Z_c}{R + j\omega L + \frac{1}{j\omega C}}$$

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$$H(\omega) = \frac{Y}{F} \hookrightarrow (j\omega)^2 Y + 4j\omega Y + 2Y = j\omega F + (j\omega)^2 F$$

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$$\hookrightarrow \boxed{\frac{Y}{F} = \frac{j\omega - \omega^2}{2 + 4j\omega - \omega^2} = H(\omega)}$$

5 10 / 10

✓ - 0 pts Correct

6. input: $f(t) = \underbrace{2e^{-2t}}_{(1)} + \underbrace{(2+j2)e^{-t}}_{(2)} + \underbrace{(2-j2)e^{jt}}_{(3)} + \underbrace{2e^{2t}}_{(4)}$

$$H(\omega) = \frac{1+j\omega}{2+j\omega} \rightarrow \frac{\sqrt{1+\omega^2}}{\sqrt{4+\omega^2}} \cdot \frac{e^{j \tan^{-1}(\omega/1)}}{e^{j \tan^{-1}(\omega/2)}} = \frac{\sqrt{1+\omega^2}}{\sqrt{4+\omega^2}} \cdot e^{j(\tan^{-1}(\omega) - \tan^{-1}(\omega/2))} = H(\omega)$$

$$f = f_1 + f_2 + f_3 + f_4 \rightarrow y = H(\omega_1) \cdot f_1 + H(\omega_2) \cdot f_2 + H(\omega_3) \cdot f_3 + H(\omega_4) \cdot f_4$$

$$\hookrightarrow \omega_1 = -2, \omega_2 = -1, \omega_3 = 1, \omega_4 = 2$$

$$\boxed{2e^{-j2t}} \quad \omega = -2 \rightarrow H(\omega) = \frac{\sqrt{1+4}}{\sqrt{4+4}} \cdot e^{j(\tan^{-1}(2) - \tan^{-1}(-1))} \quad \text{--- } H(\omega)$$

$$\hookrightarrow H(\omega) = \frac{5}{2\sqrt{2}} e^{j(\tan^{-1}(2) + \pi/4)} \rightarrow |H(\omega)| = \frac{5}{2\sqrt{2}}$$

$$y_1 = 2 \cdot \frac{5}{2\sqrt{2}} \cos(-2t + \tan^{-1}(2) + \pi/4)$$

$$\boxed{(2+j2)e^{-t}} \quad \omega = -1 \rightarrow H(\omega) = \frac{\sqrt{1+1}}{\sqrt{4+1}} \cdot e^{j(\tan^{-1}(1) - \tan^{-1}(-1/2))}$$

$$\hookrightarrow H(\omega) = \frac{\sqrt{2}}{\sqrt{5}} e^{j(-\pi/4 + \arctan(1/2))} \rightarrow |H(\omega)| = \frac{\sqrt{2}}{\sqrt{5}}$$

$$\hookrightarrow y_2 = \frac{2}{\sqrt{5}} \cdot (2+j2) \cos(-t - \pi/4 + \arctan(1/2))$$

6

$$(2-j2)e^{jt} \quad w=1 \rightarrow H(w) = \frac{1+1}{\sqrt{4+1}} e^{j(\tan^{-1}(1) - \tan^{-1}(\frac{1}{2}))}$$

$$\hookrightarrow H(w) = \frac{\sqrt{2}}{\sqrt{5}} e^{j(\pi/4 - \tan^{-1}(\frac{1}{2}))} \rightarrow |H(w)| = \frac{\sqrt{2}}{\sqrt{5}}$$

$$\hookrightarrow y_3 = \frac{\sqrt{2}}{\sqrt{5}} (2-j2) \cos(t + \pi/4 - \tan^{-1}(\frac{1}{2}))$$

$$2e^{2jt} \quad w=2 \rightarrow H(w) = \frac{1+(2)^2}{\sqrt{4+(2)^2}} e^{j(\tan^{-1}(2) - \tan^{-1}(2/2))}$$

$$\hookrightarrow H(w) = \frac{\sqrt{5}}{2\sqrt{2}} e^{j(\tan^{-1}(2) - \pi/4)} \rightarrow |H(w)| = \frac{\sqrt{5}}{2\sqrt{2}}$$

$$\hookrightarrow y_4 = \frac{2\sqrt{5}}{2\sqrt{2}} \cos(2t + \tan^{-1}(2) - \pi/4)$$

$$\hookrightarrow y(t) = y_1 + y_2 + y_3 + y_4$$

$$\hookrightarrow y(t) = \frac{\sqrt{5}}{2} \left[\cos(-2t + \tan^{-1}(2) + \pi/4) + \cos(2t + \tan^{-1}(2) - \pi/4) \right]$$

$$+ \frac{\sqrt{2}}{\sqrt{5}} \left[(2-j2) \cos(-t - \pi/4 + \tan^{-1}(\frac{1}{2})) + (2-j2) \cos(t + \pi/4 - \tan^{-1}(\frac{1}{2})) \right]$$

6 8 / 10

✓ - 1 pts Incorrect Magnitude

✓ - 1 pts Extra terms