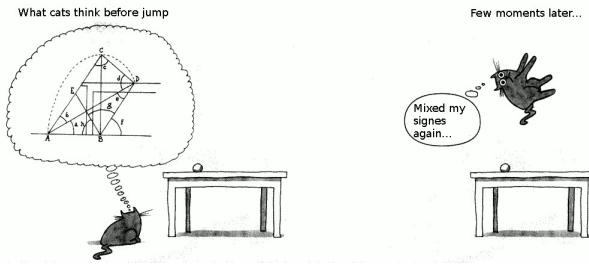


# ECE 210 (AL2)

## Chapter 11

### Laplace Transform, Transfer Function, and LTIC System Response



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# Chapter objectives

- Perform Laplace transforms
- Understand the region of convergence of Laplace transform and its relation to BIBO stability
- Understand the relation between Laplace transform and Fourier transform
- Understand and apply properties of Laplace transform
- Perform inverse Laplace transform of rational functions using partial fraction expansion
- Perform s-domain system analysis
- Obtain the general response of LTIC circuits and systems
- Perform analysis of LTIC system combinations

## Laplace transform

- Recall that

$$f(t) \rightarrow \boxed{\text{LTIC with } h(t)} \rightarrow y(t) = \int_0^{\infty} f(t-\tau)h(\tau)d\tau$$

=  $f(t) * h(t)$   
 "0 for t < 0"

- Recall also that

$$e^{j\omega t} \rightarrow \boxed{\text{LTI with } h(t) \leftrightarrow H(\omega)} \rightarrow y(t) = e^{j\omega t}H(\omega)$$

$e^{j\omega t}$  is an eigenfunction of  $H(\omega)$

- $j\omega$  is purely imaginary, extend to include real part:  $s = \sigma + j\omega$

$$e^{st} \rightarrow \boxed{\text{LTIC with } h(t)} \rightarrow y(t) = \int_0^{\infty} e^{s(t-\tau)}h(\tau)d\tau =$$

$$= \int_0^{\infty} e^{st} \cdot e^{-s\tau} h(\tau) d\tau =$$

$$= e^{st} \int_0^{\infty} h(\tau) e^{-s\tau} d\tau$$

Laplace Transform of  
 $h(t)$   
 $H(s)$

## • Laplace transform - cont

- Define the **Laplace transform** of a function  $f(t)$ :

$$\hat{F}(s) = \int_{0^-}^{\infty} f(t)e^{-st} dt$$

\*includes possible impulses at  $t = 0$

$s = \sigma + j\omega \in \mathbb{C}$

- In particular, if  $h(t)$  is the impulse response of an LTIC system:

$$\hat{H}(s) = \int_{0^-}^{\infty} h(t)e^{-st} dt \quad \text{is the } \textcolor{green}{\text{transfer function}} \text{ of the system}$$

$$f(t) \rightarrow \boxed{\text{LTIC with } h(t) \leftrightarrow \hat{H}(s)} \rightarrow y(t) = f(t) * h(t) \underset{\approx}{\approx}$$

$$\hat{F}(s) \rightarrow \boxed{\text{LTIC with } h(t) \leftrightarrow \hat{H}(s)} \rightarrow \hat{Y}(s) = \hat{F}(s)\hat{H}(s) \underset{\approx}{\approx}$$

Similar to

$$H(\omega) = \frac{Y(\omega)}{F(\omega)}$$

$$\hat{H}(s) = \frac{\hat{Y}(s)}{\hat{F}(s)}$$

## • Laplace transform - cont.

- Notice that if  $\sigma = 0$ , then  $s = \sigma + j\omega = j\omega$

$$\hat{F}(j\omega) = \int_{0^-}^{\infty} f(t)e^{-j\omega t} dt = F(\omega)$$

\* if  $\hat{F}$  exists at  $s = j\omega$

\* if  $f(t)$  is causal

$$\hat{H}(\sigma + j\omega) = \int_{0^-}^{\infty} h(t)e^{-\sigma t} e^{-j\omega t} dt$$

not A.I.  
maybe A.I.

## Laplace transform - Example # 1

- Determine the Laplace transform of  $f(t) = e^t u(t)$

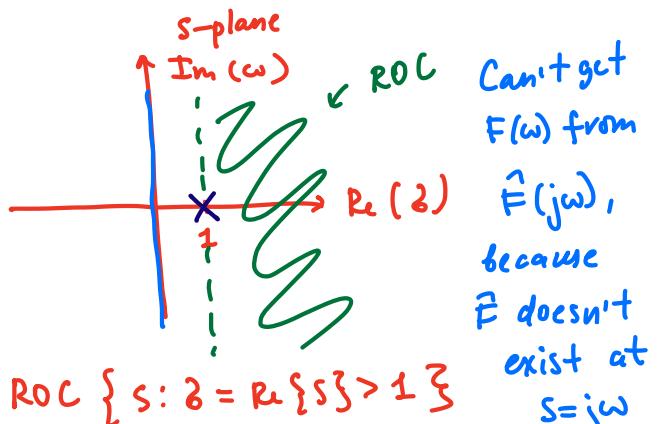
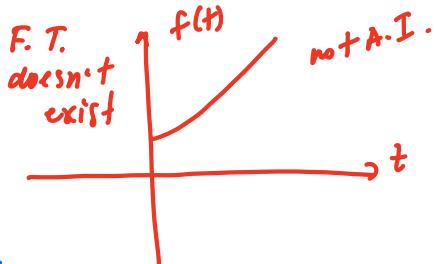
$$\begin{aligned}\hat{F}(s) &= \int_0^\infty f(t) e^{-st} dt = \int_0^\infty e^t e^{-st} dt = \\ &= \int_0^\infty e^{t(1-s)} dt = \frac{e^{t(1-s)}}{1-s} \Big|_0^\infty \quad \text{for converg-} \\ &\quad \text{we need } -s < 0 \Rightarrow s > 1 \\ e^{t(1-s)} &= e^{t(1-(\Re(s)+j\omega))} = e^{t(\Re(s)-j\omega t)} \cdot e^{-j\omega t} \\ \text{if } \Re(s) &> 1 \quad \boxed{\hat{F}(s) = \frac{0-1}{1-s} = \frac{1}{s-1}} \quad \text{pole at } s=1\end{aligned}$$

Region of convergence (ROC) is the region in the S-plane, where  $\hat{F}(s)$  converges

Pole is a location on S-plane

where  $|\hat{F}(s)| \rightarrow \infty$

Zero: where  $\hat{F}(s) = 0$  "O"



- Laplace transform - Example # 1

- Is  $f(t) = e^t u(t)$  A.I.?

## • Laplace transform - Example # 2

- Determine the Laplace transform of  $h(t) = e^{-t}u(t)$

Recall  $F(\omega) = \frac{1}{1+j\omega}$

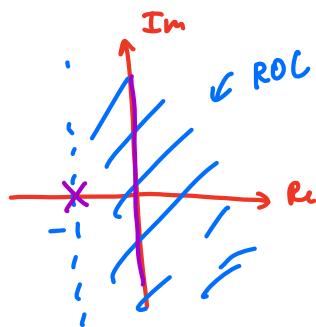
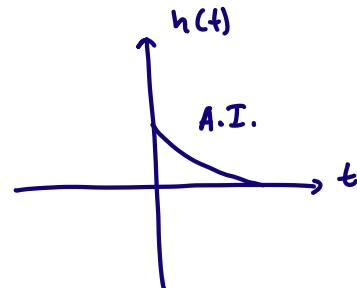
$$\tilde{F}(s) = \int_0^\infty f(t) e^{-st} dt = \int_0^\infty e^{-t} e^{-st} dt = \int_0^\infty e^{-t(1+s)} dt =$$

$$= \frac{e^{-t(1+s)}}{-(1+s)} \Big|_0^\infty$$

$$e^{-t(1+s)} = e^{-t(1+\beta + j\omega)} = e^{-t(1+\beta)} e^{-j\omega t}$$

$$\text{if } \underline{\beta > -1} \quad \tilde{F}(s) = \frac{0-1}{-(1+s)} = \frac{1}{s+1}$$

$\nwarrow$   
pole  
 $\circledast s = -1$



## • Laplace transform - Example # 3

- Determine the Laplace transform of

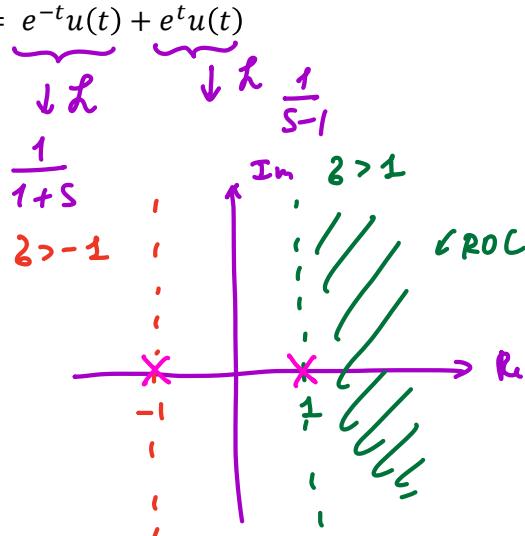
$$h(t) = \underbrace{e^{-t}u(t)}_{\downarrow \mathcal{L}} + \underbrace{e^tu(t)}_{\downarrow \mathcal{L}}$$

$$\tilde{G}(s) = \frac{1}{s+1} + \frac{1}{s-1} =$$

$$= \frac{s-1+s+1}{(s+1)(s-1)} = \frac{2s}{(s+1)(s-1)}$$

↑  
poles @  $s = \pm 1$

if  $\Re s > 1$



## • Laplace transform - cont

- The region of convergence of the Laplace transform is the region in the complex plane to the right of the rightmost pole (not including  $\infty$ )
- If there is a pole at  $s = \infty$ , then the Laplace transform has a term proportional to  $s$  (or increasing with  $s$ .)