

# VHDL ASSIGNMENT

## **Introduction:**

This assignment illustrates a VHDL (Very High-Speed Integrated Circuit Hardware Description Language) implementation of a pedestrian crossing the road project. This project emphasizes in the design of combinational and sequential digital circuits by using the VHDL. Furthermore, this report displays the use of an appropriate VHDL compiler and simulator. This report deals with the practical issues in the design of digital systems and it shows the uses of a FPGA (Field Programmable Gate Arrays) development board to implement digital logic designs.

## **Splitting of tasks:**

All the tasks were made by one student and not a group. The process to construct this project was difficult to make by only one person. However, this project started with the design creation and it continued with the compile of this design. To check that the design is working right the simulator of Quartus Prime program used. After these two steps a hardware setup made to verify the code of the design by using the DE0-Nano FPGA board, a protoboard, six Led(2 yellow, 2 Red, 2 Green Led) and lots of female-male connectors.

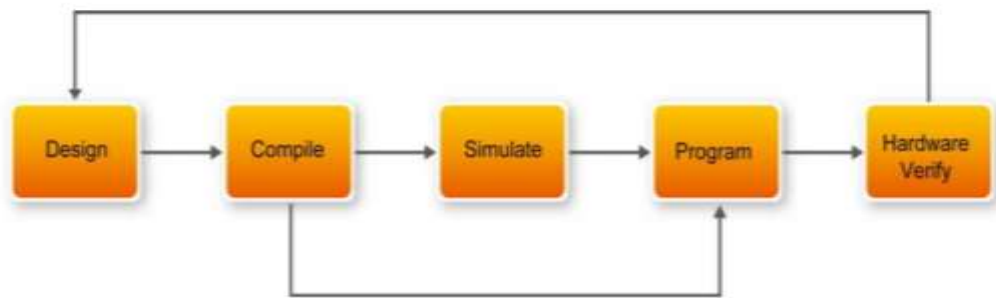


Figure 1 Design Flow

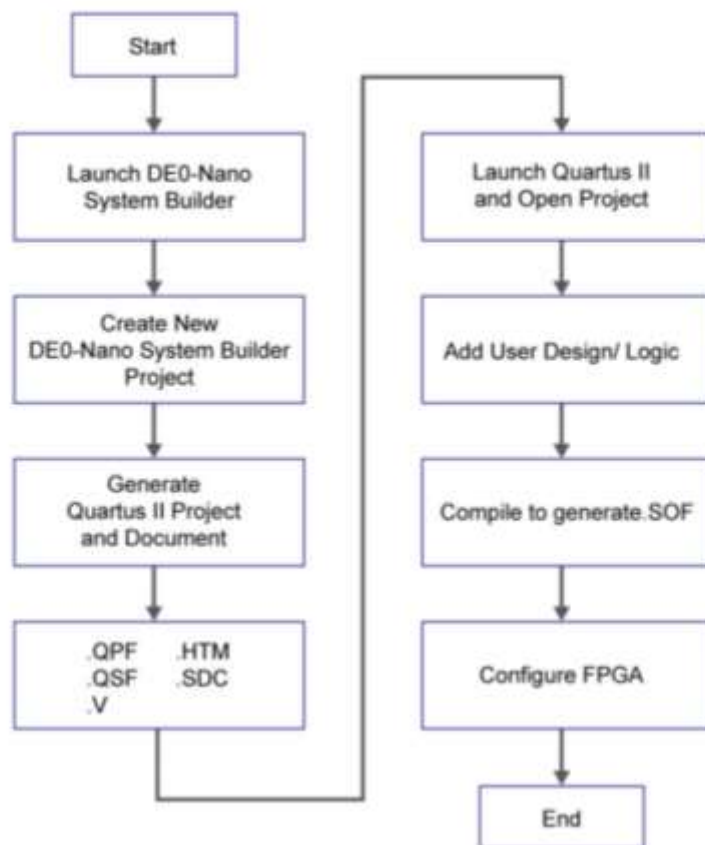


Figure 2 The general design flow of building a design

### VHDL Code:

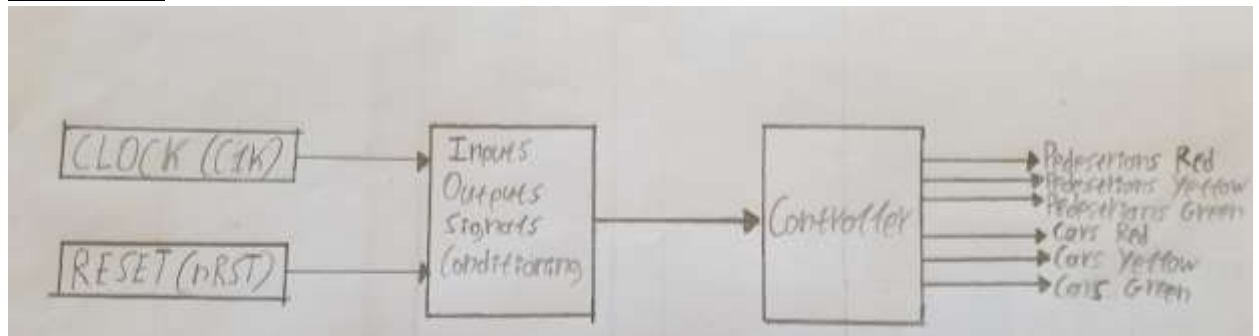


Figure 3 Block Diagram

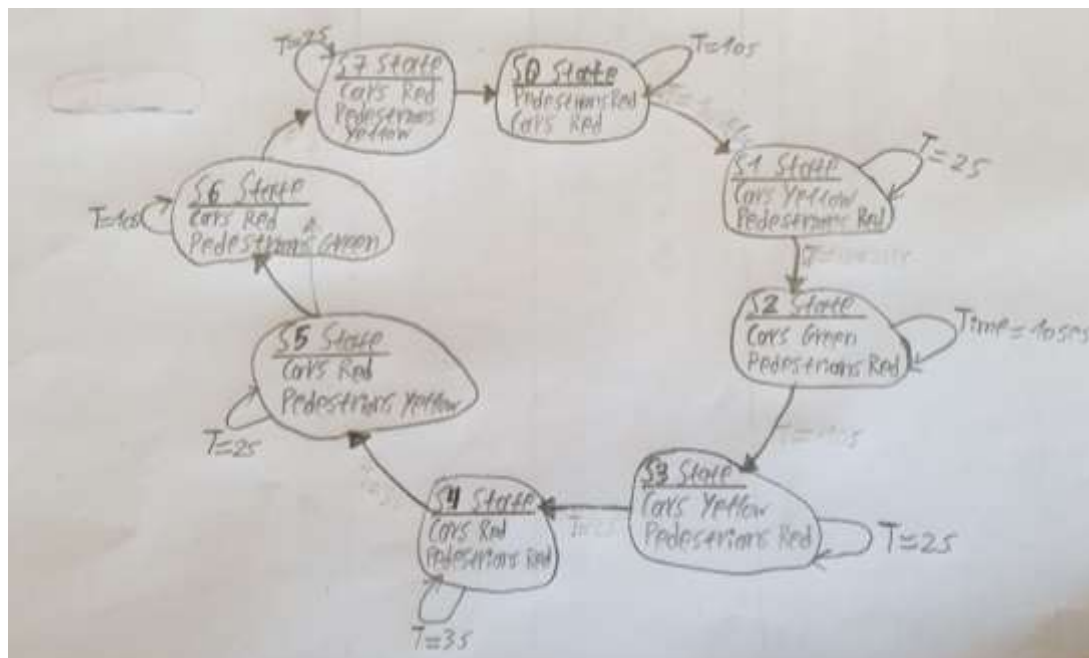


Figure 4 Structure Diagram

This design used to make the VHDL code specifications easier. Also, this design is an imitation of an FSM(Finite state machines) design, so this project works like a FSM system. The finite-state machine can be implemented using the state signal in a method with a Case statement. The statement of case contains a statement of when for each of the possible states which causes the program to take different paths for each state. Even the When statement can contain code that should be executed while in that state. Typically, when a predefined condition is met, the state must change.

### **VHDL Code Layout:**

```
-- VHDL implementation of a
-- Pedestrian crossing project

-- Title: TrafficLights.vhd
-- Designer
-- Date
-- Version No:1
-- Target DE0 board - EP4CE22F17C6
```

```
library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
```

```
entity TrafficLights is
generic(ClockFrequencyHz:integer:=5000000);
port(
Clk: in std_logic;
nRst: in std_logic;    -- Reset
PedestriansRed : out std_logic;
PedestriansYellow : out std_logic;
PedestriansGreen: out std_logic;
CarsRed : out std_logic;
CarsYellow: out std_logic;
CarsGreen : out std_logic);
end TrafficLights;
```

architecture module of TrafficLights is

-- Enumerated type declaration and state signal declaration

type t\_State is (s0, s1, s2, s3, s4, s5, s6, s7);

signal State : t\_State;

-- Counter for counting clock periods, 1 minute max

signal Counter : integer range 0 to ClockFrequencyHz \* 60;

begin

process(Clk) is

begin

if rising\_edge(Clk) then

if nRst='1' then

-- Reset values

State <= s0;

Counter <= 0;

PedestriansRed <= '0';

PedestriansYellow <= '1';

PedestriansGreen <= '1';

CarsRed <= '0';

CarsYellow <= '1';

CarsGreen <= '1';

```

else
-- Default values
Counter <= 0;

PedestriansRed   <= '0';
PedestriansYellow <= '1';
PedestriansGreen <= '1';

CarsRed          <= '0';
CarsYellow       <= '1';
CarsGreen        <= '1';

Counter <= Counter +1;

case State is
-- Red in all directions
when s0 =>

PedestriansRed   <= '0';
PedestriansYellow <= '1';
PedestriansGreen <= '1';

CarsRed          <= '0';
CarsYellow       <= '1';
CarsGreen        <= '1';

if Counter = ClockFrequencyHz *100 -1 then
Counter <=0;
State <= s1;
end if;

```

```
-- Red and yellow in Pedestrians/Cars direction  
when s1 =>
```

```
PedestriansRed  <= '0';
```

```
PedestriansYellow <= '1';
```

```
PedestriansGreen <= '1';
```

```
CarsRed         <= '1';
```

```
CarsYellow      <= '0';
```

```
CarsGreen       <= '1';
```

```
if Counter = ClockFrequencyHz * 20 -1 then
```

```
Counter <=0;
```

```
State <= s2;
```

```
end if;
```

```
-- Green/Red in Cars/Pedestrians direction  
when s2 =>
```

```
PedestriansRed  <= '0';
```

```
PedestriansYellow <= '1';
```

```
PedestriansGreen <= '1';
```

```
CarsRed         <= '1';
```

```
CarsYellow      <= '1';
```

```
CarsGreen       <= '0';
```

```
if Counter = ClockFrequencyHz * 100 -1 then
```

```
Counter <=0;
```

```
State <= s3;
```

```
end if;
```

```
-- Yellow/Red in Cars/Pedestrians direction  
when s3 =>
```

```
PedestriansRed  <= '0';
```

```
PedestriansYellow <= '1';
```

```
PedestriansGreen <= '1';
```

```
CarsRed        <= '1';
```

```
CarsYellow     <= '0';
```

```
CarsGreen      <= '1';
```

```
if Counter = ClockFrequencyHz * 20 -1 then
```

```
Counter <=0;
```

```
State <= s4;
```

```
end if;
```

```
-- Red in all directions
```

```
when s4 =>
```

```
PedestriansRed  <= '0';
```

```
PedestriansYellow <= '1';
```

```
PedestriansGreen <= '1';
```

```
CarsRed        <= '0';
```

```
CarsYellow     <= '1';
```

```
CarsGreen      <= '1';
```

```
if Counter = ClockFrequencyHz * 40 -1 then
```

```
Counter <=0;
```

```
State <= s5;
```

```
end if;
```



```
-- Red and yellow in Pedestrians/Cars direction
```

```
when s5 =>
```

```
PedestriansRed  <= '1';
```

```
PedestriansYellow <= '0';
```

```
PedestriansGreen <= '1';
```

```
CarsRed        <= '0';
```

```
CarsYellow     <= '1';
```

```
CarsGreen      <= '1';
```

```
if Counter = ClockFrequencyHz * 20 -1 then
```

```
Counter <=0;
```

```
State <= s6;
```

```
end if;
```

```
-- Green/Red in Pedestrians/Cars direction
```

```
when s6 =>
```

```
PedestriansRed  <= '1';
```

```
PedestriansYellow <= '1';
```

```
PedestriansGreen <= '0';
```

```
CarsRed        <= '0';
```

```
CarsYellow     <= '1';
```

```
CarsGreen      <= '1';
```

```
if Counter = ClockFrequencyHz * 100 -1 then
```

```
Counter <=0;
```

```
State <= s7;
```

```
end if;
```

```

-- Yellow/Red in Pedestrians/Cars direction
when s7 =>

PedestriansRed  <= '1';

PedestriansYellow <= '0';

PedestriansGreen <= '1';

CarsRed        <= '0';

CarsYellow     <= '1';

CarsGreen      <= '1';

if Counter = ClockFrequencyHz * 20 -1 then

Counter <=0;

State <= s0;

end if;

end case;


end if;

end if;

end process;

end architecture;

```

## **VHDL Simulation**

### **Testbench Code:**

```
use ieee.numeric_std.all;
```

```
entity test_bench is
```

```
end test_bench;
```

```
architecture test of test_bench is
```

```
constant ClockFrequencyHz : integer := 100;
```

```
constant ClockPeriod      : time    := 1000 ms / ClockFrequencyHz ;
```

```
signal Clk:          std_logic := '1' ;
```

```
signal nRst:         std_logic := '0' ;
```

```
signal PedestriansRed: std_logic;
```

```
signal PedestriansYellow: std_logic;
```

```
signal PedestriansGreen: std_logic;
```

```
signal CarsRed:       std_logic;
```

```
signal CarsYellow:    std_logic;
```

```
signal CarsGreen:     std_logic;
```

```
begin
```

```
i_TrafficLights : entity work.TrafficLights
```

```
generic map(ClockFrequencyHz => ClockFrequencyHz)
```

```
port map (
```

```
Clk => Clk,
```

```
nRst => nRst,
```

```
PedestriansRed => PedestriansRed,
```

```
PedestriansYellow => PedestriansYellow,
```

```
PedestriansGreen => PedestriansGreen,
```

```
CarsRed          => CarsRed,
```

```
CarsYellow       => CarsYellow,
```

```
CarsGreen        => CarsGreen);
```

```
Clk <= not Clk after ClockPeriod /2;
```

```
process is
```

```
begin
```

```
wait until rising_edge(Clk);
```

```
wait until rising_edge(Clk);
```

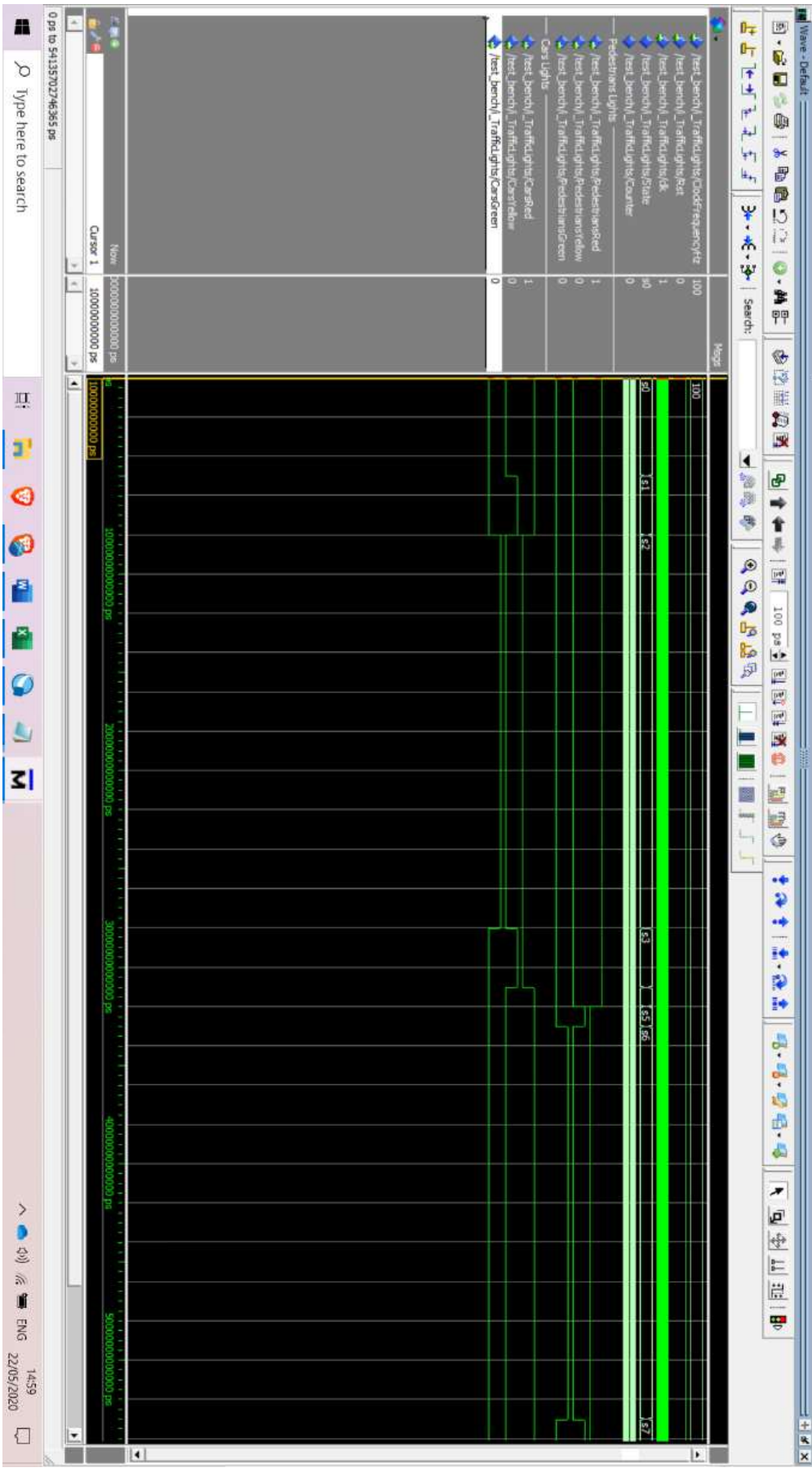
```
nRst <= '1';
```

```
wait;
```

```
end process;
```

```
end architecture;
```





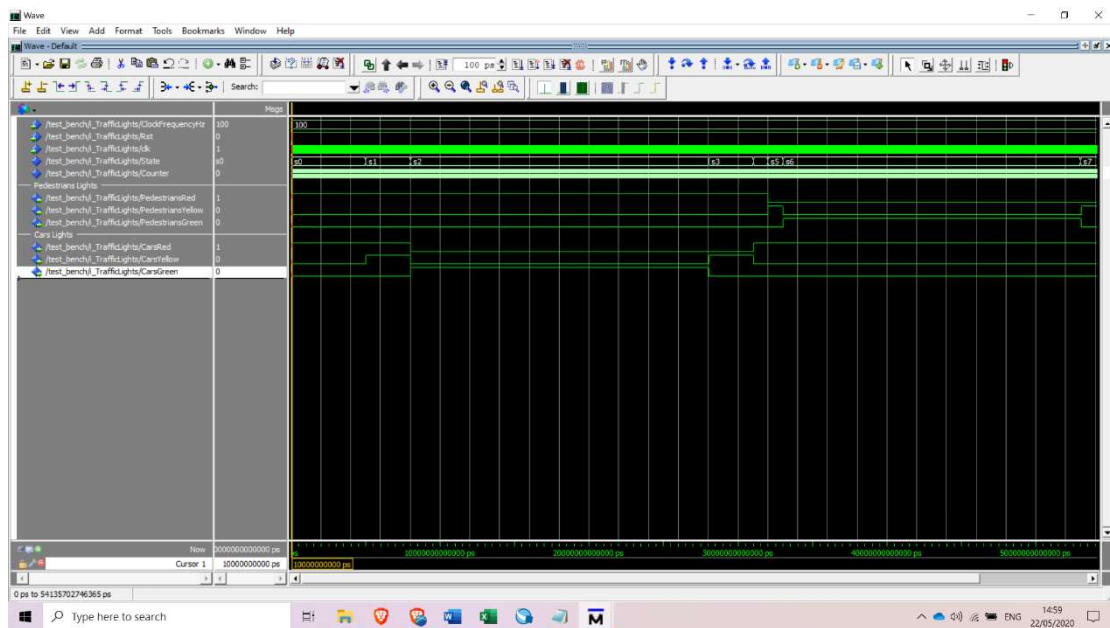


Figure 5,6,7 Simulation Results

The simulation results show how the FSM works and the delays between them. Also, it displays the frequency, the reset(Rst), the clock(clk), the state and the Counter. From the simulation images, the state change from the s0 to s7 and then goes back again in a specific time and the frequency has changed only for practice purposes from 5000000 to 100Hz. The clock and the reset works correctly.



## Testing of Code:

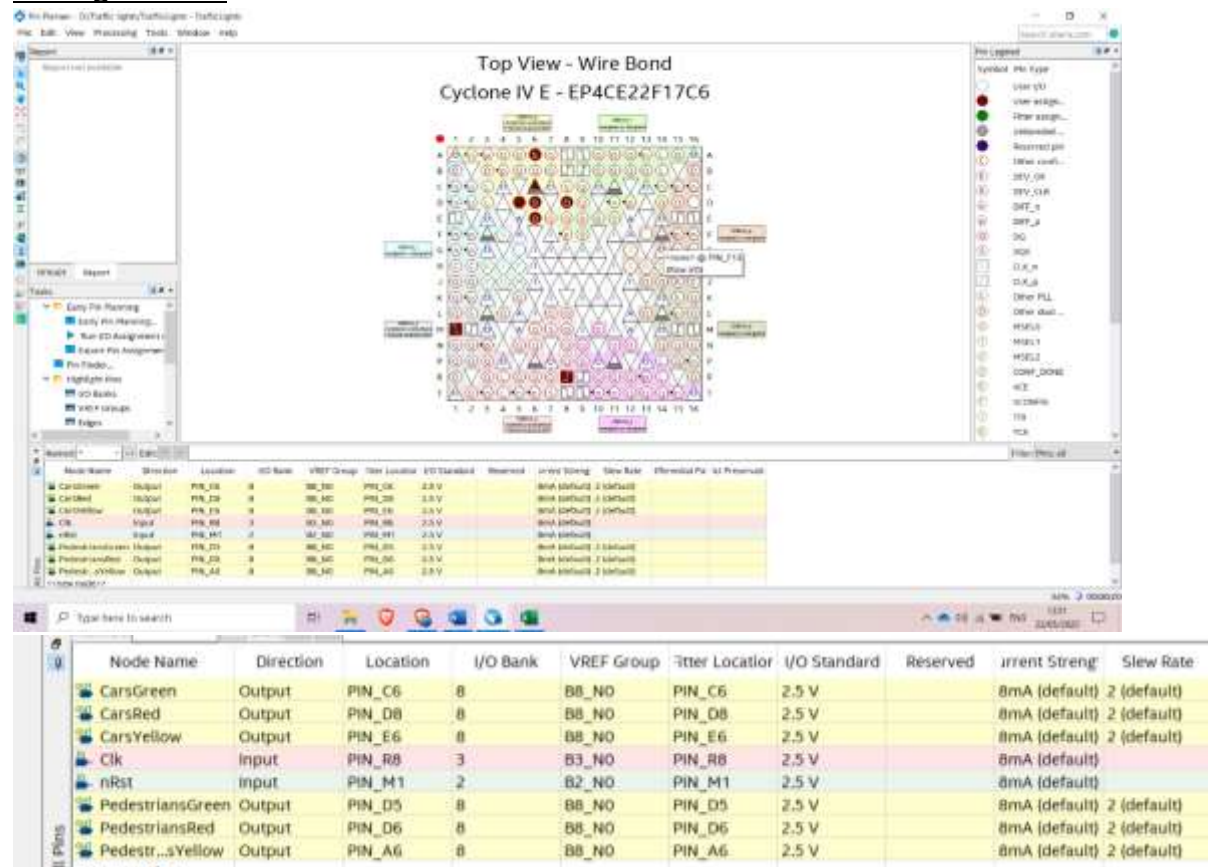


Figure 8 Pin Allocations

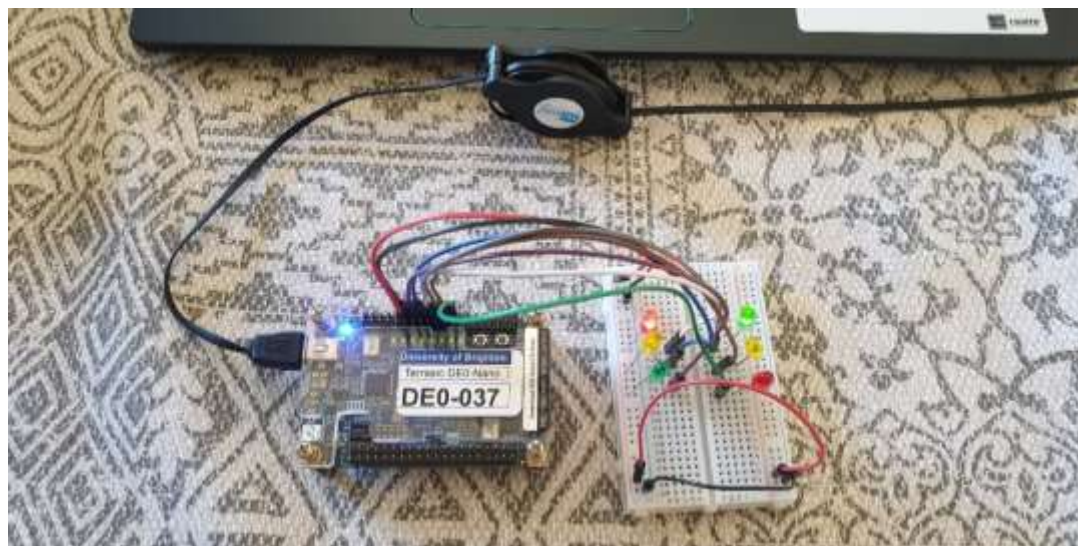


Figure 9 Target Board



The results from these connections are the led work properly. The Pin allocations, led connections were found from the DE0-Nano board Manual. The LEDs are slotted to the VCC. This protoboard takes from the de0 board all the voltage, current that it needs by using specific connections which also found in the manual.

**Conclusion:**

To conclude, the project worked well in steps during the semester. There were some issues with the delays between the changing states, but they solved by searching through the construction of the VHDL Code and studying further the lectures of this module. Furthermore, another problem that came up was the hardware setup(protoboard connection with de0 board) which also solved by reading the manual of the de0 board. This module was challenging because of the work that the student had to do. To understand fully this module a student needed to work a lot through the semester on his own time to achieve this and this is why this project was challenging.