# **Custom Deblurring Model**

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#### I. **ABSTRACT:**

There are certain methods available for deblurring, but they are not effective if used alone. Therefore, the proposed method contains a valid combination of several different functionalities. The blind devolution technique uses an iterative technique from a guess point to deblur the image but due to the abrupt guesses of the point it is not effective. Therefore, this paper includes several passes so that of blurring in the image can be corrected if that type is left by the previous passes. A regularized filter can be used effectively when limited information is known about the additive noise. Therefore, it is necessary if the input image contains a variety of added noises. The regularized filter includes in this paper have used also accompanies Point Separation Function and Noise to Signal Ratio leading to deblurring of images w ith any type of noise. This is not enough for getting totally deblurred image. Therefore, additional wiener deblurring technique is performed to the previous result using a wiener filter. This filter reduces the noise left by comparison with an estimation of the desired noiseless signal and is based on statistical approach. Further, just applying these deblurring techniques is not enough because the resultant images are degraded in terms of quality. Hence, this paper includes Gaussian noise removal method to remove added noise during the deblurring process. After that the best way to improve the output image is applying harmonic mean technique and then The proposed method is based on a heuristic algorithm series of processes fully deblurs the image and enhances it.

#### II. **KEYWORDS**

Blind devolution technique, regularized filter, Point separation function, wiener deblurring technique, Gaussian noise removal method, harmonic mean.

#### III. INTRODUCTION

Deblurring is the process of removing blurring artifacts from images, such as blur caused by defocus aberration or motion blur. The blur is typically modeled as the convolution of a point spread function with a hypothetical sharp input image, where both the sharp input image (which is to be recovered) and the point spread function are unknown. This is an example of an inverse problem. In almost all cases, there is insufficient information in the blurred image to uniquely determine a plausible original image, an ill-posed problem. In addition, the making it blurred image contains additional noise which complicates the task of determining the original image. This is generally solved by the use of a regularization te rm to attempt to eliminate implausible solutions. This problem is analogous to echo removal in the signal processing domain. Nevertheless, when coherent beam is used for imaging, the point spread function can be modeled mathematically. By proper deconvolution of the point spread function and the image, the resolution can be enhanced several times. Our aim is to design and implement a hybrid custom de-blurring model to deblur a set of sample input images and enhance it.

### IV. LITERATURE SURVEY

stretching the image to the contrast range. These to enhance the images by adjusting the factors such as brightness and contrast. Lightning problem of the image can be solved through this method, but there are some limitations of this algorithms when applied to blurred images, i.e., images with defocus blur, motion blur or fog blur. They are mainly worried for (a) image enhancement: improving upon the objective function and transformation proposed by A.Gorai and A.Ghosh and (b) image deblurring: a proposed method to estimate blur kernel and its application towards image deblurring. A filter is proposed to make edges in blurred image clearer for use as a reference image. The blur Kernel is estimated from this reference image. The blurred image is then deconvolved with the estimated blur kernel to introduce a latent image, and Blind inverse deblurring is an inverse problem, which is addressed by imposing prior knowledge on the image and on the blurring fil- ter. Most of the work on BID focused on natural images, using image prior based on statistical behaviour of generic natural images. Mainly they have proposed a method where Gaussian mixture model (GMM) is used to learn class adapted prior, by training on a dataset of clean images of that class, additionaly, experiments show that the proposed method is able to handle text images at high noise levels, outperforming state of the methods specifically designed for BID of text images. In Some paper they proposed a novel algorithm for hyper-spectral (HS) image deblurring with principal components analysis (PCA) and total variation (TV), they first decorrelate the images and separate the information content form the noise by PCA. Then they follow other steps. Experimental results on simulated and real HS images are very encouraging. Some researchers develop expectation-maximization (EM)like iterative deblurring algorithm to achieve piral CT image super-resolution for cochlear implantation, assuming a spatially invariant linear spiral CT system with a three- dimensional (3-D) se parable Gaussian point spread function (PSF). The imaging process is further expressed as convolution of an isotropic 3-D Gaussian PSF and a blurred underlying volumetric image. They have developed a blind deblurring approach enhance resolution to image retrospectively about the full knowledge of underlying knowledge of underlying point spread function (PSF). An oblique CT of Image can be approximated as convolution of an isotropic Gaussian PSF and the actual cross section. Practically, the parameter of the PSF is often unavailable, the parameter for the underlying PSF is crucially important for blind image deblurring. In some paper, they have developed a blind deblurring

reconstruction technique estimate of both the actual image and the PSF of the system, and enhance the performance of iterative reconstruction using th is technique. They formulate a blind deblurring reconstruction algorithm, which also consists of two iterative update sequences, which are corresponded for the PSF and the SPECT reconstruction, respectively. In some paper, they propose the use of a con tour let filter bank system to deblur the color images without estimating a point spread function. This multi-band deblurring method uses sharper color planes to improve blurred ones. Compared to the conventional one. The proposed contourlet-based system better adjusts to the natural image contours. This effect produces an image with a similar level of sharpness, but fewer ghosting artifacts, they propose a motion deblurring algorithm that exploits sparsity constraints of image patches using one single frame and the sparsity constraints facilitate recovering the latent image without solving a deconvolution problem. The proposed method iteratively utilizes sparsity constraints to recover latent image, estimates the deblur kernel, and updates the dictionary directly from one single image. The final deblurred image is then recovered once the deblur kernel is estimated using our method. They proposed a way of measuring the quality improvement of the deblurring is suggested. The deblurred image is reblurred by the estimated PSF and then the PSNR between the original blurred image and the re-blurred image is calculated as an indication of deblurring quality. Deblurring filters often produce noise and ringing artifacts i n the deblurred image. This quality measures further enhance the blind deblurring scheme and has been tested on both synthetic and real blurred images, they describe an image deblurring technique that uses the spatially varying point spread function of the scanner measured in the image space. To stabilize the deconvolution problem, they introduce the joint entropy between the PET image and a high resolution. MR image as an information theoretic penalty function. They then apply their method to a phantom and a human dataset and demonstrated that, compared to standalone deblurring, which tends to amplify noise, the joint entropy prior leads to a smooth PET image with sharp boundaries consistent with MRI.

# V. RESEARCH FRAMEWORK

In this custom deblurring model, this paper includes different, already formulated algorithms and techniques sequentially to a given set of images to enhance and deblur the given image in a better way as compared to applying them independently on the input images. The different techniques used are:

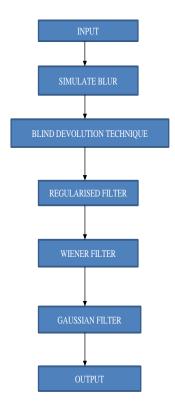


Figure-1

# VI. IMPLEMENTATION DETAILS:

# 1) Blind Image Deconvolution

There are basically two type of deconvolution methods. They are projection based blind deconvolution and maximum likelihood restoration. In the first approach it simultaneously restores the true image and point spread function. This begins by making initial estimates of the true image and PSF. The technique is cylindrical in nature. Firstly, we will find the PSF estimate and it is followed by image estimate. This cyclic process is repeated until a

predefined convergence criterion is met. The merit of this method is that it appears robust to inaccuracies of support size and this approach is insensitive to noise. The problem here is that it is not unique, and this method can have errors associated with local minima. In the second approach the maximum likelihood estimates of parameters like P SF and covariance matrices. As the PSF estimate is not unique other assumptions like size, symmetry etc. of the PSF can be considered. The main advantage is that it has got low computational complexity and helps to obtain blur, noise and power spectra of the true image. The drawback with this approach is of algorithm being converging to local minima of the estimated cost function.

$$g(x,y) = f(x,y) * h(x,y)$$

$$= \sum_{(n,m)} f(n,m)h(x-n,y-m),$$

$$= x,y,n,m \in Z$$

# 2) Wiener Deblurring Technique:

It uses the wiener filter to remove noise from images. It affects the frequency domain, attempting to minimize noise at frequencies which have a poor signal-to-noise ratio. It uses a statistical approach.

Wiener filter can be useful when the point-spread f unction and noise level are either known or estimated.

Fest(u,v) = 
$$|H(u,v)|^2 \cdot G(u,v) / (|H(u,v)|^2 \cdot H(u,v) + K(u,v))$$

# 3) Gaussian Noise Removal and Filter:

It is also called as electronic noise because it arises in amplifiers or detectors. Gaussian noise caused by natural sources such as thermal vibration of atoms and discrete nature of radiation of warm objects. Gaussian noise generally disturbs the gray values in digital images. That is why Gaussian noise model essentially

designed and characteristics by its PDF or normalizes VIII. CONCLUSION histogram with respect to gray value. Gaussian filter has been proved to be a good choice for removing noise.

$$p(z) = \frac{e^{-\frac{(z-\mu)^2}{2\sigma^2}}}{\sqrt{2\pi\sigma}}$$

where

z=gray level

*u*=mean or average of function P(z)=probability density function

## VII. RESULTS

Fig: 3 - 12 about here.

Mean square value for the input image and sharpened image is (0.0200), which is very less. So it implies method that is discussed in this paper is better then the previous methods. Mean square value of different filters like Wiener Filter is (0.0024), gaussian filter is (0.0032) and mean square value of Lucy Richardson algorithm is (0.0130). So which means that Wiener Filter is giving us better result because its mean square value is smaller than gaussian filter.

## Final output:

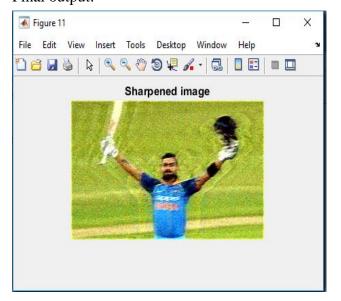


Figure-2

In this paper proposed algorithms were successfully able to apply all the filters and deblurring techniques mentioned earlier in the proposed manner to get deblurred and enhanced images from the set of sample input images. The individual fi lters used in this model were applied on the same set of input images and the result was compared at different levels of noise and blur. It was found that the proposed model gave better results while compared to applying the techniques independently.

#### IX. **FUTURE WORK**

Additional filters can be incorporated apart from the already used filters in this technique. Filters such as smoothening and sharpening filters will have to be used to remove various types of noises. Algorithms must be designed to recognize the type of noise present in the image to apply the appropriate algorithm. Apart from the deburring techniques already being use, we can also use other recent developing techniques to further deblur the image and get as close to the original image as possible.

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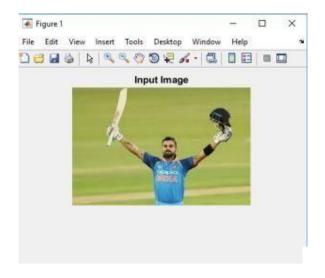
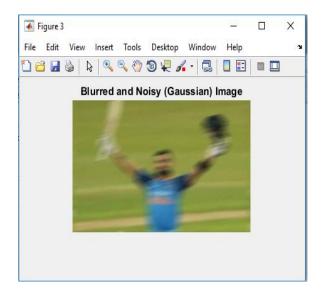




Figure-3 Figure-4



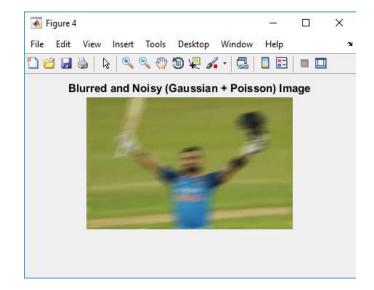


Figure-5 Figure-6

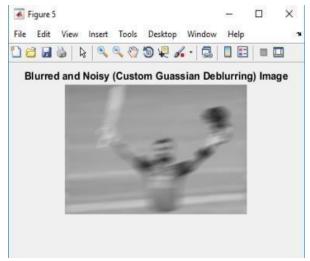


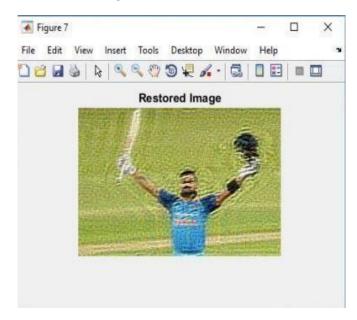
Figure-7



Figure-9 Figure-10



Figure-8



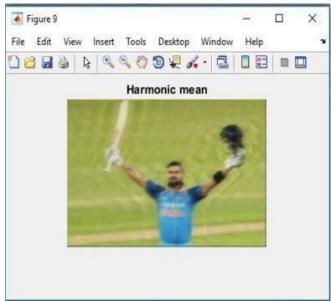


Figure-11



Figure-12