

Name: Akash Shivaji Varude

Roll No: 231110006

Assignment No 1

Que 1)

i]

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

As both the columns are linearly independent & form a standard basis in 2D space, column space of matrix A is entire 2D euclidean space  $\mathbb{R}^2$

$$\therefore \text{Col}(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

ii]

$$B = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

we can easily see ~~xx~~ second column is linearly dependent on first column. Hence column space of matrix B is one dimensional subspace spanned by first column  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$

$$\therefore \text{Col}(B) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$$

$$\text{iii]} \quad D = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 4 \end{bmatrix}$$

Here matrix D has 2<sup>nd</sup> column  $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$  linearly dependent on 1<sup>st</sup> column  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ . 3<sup>rd</sup> column is linearly independent on first two columns.

$$\therefore \text{Col}(D) = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right\}$$

## Que 2

Satellite Positions are:

```
[[ 40000000  50000000  66660000]
 [-80000000  25000000 -44000000]
 [ 65000000  98000000  10450000]
 [ 20000000 -43000000 -66060000]
 [ 55000000  35000000  42300000]]
```

- a) Fixed user location at (100,100,100) and considered the speed as  $3 \times 10^8$  mtr/sec

Hence Time=distance/speed

Here I have considered Euclidean distance i.e l2 norm

Hence for each satellite:

$$\text{Distance} = \| \text{Satellite\_position} - \text{User\_Position} \|_2$$

Hence Time required from each satellite to user is:

travel Times are: [0.30810395554513015, 0.3155422105947158, 0.39353339276680904, 0.27106664641805955, 0.2590423290170075]

- b) Calculating User position using trilateration:

We have equations :

$$\begin{aligned}(x - x_1)^2 + (y - y_1)^2 + (z - z_1)^2 &= r_1^2 \\(x - x_2)^2 + (y - y_2)^2 + (z - z_2)^2 &= r_2^2 \\(x - x_3)^2 + (y - y_3)^2 + (z - z_3)^2 &= r_3^2 \\(x - x_4)^2 + (y - y_4)^2 + (z - z_4)^2 &= r_4^2\end{aligned}$$

These Equations can be written in matrix format as:

$$\begin{bmatrix} 2(x_2 - x_1) & 2(y_2 - y_1) & 2(z_2 - z_1) \\ 2(x_3 - x_1) & 2(y_3 - y_1) & 2(z_3 - z_1) \\ 2(x_4 - x_1) & 2(y_4 - y_1) & 2(z_4 - z_1) \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} (r_1^2 - r_2^2) - (x_1^2 - x_2^2) - (y_1^2 - y_2^2) - (z_1^2 - z_2^2) \\ (r_1^2 - r_3^2) - (x_1^2 - x_3^2) - (y_1^2 - y_3^2) - (z_1^2 - z_3^2) \\ (r_1^2 - r_4^2) - (x_1^2 - x_4^2) - (y_1^2 - y_4^2) - (z_1^2 - z_4^2) \end{bmatrix}$$

We can get the solution of this by using formula:

$$\hat{x} = (A^T A)^{-1} A^T b$$

Used Command:

```
solution= np.matmul(np.linalg.inv(np.matmul(A.T,A)), np.matmul(A.T,B))
```

Output:

```
User Postion(No Error Introduced): [ 99.99999999  99.99999997 100.00000002]
inaccuracy in position: 3.5732363043569984e-08
```

- c) Calculating User position using trilateration ( Introducing error in time):

I used command

```
rand_error=np.random.rand()/10**8
```

to generate random error and introduced that in time and calculated user position and inaccuracy

```
User Postions: [ 99.84642565  99.55079524 100.34796417]  
inaccuracy in position: 0.5885992308383305
```

- d) I have created numpy array of size 20 with randomly generated values in it and divided it by  $10^8$  as error would be small in time. And resultant graph is :

Avarage Inaccuracy : 0.6796791135039068

