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Assignment 4

Implementation Details:

I have considered range i.e. [min val, max val] for abstract representations. Further I have considered rotation angle as theta. Clockwise rotation is considered to be as negative direction rotation and anticlockwise rotation as positive direction rotation.

Initialization function:

if the node is start node, then initialize it as $x=0$, $y=0$ and theta as 0. This initialize is done using dictionary. However this initialization is done like x : `IntervalDomain(0, 0)` where `intervalDomain` is class where `Lattice` is implemented

Transfer Function Details:

- Transfer function calculates here OUT value of each Basic block.

1. For Mov type Commands(forward,backward,left,right):

- First, values from command are extracted. For e.g. 'forward 30' command, here 30 is extracted and represented in abstract format [30,30]. To represent this in abstract format, I have used **IntervalDomain(Lattice)** class. So `mov.L` and `mov.R` stores lower bound and upper bound respectively.
- If command is 'left' then just add rotation angle to theta and if command is 'right' then subtract rotation angle value from theta.
- When kachua s moving, i.e. for forward and backward commands: I have calculated lower bounds and upper bounds of both x and y axis.

Below is example for forward: (if backward command then just subtract)

- $Lb\ of\ x = current\ x.L + mov.L * \cos(\theta)$
- $Ub\ of\ x = current\ x.R + mov.R * \cos(\theta)$
- $Lb\ of\ y = current\ y.L + mov.L * \sin(\theta)$
- $Ub\ of\ y = current\ y.R + mov.R * \sin(\theta)$

2. For condition type commands: (i.e. for branches in cfg):

For these type of commands, implementation of **correct lattice** is necessary. We have variable, operator and value.

Let operator is less than '<', so in 'if' condition, if the condition is true, then range of the variable will be:

Lb of variable = minimum till now

Ub of variable = value-1

if the condition is false, then range of the variable will be:

Lb of variable = value

Ub of variable = maximum till now

Similar operations are also performed for '<=', '>', '>=', '==' with corresponding logics

Meet Function:

Created separate lists for lower and upper bounds of x and y both. inserted x lower bounds of predecessors in xlb, and upper bounds of x in xub. Similarl for y.

Now final lower bound is just minimum of all lower bounds and upper bound is maximum of all upper bounds. So I have calculated meetvalue i.e. abstract values of x and y after meet operation

Interval Domain(lattice) :

Class interval domain is initialized with abstract values as interval, self.L means lower bound and self.R means upper bounds

1. isBot function: As bottom is defined as 'None'. This function checks the parameter passed is None or not
2. __str__: is just to convert into strings.
3. isTop function: As top is defined as (int('-inf'), int('inf')). This function is to check whether abstract value is top or not
4. sub function: To carry out subtraction operation for two intervals(abstract values). So, lb of resultant interval is (lb of first – ub of second) and ub of resultant interval is (ub of first - lb of second)
5. add function: To carry out addition operation for two intervals(abstract values). So, lb of resultant interval is (lb of first + lb of second) and ub of resultant interval is (ub of first + ub of second)
6. join function: if either of two abstract values is top then their join is Top element itself. Otherwise just finding the union of the intervals
7. meet function: if either of two abstract values is bottom then their join is bot element itself. Otherwise just finding the intersection of the intervals
8. __le__: just comparing first abstract value is less than or equal to other abstract value or not. So if ub of first abstract value is <= lb of second abstract value then return true
9. __eq__: compare both lb and ub of both abstract values. Is same then return true
10. __lt__: just comparing first abstract value is less than other abstract value or not. So if ub of first abstract value is < lb of second abstract value then return true

11. `__gt__`: comparing first abstract value is greater than other abstract value or not. So if lb of first abstract value is $>$ ub of second abstract value then return true
12. `__ge__`: to check greater than equal to. If lb of first abstract value \geq ub of second abstract value then return true

Limitations:

Implementation is done for all if, else, forward, backward, left, right commands of chiron. However, code doesn't work for repeat statements.

Sample Output:

Running on test.tl and test2.json : Kachua is **unsafe**

```
D:\Mtech IITK\First SEM\PAVT\Assignment_4_231110006\Chiron-Framework-master\ChironCore>chiron.py --control_flow -ai examples/test1.tl
Chiron v5.3

  CHIRON

:a = 10
if :a <= 10[
    right 90
    forward 30
]
else[
    forward 40
]

Possibility of kachua to halt in the region : X from 0 TO 40 and y from -30 to 0

Magarmach region : X from -6 TO 20 and y from -5 to -40
Hence there is overlap between possible region where kachua stops and magarmach region

",{VERIFIED} Kachua can be inside magarmach region. Hence Unsafe
== Abstract Interpretation ==
```

Running on test3.tl and test3.json: Kachua is **safe**

```
D:\Mtech IITK\FIRST SEM\PAVT\Assignment_4_231110006\Chiron-master\chiron.py --control_flow -ai examples/test3.tl
S Chiron v5.3
S
S
C
P
R
I
S
S
S
S
C
]
else[
    right 50
]
]
Possibility of kachua to halt in the region : X from -100 TO 50 and y from 0 to 50
Magarmach region : X from 50 TO 100 and y from 60 to 220
Hence there is no overlap between possibile region where kachua stops and magarmach region
"Kachua can't be in magarmach region. Hence kachua is safe
== Abstract Interpretation ==
```