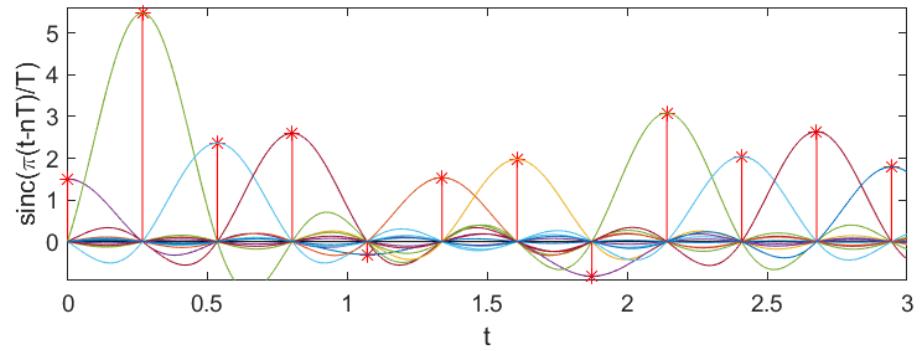
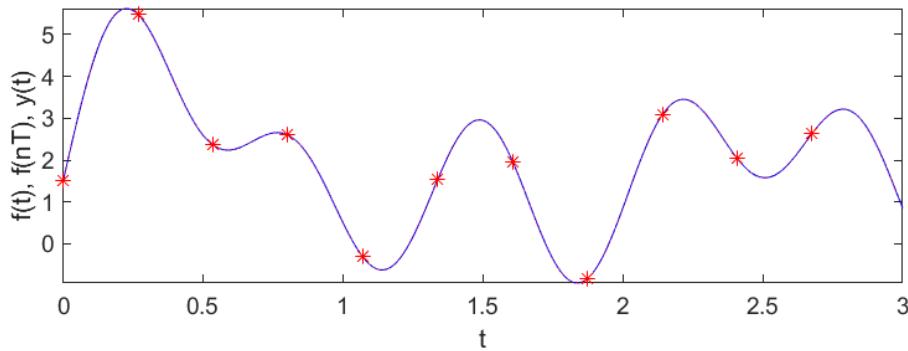


## Lecture 44, Friday, April 15, 2022

- Sampling and the reconstruction formula
  - Reconstruction formula:

$$y(t) = \sum_{n=-\infty}^{\infty} f(nT) \text{sinc}\left(\frac{\pi}{T}(t - nT)\right) = f(t), \quad \text{reconstruction formula}$$

- \*  $f(t)$  is reconstructed via an infinite sum of sinc functions centered at multiples of  $T$
- \* At each sinc peak, all other sincs have a zero crossing.



- **Note:** The sampling bandwidth,  $\Omega$ , is the largest frequency  $\omega$  such that  $F(\omega) \neq 0$ .

For bandpass signals, that is very different than the *energy bandwidth*, discussed in earlier chapters, which would ignore the zero portions of the spectrum around zero.

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## Lecture 44, continued from previous page...

- Recall

$$s(t) = f(t)p(t) \longleftrightarrow S(\omega) = \sum_{n=-\infty}^{\infty} \frac{1}{T} F(\omega - n\omega_0)$$

- \* If  $\omega_0 < 2\Omega$ , the frequency copies overlap, creating *aliasing*  
It is called *undersampling*, and signal cannot be usually reconstructed
- \* If  $\omega_0 = 2\Omega$ , the frequency copies touch each other right at the boundary  
It is sampled at *Nyquist sampling frequency*
- \* If  $\omega_0 > 2\Omega$ , the frequency copies are spaced out and there are gaps in-between  
It is called *oversampling*, and signal can be reconstructed

- Impulse response

- Recall  $h(t)$  is called the *impulse response*, because it is the response to an impulse:

$$\delta(t) \longrightarrow \boxed{h(t)} \longrightarrow y_{ZS}(t) = \delta(t) * h(t) = h(t)$$

- The *unit-step response*, is the LTI system response to a unit-step:

$$u(t) \longrightarrow \boxed{h(t)} \longrightarrow y_{ZS}(t) = u(t) * h(t)$$

- \* By properties of convolution

$$h(t) = \frac{d}{dt} y_{ZS}(t) \quad \text{only if } y_{ZS}(t) \text{ is the unit-step response}$$

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## Lecture 44, continued from previous page...

- Bounded input-bounded output stability (BIBO) stability

- In a bounded input-bounded output (BIBO) stable system

$$\text{bounded input } f(t) \longrightarrow \boxed{\text{system}} \longrightarrow \text{bounded output } y(t)$$

for **all** bounded  $f(t)$

- Bounded  $f(t)$  means  $|f(t)| \leq C$  for some real-valued constant  $C$  and all  $t$
  - BIBO may apply to any type of system, but if the system is LTI with impulse response  $h(t)$ , then

$$\text{BIBO} \leftrightarrow h(t) \text{ is absolutely integrable : } \int_{-\infty}^{\infty} |h(t)| dt < \infty$$

- Boundedness of  $h(t)$  does not imply BIBO, only absolute integrability does