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05/02/2022 ECE 210 HW14

2. Given transfer function  $A(s)$  determine inverse Laplace transform  $h(t)$  and BIBO stability

a)  $A(s) = \frac{s+3}{(s+2)(s-4)} \rightarrow$  proper, real, distinct poles (✓✓)

$\xrightarrow{s=2, 4}$

$$(s-A_1 = H(s)|_{s=-2} = \frac{(s+3)(s-4)}{(s+2)(s-4)}|_{s=-2} = \frac{-1}{6})$$

$$\xrightarrow{s+2} \frac{A_1}{s+2} + \frac{A_2}{s-4}$$

$$A_2 = H(s)|_{s=4} = \frac{(s+3)(s-4)}{(s+2)(s-4)}|_{s=4} = \frac{7}{6}$$

$$H(s) = -\frac{1}{6} + \frac{7}{6(s-4)}$$

Table 7.2

$$h(t) = -\frac{1}{6}e^{-2t}u(t) - \frac{7}{6}e^{4t}u(t) \Leftrightarrow \mathcal{L}^{-1}[e^{pt}u(t)] \Leftrightarrow \frac{1}{s-p}$$

$s = -2$  (Unstable due to a pole not located on the left of the plane  $(s=4)$ )

b)  $H(s) = \frac{2}{s(s-4)^2} \xrightarrow[s=4]{\text{repeated}} \left[ \frac{A_0}{s} + \frac{A_1}{s-4} + \frac{A_2}{(s-4)^2} \right]$

$$A_n = \lim_{s \rightarrow \infty} (s-p)^n H(s) \quad \text{order terms: } A_{n-m} = \frac{1}{m!} \left. \frac{d^m}{ds^m} \frac{1}{s} \lim_{s \rightarrow \infty} (s-p)^n H(s) \right|_{s=p}$$

$$= \left[ \frac{2}{s} \Big|_{s=0} + \frac{-1}{(s-4)^2} \Big|_{s=4} + \frac{2}{(s-4)^2} \Big|_{s=4} \right]$$

$$A_1 = A_{2-1} = \frac{1}{1!} \frac{d}{ds} H(s)|_{s=4} = \frac{d}{ds} \left[ \frac{2(s-4)^2}{s(s-4)^2} \right]_{s=4} = \frac{2}{s^2} \Big|_{s=4}$$

$$= \frac{s(0) - 2(1)}{s^2} = \frac{-2}{s^2} \Big|_{s=4} = \frac{-2}{16} = -\frac{1}{8}$$

$$H(s) = \frac{1}{8s} - \frac{1}{8(s-4)} - \frac{1}{2(s-4)^2}$$

$$h(t) = \frac{1}{8}u(t) - \frac{1}{8}e^{-4t}u(t) - \frac{1}{2}te^{-4t}u(t) \rightarrow s=0 \Rightarrow \text{BIBO Unstable}$$

(2)

$$2c) H(s) = \frac{s^2 + 4s + 4}{(s+1)(s+2)} = \frac{(s+2)^2}{(s+1)(s+2)} = \frac{s^2 + 4s + 4 - s - 2}{s^2 + 3s + 2}$$

$$= 1 - \frac{s+2}{s+1(s+2)} \rightarrow \mathcal{L}^{-1} \rightarrow h(t) = g(t) - \mathcal{L}^{-1} \left\{ \frac{s+2}{s+1(s+2)} \right\}$$

$$A_1 = \frac{(s+2)(s+1)}{(s+1)(s+2)} \Big|_{s=-1} = 1, A_2 = \frac{(s+2)(s+2)}{(s+1)(s+2)} \Big|_{s=-2} = 0$$

$$h(t) = g(t) - \mathcal{L}^{-1} \left\{ \frac{1}{s+1} \right\} = \boxed{g(t) - e^{t \cdot 1} \cdot \sin(t) = h(t)}$$

$s = -1, -2 \rightarrow \text{BIBO Stable}$

$$2d) H(s) = \frac{s^3}{s^2 + 4} \rightarrow \frac{s^3 - s}{s^2 + 4} \Big|_{s^3 + 0} \rightarrow s - \frac{4s}{s^2 + 4} \rightarrow \mathcal{L}^{-1}$$

$$\Leftrightarrow s = \pm 2j \quad \frac{-s^3 + 4s}{0 - 4s}$$

$$= \mathcal{L}^{-1} \{ s \} - \mathcal{L}^{-1} \left\{ \frac{4s}{s^2 + 4} \right\} = g'(t) - \mathcal{L}^{-1} \left\{ \frac{4 \cdot s}{s^2 + (2j)^2} \right\}$$

$$\Rightarrow h(t) = g'(t) - 4 \cos(2t) \sin(t)$$

$s = \pm 2j$

(3)

$$2e) \quad H(s) = \frac{e^{-2s}}{(s+1)(s+2)} = e^{-2s} \cdot \frac{1}{(s+1)(s+2)} \rightarrow A_1 + \frac{A_2}{s+2}$$

$\hookrightarrow s = -1, -2$

$$A_1: \left. \frac{s+1}{(s+1)(s+2)} \right|_{s=-1} = \frac{1}{s+2} = \frac{1}{1} = 1$$

$$A_2: \left. \frac{(s+2)}{(s+1)(s+2)} \right|_{s=-2} = \frac{1}{s+1} = \frac{1}{-1} = -1$$

$$\rightarrow \left( \frac{1}{s+1} - \frac{1}{s+2} \right) e^{-2s} \rightarrow \text{time shift by 3}$$

$$h(t) = (e^{-1(t-3)} - e^{-2(t-3)}) u(t) \rightarrow h(t) = (e^{3-t} - e^{6-2t}) u(t)$$

$\hookrightarrow s = -1, -2 \rightarrow \text{BIBO stable}$

$$2f) \quad H(s) = \frac{s+1}{s^2+3s+2} = \frac{s+1}{(s+1)(s+2)} = \frac{A_1}{s+1} + \frac{A_2}{s+2}, \quad s = -1, -2$$

$$A_1 = \left. \frac{(s+1)(s+2)}{(s+1)(s+2)} \right|_{s=-1} = \left. \frac{(s+1)}{(s+2)} \right|_{s=-1} = 0$$

$$A_2 = \left. \frac{(s+1)(s+2)}{(s+1)(s+2)} \right|_{s=-2} = \left. \frac{1}{(s+2)} \right|_{s=-2} = \frac{1}{0} \rightarrow \text{unstable}$$

$$\hookrightarrow h(t) = e^{-2t} u(t), \quad s = -1, -2 \rightarrow \text{BIBO stable}$$

Input to Laplace Domain. Multiply this conversion by the Transfer Function to obtain  $Y(s)$ . Expand with Partial Fractions, then use Inverse Laplace Transform, referencing Table 7.5, producing the LTI system zero-state response in Time Domain (4)

3.  $H(s) = \frac{1}{s^2 + 9}$ ,  $f(t) = \cos(2t) u(t)$  Table 7.5

$\downarrow$   $\frac{1}{s^2 + 9} \xrightarrow{\text{Table 7.11}} \frac{1}{s^2 + 3^2}$  constant  $\xrightarrow{s} \frac{s}{s^2 + w_0^2}$

$\frac{1}{s^2 + 4} \xrightarrow{\text{Table 7.11}} \frac{1}{s^2 + 2^2}$

$F(s) = \frac{s}{s^2 + 4} \rightarrow Y(s) = \frac{s}{(s^2 + 4)(s^2 + 9)} \rightarrow \text{P.F.P.}$

$$= \frac{A_1 s + A_0}{s^2 + 4} + \frac{A_3 s + A_2}{s^2 + 9} \rightarrow \frac{s(s^2 + 4)(s^2 + 9)}{(s^2 + 4)(s^2 + 9)}$$

$$\downarrow = \frac{(A_1 s + A_0)(s^2 + 9)(s^2 + 9)}{(s^2 + 4)} + \frac{(A_3 s)(s^2 + 4)(s^2 + 9)}{(s^2 + 9)}$$

$$\Leftrightarrow s = (A_1 s + A_0)(s^2 + 9) + (A_3 s)(s^2 + 4)$$

$$= A_1 s^3 + 9A_0 s + A_3 s^3 + 4A_3 s + A_3 s^3 + 4A_3 s + A_2 s^2 + 9A_2$$

$$s^3 = s^3(a_1 + a_3) + s^2(a_0 + a_2) + s(a_1 + 4a_3) + (a_0 + 4a_2)$$

$$a_0 + 4a_2 = 0, a_1 + 4a_3 = 1, a_0 + a_2 = 0, a_1 + a_3 = 0 \rightarrow a_0 = 0, a_2 = \frac{1}{5}, a_3 = -\frac{1}{5}$$

$$\Leftrightarrow \frac{(5)s}{s^2 + 4} + \frac{(-1/5)s}{s^2 + 9} = \frac{s}{5(s^2 + 4)} - \frac{s}{5(s^2 + 9)} \rightarrow 2^{-1}$$

$$= \frac{1}{5} \left[ 2^{-1} \left\{ \frac{s}{s^2 + 4} \right\} - 2^{-1} \left\{ \frac{s}{s^2 + 9} \right\} \right] = \frac{1}{5} [\cos(2t) - \cos(3t)] u(t)$$

$$\Leftrightarrow y_{zs}(t) = \left[ \frac{\cos(2t) - \cos(3t)}{5} \right] u(t)$$

(5)

4. For each LTI system, determine the transfer function ( $H(s)$ ) characteristic poles and modes, zero state and zero-input responses ( $\mathcal{Y}_{2s}(s)$  and  $\mathcal{Y}_{2i}(s)$ ), BIBO/Asymptotic/marginal stability

a)  $\frac{d^2y}{dt^2} + 2\frac{dy}{dt} - 8y(t) = 6f(t), \quad y(0) = 0, \quad y'(0) = 1, \quad f(t) = e^{-st}u(t)$

$$\mathcal{L} \quad s^2 + 2s - 8 \quad \rightarrow \quad (s^2 + 2s - 8)Y(s) - s^2 y(0) - s y'(0) + 2sY(s) - 8Y(s) = 6F(s)$$

?  $\rightarrow Y(s^2 + 2s - 8) = 6F(s) + y(0)(s+2) + y'(0)$

$$s^2 + 2s - 8 = (s+4)(s-2) \rightarrow \begin{cases} \text{characteristic poles at } p_1 = -4, p_2 = 2 \\ \text{characteristic modes: } e^{-4t}, e^{2t} \end{cases}$$

$$\mathcal{L} \quad \mathcal{Y}_{2s} = \frac{1}{(s+4)(s-2)}, \quad \mathcal{Y}_{2i} = \frac{6}{(s+4)(s-2)(s+2)}$$

$$H(s) = \frac{6}{(s+4)(s-2)} \quad \text{BIBO Unstable Asymptotically Stable and Marginally Stable?}$$

b)  $\frac{d^2y}{dt^2} + 2\frac{dy}{dt} + y(t) = 2f(t), \quad y(0) = 1, \quad y'(0) = 1, \quad f(t) = f(t)$

$$\rightarrow s^2 + 2s + 1 \rightarrow (s+1)^2$$

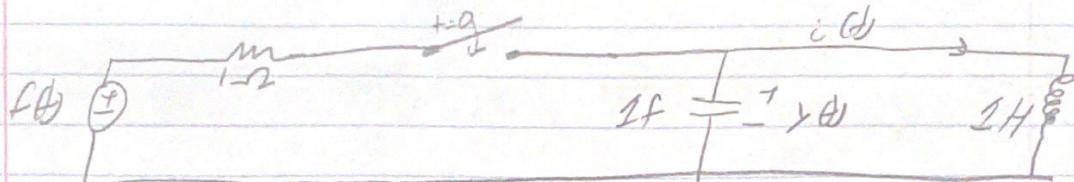
$$\rightarrow \begin{cases} \text{characteristic poles at } s = -1 \text{ repeated} \\ \text{characteristic modes: } e^{-t}, te^{-t} \end{cases}$$

$$H(s) = \frac{-1}{(s+1)^2}, \quad \mathcal{Y}_{2s} = \frac{(s+1)}{(s+1)^2}, \quad \mathcal{Y}_{2i} = \frac{-2}{(s+1)^2}$$

BIBO Stable  
Asymptotically Stable

Marginal Unstable?

5.  $f(t) = e^{2t} V, v(0) = 2 V, i(0) = 0 \rightarrow$



a) Show for  $t > 0$  that  $\hat{V}_{AC} = \frac{V_0}{F(s)} = \frac{1}{s^2 + s + 1}$ : Laplace Domain Circuit

$$Z_L = s, \quad Z_R = \frac{1}{s}$$

Node-Voltage:  $\frac{F - Y}{1} = \frac{Y}{s} + \frac{Y}{s}, \quad F - Y = Y_s + Y, \quad F - Y = \frac{s^2 Y + Y}{s}$

$$sF - sY = s^2 Y + Y$$

$$sF = s^2 F + sY + Y \rightarrow s = \frac{Y (s^2 + s + 1)}{F} \rightarrow \boxed{H_{AC} = \frac{V_{AC}}{F(s)} = \frac{s}{s^2 + s + 1}}$$

b) Characteristic Poles/ Modes:  $s^2 + s + 1 \rightarrow s = -\frac{1 \pm \sqrt{1-4}}{2} = \frac{-1 \pm \beta_j}{2}$

↳ characteristic poles  $\Rightarrow s = -\frac{1}{2} + \frac{\beta_j}{2}j, -\frac{1}{2} - \frac{\beta_j}{2}j$

↳ characteristic modes  $\Rightarrow e^{\left(\frac{-1+\beta_j}{2}\right)t}$  and  $e^{\left(\frac{-1-\beta_j}{2}\right)t}$

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5c) determine  $y_{2s}(t)$  for  $t > 0$ 

$$f(t) = e^{jt} \rightarrow F_{2s} = \frac{1}{s-j} \rightarrow Y_{2s} = F_{2s} / 1s = \left( \frac{1}{s-j} \right) \left( \frac{s}{s^2 + s + 1} \right)$$

$$= \frac{1}{(s-j)(s^2 + s + 1)}$$

$$\hookrightarrow \frac{A}{s-j} + \frac{Bs + C}{s^2 + s + 1} = \frac{s}{(s-j)(s^2 + s + 1)}$$

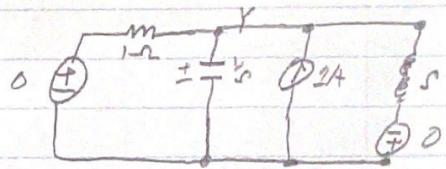
$$\hookrightarrow A(s^2 + s + 1) + (Bs + C)s - B = s \rightarrow s^2(A + B) + s(C - 3B + C) + A - 3B = s \quad A + B = 0$$

$$A - 3B + C = 1, \quad A - 3C = 0 \rightarrow A = \frac{1}{13}, \quad B = -\frac{1}{13}, \quad C = \frac{1}{13}$$

$$\hookrightarrow \hat{Y} = \frac{Y_{1s}}{s-j} + \frac{V_{1s} - 3Y_{1s}}{s^2 + s + 1} \rightarrow \text{complete the square} \rightarrow Y_{2s}(s) = \frac{Y_{1s}}{s-j} + \frac{V_{1s} - 3Y_{1s}}{(s + \frac{1}{2})^2 + \frac{3}{4}}$$

$$= \frac{Y_{1s}}{s-j} + \left( \frac{V_{1s}}{(s + \frac{1}{2})^2 + \frac{3}{4}} \right) \rightarrow Y_{2s}(t) = 2^{-1} \{ \hat{Y}_{2s}(s) \}$$

$$\hookrightarrow y_{2s}(t) = \frac{1}{13} e^{\frac{jt}{2}} u(t) + \left( \frac{5e^{-\frac{jt}{2}}}{13\sqrt{3}} \sin\left(\frac{\sqrt{3}}{2}t\right) - \frac{3e^{-\frac{jt}{2}}}{13} \cos\left(\frac{\sqrt{3}}{2}t\right) \right) u(t) \quad \text{Volts}$$

5d) determine  $y_{21}(t)$  for  $t > 0 \rightarrow$  Laplace Domain  $\rightarrow$ 

$$\text{Node-Voltage at } Y: I - \frac{0-Y}{1} = sY + V_2s$$

$$\hookrightarrow I - Y = sY + V_2s, \quad I = sY + V_2s + Y$$

$$\hookrightarrow I = \left( \frac{s+1}{s} \right) Y \rightarrow Y_{21s} = \frac{s}{s^2 + s + 1} \rightarrow y_{21s}(t) = 2^{-1} \{ \hat{Y}_{21s}(s) \}$$

$$\text{complete the square} \hookrightarrow = 2^{-1} \{ \frac{1}{s^2 + s + 1} \}$$

$$\hookrightarrow \frac{1}{s^2 + s + 1} = \frac{s + \frac{1}{2}}{(s + \frac{1}{2})^2 + \frac{3}{4}} - \frac{\frac{1}{2}}{(s + \frac{1}{2})^2 + \frac{3}{4}}$$

$$\hookrightarrow \frac{s + \frac{1}{2}}{(s + \frac{1}{2})^2 + \frac{3}{4}} - \frac{\frac{1}{2}}{(s + \frac{1}{2})^2 + \frac{3}{4}}$$

$$2^{-1} = \left( e^{\frac{jt}{2}} \cos\left(\frac{\sqrt{3}}{2}t\right) - e^{-\frac{jt}{2}} \cdot \frac{1}{\sqrt{3}} \sin\left(\frac{\sqrt{3}}{2}t\right) \right) u(t)$$

$$\hookrightarrow y_{21s}(t) = e^{\frac{jt}{2}} \cos\left(\frac{\sqrt{3}}{2}t\right) u(t) - e^{-\frac{jt}{2}} \cdot \frac{1}{\sqrt{3}} \sin\left(\frac{\sqrt{3}}{2}t\right) u(t) \quad \text{Volts}$$

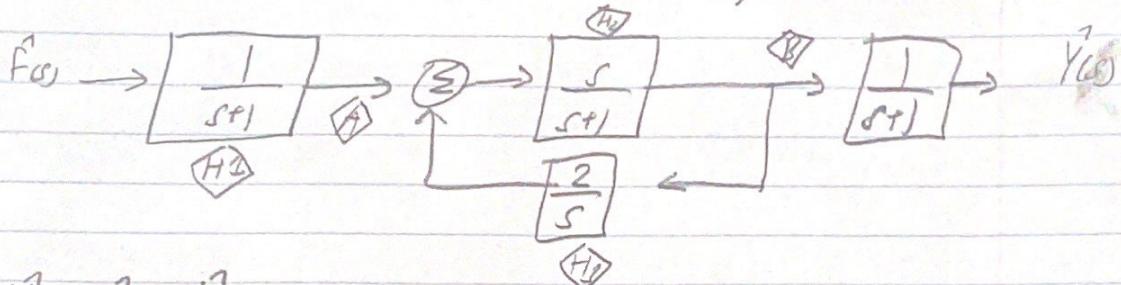
(8)

5e)  $y(t)$  for  $t > 0$ :  $y(t) = y_{22}(t) + y_{23}(t)$

$$y(t) = \frac{7}{13} e^{3t} u(t) + \frac{10}{13} e^{-2t} u(t) \cos\left(\frac{5\pi}{2}t\right) - \frac{6}{13\pi} e^{-2t} \sin\left(\frac{5\pi}{2}t\right) \text{ Volts}$$

5f) BIBO Stable, Asymptotically Stable, Marginally Unstable

6. Determine the transfer function and BIBO stability



$$Y(s) = F(s) \cdot H_1(s) \rightarrow \text{Take intermediate outputs } A \text{ and } B$$

$$\hookrightarrow B = (A + BH_2) + H_2, \quad B = AH_2 + BH_2H_3, \quad B(1 - H_2H_3) = AH_2$$

$$\frac{B}{A} = \frac{H_2}{1 - H_2H_3} = \left(\frac{s}{s+1}\right) \div \left(1 - \frac{2}{s+1} \left(\frac{s}{s+1}\right)\right) = \frac{\frac{s}{s+1}}{1 - \frac{2}{s+1}}$$

$$\hookrightarrow B_A = \frac{s}{s-1} \rightarrow \text{for the system}$$

$$\hookrightarrow F(s) = \left(\frac{1}{s+1}\right) \left(\frac{s}{s-1}\right) \left(\frac{1}{s+1}\right) \rightarrow H(s) = \frac{s}{(s+1)^2(s-1)}$$

Poles at  $s = -1, s = 1$   
BIBO Unstable