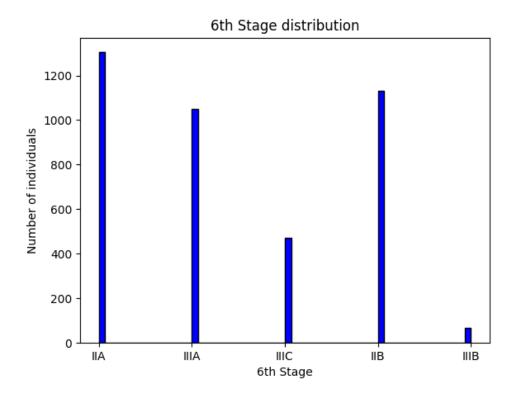
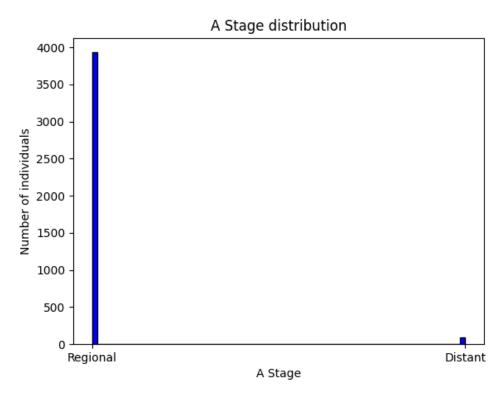
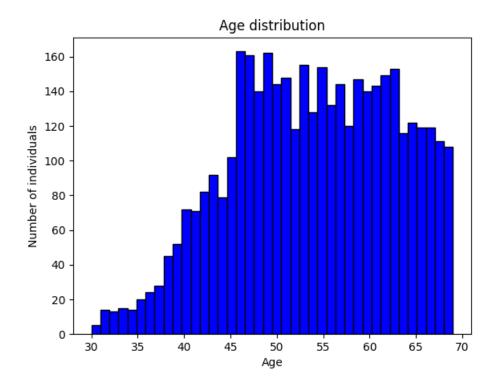
## **Homework 1**

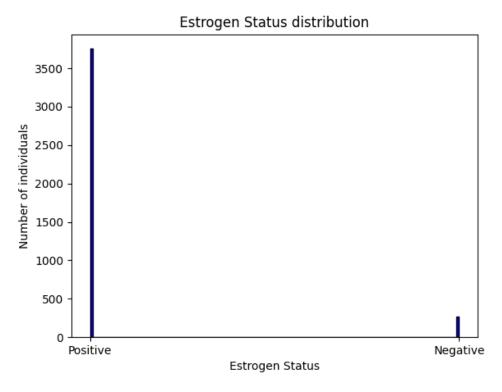
Varun Hoskere

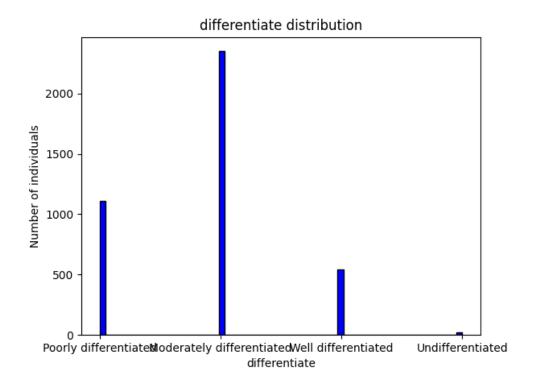
```
import pandas as pd
import matplotlib.pyplot as plt
data = pd.read_csv('Breast_Cancer.csv')
values = []
<u>(a)</u>
def a():
  for variable in list(data.columns):
   for i in data[variable]:
      if i not in values:
        values.append(i)
    plt.hist(data[variable], bins=len(values), color='blue', edgecolor='black')
    plt.title(f'{variable} distribution')
    plt.xlabel(f'{variable}')
    plt.ylabel('Number of individuals')
    plt.savefig(f'{variable} plot.png')
    # plot.show()
  return
```

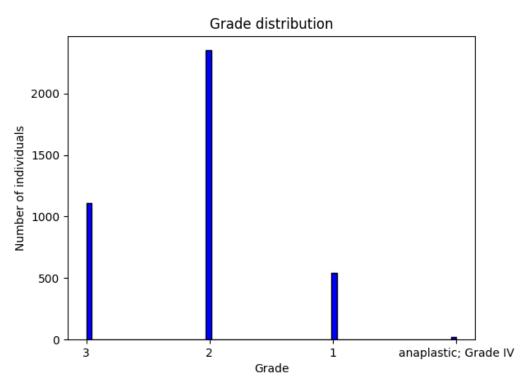


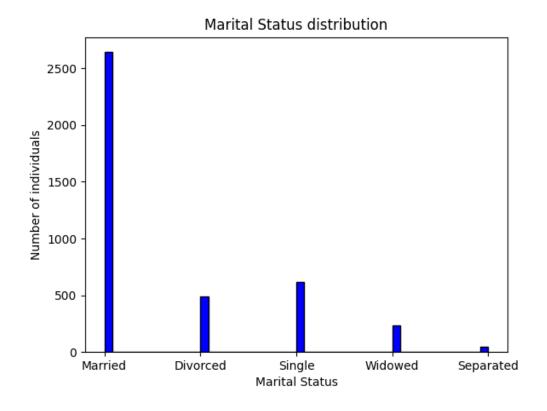


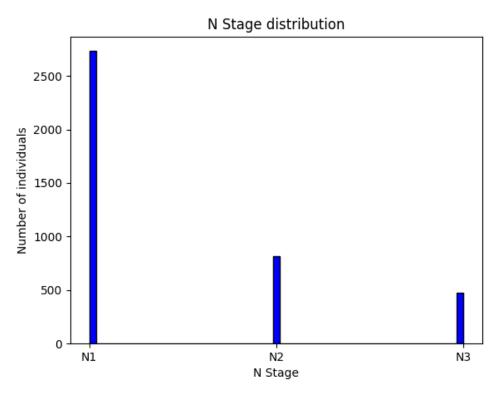


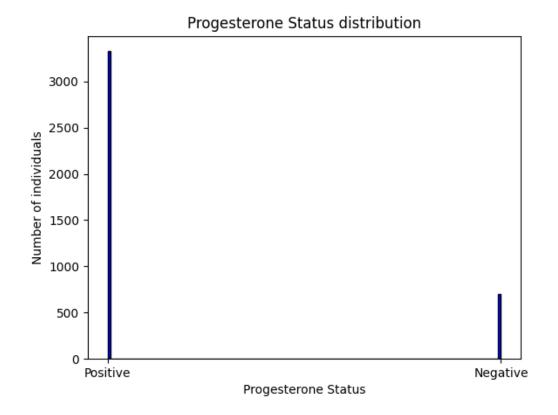


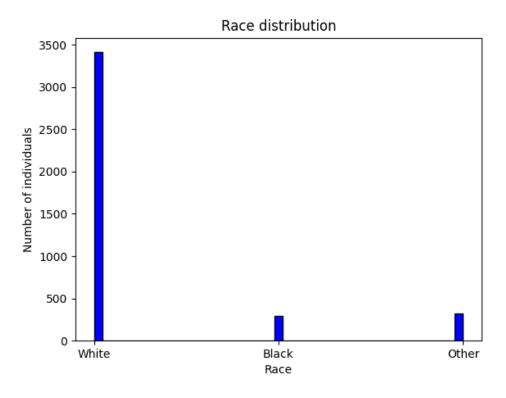


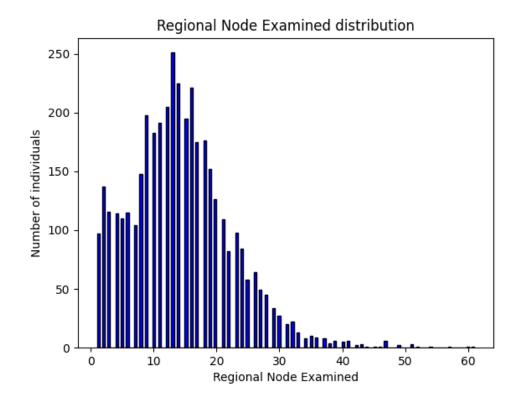


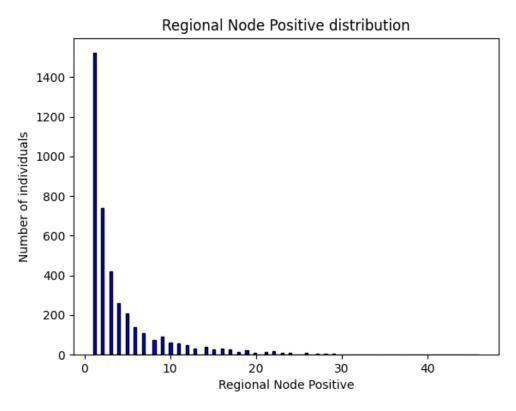


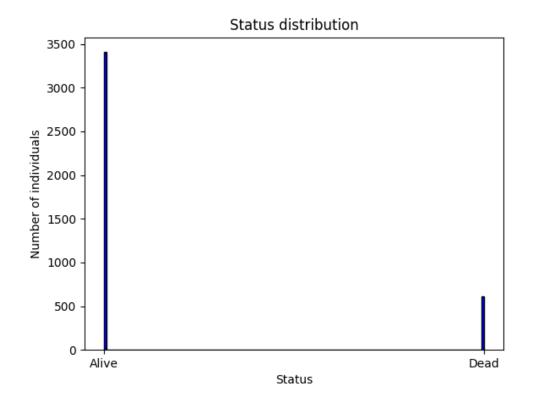


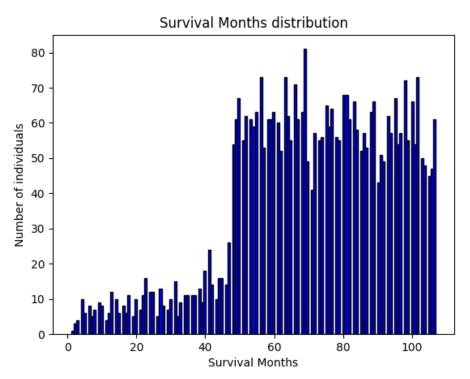


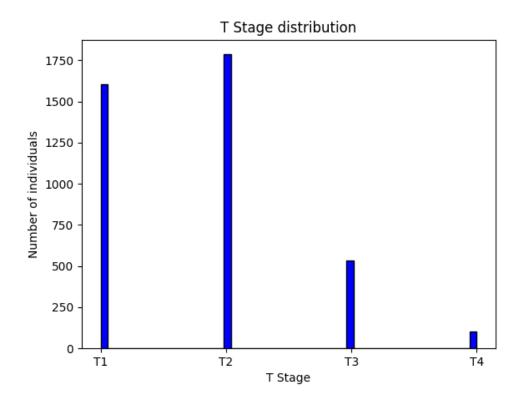


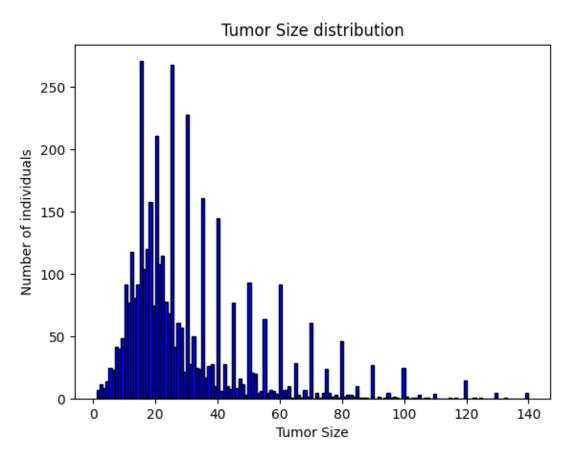












```
(b)
def
```

```
def b():
 # Age, Regional node examined, regional nodde +ve, survival months, tumour size are the
continuous variables
 # variables = ['Age', 'Regional Node Examined', 'Regional Node Positive', 'Tumor Size']
 # for var in variables:
 # plot.scatter(data[var], data['Survival Months'])
 # plot.savefig(f'{var} vs Surival Months')
  plt.scatter(data['Age'], data['Survival Months'], color='blue')
  plt.xlabel('Age')
  plt.ylabel('Survivial Months')
 # plot.show()
  plt.savefig('Age vs Survival Months')
  plt.scatter(data['Regional Node Examined'], data['Survival Months'], color='blue')
  plt.xlabel('Regional Node Examined')
  plt.ylabel('Survivial Months')
 # plt.show()
  plt.savefig('Regional Node Examined vs Survival Months')
  plt.scatter(data['Tumor Size'], data['Survival Months'], color='blue')
  plt.xlabel('Tumor Size')
  plt.ylabel('Survivial Months')
 # plt.show()
 plt.savefig('Tumor Size vs Survival Months')
```

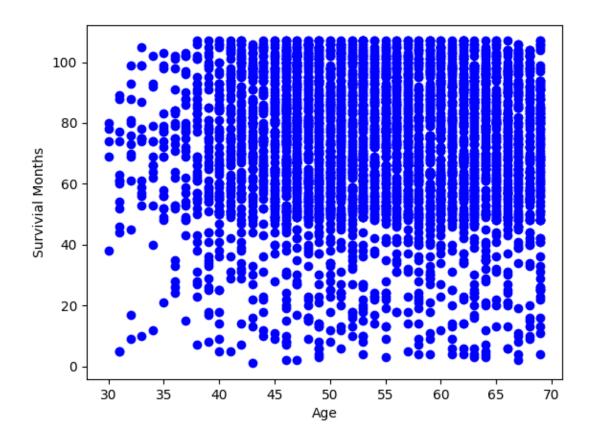
```
plt.scatter(data['Regional Node Positive'], data['Survival Months'], color='blue')
 plt.xlabel('Regional Node Positive')
  plt.ylabel('Survivial Months')
  plt.savefig('Regional Node Positive vs Survival Months')
 # plt.show()
 return
def bPearsons():
 print("=======")
 print("Pearsons coefficient against Survival Months:")
 print("Age: ", data['Age'].corr(data['Survival Months']))
 print("Regional Node Examined", data['Regional Node Examined'].corr(data['Survival
Months']))
 print("Regional Node Positive", data['Regional Node Positive'].corr(data['Survival
Months']))
 print("Tumor Size", data['Tumor Size'].corr(data['Survival Months']))
 print("=======")
 print()
 return
```

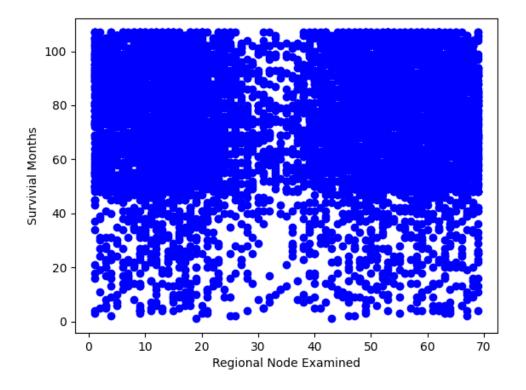
Pearsons coefficient against Survival Months: Age: -0.009389559920833184

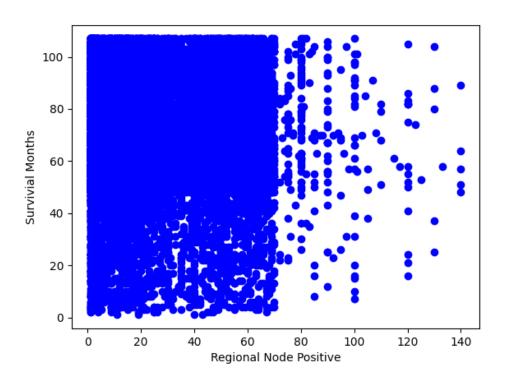
Regional Node Examined -0.022054212048869107 Regional Node Positive -0.13521384862427394

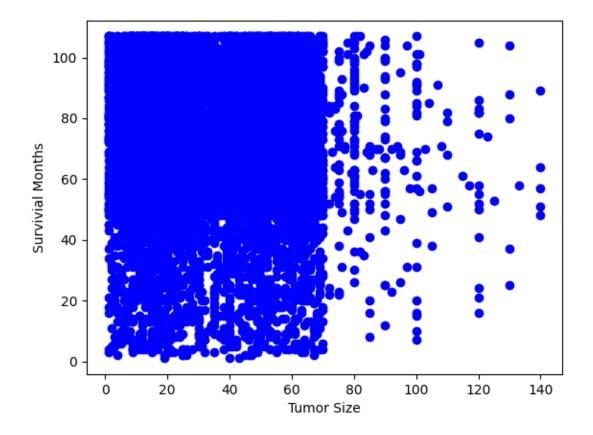
Tumor Size -0.08690123938973021

\_\_\_\_\_









```
def variable_type(data, column_name, threshold=2):
  # print(data[column_name])
  unique_values = []
 for point in data[column_name]:
   if point not in unique_values:
      unique_values.append(point)
  if len(unique_values) > 10:
    return 0
  return 1
def c():
 status = ['Alive', 'Dead']
 vars_x = []
 for variable in list(data.columns):
   if variable_type(data, variable):
     vars_x.append(variable)
  categories = {}
 for var in vars_x:
    categories[var] = []
   for i in data[var]:
     if i not in categories[var]:
        categories[var].append(i)
```

```
for category in categories.keys():

miniDF = data.groupby([f'{category}', 'Status']).size().reset_index(name='count')

finalDF = miniDF.pivot(index=f'{category}', columns='Status', values='count')

finalDF.plot(kind='bar', stacked=False)

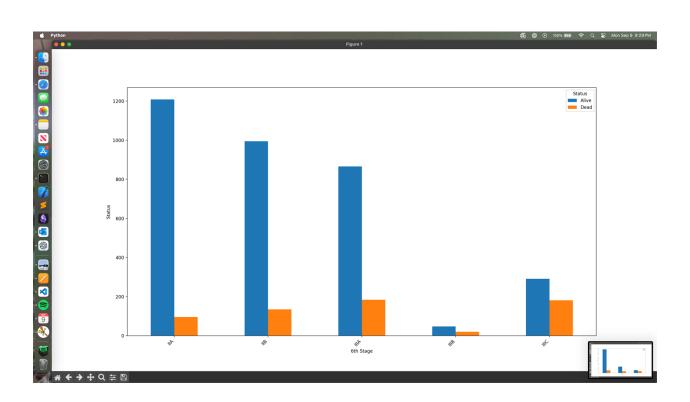
plt.xlabel(f'{category}')

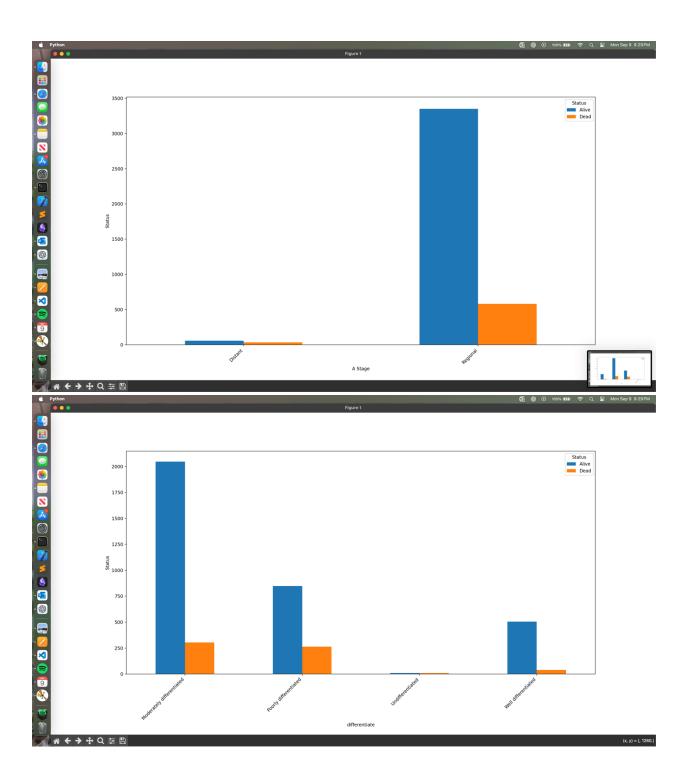
plt.ylabel('Status')

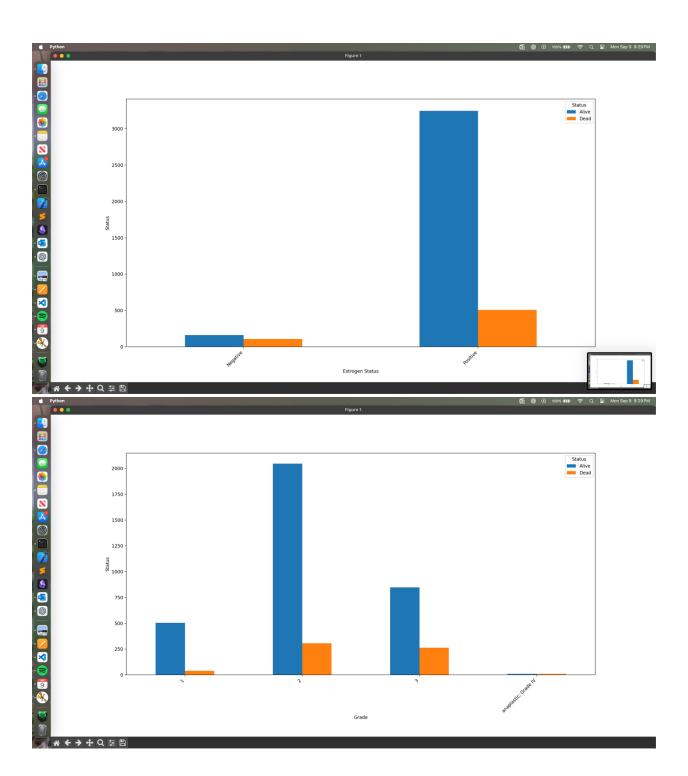
plt.xticks(rotation=45, ha='right')

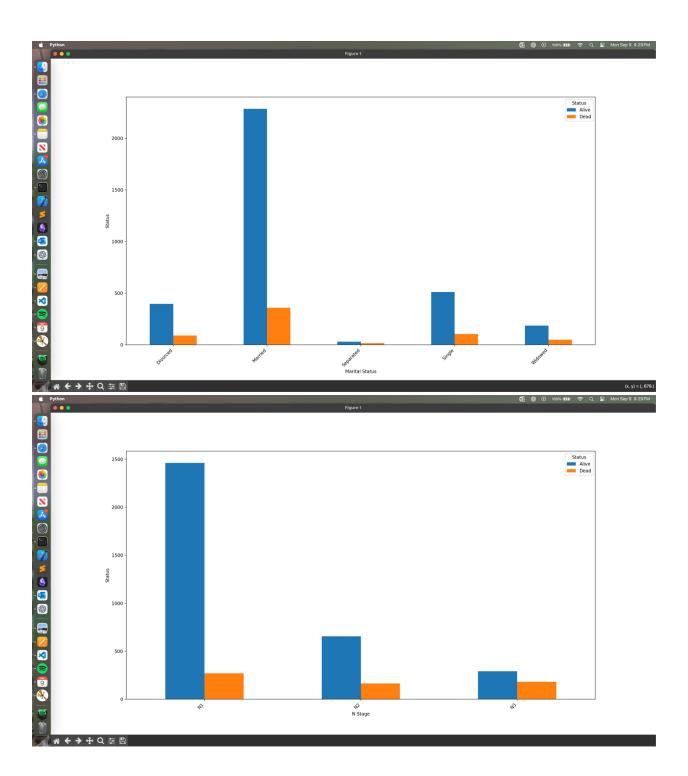
plt.savefig(f'{category} vs Status.png')

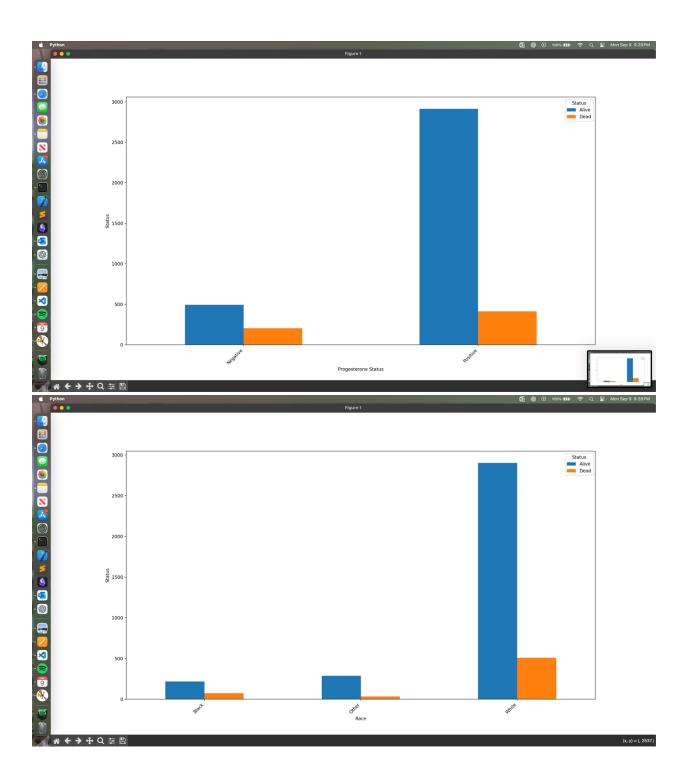
plt.show()
```

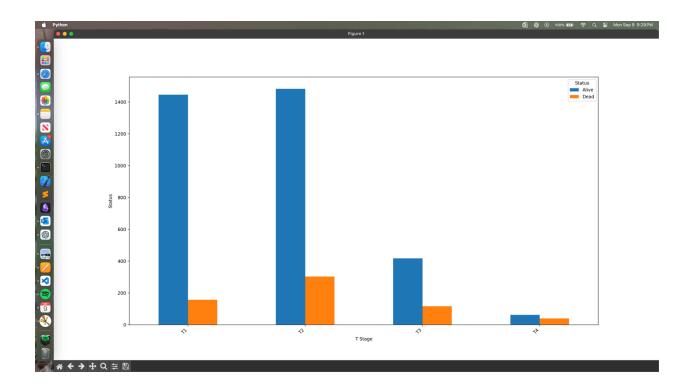












```
(d) K N N Algorithm
import pandas as pd
import math
from collections import Counter
# import time as t
from tqdm import tqdm
import random
data = pd.read_csv('Breast_Cancer.csv')
def compute_distances(point1, point2):
   Age, survival months, regional node positive, regional node examined and Tumor size
   are the continuous variables. Euclidean distance is used for measuring similarity
   between these variables.
   Race, Marital Status, T Stage, N Stage, 6th Stage, Defferentiated, Grade, A Stage,
   Estrogen Status, Progesterone Status are the categorical values. Hamming distance
   is used for measuring the similarity across these variables.
  .....
  euclidean_distance = math.sqrt(
   (point1['Age'] - point2['Age']) **2+
   (point1['Tumor Size'] - point2['Tumor Size']) **2+
   (point1['Regional Node Examined'] - point2['Regional Node Examined']) **2+
   (point1['Regional Node Positive'] - point2['Regional Node Positive']) **2+
   (point1['Survival Months'] - point2['Survival Months'])**2
 )
```

```
# print("ed: ", euclidean_distance)
  hamming_distance = (
    (0 if point1['Race']==point2['Race'] else 1) +
    (0 if point1['Marital Status']==point2['Marital Status'] else 1) +
    (0 if point1['T Stage']==point2['T Stage'] else 1) +
    (0 if point1['N Stage']==point2['N Stage'] else 1) +
    (0 if point1['6th Stage']==point2['6th Stage'] else 1) +
    (0 if point1['differentiate']==point2['differentiate'] else 1) +
    (0 if point1['Grade']==point2['Grade'] else 1) +
    (0 if point1['A Stage']==point2['A Stage'] else 1) +
    (0 if point1['Estrogen Status']==point2['Estrogen Status'] else 1) +
    (0 if point1['Progesterone Status']==point2['Progesterone Status'] else 1)
  )
  # print("hd: ", hamming_distance)
  return euclidean_distance + hamming_distance
def split_dataset(data):
  totalRows = data.shape[0] - 1
  111111
```

```
split data into train, validation and testing sets: 75-15-15% each
   find the total size of the dataset and *0.75, .15, .15
  .....
 train boundary = math.floor(0.70*totalRows)
 val_boundary = train_boundary + math.ceil(0.15*totalRows)
 test_boundary = val_boundary + math.ceil(0.15*totalRows)
 train_data = data.iloc[:train_boundary]
 val_data = data.iloc[train_boundary:val_boundary]
 test_data = data.iloc[val_boundary:test_boundary]
 train_Y = train_data['Status']
 train_X = train_data.drop(['Status'], axis=1)
 val_Y = val_data['Status']
 val_X = val_data.drop(['Status'], axis=1)
 test_Y = test_data['Status']
 test_X = test_data.drop(['Status'], axis=1)
 # print(train_X.shape[0])
 # print(val_X.shape[0])
 return train_X, train_Y, val_X, val_Y, test_X, test_Y
data['ID'] = data.index
```

```
train_X, train_Y, val_X, val_Y, test_X, test_Y = split_dataset(data.sample(frac=1))
point_distance_map = {}
val_point_to_sorted_distances = {}
for val index in tqdm(range(val X.shape[0])):
 for train_index in range(train_X.shape[0]):
   distance = compute_distances(val_X.iloc[val_index], train_X.iloc[train_index])
   point_distance_map[train_index] = distance
  sorted_distances = dict(sorted(point_distance_map.items(), key=lambda item: item[1]))
 val_point_to_sorted_distances[val_index] = sorted_distances
def get_k_neighbours(k):
 kNeighbours = {}
 for val_point in val_point_to_sorted_distances:
   neighbours = val_point_to_sorted_distances[val_point]
   kNeighbours[val_point] = list(neighbours.keys())[:k]
  return kNeighbours
def predict_for_val(kNeighbours):
 validation_predictions = {}
 for val_point in kNeighbours.keys():
   output = []
   for neigh in kNeighbours[val_point]:
     # print(train_X.loc[train_X['ID'] == neigh])
     output.append(train_Y.iloc[neigh])
     pred_status, trash = Counter(output).most_common()[0]
     validation_predictions[val_point] = pred_status
```

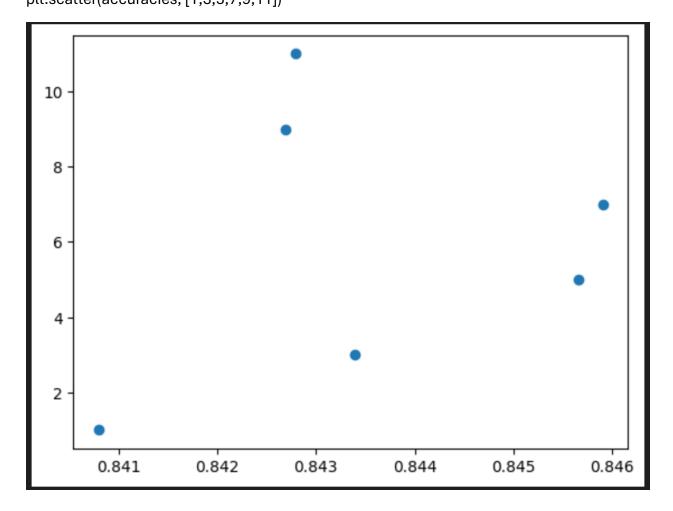
```
tp = \{\}
fp = \{\}
tn = {}
fn = \{\}
def confusion_matrix(predictions, k, actual_Y):
  global tp
  global tn
  global fn
  global fp
  tp.setdefault(k,0)
  tn.setdefault(k,0)
  fn.setdefault(k,0)
  fp.setdefault(k,0)
  for point in predictions:
    if predictions[point] == actual_Y.iloc[point]:
      if actual_Y.iloc[point] == 'Alive':
        tp[k]+=1
      else:
        tn[k]+=1
    else:
      if actual_Y.iloc[point] == 'Alive':
        fn[k]+=1
```

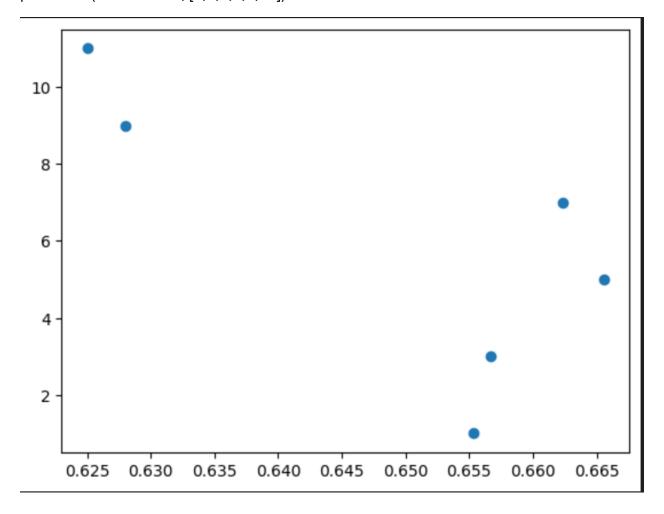
```
fp[k]+=1
def compute_accuracies(tp, fp, tn, fn, k):
 recall_1 = tp[k]/(tp[k]+fn[k])
 recall_2 = tn[k]/(tn[k]+fp[k])
 return ((tp[k]+tn[k])/(tp[k]+tn[k]+fp[k]+tn[k])), (0.5*(recall_1 + recall_2)), (2*tp[k]/(2*tp[k])
+ fp[k] + fn[k])
accuracies = []
bAccuracies = []
f1_scores = []
for k in [1,3,5,7,9,11]:
 kNeighbours = get_k_neighbours(k)
 validation_predictions = predict_for_val(kNeighbours=kNeighbours)
 confusion_matrix(validation_predictions, k, val_Y)
 acc , bAcc , f1 = compute_accuracies(tp, fp, tn, fn, k)
 accuracies.append(acc)
 bAccuracies.append(bAcc)
 f1_scores.append(f1)
 print(f"For k = {k}: Accuracy = {acc}-----Balanced Accuracy = {bAcc}-----F1 score = {f1}")
```

else:

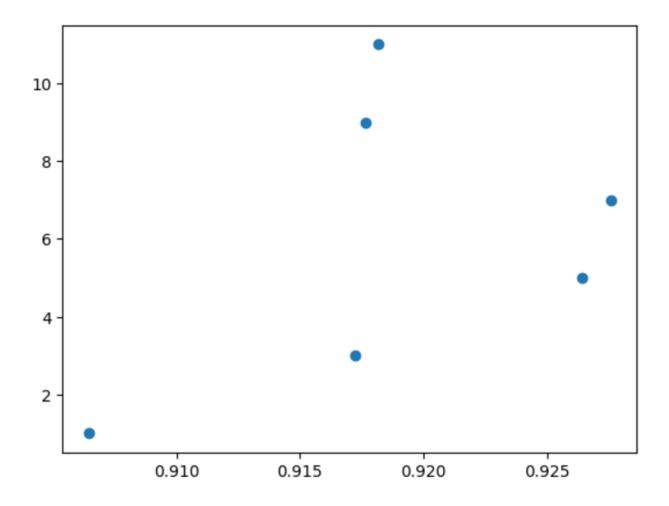
```
For k = 1 : Accuracy = 0.8407960199004975---
                                              --Balanced Accuracy = 0.6553067585301837--
                                                                                           --F1 score = 0.9064609450337512
For k = 3: Accuracy = 0.8433931484502447--
                                               -Balanced Accuracy = 0.6567011154855643--
                                                                                           --F1 score = 0.9264150943396227
For k = 5: Accuracy = 0.8456591639871383---
                                               -Balanced Accuracy = 0.6655593832020997---
For k = 7: Accuracy = 0.8459069020866774-----Balanced Accuracy = 0.6623195538057743----
For k = 9: Accuracy = 0.8426892950391645--
                                               -Balanced Accuracy = 0.6279963639811791--
                                                                                           -F1 score = 0.9176382098533283
For k = 11: Accuracy = 0.8427919112850619--
                                                -Balanced Accuracy = 0.6250290194847448-
   Best value for K based on :
       1. Accuracy : K*=9
       2. Balanced accuracy : K**=9
       3. F1 score : K+=11
```

import matplotlib.pyplot as plt plt.scatter(accuracies, [1,3,5,7,9,11])





plt.scatter(f1\_scores, [1,3,5,7,9,11])



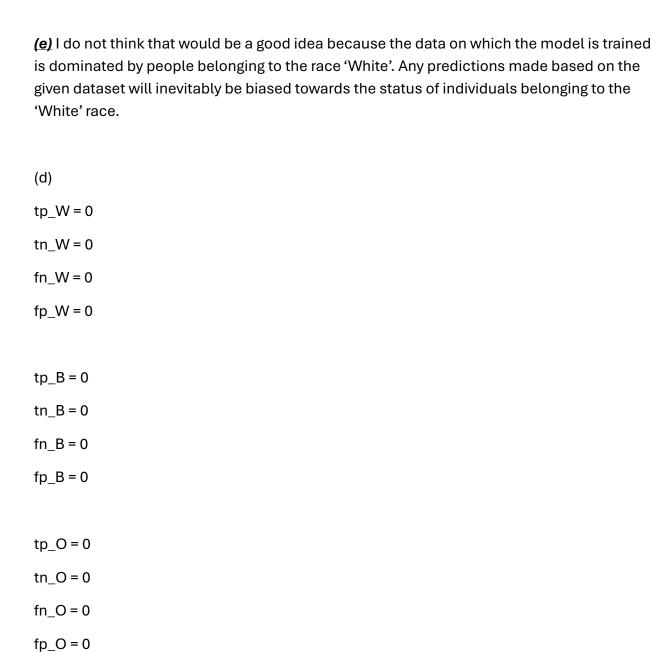
```
point_distance_map = {}

test_point_to_sorted_distances = {}

for test_index in tqdm(range(test_X.shape[0])):
    for train_index in range(train_X.shape[0]):
        distance = compute_distances(test_X.iloc[test_index], train_X.iloc[train_index]))
        point_distance_map[train_index] = distance
        sorted_distances = dict(sorted(point_distance_map.items(), key=lambda item: item[1]))
        test_point_to_sorted_distances[test_index] = sorted_distances

def get_k_neighbours(k):
        kNeighbours = {}
```

```
for test_point in test_point_to_sorted_distances:
   neighbours = test_point_to_sorted_distances[test_point]
   kNeighbours[test_point] = list(neighbours.keys())[:k]
  return kNeighbours
def predict_for_test(kNeighbours):
 test_predictions = {}
 for test_point in kNeighbours.keys():
   output = []
   for neigh in kNeighbours[test_point]:
     # print(train_X.loc[train_X['ID'] == neigh])
     output.append(train_Y.iloc[neigh])
     pred_status, trash = Counter(output).most_common()[0]
     test_predictions[test_point] = pred_status
  return test_predictions
for k in [9,11]:
  kNeighbours = get_k_neighbours(k)
 test predictions = predict for test(kNeighbours=kNeighbours)
  confusion_matrix(test_predictions, k, test_Y)
  acc, bAcc, f1 = compute_accuracies(tp, fp, tn, fn, k)
  print(f"For k = {k}: Accuracy = {acc}-----Balanced Accuracy = {bAcc}-----F1 score = {f1}")
For k = 9: Accuracy = 0.825------Balanced Accuracy = 0.4647495361781076------F1 score = 0.8662900188323918
 For k = 11 : Accuracy = 0.8256227758007118-----Balanced Accuracy = 0.46672582076308783---
                                                                  --F1 score = 0.868421052631579
```



```
def confusion_matrix_optimal(predictions, k, actual_Y):
    for point in predictions:
        if test_X.iloc[point]['Race'] == "White" :
            if predictions[point] == actual_Y.iloc[point]:
                  if actual_Y.iloc[point] == 'Alive':
```

```
global tp_W
     tp_W+=1
   else:
     global tn_W
     tn_W+=1
 else:
   if actual_Y.iloc[point] == 'Alive':
     global fn_W
     fn_W+=1
   else:
     global fp_W
     fp_W+=1
elif test_X.iloc[point]['Race'] == "Black":
 if predictions[point] == actual_Y.iloc[point]:
   if actual_Y.iloc[point] == 'Alive':
     global tp_B
     tp_B+=1
   else:
     global tn_B
     tn_B+=1
 else:
   if actual_Y.iloc[point] == 'Alive':
     global fn_B
     fn_B+=1
   else:
     global fp_B
```

```
fp_B+=1
    elif test_X.iloc[point]['Race'] == "Other":
     if predictions[point] == actual_Y.iloc[point]:
       if actual_Y.iloc[point] == 'Alive':
         global tp_O
         tp_O+=1
       else:
         global tn_O
         tn_O+=1
     else:
       if actual_Y.iloc[point] == 'Alive':
         global fn_O
         fn_O+=1
       else:
         global fp_O
         fp_O+=1
kNeighbours = get_k_neighbours(11)
test_predictions = predict_for_test(kNeighbours)
confusion_matrix_optimal(test_predictions, 11, test_Y)
def compute_accuracies_optimal(tp, fp, tn, fn, k):
  recall_1 = tp/(tp+fn)
  recall_2 = tn/(tn+fp)
  return ((tp+tn)/(tp+tn+fp+tn)), (0.5*(recall_1 + recall_2)), (2*tp / (2*tp + fp + fn))
f1_W = compute_accuracies_optimal(tp=tp_W, tn=tn_W, fp=fp_W, fn=fn_W, k=11)
```

 $f1\_B = compute\_accuracies\_optimal(tp=tp\_B, tn=tn\_B, fp=fp\_B, fn=fn\_B, k=11)$   $f1\_O = compute\_accuracies\_optimal(tp=tp\_O, tn=tn\_O, fp=fp\_O, fn=fn\_O, k=11)$   $f1\_W[2], f1\_B[2], f1\_O[2]$ 

(0.8706009745533297, 0.8387096774193549, 0.8641975308641975)

## F1 Scored for

White: 0.8706
 Black: 0.8387
 Other: 0.8641

## Comments:

The above code only implements a basic version of the KNN algorithm. There are multiple scopes for optimization, which I have not implemented due to lack of time. For example, the functions for computing distances between two validation and train can be generalized, and then would not be needed to be duplicated and modified for computing the same distance set between train and test sets. The distance computation has scope for performance optimization by using numpy arrays. However, for simplicity's sake I stuck with straightforward simple approach.