AutonomySi Documentation

The application runs as a ROS2 node
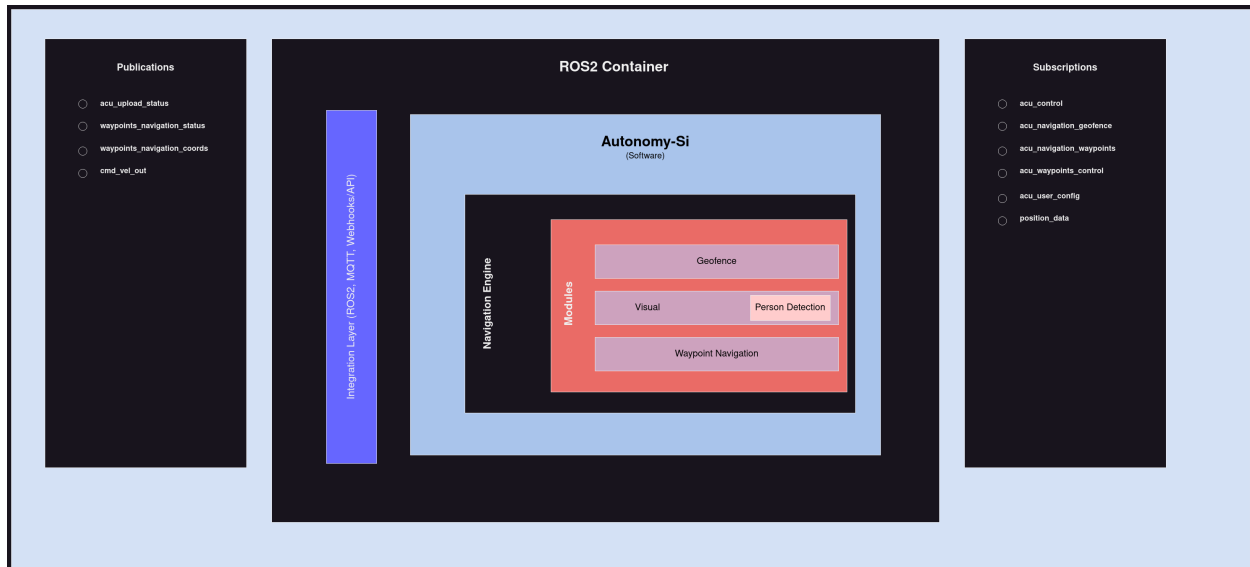
img

Updates

In case updates has been pushed use the following commands to restart the container

1   Stop the already running service

```
sudo systemctl stop container-autonomy-si-ros2.service
sudo podman images
sudo podman rmi <image_id>
```

2   Pull the latest container

```
sudo podman login <ip-address>:<port>        # credentials will be
provided
sudo podman pull <ip-address>:<port>/atonomy-si/ros2:v1.2
```

3   Run the container

```
sudo systemctl start container-autonomy-si-ros2.service
```

Topics list

The following topics has been subscribed and published when AutonomySi is powered on.