## LAB-02 Particle Swarm Optimization

```
import numpy as np
import matplotlib.pyplot as plt
# Sphere function (fitness function)
def sphere function(position):
   return np.sum(position**2)
# Parameters
num particles = 30 # Number of particles
num iterations = 100 # Number of iterations
dim = 2 # Dimensionality of the problem
bounds = [-10, 10] # Search space bounds
inertia weight = 0.7 # w
cognitive coefficient = 1.5 # c1
social coefficient = 1.5 # c2
tolerance = 1e-6 # Stopping tolerance for fitness
# Initialize particles
class Particle:
   def init (self):
       self.position = np.random.uniform(bounds[0],
bounds[1], dim) # Random position
       self.velocity = np.random.uniform(-1, 1, dim)
# Random velocity
       self.best position = np.copy(self.position)
Personal best position
       self.best fitness =
sphere function(self.position) # Personal best
fitness
```

```
self.fitness = self.best fitness # Current
fitness
   def update velocity (self, global best position):
       r1, r2 = np.random.rand(dim),
np.random.rand(dim)
       cognitive term = cognitive coefficient * r1 *
(self.best position - self.position)
       social term = social coefficient * r2 *
(global best position - self.position)
       self.velocity = inertia weight * self.velocity
+ cognitive term + social term
   def update position(self):
       self.position += self.velocity
       self.position = np.clip(self.position,
bounds[0], bounds[1]) # Keep within bounds
       self.fitness = sphere function(self.position)
       if self.fitness < self.best fitness: # Update</pre>
personal best
           self.best fitness = self.fitness
           self.best position =
np.copy(self.position)
# PSO implementation
def particle swarm optimization():
  particles = [Particle() for in
range(num particles)]
   global best position = particles[0].best position
   global best fitness = particles[0].best fitness
```

```
fitness history = []
   # Update global best from the initial population
   for particle in particles:
       if particle.best fitness <</pre>
global best fitness:
           global best fitness =
particle.best fitness
           global best position =
np.copy(particle.best position)
   for iteration in range (num iterations):
       for particle in particles:
particle.update velocity(global best position)
           particle.update position()
           # Update global best
           if particle.best fitness <</pre>
global best fitness:
               global best fitness =
particle.best fitness
               global best position =
np.copy(particle.best position)
       fitness history.append(global best fitness)
Track global best fitness
       # Early stopping if fitness reaches tolerance
       if global best fitness <= tolerance:</pre>
```

```
print(f"Converged at iteration
{iteration}")
           break
   return global best position, global best fitness,
fitness history
# Run the PSO algorithm
best position, best fitness, fitness history =
particle swarm optimization()
# Print the results
print("Best position found:", best position)
print("Best fitness achieved:", best fitness)
# Plot fitness over iterations
plt.plot(fitness history)
plt.title("Fitness Over Iterations (PSO on Sphere
Function)")
plt.xlabel("Iteration")
plt.ylabel("Fitness (Objective Function Value)")
plt.grid()
plt.show()
```

## OUTPUT

